# Partially Defined Boolean Functions, Classification, and Logical Analysis of Data

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#### based on earlier presentations by Endre Boros

Based on numerous papers by E. Boros, Y. Crama, P.L. Hammer, T. Ibaraki, A. Kogan, K. Makino, etc.

#### Outline

- Learning from Examples
- Partially Defined Boolean Functions
- Logical Analysis of Data

#### Data: Examples















## **Testing:**













Common measures of classifier quality involve new data:

• training - test partition, cross validation (assumes distribution of future examples follows that of data)



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Common measures of classifier quality involve new data:

- training test partition, cross validation (assumes distribution of future examples follows that of data)
- **simulation** (assumes knowledge of distribution of future examples)
- clinical trial (done "in the future")

# WHAT (ANNOT BE LEARNED FROM EXAMPLES!



"Just a darn minute! — Yesterday you said that X equals **two**!"

## Some typical examples

- Credit approval. Data: attributes of applicants for credit card vs. decision.
- Customer targeting. Data: attributes of customers vs. decision to buy.
- Medical diagnosis. Data: symptoms or bio-medical features vs. diagnosis.

Attributes:	$A, B, \dots$ in domains A, B,
Data Set:	$\mathbf{D} = \left\{ \mathbf{X}^{i} = (X_{A}^{i}, X_{B}^{i},) \mid i = 1,, M \right\}$
Class:	$c:\mathbf{D}\longrightarrow \{0,1\}$

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**Classifier:**  $f : A \times B \times \cdots \longmapsto \{0, 1\}$ 

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There may be many classifiers for a same data set.

		Test Results				
	ID	$x_1$	$x_2$	xз	x4	
	А	1	1	0	1	
$\mathbb{T}$	В	0	1	1	1	
	С	1	1	1	0	
	Т	0	0	1	1	
יקו	U	1	0	0	1	
Ш	V	1	0	1	0	
	$\mathbf{V}$	0	1	1	0	

		ר	Test F	Result	S	Dr. F
	ID	$x_1$	$x_2$	x3	$x_{4}$	$ x_1 + x_2 + x_3 + x_4 \ge 3$
	А	1	1	0	1	1
$\mathbb{T}$	В	0	1	1	1	1
	С	1	1	1	0	1
F	Т	0	0	1	1	0
	U	1	0	0	1	0
	V	1	0	1	0	0
	$\mathbf{W}$	0	1	1	0	0

		ר	Test F	Result	S	Dr. F	Dr. G
	ID	$x_1$	$x_2$	xз	$x_{4}$	$x_1 + x_2 + x_3 + x_4 \ge 3$	$\mathbf{x}_1 + 2\mathbf{x}_2 + \mathbf{x}_4 \ge 3$
	A	1	1	0	1	1	1
$\mathbb{T}$	В	0	1	1	1	1	1
	С	1	1	1	0	1	1
	Т	0	0	1	1	0	0
$\mathbb{F}$	U	1	0	0	1	0	0
	V	1	0	1	0	0	0
	$\mathbf{W}$	0	1	1	0	0	0

		Test Results			Test Results Dr. F	Dr. G		
	ID	$x_1$	$x_2$	xз	<i>x</i> 4	$x_1 + x_2 + x_3 + x_4 \ge 3$	$\mathbf{x}_1 + 2\mathbf{x}_2 + \mathbf{x}_4 \geq 3$	
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Щ	V	1	0	1	0	0	0	
	W	0	1	1	0	0	0	
	Ms. Y	1	1	0	0			
	Mr. Z	1	0	1	1			

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#### **Partially Defined Boolean Functions**

- Definition
- Support sets
- Patterns
- Theories

#### **Definitions**

**Attributes**:  $V = \{1, 2, ..., n\}$ .

**Boolean function**:  $f : \{0, 1\}^V \longrightarrow \{0, 1\}.$ 

True vectors of  $f: T(f) = \{x \in \{0, 1\}^V | f(x) = 1\}.$ 

False vectors of f:  $F(f) = \{x \in \{0, 1\}^V | f(x) = 0\}.$ 

$$T(f) \cap F(f) = \emptyset$$
 and  $T(f) \cup F(f) = \{0, 1\}^V$ 

#### **Definitions**

A term  ${\bf t}$  is a Boolean function defined by an elementary conjunction

$$\mathbf{t}(\mathbf{x}) = \bigwedge_{j \in P} x_j \wedge \bigwedge_{j \in N} \overline{x}_j$$

where  $P, N \subseteq V$ , and  $\overline{x} = 1 - x$ .

The conjunction takes value 1 (or "true") if and only if

$$x_j = 1$$
 for all  $j \in P$  and  $x_j = 0$  for all  $j \in N$ .

The set of true vectors of a term forms a **sub-cube** of  $\{0,1\}^V$ , and vice-versa, every sub-cube, is the set of true vectors of a Boolean function, defined by a unique term.

## Sub-cubes and Terms in $\{0,1\}^3$



 $[a,b] = \{(000),(001),(100),(101)\} \ = \ (*0*) \ = \ T(\overline{x}_2)$ 

# Sub-cubes and Terms in $\{0,1\}^3$



#### **Definitions**

Every Boolean function can be represented as a **disjunctive normal form (DNF)**, that is, as a disjunction (OR) of terms (elementary conjunctions):

$$f(\mathbf{x}) = \bigvee_{(P,N)\in E} \left( \bigwedge_{j\in P} x_j \wedge \bigwedge_{j\in N} \overline{x}_j \right)$$

where  $P, N \subseteq V$ , and  $\overline{x} = 1 - x$ .

The DNF takes value 1 (or "true") if and only if at least one of its terms takes value 1.

Geometrically: the set of true vectors of f is covered by a union of subcubes of  $\{0,1\}^V$ .

#### Boolean functions as DNFs



#### **Definitions**

**Training Data**: a pair of subsets  $(\mathbf{T}, \mathbf{F})$  such that

 $\mathbf{T} \subseteq \{0,1\}^V, \quad \mathbf{F} \subseteq \{0,1\}^V, \quad \text{and} \quad \mathbf{T} \cap \mathbf{F} = \emptyset.$ 

We call such a pair  $(\mathbf{T}, \mathbf{F})$  a *partially defined Boolean function* (or **pdBf** in short).

**Classifier**: a Boolean function  $f : \{0, 1\}^V \longrightarrow \{0, 1\}$ , which is an **extension** of  $(\mathbf{T}, \mathbf{F})$ , i.e., for which

$$\mathbf{T} \subseteq T(f)$$
 and  $\mathbf{F} \subseteq F(f)$ .

Let  $\mathcal{E}(\mathbf{T}, \mathbf{F})$  denote the family of all extensions. Clearly, we have

$$|\mathcal{E}(\mathbf{T},\mathbf{F})| = 2^{2^n - |\mathbf{T} \cup \mathbf{F}|}$$

#### What can guide learning?

If |V| = 20 and  $|(\mathbf{T}, \mathbf{F})| = 1000$ , then

 $|\mathcal{E}(\mathbf{T},\mathbf{F})| > 2^{1,000,000}$ 

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- Simplicity
  - Essential attributes
  - Function  $f \in \mathcal{E}(\mathbf{T}, \mathbf{F})$
  - Representation (DNF, CNF, decision tree, etc.)

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- Simplicity
  - Essential attributes
  - Efficient representation (DNF, CNF, decision tree, etc.)
- Justifiability

Note on framework: we mostly speak here of building *unspecified models*, as opposed to *specified models* such as regression models (which assume a priori knowledge about the relation between inputs and outputs).

#### **Building reasonable extensions**

Given  $(\mathbf{T}, \mathbf{F})$ , how can we build a reasonable extension  $f \in \mathcal{E}_T(\mathbf{T}, \mathbf{F})$ ?

#### Many ways....

For example, **nearest neighbor** methods, **decision trees**, or **neural networks** build such classifiers.

Define a notion of **distance**  $\rho(X, Y)$  between any two points X, Y in the input space.

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Example in the Boolean case.



 $\mathbf{F} = \{(110), (101)\}$ 

 $\mathbf{T} = \{(010), (100)\}$
#### **Nearest Neighbor classifiers**

Example in the Boolean case.



(111) is classified as red (false)

(000) is classified as blue (true)



 $\mathbf{F} = \{(110), (101)\}$ 

 $T = \{(010), (100)\}$ 

















 $\mathrm{f}_D = \overline{\mathrm{x}}_1 \vee \mathrm{x}_1 \overline{\mathrm{x}}_2 \overline{\mathrm{x}}_3 = \overline{\mathrm{x}}_1 \vee \overline{\mathrm{x}}_2 \overline{\mathrm{x}}_3$ 





$$\begin{split} \mathbf{f}_D &= \overline{\mathbf{x}}_1 \lor \mathbf{x}_1 \overline{\mathbf{x}}_2 \overline{\mathbf{x}}_3 = \overline{\mathbf{x}}_1 \lor \overline{\mathbf{x}}_2 \overline{\mathbf{x}}_3 \\ \\ \overline{\mathbf{f}}_D &= \mathbf{x}_1 \mathbf{x}_2 \lor \mathbf{x}_1 \overline{\mathbf{x}}_2 \mathbf{x}_3 = \mathbf{x}_1 \mathbf{x}_2 \lor \mathbf{x}_1 \mathbf{x}_3 \end{split}$$

Note: (001) is classified differently by NN and by DT

#### Linear separator



Decide whether  $\mathbf{T}$  and  $\mathbf{F}$  can be separated by a hyperplane.

This is a simple linear programming problem.

Similar to recognizing a weighted majority game.

# Logical Analysis of Data

LAD: Introduced in Crama, Hammer and Ibaraki (1988).

Based on the representation of extensions by DNFs and on selection of

- subsets of relevant variables (support sets)
- relevant terms (patterns)
- relevant disjunctions of terms (theories)

## **Partially Defined Boolean Functions**

- Definition
- Support sets
- Patterns
- Theories

## **Finding Essential Attributes**

- Select relevant features.
- Eliminate noise.
- Compress data.

## **Relevance and its evaluations**

- Well defined for *complete* systems: an attribute is relevant, if changing its value changes the classification of some situations.
- Measures of relevance are based on counting such situations (with slight variations, e.g., *coalitions' power* in game theory; *voters' influence* in voting schemes, etc., Shapley (1954), Chow (1961), Banzhaf (1965), Winder (1971), Kahn, Kalai and Linial (1988), Hammer, Kogan and Rohtblum (2000))
- These definitions cannot be easily extended to incomplete data sets in a consistent way, see e.g., John, Kohavi and Pfleger (1994).

# Eliminate Noise: What is it?

- A random attribute?
- An irrelevant attribute?
- An (almost) constant attribute?
- A dependent attribute?

# Data compression

- The simpler, the better! "Occam's Razor:" Theories built on smaller attribute sets, generalize better. Blumer,Ehrenfeucht,Haussler and Warmuth (1987)
- Decreases the computational complexity of finding and using a classifier.
- Decreases the cost of future data collection.

Find a small (smallest, if possible) subset of the attributes which distinguishes the sets  $\mathbb{T}$  and  $\mathbb{F}$ . Such a subset is called a support set.

Crama, Hammer and Ibaraki (1988).

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Finding a smallest support set is NP-hard.

Algorithmic Approaches to find a small(est) support set:

- complete enumeration: FOCUS (Almuallim and Dietterich, 1994) ...
- greedy search: Rel-FSS (Bell and Wang, 2000) ...
- computing relevance index: (Kira and Rendell, 1992) ...
- etc., ... over 40 references in the past decade.

Note that decision trees automatically select a (small) support set.

A set covering model to find a small(est) support set:

- associate a 0-1 variable  $a_i$  with each attribute  $A_i$
- for every pair of false example X and true example Y, express that at least one of the attributes differentiating X from Y must be chosen:

for all 
$$X \in \mathbb{F}, Y \in \mathbb{T}, \sum_{i:x_i \neq y_i} a_i \ge 1$$

• minimize  $\sum_i a_i$ .

This model can be solved either exactly, or heuristically.

Questions to clarify

Why a small(est) feature set??

Which one??

How to measure the quality of a support set?

• Typically, there are many support sets of different sizes.

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- Typically, there are many support sets of different sizes.
- The larger the data set, the less likely to have a small support set.
- The larger the data set, the more **surprising** to have a small support set.
- OUR SURPRISE  $\approx$  INFORMATION IN DATA

## **The Good News**

#### Boros, Horiyama, Ibaraki, Makino and Yagiura, 2003 Distribution of Support Sets in Randomly Generated Data

	K	5	6	7	8	9	10	11	12
n = 10	LB	22	34	46	60	66			
	UB	60	58	68	80	84			
n = 15	LB	26	42	62	90	126	176	238	312
	UB	$\infty$	82	98	126	164	214	278	352
n = 20	LB	30	46	70	102	150	216	306	432
	UB	$\infty$	102	116	150	198	268	364	494
n = 40	LB	34	54	84	126	198	278	408	594
	UB	$\infty$	$\infty$	156	196	262	358	498	694
n = 100	LB	38	62	96	148	226	336	500	734
	UB	$\infty$	$\infty$	236	252	330	450	624	876
n = 1000	LB	46	76	122	190	292	442	662	982
	UB	$\infty$	$\infty$	$\infty$	420	480	672	874	1220

Lower and upper bounds on the threshold size of data sets (assuming  $|\mathbb{T}| = |\mathbb{F}|$  and uniform random generation) above which support sets of size K are unlikely to exists.

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- If we have 20 attributes and less than 46 records, then it is very likely to have many support sets of size 6 or smaller.
- If we have more than 102 records, then it is very unlikely to have a support set of size 6 or smaller ⇒ If there is one ...

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- If, in a data set with 1000 attributes and more than 672 records, we find a **support set of size** 10, then
  - it might be a unique one;
  - it is probably related to the structure of the data, and not to random noise.

# **Partially Defined Boolean Functions**

- Definition
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# Definitions

```
A term t is a pattern of (T, F) if
```

 $\mathbf{T} \cap T(\mathbf{t}) \neq \emptyset$  and  $\mathbf{F} \subseteq F(\mathbf{t}),$ 

or

t(x) = 1 for at least one  $x \in T$  and t(x) = 0 for all  $x \in F$ .

A pattern corresponds to a combination of attributes which has been observed at least once in a true data point, but which never occurs in a false data point.

A pattern of  $(\mathbf{F}, \mathbf{T})$  is called a **co-pattern** of  $(\mathbf{T}, \mathbf{F})$ .

Pat(T, F) and co-Pat(T, F) denote the families of all patterns and copatterns of (T, F), respectively.

# Returning to the medical example

		Test Results						
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	V	1	0	1	0			
	W	0	1	1	0			
	Ms. Y	1	1	0	0			
	Mr. Z	1	0	1	1			

Some patterns:

 $x_1x_2, x_2\overline{x}_3, x_2x_4, \ldots$ 

Some co-patterns:

 $\overline{x}_1\overline{x}_2, \overline{x}_2, \overline{x}_1\overline{x}_4, \dots$ 

# **Partially Defined Boolean Functions**

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## **Theories and Co-Theories**

An extension  $f \in \mathcal{E}(\mathbf{T}, \mathbf{F})$  is called a **theory** of  $(\mathbf{T}, \mathbf{F})$  if it can be represented as a disjunction of some of the patterns of  $(\mathbf{T}, \mathbf{F})$ .

A theory g of  $(\mathbf{F}, \mathbf{T})$  is called a **co-theory** of  $(\mathbf{T}, \mathbf{F})$  (it can be represented by a disjunction of some of the co-patterns of  $(\mathbf{T}, \mathbf{F})$ ).

Denote by  $\mathcal{E}_T(\mathbf{T}, \mathbf{F})$  and  $\mathcal{E}_T(\mathbf{F}, \mathbf{T})$  the families of theories and co-theories of a given pdBf  $(\mathbf{T}, \mathbf{F})$ .

Typically we have

 $|\mathcal{E}_T(\mathbf{T},\mathbf{F})| \ll |\mathcal{E}(\mathbf{T},\mathbf{F})|$ 

#### **Examples**

#### **Nearest Neighbor classifier**



(111) is classified as red (false)

(000) is classified as blue (true)

**Classifier:**  $f_{NN} = \overline{x}_1 x_2 \lor \overline{x}_2 \overline{x}_3$ .

This classifier is a theory.

#### **Examples**

#### **Decision Trees for pdBfs**





$$\begin{split} \mathbf{f}_{\mathrm{D}} &= \overline{\mathbf{x}}_1 \vee \mathbf{x}_1 \overline{\mathbf{x}}_2 \overline{\mathbf{x}}_3 = \overline{\mathbf{x}}_1 \vee \overline{\mathbf{x}}_2 \overline{\mathbf{x}}_3 \\ \\ \overline{\mathbf{f}}_{\mathrm{D}} &= \mathbf{x}_1 \mathbf{x}_2 \vee \mathbf{x}_1 \overline{\mathbf{x}}_2 \mathbf{x}_3 = \mathbf{x}_1 \mathbf{x}_2 \vee \mathbf{x}_1 \mathbf{x}_3 \end{split}$$

 $f_D$  is a theory and  $\overline{f}_D$  is a co-theory .

## Theories as justifiable classifiers

Theory f classifies an example x as a "positive" example if f(x) = 1.

This is the case only if (at least) one pattern of f is "triggered" by x, meaning that we have observed earlier another positive example displaying the same features, and we have never observed a negative example displaying these features.

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In both cases, we can provide some explanation or justification for the classification, but not for the opposite one.

A pair of a theory  $f \in \mathcal{E}_T(\mathbf{T}, \mathbf{F})$  and a co-theory  $g \in \mathcal{E}_T(\mathbf{F}, \mathbf{T})$  can be used to define a classifier F:

$$F_{f,g}(\mathbf{x}) = \begin{cases} 1 & \text{if } f(\mathbf{x}) = 1 \text{ and } g(\mathbf{x}) = 0, \\ 0 & \text{if } f(\mathbf{x}) = 0 \text{ and } g(\mathbf{x}) = 1, \\ ? & \text{otherwise} \end{cases}$$

Such a classifier can justify all its definite answers with evidence from  $(\mathbf{T}, \mathbf{F})$ , however, it may not be able to give an answer for all  $\mathbf{x} \in \{0, 1\}^V$ !

To avoid such uncertainties, ideally we would like to use a pair for which

$$\overline{g} = f$$

A theory  $f \in \mathcal{E}_T(\mathbf{T}, \mathbf{F})$  is called a **bi-theory** of  $(\mathbf{T}, \mathbf{F})$  if  $\overline{f}$  is a co-theory of  $(\mathbf{T}, \mathbf{F})$ .

Then, the pair  $(f, \overline{f})$  defines a classifier  $F_{f,\overline{f}}$  which always provides evidence to support its answers.

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#### Do we always have bi-theories?

**YES**, in fact (most) nearest neighbor approaches and decision tree based methods build a classifier  $F_{f,\overline{f}}$  for some bi-theory  $f \in \mathcal{E}_B(\mathbf{T}, \mathbf{F})$ .

A theory  $f \in \mathcal{E}_T(\mathbf{T}, \mathbf{F})$  is called a **bi-theory** of  $(\mathbf{T}, \mathbf{F})$  if  $\overline{f}$  is a co-theory of  $(\mathbf{T}, \mathbf{F})$ .

Then, the pair  $(f, \overline{f})$  defines a classifier  $F_{f,\overline{f}}$  which always provides evidence to support its answers.

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But in general, some bi-theories do not correspond to any decision tree nor to any nearest neighbor classifier.

### Conclusions

• Bi-theories and decision trees are very strongly related.

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- Bi-theories and decision trees are very strongly related.
- Bi-theories and nearest neighbor approaches are very strongly related.
- Patterns and co-patterns are the basic building blocks in all these methods.

### Logical Analysis of Data

Extensions and applications of LAD

- Binarization of numerical attributes
- Binarization of categorical attributes
- Pattern generation
- Theory building

#### **Binarization – Numerical Attributes**

		Attrib	outes				Binarized	Attributes
	ID	Α	• • •			ID	$A \ge 2.9$	
@+	001	1.7		_		001	0	
	002	3.5			et the second	002	1	
2	003	4.2			ш	003	1	
	004	9.3				004	1	
	991	2.3				991	0	
$\mathbb{S}^{-}$	992	6.2			$\mathbb{F}$	992	1	
	993	7.5				993	1	



#### **Binarization – Numerical Attributes**

		Attributes			Binarize	ed Attrib	utes
	ID	<b>A</b> ····		ID	$A \ge 2.9$	$A \ge 5.2$	• • •
s+	001	1.7		001	0	0	
	002	3.5		002	1	0	
	003	4.2	Ш	003	1	0	
	004	9.3		004	1	1	
	991	2.3		991	0	0	
$\mathbb{S}^-$	992	6.2	$\mathbb{F}$	992	1	1	
	993	7.5		993	1	1	



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		Attrib	utes			Binarize	ed Attrib	utes
	ID	Α	• • •		ID	$A \ge 2.9$	$A \ge 5.2$	• • •
s+	001	1.7			001	0	0	
	002	3.5		dl.	002	1	0	
	003	4.2		ш	003	1	0	
	004	9.3			004	1	1	
	991	2.3			991	0	0	
$\mathbb{S}^-$	992	6.2		$\mathbb{F}$	992	1	1	
	993	7.5			993	1	1	



Linear time generation; up to 40 cut points per attribute

# **Binarization**

$c(\mathbf{X})$	A	B	C
1	5.7	3.1	blue
1	1.2	4.2	green
1	3.1	5.1	blue
1	2.8	3.2	green
0	7.1	7.3	red
0	5.9	3.6	yellow
0	6.4	4.2	blue
0	3.4	1.6	green

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1	5.7	3.1	blue
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0	7.1	7.3	red
0	5.9	3.6	yellow
0	6.4	4.2	blue
0	3.4	1.6	green

	$A \ge 6$	• • •	$B \geq 3$	• • •	C = blue	• • •
	0		1		1	
	0		1		0	
	0	• • •	1	•••	1	•••
$\longrightarrow$	0		1		0	
	1		1		0	
	0		1		0	
	1	• • •	1	• • •	1	• • •
	0		0		0	

# **Binarization**

$c(\mathbf{X})$	A	B	C		$A \ge 6$	• • •	$B \geq 3$	• • •	C = blue	•••
1	5.7	3.1	blue		0		1		1	
1	1.2	4.2	green		0		1		0	
1	3.1	5.1	blue		0	•••	1	•••	1	• • •
1	2.8	3.2	green	$\longrightarrow$	0		1		0	
0	7.1	7.3	red		1		1		0	
0	5.9	3.6	yellow		0		1		0	
0	6.4	4.2	blue		1	•••	1	•••	1	• • •
0	3.4	1.6	green		0		0		0	

 $c(\mathbf{X}) = (A < \mathbf{6}) \land (B \ge \mathbf{3}) \land (C \in \{blue, green\})$ 

### Logical Analysis of Data

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		Test Results					
	ID	$\mathbf{x}_1$	$\mathbf{x}_2$	$\mathbf{x_3}$	x <sub>4</sub>		
	А	1	1	0	1		
$\mathbb{T}$	В	0	1	0	1		
	С	1	0	0	0		
	Т	0	0	0	1		
יקו	U	1	0	1	1		
ш	V	1	1	0	0		
	$\mathbf{V}\mathbf{V}$	0	1	0	0		

Pattern:  $P(x) = x_2 x_4$ 

 $P(b) = 0 \quad \forall \ b \in \mathbb{F}$ 

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	ID	$\mathbf{x}_1$	$\mathbf{x_2}$	$\mathbf{x_3}$	$\mathbf{x}_4$			
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$\mathbb{T}$	В	0	1	0	1			
	С	1	0	0	0			
	Т	0	0	0	1			
יבו	U	1	0	1	1			
Г	V	1	1	0	0			
	$\mathbf{W}$	0	1	0	0			

Pattern:  $P(x) = x_2 x_4$ 

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**Coverage**:  $cov(\mathbf{P}) = 2 > 0$ number of positive examples covered

**Precision**:  $\pi(\mathbf{P}) = 2/7 > 0$ fraction of data correctly classified

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	ID	x <sub>1</sub>	$\mathbf{x_2}$	$\mathbf{x_3}$	$\mathbf{x}_4$		
	А	1	1	0	1		
$\mathbb{T}$	В	0	1	0	1		
	С	1	0	0	0		
	Т	0	0	0	1		
יבו	U	1	0	1	1		
Ц	V	1	1	0	0		
	W	0	1	0	0		

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	А	1	1	0	1		
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ľ	V	1	1	0	0		
	$\mathbf{W}$	0	1	0	0		

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#### TOO MANY!

		<b>Test Results</b>					
	ID	$\mathbf{x}_1$	$\mathbf{x_2}$	$\mathbf{x_3}$	$\mathbf{x}_4$		
	А	1	1	0	1		
$\mathbb{T}$	В	0	1	0	1		
	С	1	0	0	0		
	Т	0	0	0	1		
יבו	U	1	0	1	1		
ľ	V	1	1	0	0		
	$\mathbf{W}$	0	1	0	0		

Pattern:  $P(x) = x_2 x_4$ 

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Ideally, we would like to generate all patterns with high coverage:

 $\mathcal{P}(\mathbf{T}, \mathbf{F}, \gamma) = \{\mathbf{P} \mid cov(\mathbf{P}) \geq \gamma |\mathbf{T}|\}$ 

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	ID	x <sub>1</sub>	$\mathbf{x}_{2}$	$\mathbf{x_3}$	$\mathbf{x}_4$			
T	А	1	1	0	1			
	В	0	1	0	1			
	С	1	0	0	0			
F	Т	0	0	0	1			
	U	1	0	1	1			
	V	1	1	0	0			
	$\mathbf{W}$	0	1	0	0			

Pattern:  $P(x) = x_2 x_4$ 

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Ideally, we would like to generate **all** patterns with high coverage:

 $\mathcal{P}(\mathbf{T}, \mathbf{F}, \gamma) = \{\mathbf{P} \mid cov(\mathbf{P}) \geq \gamma |\mathbf{T}|\}$ 

#### NP-hard!

Even if  $|\mathcal{P}(\mathbf{T}, \mathbf{F}, \gamma)|$  is *small*, we cannot guarantee finding them all, unless P=NP!

### **Patterns**

In practice, generation heuristics concentrate for instance on patterns of small degree, high coverage, high precision.

Remember:

 $cov(\mathbf{P}) =$  number of positive examples covered by  $\mathbf{P}$ 

 $\pi(\mathbf{P}) =$  fraction of examples correctly classified by  $\mathbf{P}$ 

$c(\mathbf{X})$	$ A_1 $	$A_2$	$A_3$	$A_4$	$A_5$	$  \mathbf{P}(\mathbf{X}) = \overline{\mathbf{A}}_1 \wedge \mathbf{A}_3 \wedge \mathbf{A}_4  $
1	0	0	1	1	1	1
1	0	1	1	0	1	0
1	0	0	1	1	0	1
1	0	0	1	0	1	0
1	0	1	1	1	0	1
0	1	0	1	1	0	0
0	1	1	1	1	1	0
0	0	1	1	0	0	0
0	0	0	0	0	0	0
0	0	1	0	1	1	0

**Coverage**:  $cov(\mathbf{P}) = 3$  **Precision**:  $\pi(\mathbf{P}) = 0.8$ 

### **Patterns**

There is considerable empirical evidence that patterns with high precision on a training (data) set **generalize** well, in the sense that they provide classifiers with high precision on subsequent test sets.

http://www.ics.uci.edu/ mlearn/MLRepository.html

O. L. Mangasarian and W. H. Wolberg: "Cancer diagnosis via linear programming", *SIAM News*, Volume **23**, Number 5, September 1990, pp. 1-18.

- Number of Instances: 699 (status of 15 July 1992)
- Number of Attributes: 9 with integer values between 1 and 10
- Missing attribute values: 16, all for attribute "Bare-nuclei".
- Class distribution:
  - Benign: **458** (65.5%)
  - Malignant: 241 (34.5%)

- Training set: 63 records ( $\approx 10\%$ )
- Attributes: 13 binary
- Number of patterns P with  $\pi(P) \ge 0.7$ : 36 (of degrees 2 5)

Performance of the Best Patterns on the Wisconsin Breast Cancer Data Set (10%, 0.6)



- Training set: 63 records ( $\approx 10\%$ )
- Attributes: 13 binary
- Number of patterns P with  $\pi(P) \ge 0.7$ : 36 (of degrees 2 5)
- Single **best** pattern: 95.1%-classifier!!

 $P_1(X) = (Clump-Thickness \le 6) \land (Bare-Nuclei \le 4) \land (Normal-Nucleoli \le 3)$ 

- Misclassifies only 5 malignant cases (all with missing data!)
- Best results reported in literature: 95 98%

http://www.ics.uci.edu/ mlearn/MLRepository.html

- Number of Instances: 8124 (status of April 27, 1987)
- Number of Attributes: 22 with nominal values (126 categories)
- Missing attribute values: 2480, all for attribute stalk-root.
- Class distribution:
  - edible: 4208 (51.8%)
  - poisonous: **3916** (48.2%)

- Training set: 161 records ( $\approx 2\%$ )
- Attributes: **56** binary
- Number of patterns **P** with  $\pi(\mathbf{P}) \ge 0.85$ : **218** (of degrees 2 9)



- Training set: 161 records ( $\approx 2\%$ )
- Attributes: **56** binary
- Number of patterns **P** with  $\pi(\mathbf{P}) \ge 0.85$ : **218** (of degrees 2 9)
- Single **best** pattern: 98.5%-classifier!!

 $P(X) = (Odor \neq none) \land (Odor \neq anise) \land (Odor \neq almond)$ 

• Best results reported in literature: 95 – 99%

# Australian Credit Card Data Set

STATLOG: http://www.ncc.up.pt/liacc/ML/statlog/datasets.html

- Number of Instances: 690
- Number of Attributes: 14 (6 numerical and 8 categorical)
- Missing attribute values: none
- Class distribution:
  - positive: **307** (44.5%)
  - negative: **383** (55.5%)

# Australian Credit Card Data Set

- Training set: **36** records ( $\approx$  5%)
- Attributes: **12** binary
- Number of patterns P with  $\pi(P) \ge 0.60$ : 26 (of degrees 1-4)
## Australian Credit Card Data Set



## Australian Credit Card Data Set

- Training set: 36 records ( $\approx$  5%)
- Attributes: **12** binary
- Number of patterns P with  $\pi(P) \ge 0.60$ : 26 (of degrees 1-4)
- Single **best** pattern: 85.4%-classifier!!

 $\mathbf{P}(\mathbf{X}) = (\mathbf{A8} = \mathbf{0})$ 

• Best results reported in literature: 80 - 87%

#### **STATLOG Results: Australian Credit Card**

	Error Rate	
Algorithm	on training	on test
Cal5	0.132	0.131
Itrule	0.162	0.137
LogDisc	0.125	0.141
Discrim	0.139	0.141
Dipol92	0.139	0.141
Radial	0.107	0.145
Cart	0.145	0.145
Best Pattern	0.111	0.146
Castle	0.144	0.148
Bayes	0.136	0.151
IndCart	0.081	0.152
BackProp	0.087	0.154
C4.5	0.099	0.155
Smart	0.090	0.158
BayTree	0.000	0.171
KNN	0.000	0.181
Ac2	0.000	0.181
NewId	0.000	0.181
LVQ	0.065	0.197
Alloc80	0.194	0.201
Cn2	0.001	0.204
QuaDisc	0.185	0.207
Default	0.440	0.440
Cascade	?	100.0
Kohonen	?	100.0

# **STATLOG: Vehicle Data Set**

STATLOG: http://www.ncc.up.pt/liacc/ML/statlog/datasets.html

- Number of Instances: 846
- Number of Attributes: 18 numerical
- Missing attribute values: none
- Class distribution:
  - OPEL: **212** (25.06%)
  - SAAB: 217 (25.65%)
  - BUS: 218 (25.77%)
  - VAN: **199** (23.52%)

# **STATLOG: Vehicle Data Set**

Averages over the 4 classes

	Error Rate	
Algorithm	on training	on test
QuaDisc	0.085	0.150
Dipol92	0.079	0.151
Alloc80	0.000	0.173
Best Patterns	0.068	0.192
LogDisc	0.167	0.192
BackProp	0.168	0.207
Discrim	0.202	0.216
Smart	0.062	0.217
Cart	0.284	0.235
C4.5	0.065	0.266
BayTree	0.079	0.271
KNN	0.000	0.275
Cal5	0.068	0.279
Cascade	0.263	0.280
LVQ	0.171	0.287
Ac2	?	0.296
IndCart	0.047	0.298
NewId	0.030	0.298
Radial	0.098	0.307
Cn2	0.018	0.314
Itrule	?	0.324
Kohonen	0.115	0.340
Castle	0.545	0.505
Bayes	0.519	0.558
Default	0.750	0.750

A pattern is **good**, if its precision on the **test** set is **high**.

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 $\diamond$  A pattern is **best**, if its precision on the training set is high.

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- ♦ A pattern is **best**, if its precision on the training set is high.
- ♡ Empirical evidence suggests that best patterns generalize very well.

The average precision on the test set, as a function of the precision on the training set, is increasing; its variance, as a function of the precision on the training set, is decreasing.

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A best pattern alone is a very good, simple and robust classifier.

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#### **Theory Building**

Theories can be built by selecting enough patterns to cover all positive examples.

This can be done for instance by solving an optimization problem, either exactly or in a greedy way.

Similarly for co-theories.

Many applications in the literature...

#### **Theory Building**

**Theory formation**: for each vector  $\mathbf{a} \in \mathbf{T}$  we choose at most 5 patterns with the highest coverage from  $\mathcal{P}(\mathbf{a}, \mathbf{T}, \mathbf{F}, \gamma)$ .

Data Set	Training	Test
AU CREDIT*	88.9%	85.4%
BCW	99.7%	97.4%
BUPA	97.4%	90.1%
DNA*	87.2%	87.5%
HEART	100.0%	96.3%
HEPATITIS	100.0%	87.0%
IONOSPHERE	99.9%	95.2%
PIMA	81.3%	77.9%
VEHICLE* <sup>†</sup>	93.2%	80.8%
VOTES	100.0%	98.3%
WINE	100.0%	97.9%

#### **Results of 10-fold cross validation**

- \* STATLOG Data Collection
- <sup>†</sup> 4 classes

# Conclusions

In conclusion

- A best pattern alone is a very good, simple and robust classifier.
- ♡ Theories built as disjunctions of good patterns provide excellent classifiers for a large variety of applications.
- Theories provide classifications that are both understandable and justifiable.
- ♦ Several **software packages** have been developed.

## Software

Software available from Christhophe Meyer's LAD site

http://www.gerad.ca/~christop/LAD\_en.html

1) Datascope (package written by Sorin Alexe in Visual Basic for Windows)

2) **LADTools** (program in C++ written by Eddy Mayoraz; may need CPLEX)

3) Ladoscope Gang (a set of programs written in Objective Caml by Pierre Lemaire)

Software available by request from E. Boros

4) **PLAD** (a PERL LAD Tool package, "use at your own risk researchware")

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