

Diagnostic de l'état mécanique de structures par analyse de vibrations

GOLINVAL Jean-Claude

Université de Liège, Belgique

Département d'Aérospatiale et Mécanique
Chemin des Chevreuils, 1 Bât. B 52
B-4000 Liège (Belgium)
E-mail : JC.GolINVAL@ulg.ac.be

- **Classical Methods for Machine Condition Monitoring**
- **Recent Methods for Structural Health Monitoring**
 - **Principal Component Analysis (PCA)**
 - **Null Subspace Analysis (NSA)**
 - **Kernel Principal Component Analysis (KPCA)**
- **Examples of Application**
- **Conclusion**

Two categories of inspection techniques may be used:

1. Destructive techniques
2. Non destructive techniques
 - Acoustic emission (cracks in structures)
 - Oil analysis (bearings and gears)
 - Thermography, holography, interferometry, ...
 - Vibration monitoring (rotating machinery, structures)



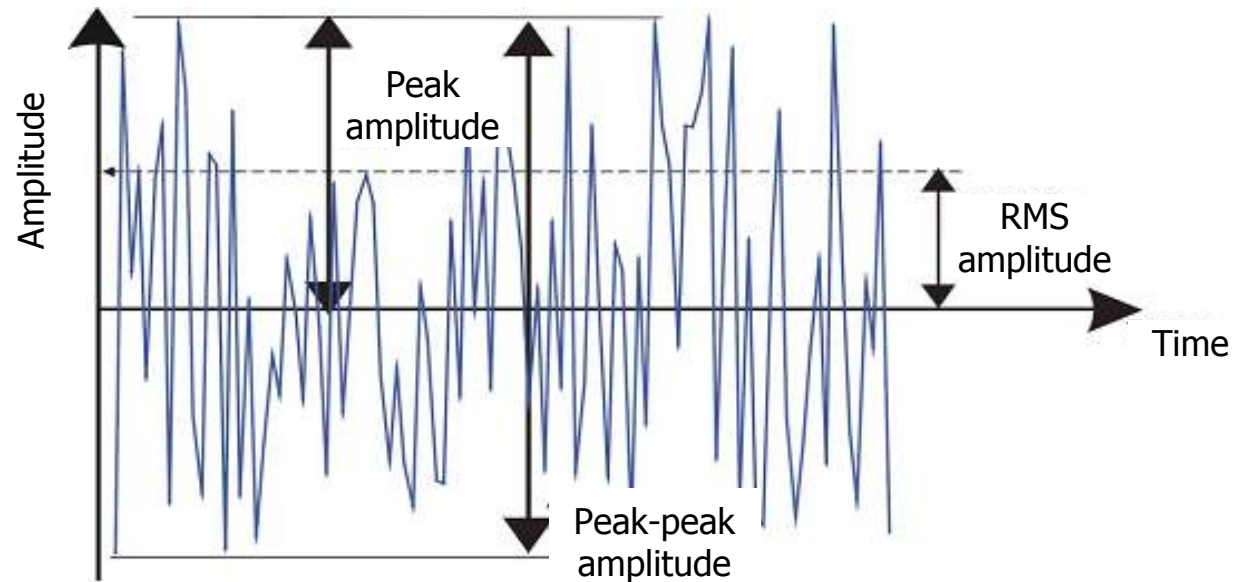
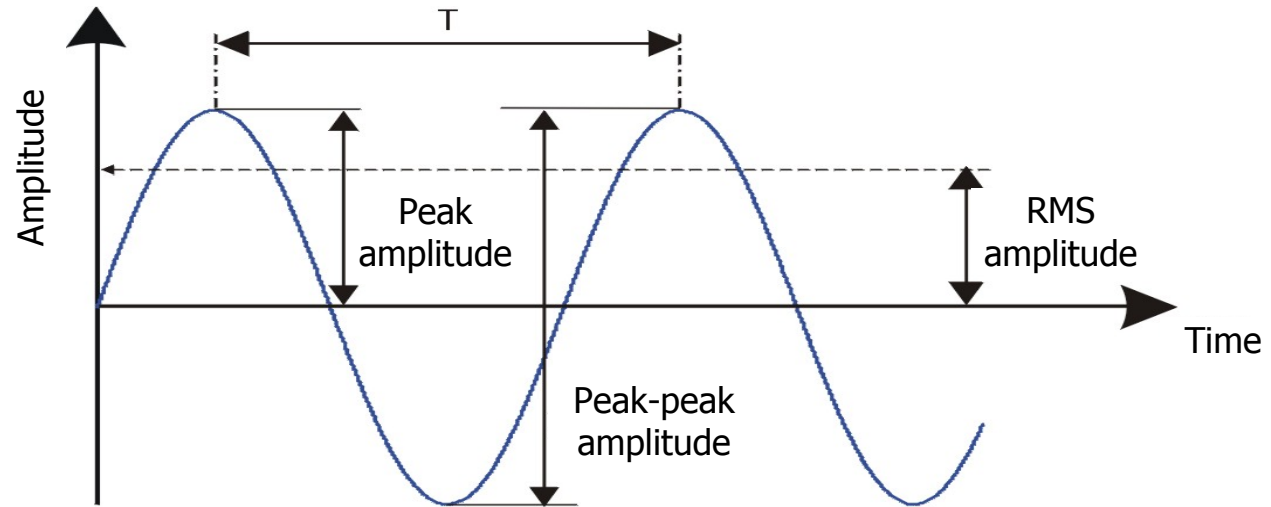
Classical Methods

For

Machine Condition Monitoring

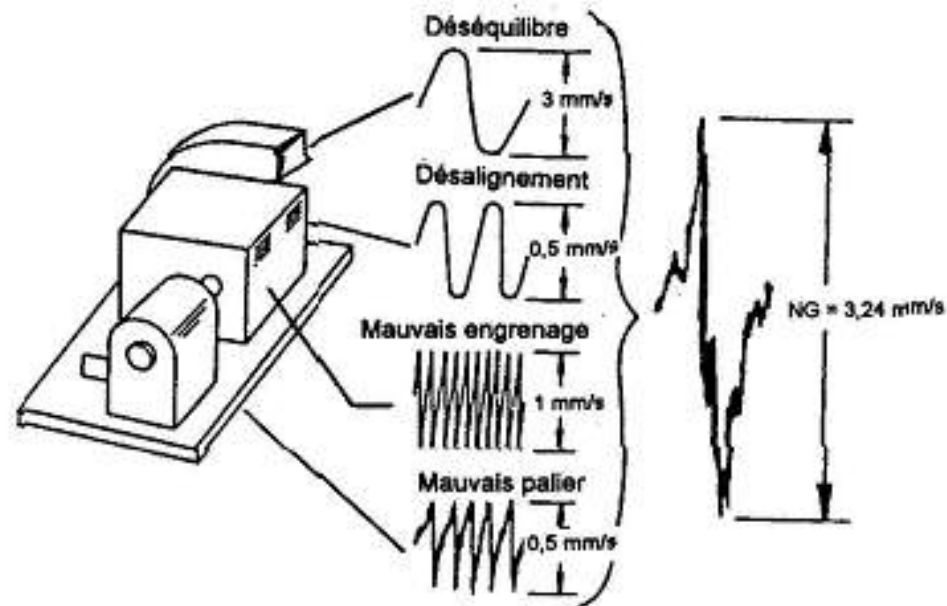
Vibration analysis – a key predictive maintenance technique

The nature
of
vibration



Monitoring of the global vibration amplitude level

Example of a fan driven by an electric motor through a gear box

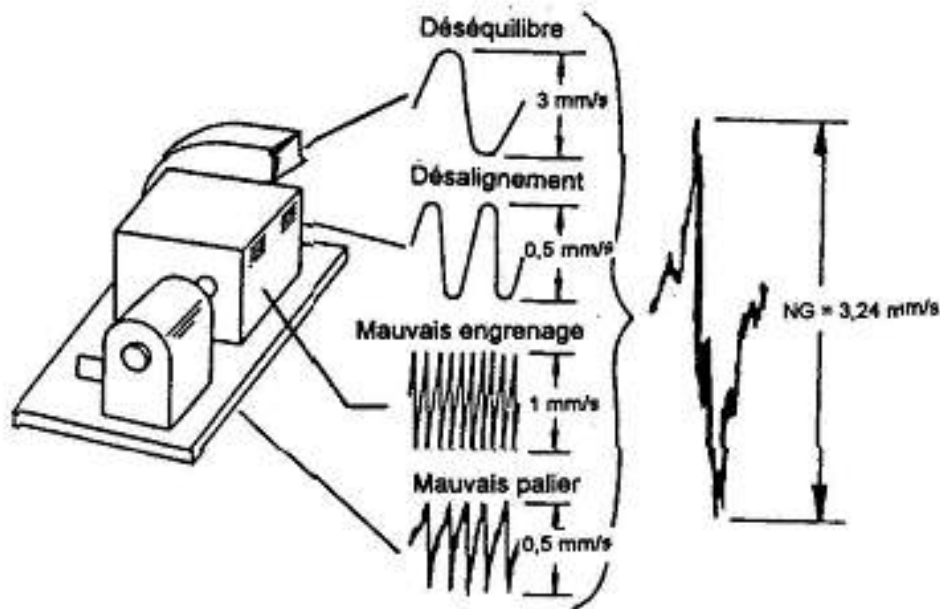


The global vibration level may be calculated as

$$NG = \sqrt{a^2 + b^2 + c^2 + d^2 + \dots}$$

where a, b, c, d, \dots are the RMS amplitudes of the different signal components.

Machine Condition Monitoring (Example)



Initial RMS amplitude level

$$NG = \sqrt{3^2 + 0.5^2 + 1^2 + 0.5^2} = 3.24 \text{ mm/s}$$

A variation of 30 % on the unbalance (**low severity**) gives:

$$NG = \sqrt{3.9^2 + 0.5^2 + 1^2 + 0.5^2} = 4.08 \text{ mm/s} \quad (+ 26 \%)$$

A variation of 300 % on the bearing defect (**extreme severity**) gives:

$$NG = \sqrt{3^2 + 0.5^2 + 1^2 + 1.5^2} = 3.53 \text{ mm/s} \quad (+ 9 \%)$$

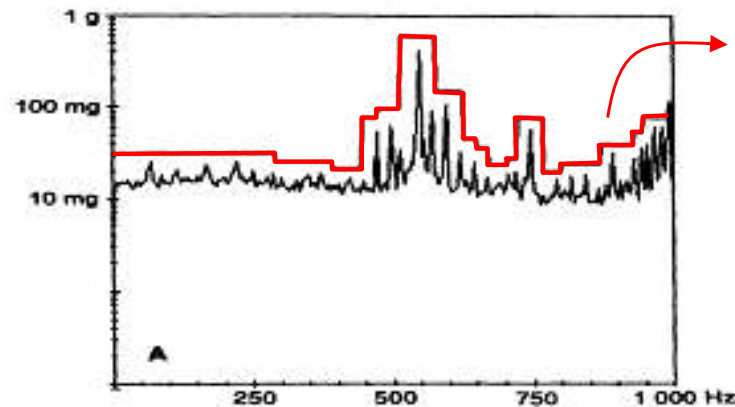
Machine Condition Monitoring (Example)

Monitoring of the indicators by comparison with an envelope

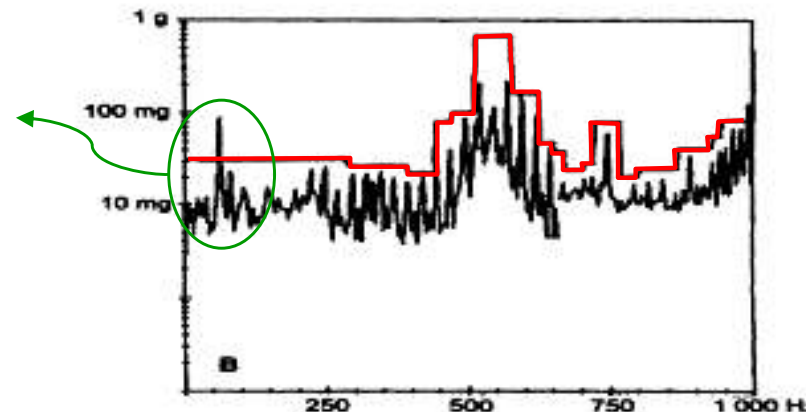
The envelope is determined from a reference spectrum (« vibratory signature ») obtained in good operating conditions.

Example

Vibration signature
 at the bearing
 (normal state)



Overshoot



Vibration signature
 at the bearing
 (after occurrence
 of a defect)



Machine Condition Monitoring

ISO Guidelines for Machinery Vibration Severity

mm/s				
18 – 28		NOT ACCEPTABLE		
11 – 18				
7 – 11				
4,5 – 7		STILL ACCEPTABLE		
2,8 – 4,5				
1,8 – 2,8		ACCEPTABLE		
1,1 – 1,8				
0,7 – 1,1				
0,45 – 0,7		GOOD		
0,28 – 0,45				
	Class I	Class II	Class III	Class IV

Various classes of machinery

Recent Methods For Structural Health Monitoring



Structural Health Monitoring (SHM)

Process of implementing a damage detection strategy for aerospace, civil and mechanical engineering structures.

Damage

Changes to the material and/or geometric properties which affect the performance of the system.

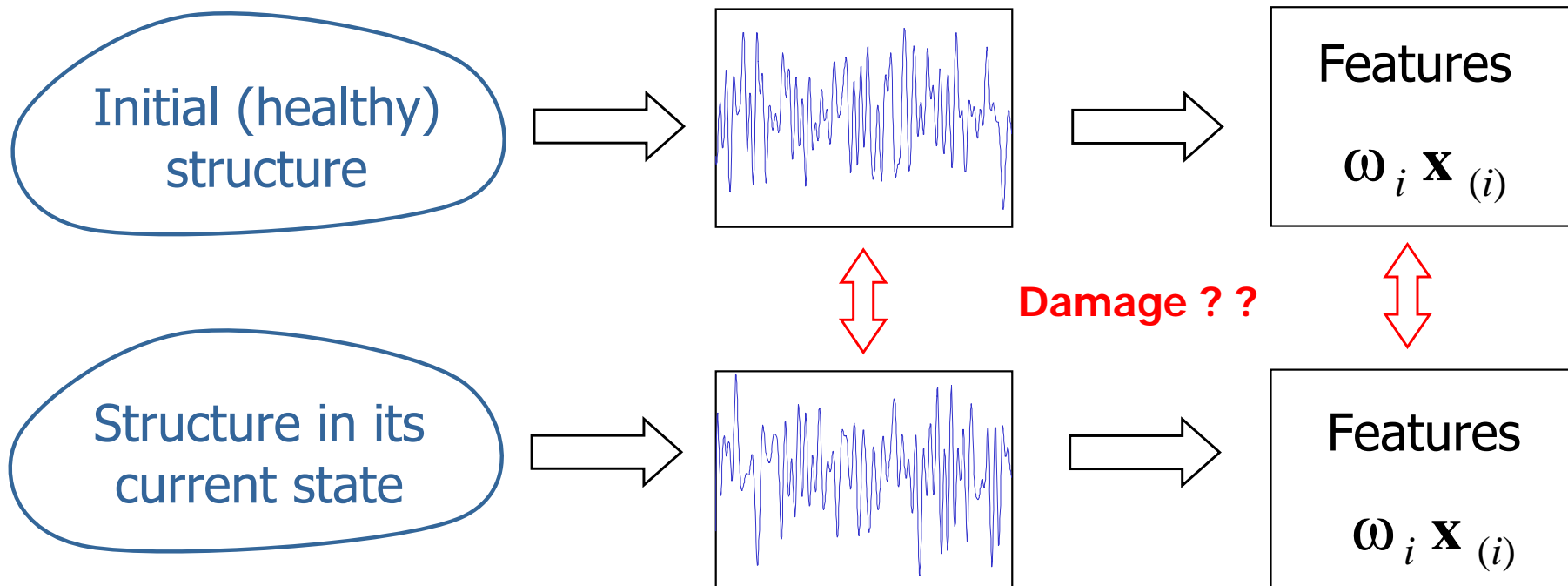
Problem of detection

Damage is detected through changes in some carefully selected structural features (e.g. modal parameters)

Structural Health Monitoring Process

The SHM process involves three steps:

- the observation of a system over time using periodically sampled dynamic measurements from an array of sensors,
- the extraction of damage-sensitive features from these measurements,
- the statistical analysis of these features to determine the current state of system health.



The damage state of a system can be described as a five-step process (Rytter, 1993) to answer the following questions.

- Level 1: *Existence*. Is there damage in the system?
- Level 2: *Location*. Where is the damage in the system?
- Level 3: *Type*. What kind of damage is present?
- Level 4: *Extent*. How severe is the damage?
- Level 5: *Prognosis*. How much useful life remains?

Categories of false indications of damage

- **False-positive** damage indication = indication of damage when none is present.
 - **False-negative** damage indication = no indication of damage when damage is present.
- Use of statistical procedures to increase robustness

Model-based techniques

Updating of structural parameters or matrices (inverse problem)

Non-model based techniques

Identification of modal parameters

- non-supervised methods (statistics)
- supervised methods (pattern recognition, neural networks, ...)

Structural Dynamics Problem



Homogeneous equation of motion

Inertia forces \leftarrow \leftarrow Restoring forces \rightarrow \rightarrow

$$\mathbf{M} \ddot{\mathbf{x}} + \mathbf{K} \mathbf{x} = 0$$

where $\mathbf{x} = \begin{Bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{Bmatrix}$

Mass matrix Stiffness matrix

Structural Dynamics Problem

The general solution of the equation of motion is of the form

$$\mathbf{x} = \mathbf{x}_{(i)} \cos \omega_i t \quad (i = 1, 2, \dots, n)$$

↓

mode-shape
vector n° i

↓

natural
frequency n° i

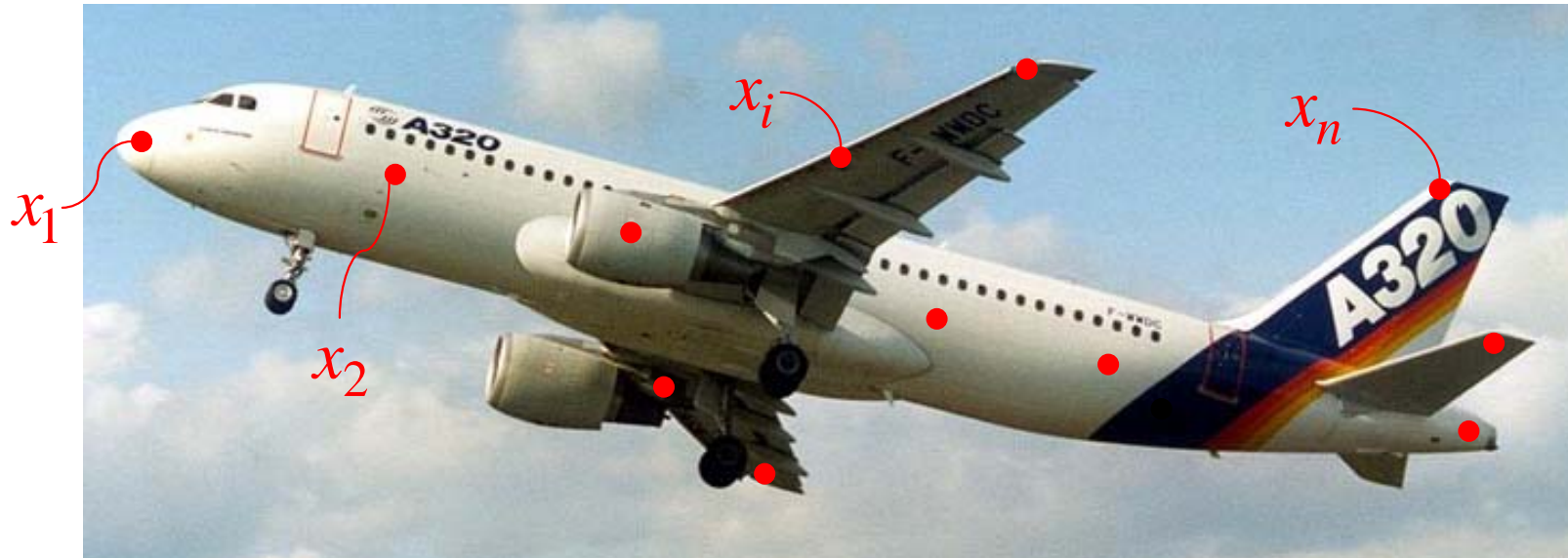
→ the dynamic behavior of a structure is completely characterized by its modal parameters

(i.e. the natural frequencies ω_i and mode-shapes $\mathbf{x}_{(i)}$).

Principal Component Analysis (PCA)

Principal Component Analysis (PCA)

Instrumented structure



N snapshots

Observation matrix:

$$\mathbf{X} = \begin{bmatrix} x_1(t_1) & \cdots & x_1(t_N) \\ \vdots & \ddots & \vdots \\ x_n(t_1) & \cdots & x_n(t_N) \end{bmatrix}$$

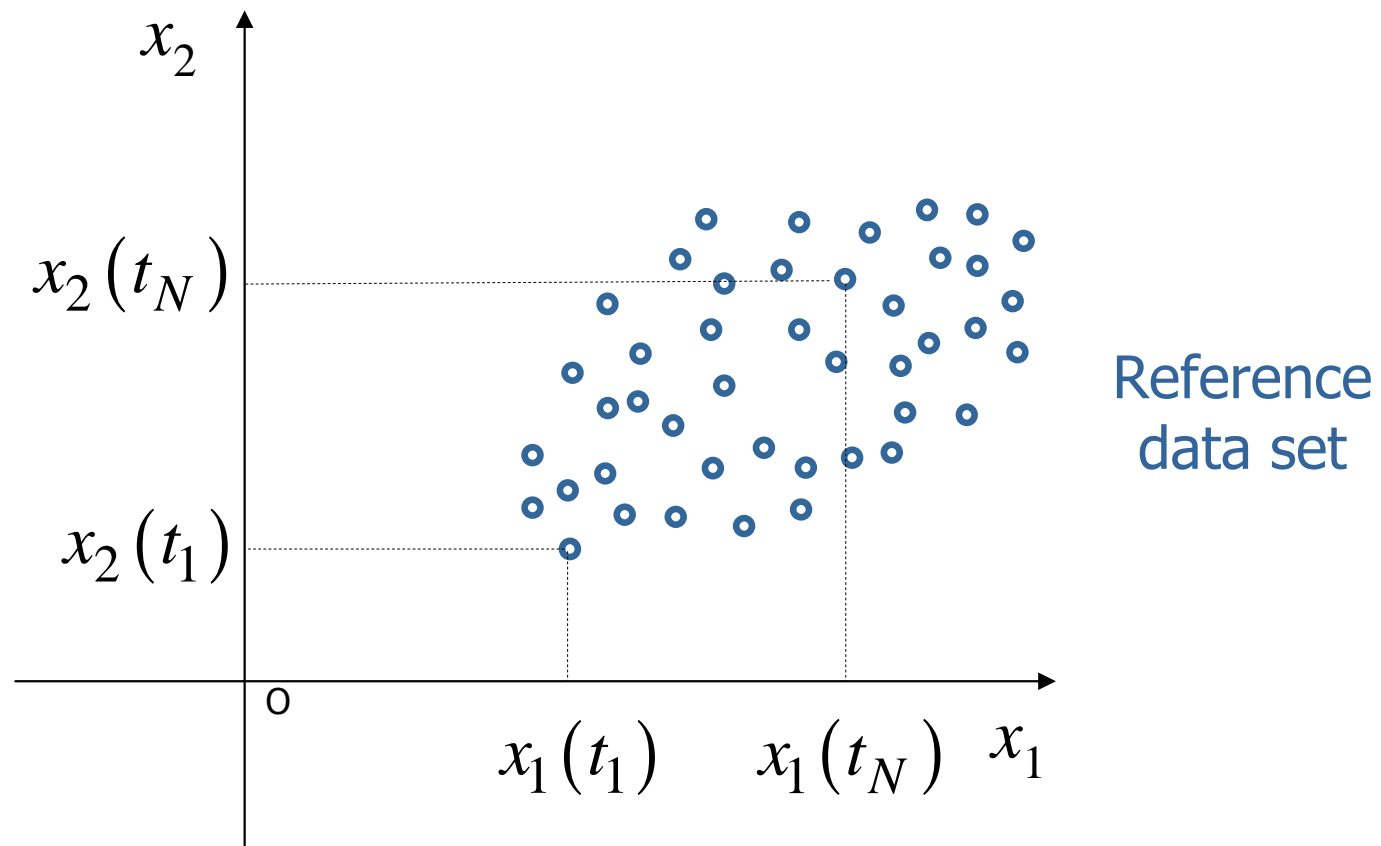
n
 measurement
 co-ordinates

Principal Component Analysis (PCA)

PCA in 2D-space

Geometric interpretation

$$\mathbf{X} = \begin{bmatrix} x_1(t_1) & x_1(t_2) & \cdots & x_1(t_N) \\ x_2(t_1) & x_2(t_2) & \cdots & x_2(t_N) \end{bmatrix}$$

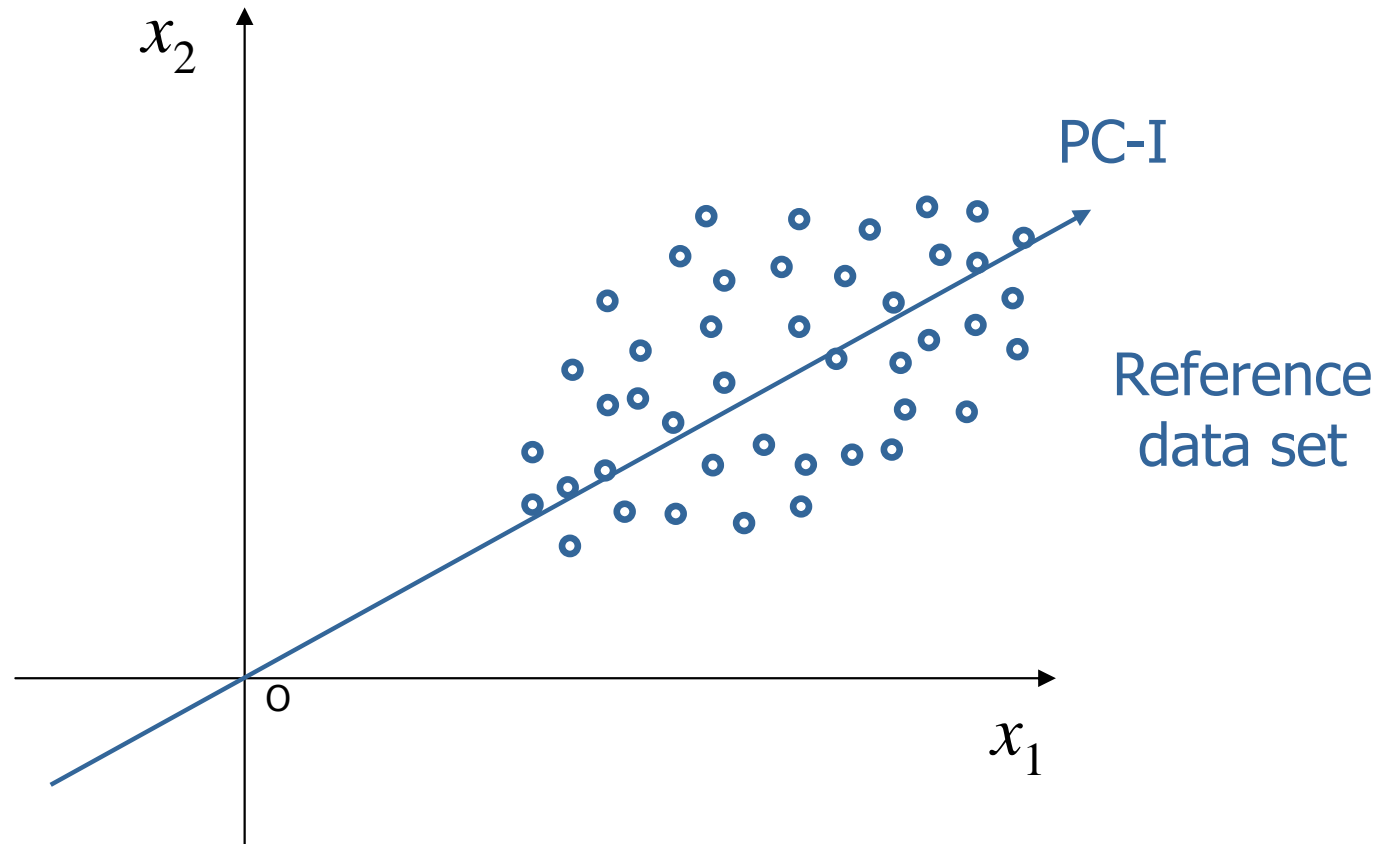




Principal Component Analysis (PCA)

Geometric interpretation

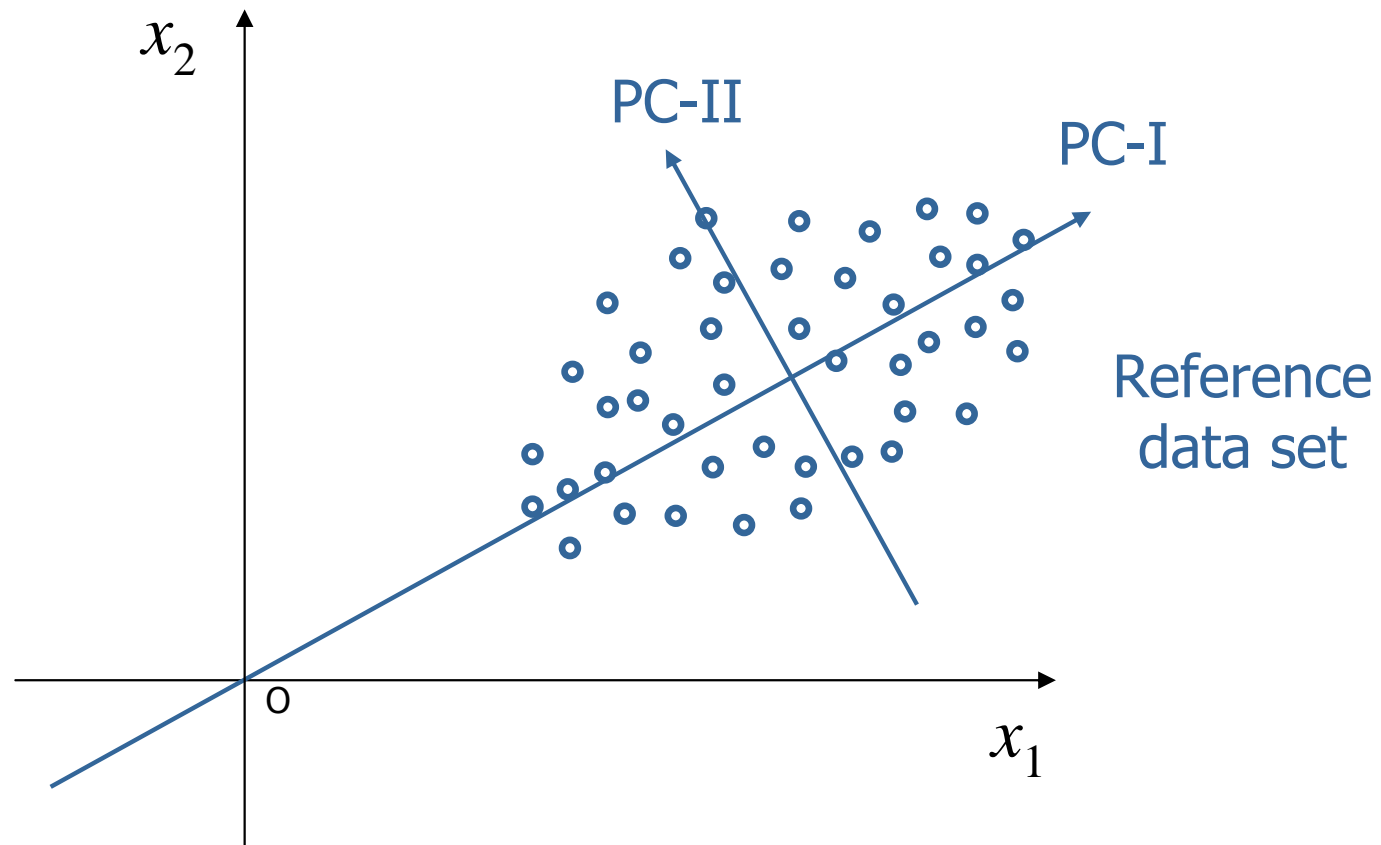
PCA in 2D-space





Geometric interpretation

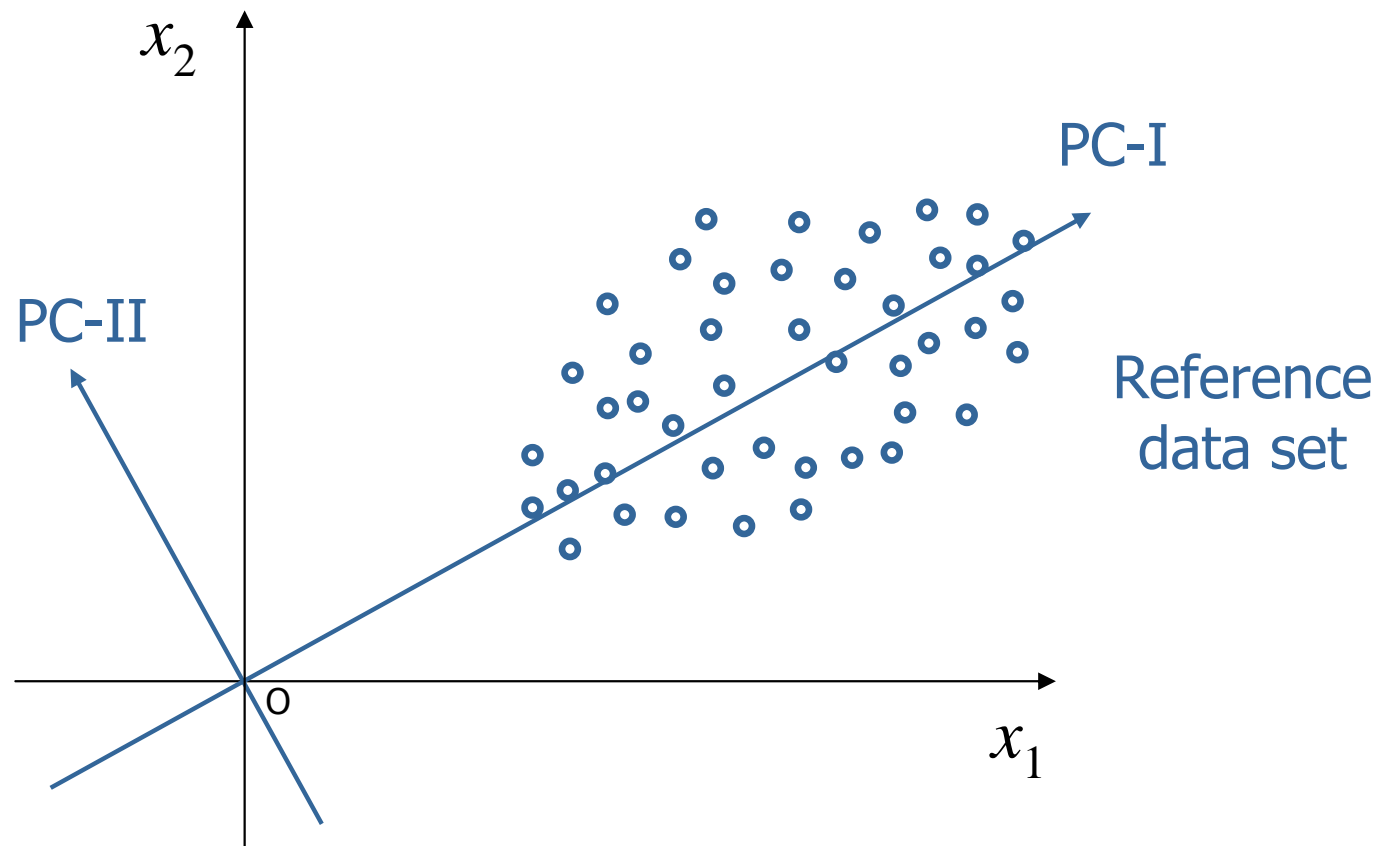
PCA in 2D-space



Principal Component Analysis (PCA)

Geometric interpretation

PCA in 2D-space



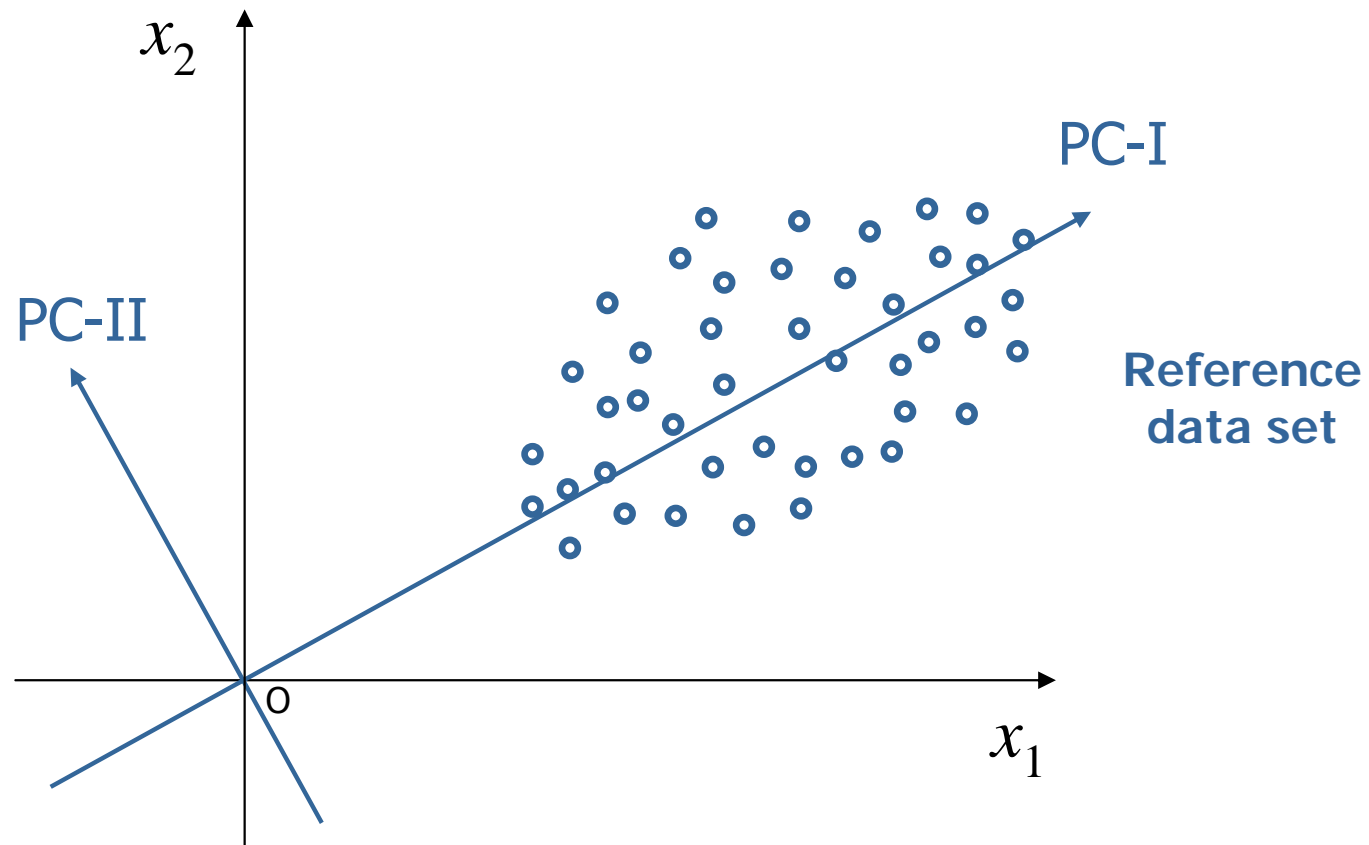
Concept of Subspace Angle (Golub-Van Loan)

Key idea

- Use PCA to extract the structural response subspace (PC-I, PC-II)
- Use the concept of subspace angles to compare the hyperplanes associated with the **reference (undamaged)** state and with the **current (possibly damaged?)** state of the structure.

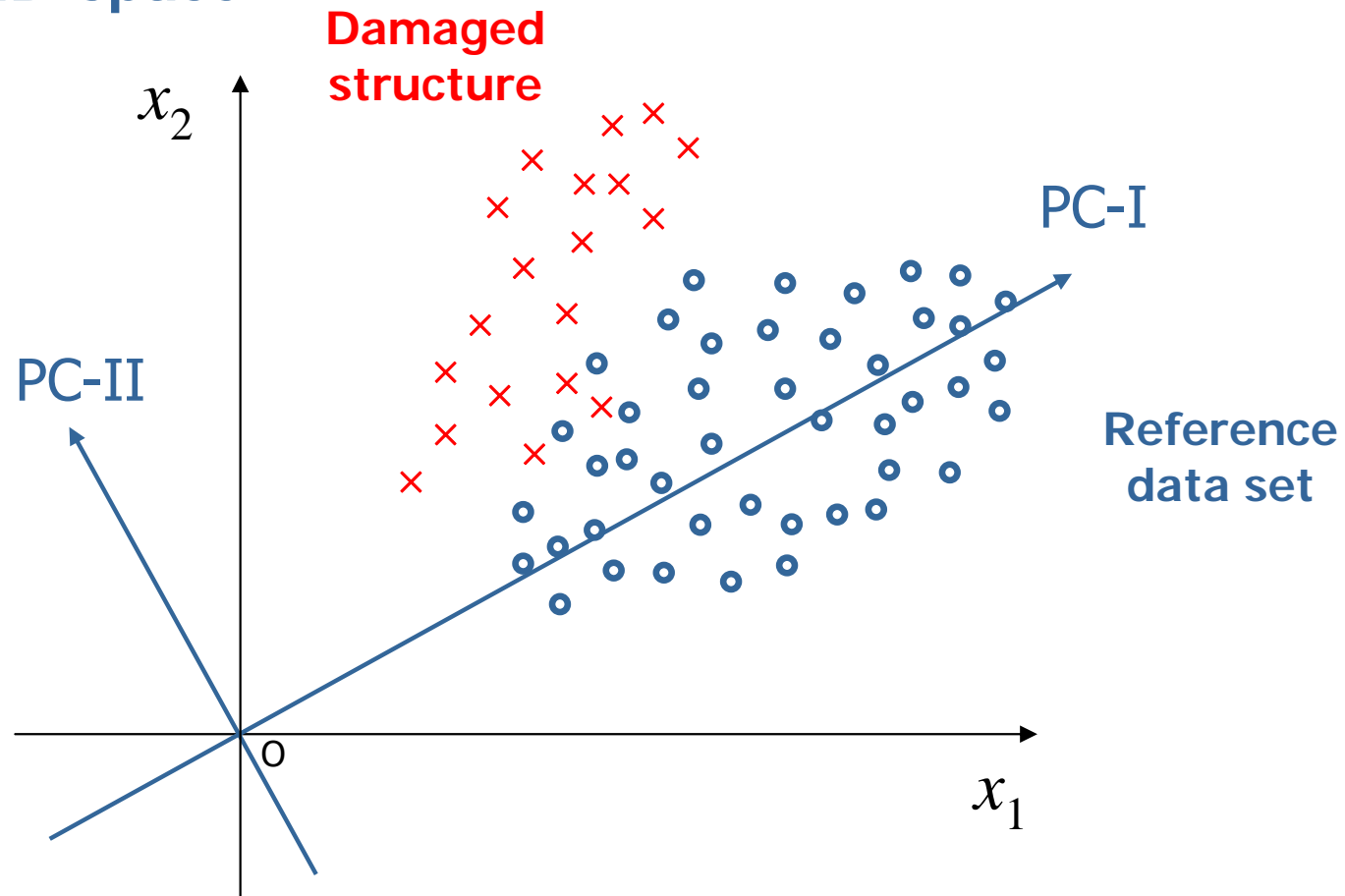
Geometric interpretation

PCA in 2D-space



Geometric interpretation

PCA in 2D-space

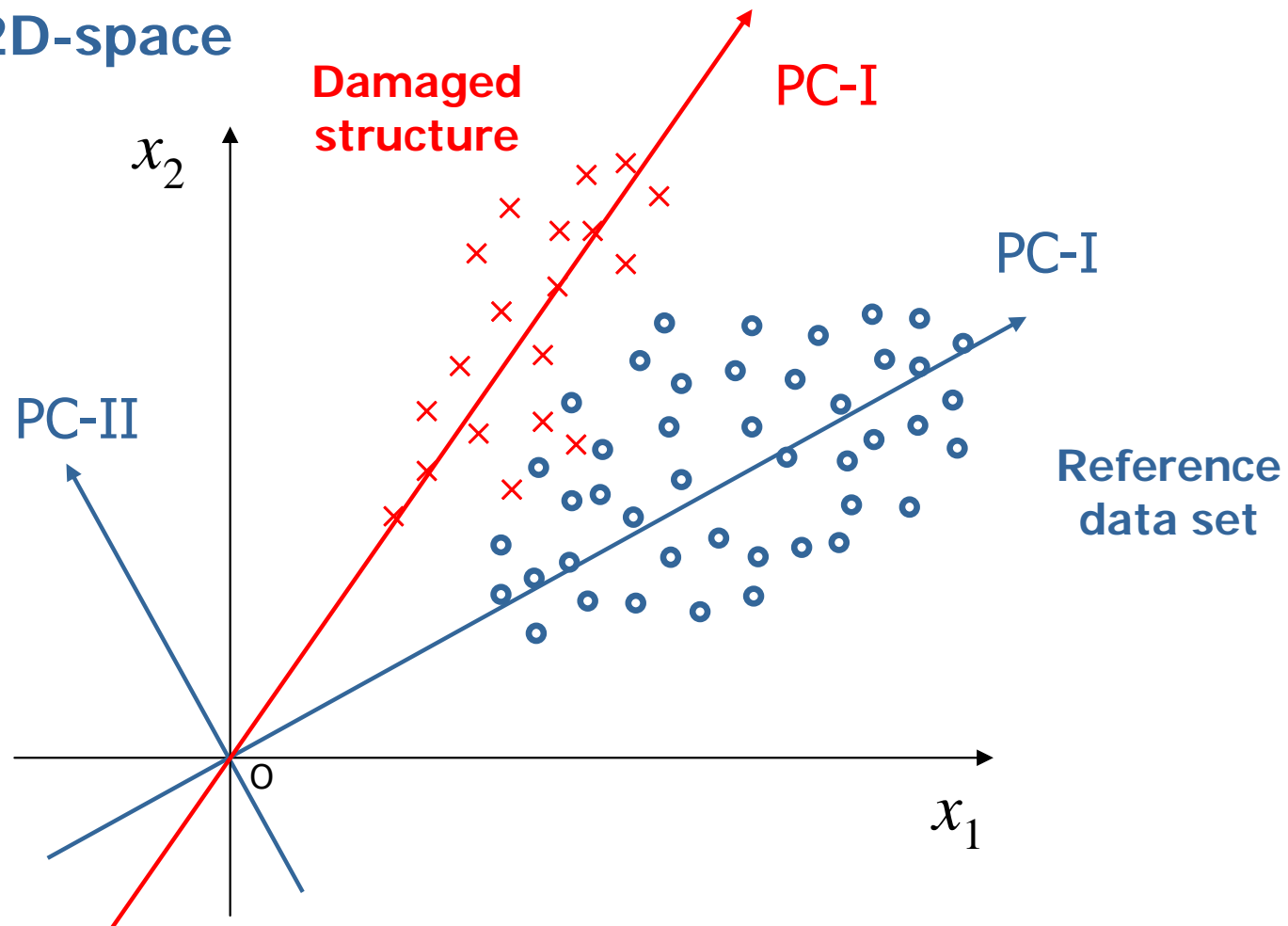




Structural Damage Detection Problem

Geometric interpretation

PCA in 2D-space

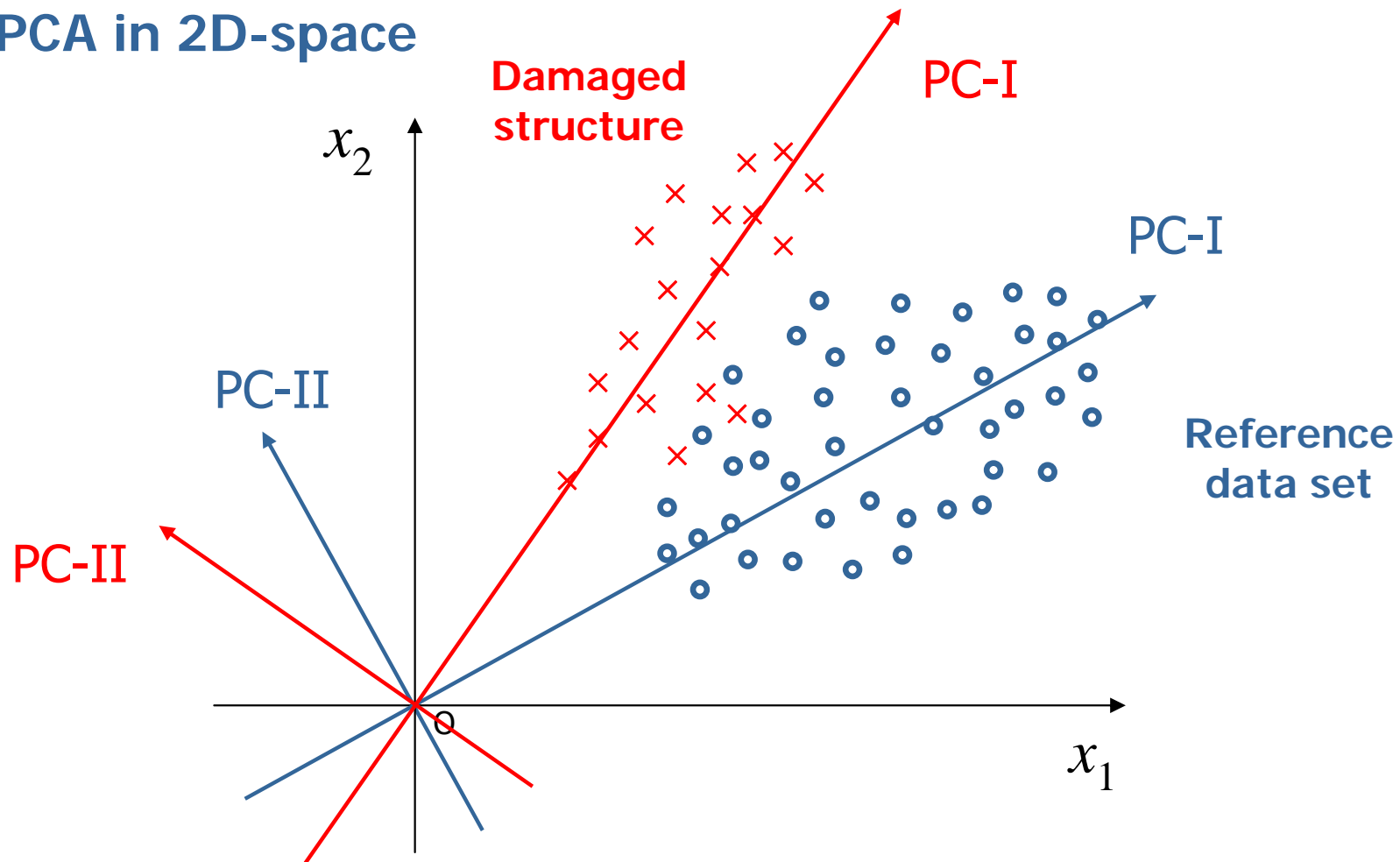




Structural Damage Detection Problem

Geometric interpretation

PCA in 2D-space

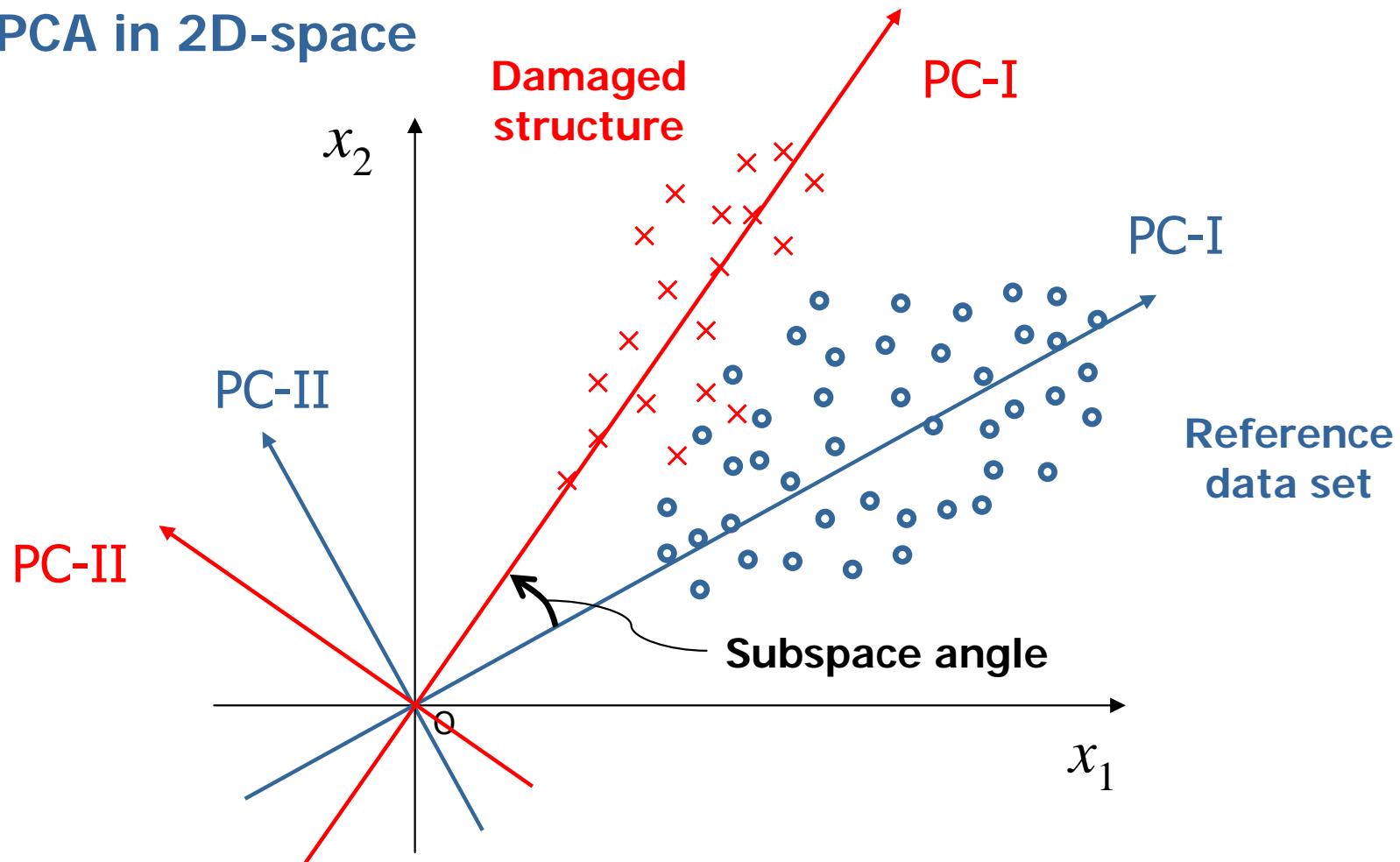




Structural Damage Detection Problem

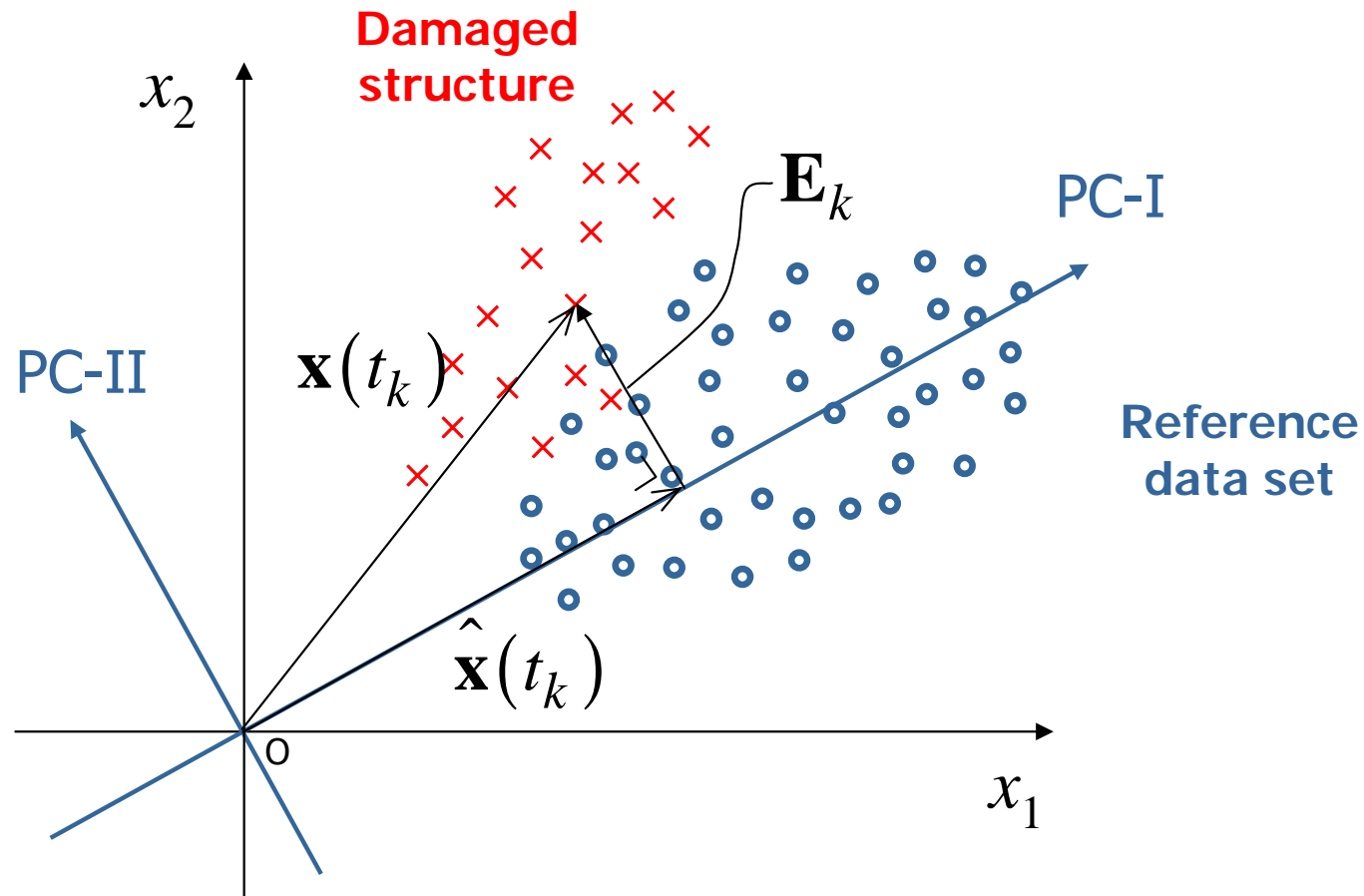
Geometric interpretation

PCA in 2D-space



Novelty Analysis

The aim is to build a prediction model using the principal components of reference.



Definition of the Novelty Index

Residual error matrix :

$$\mathbf{E} = \mathbf{X} - \hat{\mathbf{X}}$$

Euclidean norm :

$$NI_k^E = \|\mathbf{E}_k\|$$

prediction error vector at time t_k

Statistical tool :

$$CL = \overline{NI} + 3\sigma$$

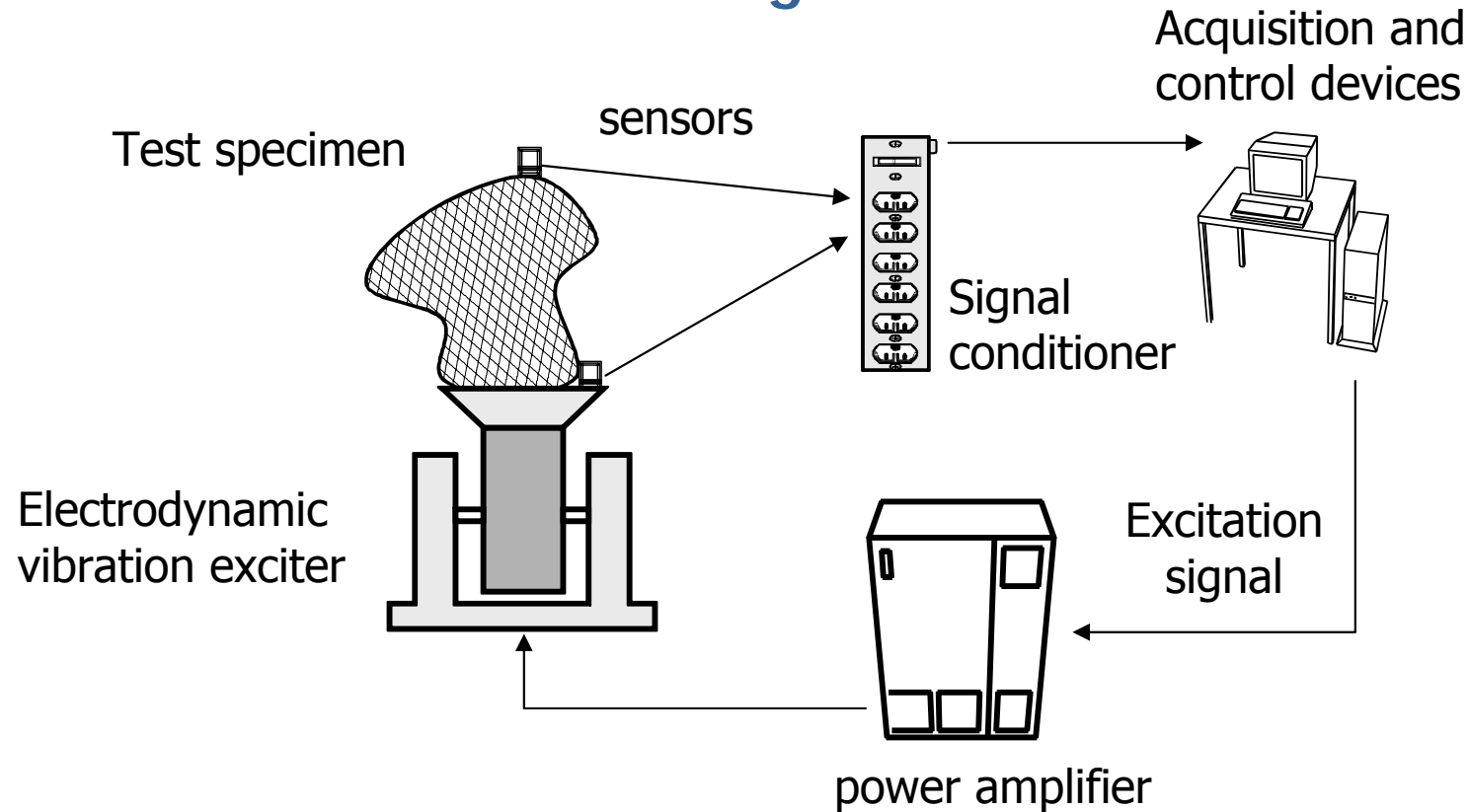
mean value

(Upper Control Limit at 99.7 % confidence interval)

standard deviation

Example of Damage Detection

Environmental Vibration Testing



Detection of damages usually by visual inspection or by comparison of frequency spectra before and after the test.

Objective : to be able to detect damage as soon as it appears.

Example of Damage Detection

Fatigue testing of a street lighting device

Control accelerometer



+ 10 measurement accelerometers

Total test duration: ~ 4 hours

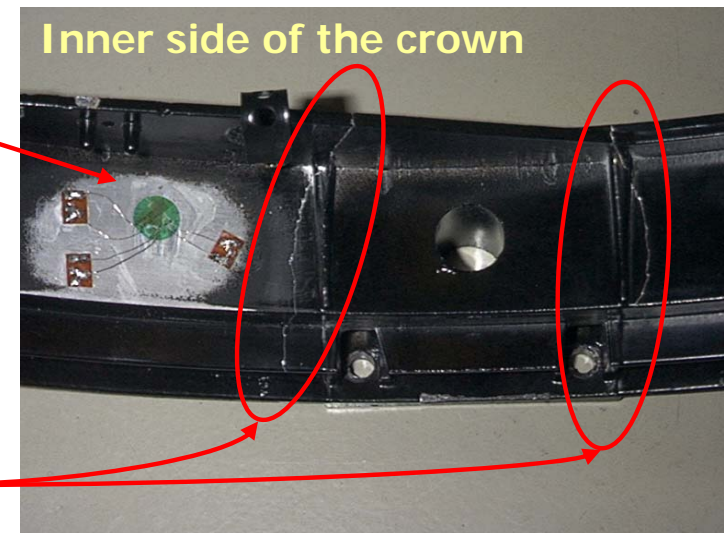
Mode of failure of the crown

Crack initiation and propagation

Vibration specifications

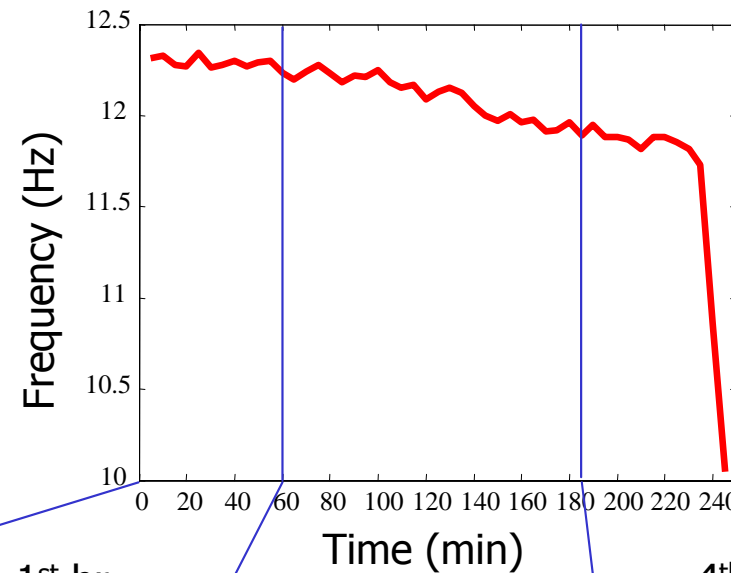
- Sine excitation at the first resonance frequency ($\sim 12,4$ Hz) during 1 hour.
- Acceleration level of 0,5 g at the fixation.

Strain gauges





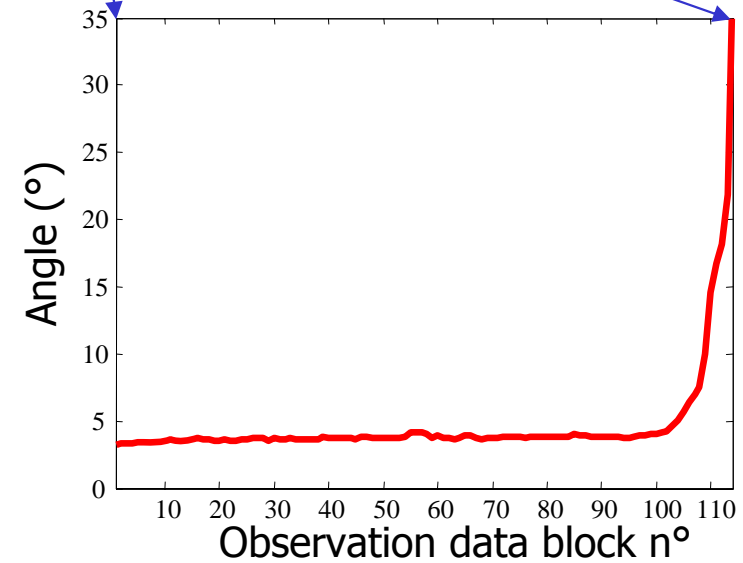
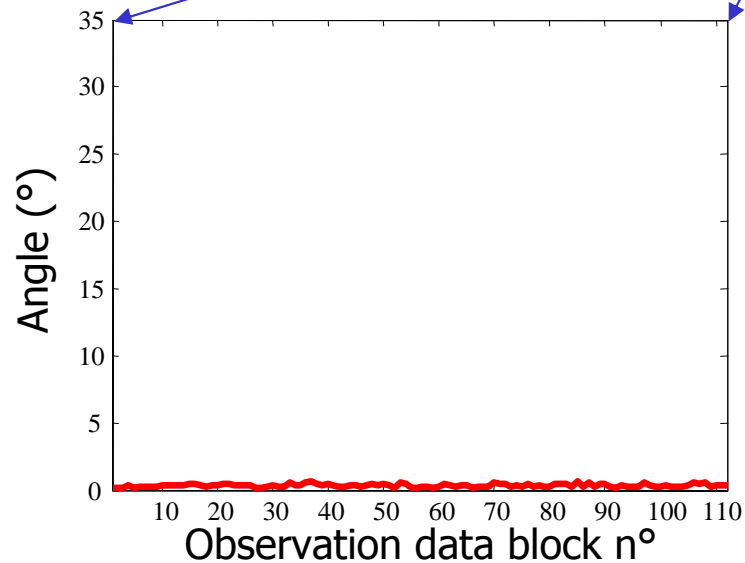
Damage Detection (Results)



Time-evolution of the
resonance frequency

1st hr

4th hr



Time-evolution of the angle

Limitation of the PCA-based method

The number of sensors must be larger than the number of active modes → it can be solved using the concept of null-subspace of the Hankel matrices of responses.

Null Subspace Analysis (NSA)

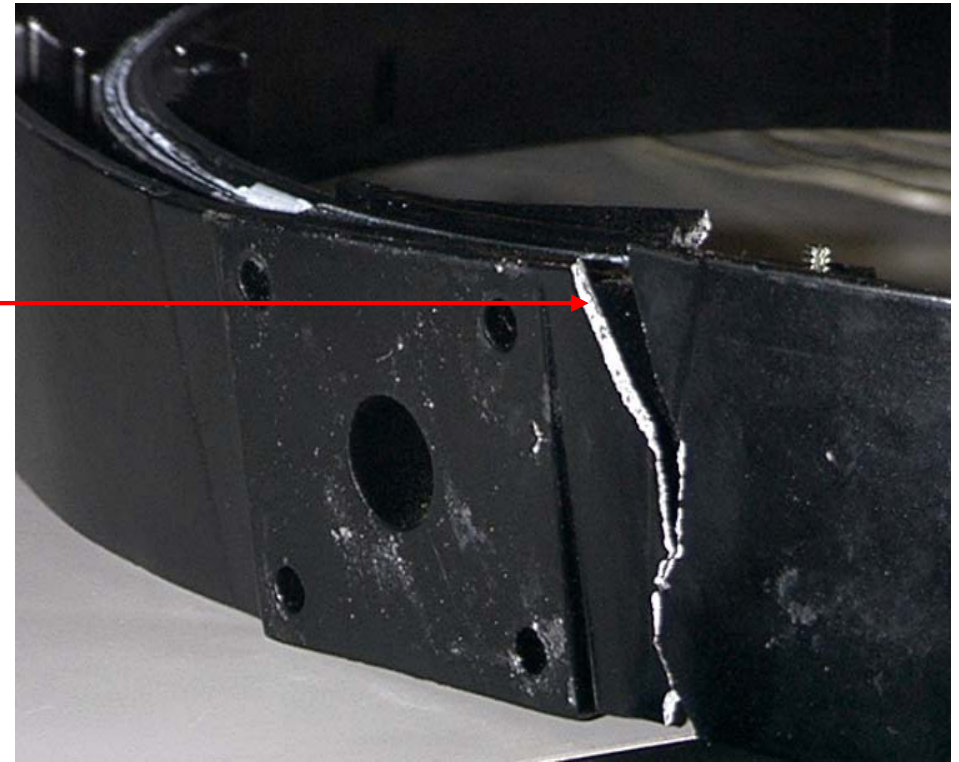
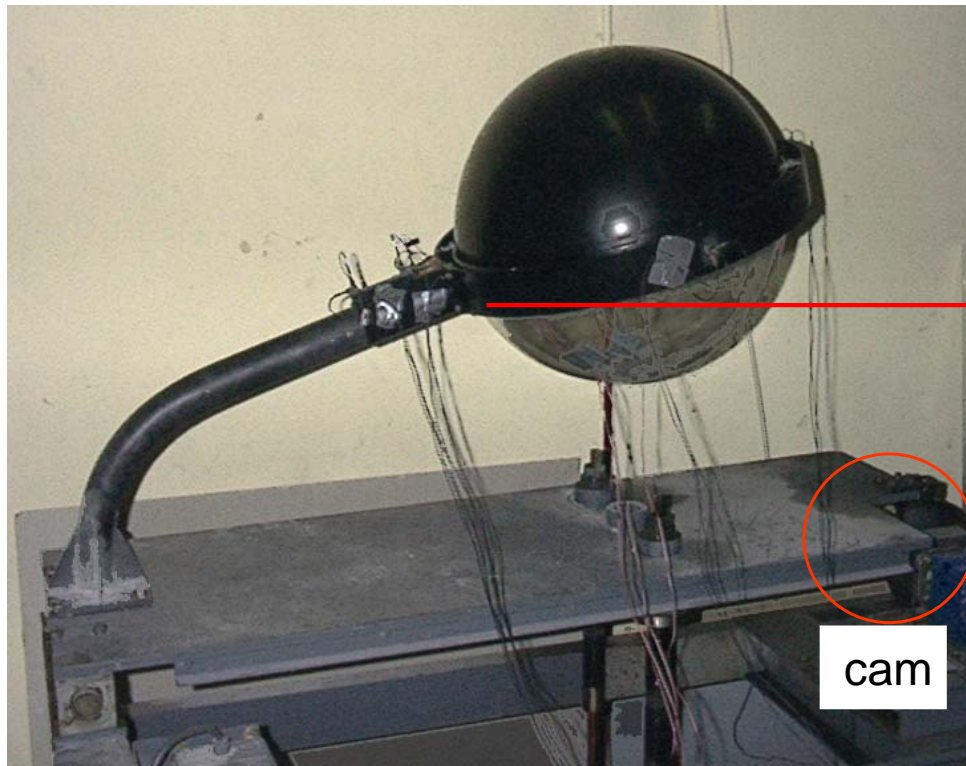
Aim : to replace the observation matrix \mathbf{X} by a “dynamic” response matrix (i.e. the Hankel matrix)

- Definition of the data-driven Hankel matrix

$$\mathbf{H}_{1,2i} = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \dots & \dots & \mathbf{x}_j \\ \mathbf{x}_2 & \mathbf{x}_3 & \dots & \dots & \mathbf{x}_{j+1} \\ \dots & \dots & \dots & \dots & \dots \\ \mathbf{x}_i & \mathbf{x}_{i+1} & \dots & \dots & \mathbf{x}_{i+j-1} \\ \text{-----} \\ \mathbf{x}_{i+1} & \mathbf{x}_{i+2} & \dots & \dots & \mathbf{x}_{i+j} \\ \mathbf{x}_{i+2} & \mathbf{x}_{i+3} & \dots & \dots & \mathbf{x}_{i+j+1} \\ \dots & \dots & \dots & \dots & \dots \\ \mathbf{x}_{2i} & \mathbf{x}_{2i+1} & \dots & \dots & \mathbf{x}_{2i+j-1} \end{bmatrix} \equiv \begin{pmatrix} \mathbf{X}_p \\ \text{---} \\ \mathbf{X}_f \end{pmatrix} \equiv \frac{\text{"past"}}{\text{"future"}}$$

where $2i$ is the (user-defined) number of row blocks, each row block contains m terms (number of measurement sensors), j is number of columns (in practice, $j = N - 2i + 1$, N is the number of sampling points)

Null Subspace Analysis (NSA)

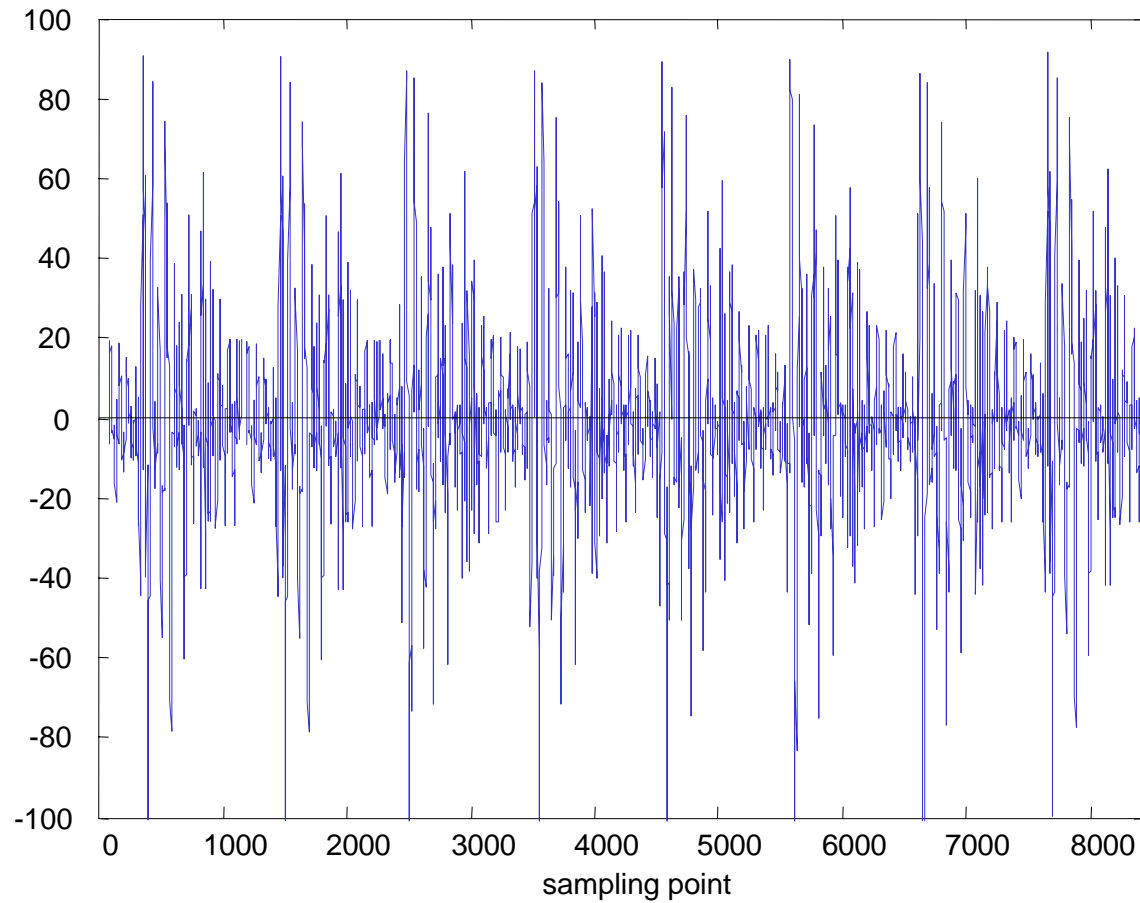


- The street-lighting device is excited by a shock applied every 2 sec. by a cam mechanism.
- Accelerometers and strain-gauges measure the structural responses with a sampling frequency of 528 Hz.
- Test duration : 2 hrs 38 min with a failure in the frame close to the fixation.



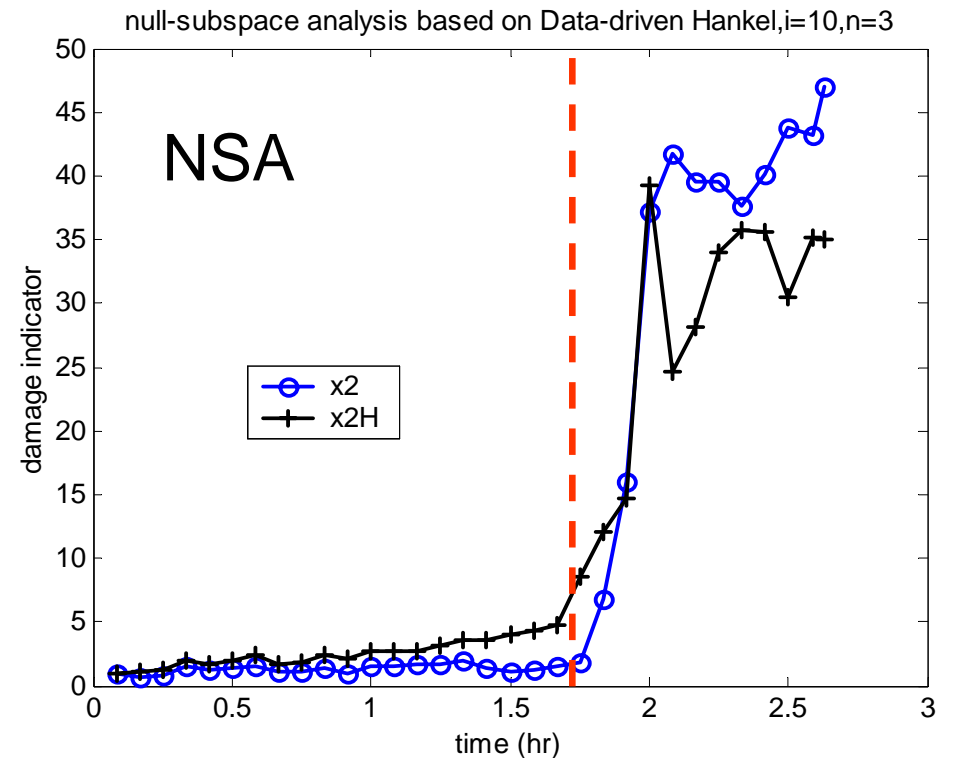
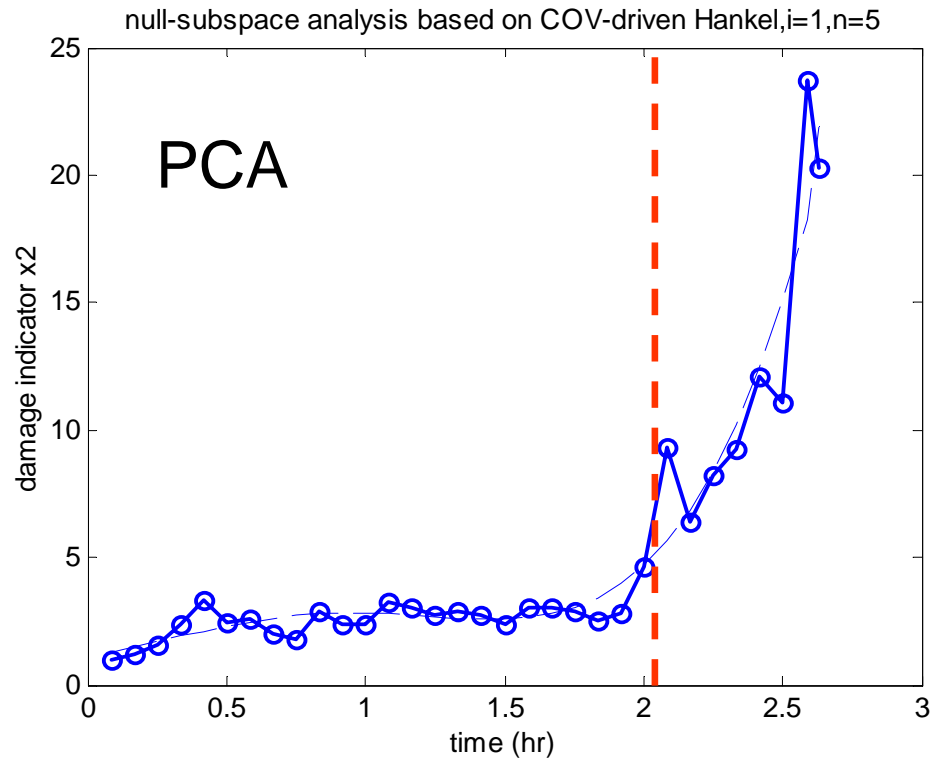
Null Subspace Analysis (NSA)

Example of the system response under repeated impulses

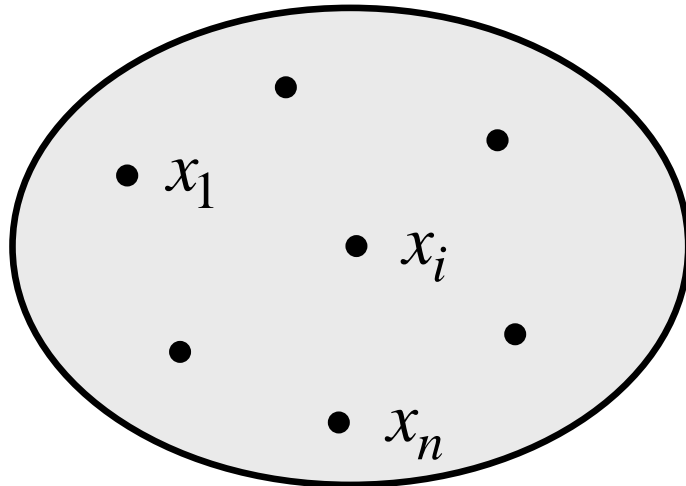


Null Subspace Analysis (NSA)

On-line monitoring: the NSA-based method indicates obvious damage development earlier than the PCA-based method



Kernel Principal Component Analysis (KPCA)



n measurement co-ordinates

N time samples

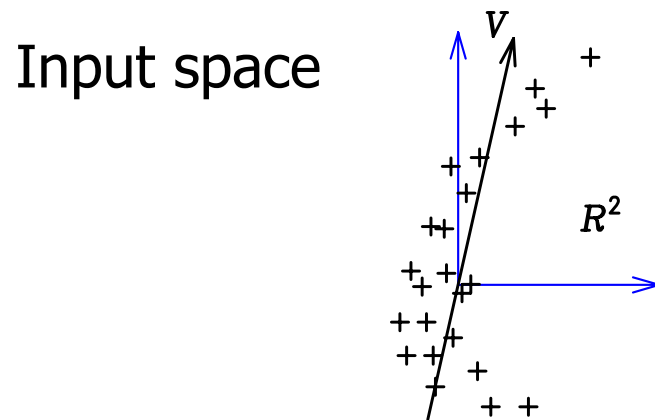
$$\mathbf{X} = \begin{bmatrix} x_1(t_1) & \cdots & x_1(t_N) \\ \vdots & \ddots & \vdots \\ x_n(t_1) & \cdots & x_n(t_N) \end{bmatrix}$$

Key idea

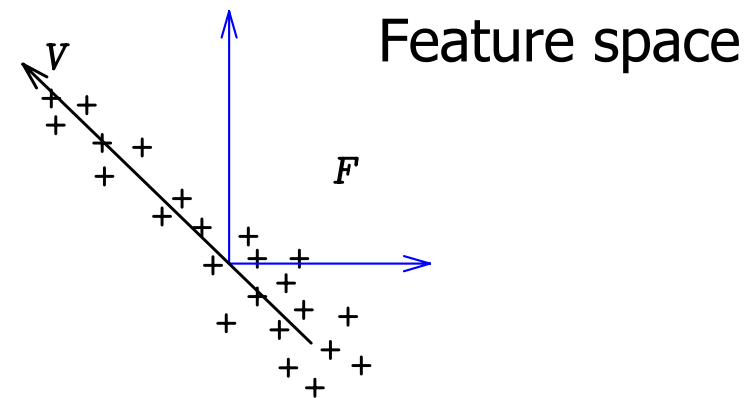
- Create a map $\mathbf{x}(t_k) \mapsto \Phi(\mathbf{x}(t_k))$ which defines a high dimensional feature space F
- Apply PCA in space F

Kernel Principal Component Analysis (KPCA)

The eigenvectors identified in the feature space F can be considered as kernel principal components (KPCs), which characterize the dynamical system in each working state.



a) Linear PCA

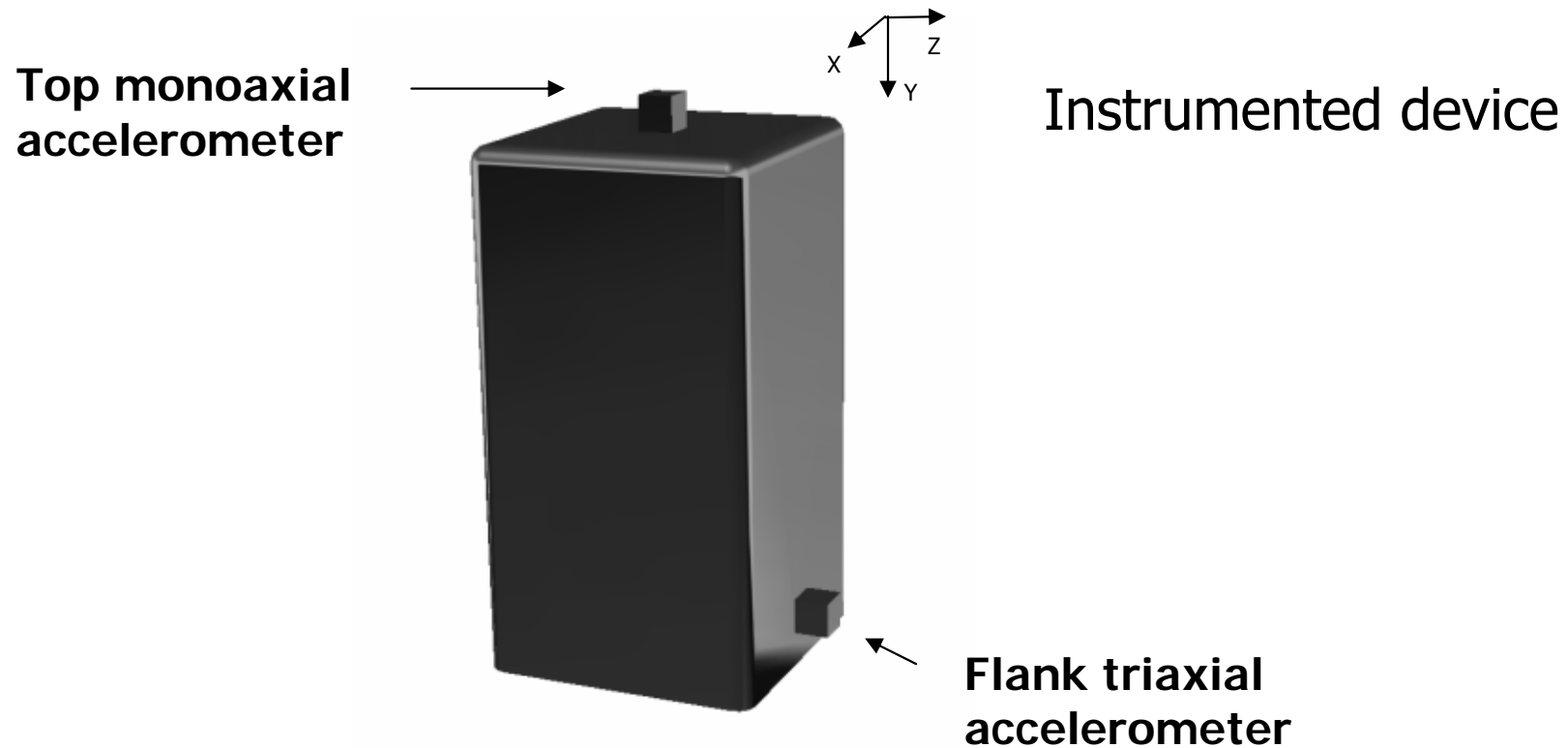


b) Kernel PCA



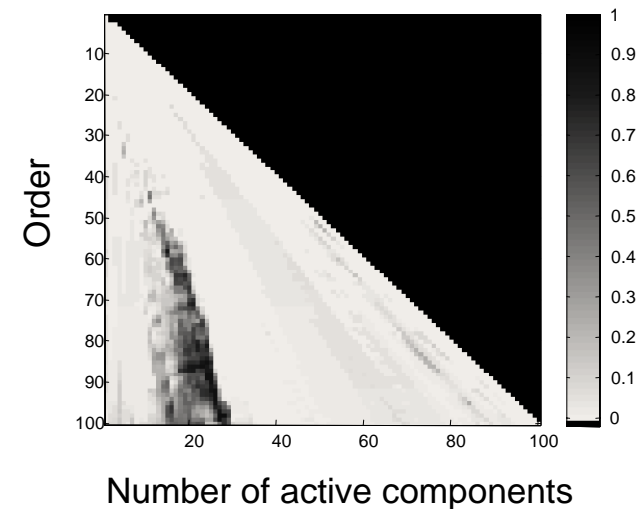
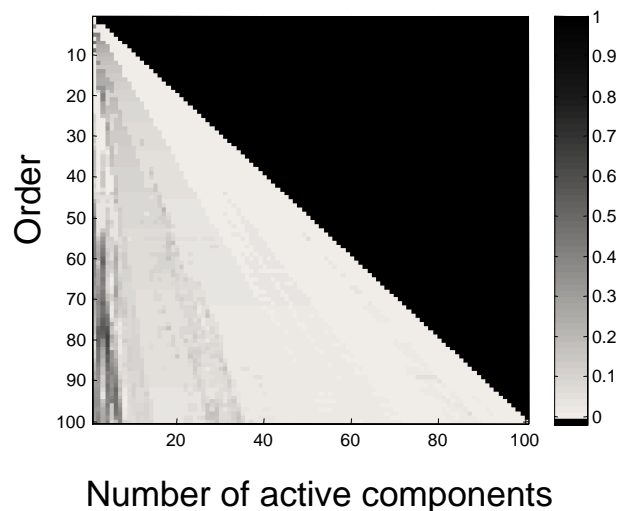
Examples of Fault Detection in Industrial Systems

Example 1: Quality tests on electro-mechanical devices at the end of the assembly line



NSA-based detection method

Mapping of the space [number of PCs, system order]



Mapping of a healthy component
 in the X direction using 6σ -limit

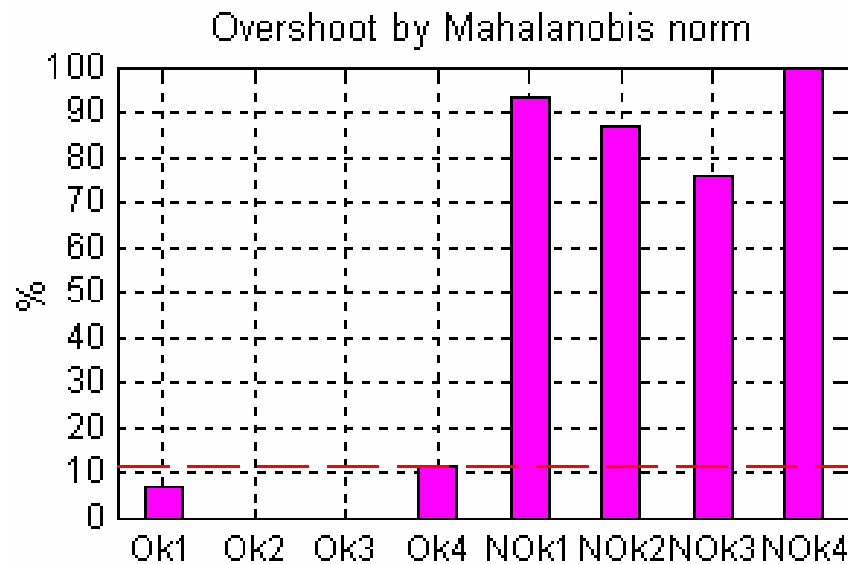
Mapping of a damaged component
 in the X direction using 6σ -limit

Damage indicator based on the reconstruction error (Novelty index)

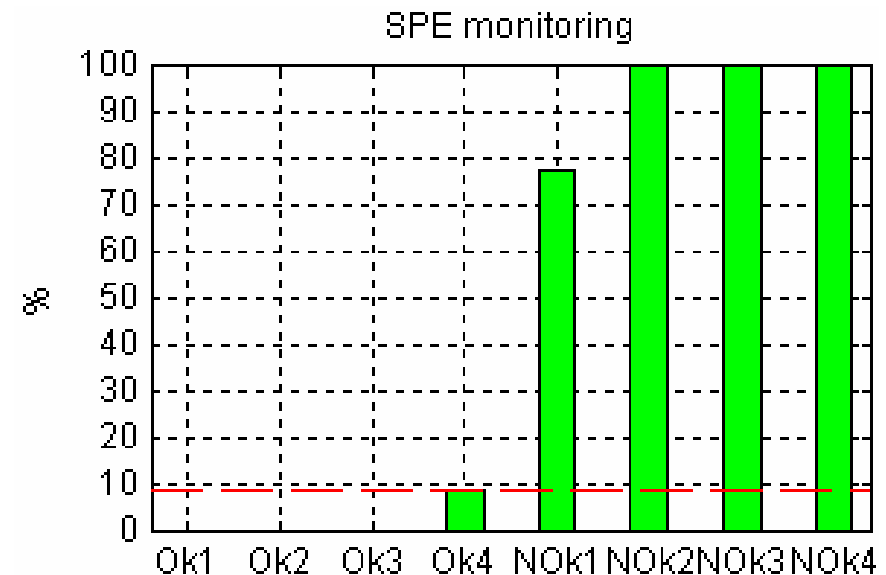


Fault Detection in Industrial Systems

Damage detection by NSA and KPCA methods based on statistics –
(the dashed horizontal line correspond to the maximal value for
good devices)

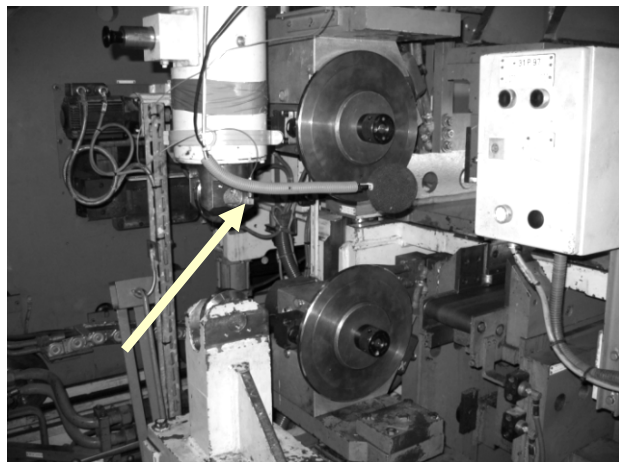


NSA based - detection



KPCA based - detection

Example 2: Quality control of welded joints

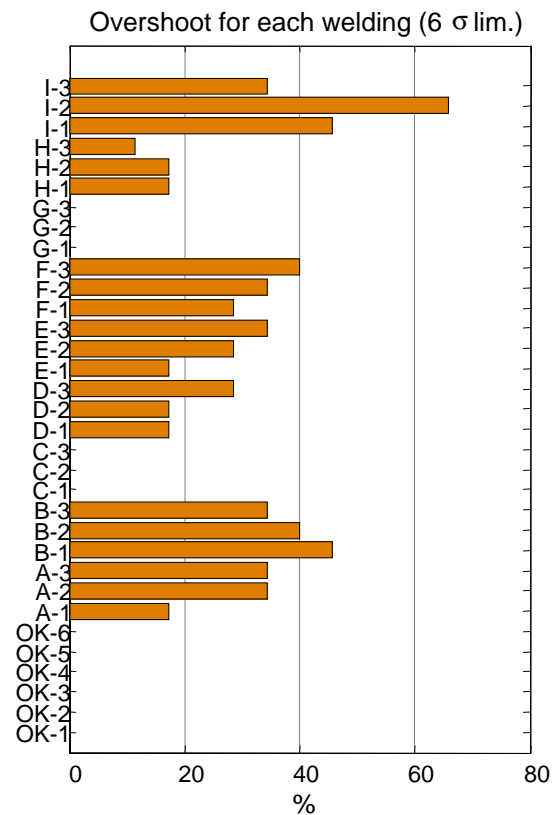


Name	Modified parameter	Weld quality
Welding A	-33% covering	Acceptable
Welding B	-66% covering	Bad
Welding C	-33% compensation	Good
Welding D	-66% compensation	Acceptable
Welding E	-10% current	Acceptable
Welding F	-20% current	Bad
Welding G	-10% forging pressure	Good
Welding H	+5% forging pressure	Acceptable
Welding I	-66% covering and compensation	Bad

Welds realized with modified parameters (with respect to the nominal parameters)

Fault Detection in Industrial Systems

Fault detection based on Null subspace analysis (NSA), using the Novelty Index (NI) based on the Mahalanobis norm

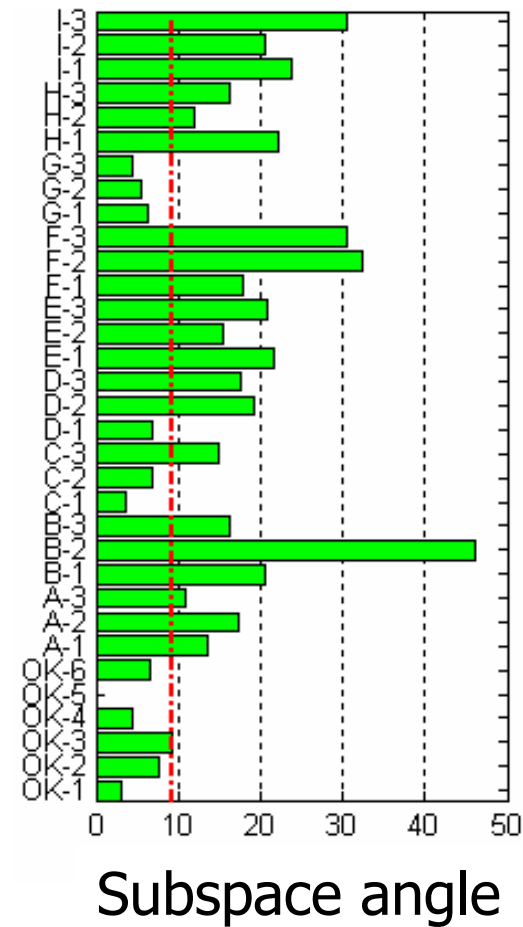
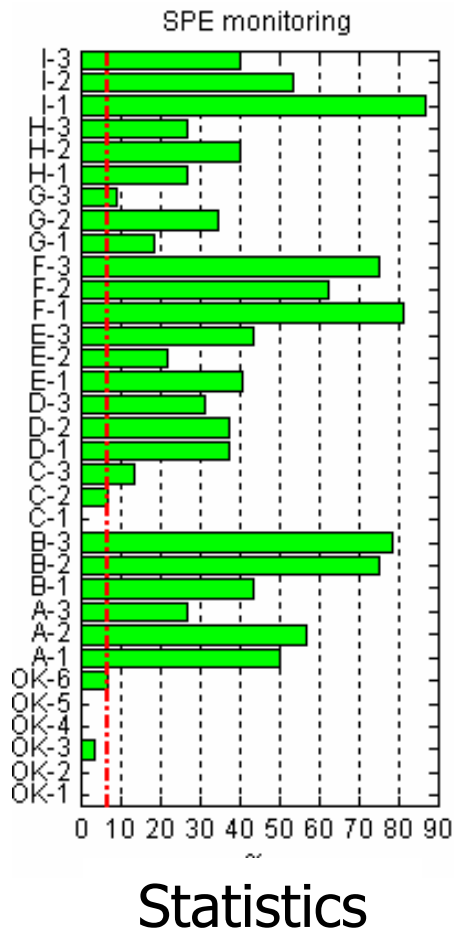


$$NI_{\text{lim}} = \overline{NI} + 6\sigma$$

standard
deviation of NI for
the reference test

Fault Detection in Industrial Systems

Fault detection based on KPCA



- Analyse vibratoire est un outil puissant et complexe
- Pas simple à mettre en place, demande réflexion
- Coût important d'une maintenance vibratoire
=> machine stratégique

Further readings

- Christian Boller, Fu-Kuo Chang, Yozo Fujino,
Encyclopedia of Structural Health Monitoring (5 volumes),
Wiley, 2009

- Nguyen Viet Ha,
Damage Detection and Fault Diagnosis in Mechanical
Systems Using Vibration Signals,
University of Liege, PhD thesis, 2010



Thank you for your attention.