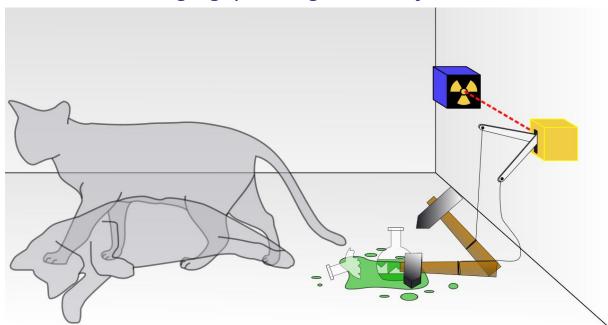


Elasto-Plastic Finite Element Simulations on Quantum Annealers

Van Dung Nguyen, Ling Wu, Françoise Remacle, and Ludovic Noels



V.-D.N acknowledges the support of the Fonds National de la Recherche (F.R.S.-FNRS, Belgium). F.R. acknowledges the support of the Fonds National de la Recherche (F.R.S.-FNRS, Belgium), #T0205.20. This work is partially supported by a "Strategic Opportunity" grant from the University of Liege

By Dhatfield - Own work, CC BY-SA 3.0, https://commons.wikimedia.org/w/index.php?curid=4279886



Bits vs. Qubits:

- Superposition of states:
 - A quantum bit can be 0 or 1 at the same time



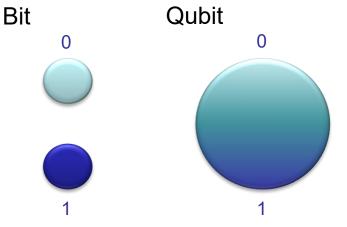
• Computational basis
$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 & $|1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

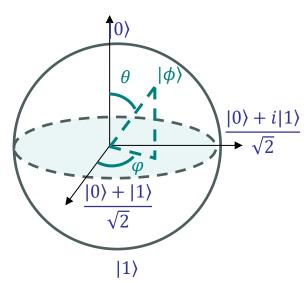
• Notations:
$$\begin{cases} |\phi\rangle = \binom{\alpha}{\beta} = \alpha |0\rangle + \beta |1\rangle \\ |\alpha|^2 + |\beta|^2 = 1 \end{cases}$$
$$|\alpha|^2 + |\beta|^2 = 1$$

Qubit represented on the surface of the Bloch Sphere

$$|\phi\rangle = e^{i\delta} \left(\cos\left(\frac{\theta}{2}\right)|0\rangle + e^{i\varphi}\sin\left(\frac{\theta}{2}\right)|1\rangle\right)$$

- Global phase ${
 m e}^{i\delta}$ has no observable consequence (NB relative phase has consequence)
- At measurement (in the computational basis)
 - Either $|0\rangle$ or $|1\rangle$ with respective probability $|\alpha|^2$ and $|\beta|^2$





- Multiple (connected) qubits:
 - Product state of 2 1-qubit states: -

$$\begin{cases} |\phi_0\rangle = \alpha_0|0\rangle + \beta_0|1\rangle \\ |\phi_1\rangle = \alpha_1|0\rangle + \beta_1|1\rangle \end{cases}$$



$$| \boldsymbol{\phi} \rangle = | \phi_0 \rangle \otimes | \phi_1 \rangle = \alpha_0 \alpha_1 | 00 \rangle + \alpha_0 \beta_1 | 01 \rangle + \alpha_1 \beta_0 | 10 \rangle + \beta_0 \beta_1 | 11 \rangle$$

Most general 2-qubit state

$$|\phi\rangle = \alpha_{00}|00\rangle + \alpha_{01}|01\rangle + \alpha_{10}|10\rangle + \alpha_{11}|11\rangle$$

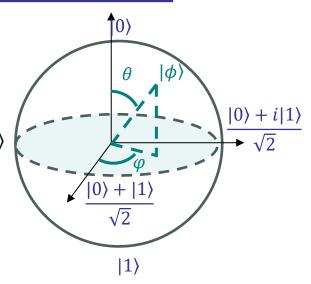
Because of entanglement, a *K*-qubit state is more general

(it cannot always be written as the product of K 1-qubit states)



There is not always K equivalent 1-qubit states to a K-qubit state, e.g.

$$|\phi\rangle = \frac{1}{\sqrt{2}}|00\rangle + 0|01\rangle + 0|10\rangle + \frac{1}{\sqrt{2}}|11\rangle$$



Multiple (connected) qubits:

Product state of 2 1-qubit states:
$$|\phi_0\rangle = \alpha_0|0\rangle + \beta_0|1\rangle$$

$$|\phi_1\rangle = \alpha_1|0\rangle + \beta_1|1\rangle$$



$$| \boldsymbol{\phi} \rangle = | \phi_0 \rangle \otimes | \phi_1 \rangle = \alpha_0 \alpha_1 | 00 \rangle + \alpha_0 \beta_1 | 01 \rangle + \alpha_1 \beta_0 | 10 \rangle + \beta_0 \beta_1 | 11 \rangle$$

Most general 2-qubit state

$$|\pmb{\phi}\rangle = \alpha_{00}|00\rangle + \alpha_{01}|01\rangle + \alpha_{10}|10\rangle + \alpha_{11}|11\rangle$$



Because of entanglement, a *K*-qubit state is more general

(it cannot always be written as the product of *K* 1-qubit states)



There is not always *K* equivalent 1-qubit states to a *K*-qubit state, e.g.

$$|\phi\rangle = \frac{1}{\sqrt{2}}|00\rangle + 0|01\rangle + 0|10\rangle + \frac{1}{\sqrt{2}}|11\rangle$$

- A system of *K* coupled qubits
 - Is a 2^K -state quantum-mechanical system
 - Whose state can be represented by any normalised linear combination of 2^K basis states:

$$|\pmb{\phi}\rangle=\phi_0|0\rangle\otimes|0\rangle\ldots\otimes|0\rangle+\phi_1|0\rangle\otimes|0\rangle\ldots\otimes|1\rangle+\cdots+\phi_{2^K-1}|1\rangle\ldots\otimes|1\rangle\otimes|1\rangle$$

with
$$\sum_{i=0}^{2^{n}-1} |\phi_i|^2 = 1$$

Because of superposition, potentially, a quantum computer with *K* qubits can take 2^K bitstrings of size K in parallel at the same time. A classical computer can only take 1 bitstring of size K

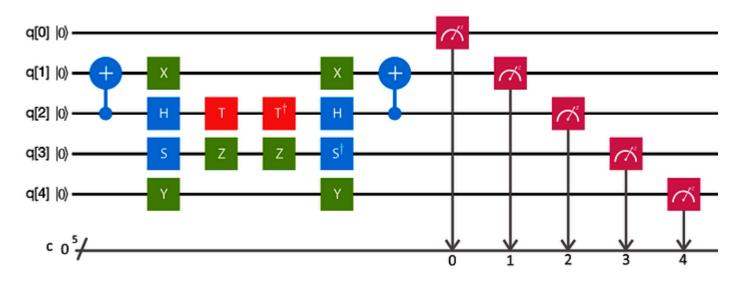


10

|1)

Universal gate

Circuit, e.g. on 5-qubits



Gate-based QC

- Universal approach (like classical computers operations are performed on qubits)
- Highly sensitive to noise difficulty in controlling error
- Error controlled by using control qubits



Quantum annealer

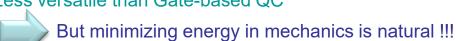
Goal: finding the ground state of a Hamiltonian H

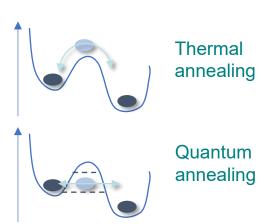
$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi|H|\phi\rangle$$

- Based on quantum adiabatic theorem:
 - Considering a time-varying Hamiltonian $H_{QA}(t)$ initially at ground state, if its time evolution is slow enough, it is likely to remain at the ground state
- Adiabatic quantum computing:
 - Starts from the ground state of an easy to prepare Hamiltonian H_i
 - Evolves to the ground state of the Hamiltonian H which encodes the sought solution

$$\mathbf{H}_{\mathbf{QA}}(t) = \frac{(t_a - t)}{t_a} \; \mathbf{H}_i + \frac{t}{t_a} \; \mathbf{H}$$

- Quantum annealing
 - Exploits quantum effect such as quantum tunneling
 - Less sensitive to noise than Gate-based QC
 - We still need to design error-contained algorithm !!!
 - Less versatile than Gate-based QC





Ising Hamiltonian

Goal: finding the ground state of a Hamiltonian H

$$|\boldsymbol{\phi}_0\rangle = \arg\min_{|\boldsymbol{\phi}\rangle} \langle \boldsymbol{\phi} | \mathbf{H} | \boldsymbol{\phi} \rangle$$

- Some definitions
 - Set of *K* qubits $V = \{0, ... K 1\}$
 - Set of interactions between 2 qubits $E \subset \{(i,j) \mid i \in V, j \in V, i < j\}$
 - Pauli- Z operator $\mathbf{Z} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ and identity $\mathbf{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
 - Pauli- Z operator applied on qubit i: $\mathbf{Z}_i = \underbrace{\mathbf{I}}_0 \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_i \otimes \mathbf{I} \otimes \cdots \otimes \underbrace{\mathbf{I}}_{K-1}$
 - Pauli- Z operator applied on qubits i and j:

$$\mathbf{Z}_{ij} = \underbrace{\mathbf{I}}_{0} \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_{i} \otimes \mathbf{I} \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_{j} \otimes \mathbf{I} \otimes \cdots \otimes \underbrace{\mathbf{I}}_{K-1}$$

- Ising Hamiltonian represented by an undirected graph (V, E):

•
$$\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$$

• Is a $2^K \times 2^K$ diagonal operator in the computational basis



- Quadratic Unconstrained Binary Optimization (QUBO)
 - Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$
 with $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$



- Quadratic Unconstrained Binary Optimization (QUBO)
 - Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$
 with $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$

- In terms of spin variables
 - Computational basis of **H** $|\phi\rangle = |b_0 \ b_1 \ ... \ b_{K-1}\rangle$ with $b_i \in \{0, 1\}$
 - Vector of spin variables: $\mathbf{s} = [(-1)^{b_i} \ \forall i \in V]$

The eigenvalue of
$$\mathbf{H}$$
 reads $\mathcal{F}_{\mathrm{Ising}} = \sum_{i \in V} h_i s_i + \sum_{(i,j) \in E} J_{ij} s_i s_j = \mathbf{s}^T \mathbf{h} + \mathbf{s}^T \mathbf{J} \mathbf{s}$
with $\mathbf{h} = [h_i \ \forall i \in V]$ & $\mathbf{J} = [J_{ij} \ \forall (i,j) \in E]$ User programmable $|\phi_0\rangle = \arg\min_{\phi} \langle \phi | \mathbf{H} | \phi \rangle$ $\mathbf{s} = \arg\min_{\mathbf{s}'} \mathcal{F}_{\mathrm{Ising}}(\mathbf{s}'; \mathbf{h}, \mathbf{J})$ parameters

with
$$\mathbf{h} = [h_i \ \forall i \in V]$$
 & $\mathbf{J} = [J_{ij} \ \forall (i,j) \in V]$

$$|\phi_0\rangle = \arg\min_{\phi} \langle q$$



$$\mathbf{s} = \arg\min_{\mathbf{s'}} \mathcal{F}_{\text{Ising}}(\mathbf{s'}; \mathbf{h}, \mathbf{J})$$

- Quadratic Unconstrained Binary Optimization (QUBO)
 - Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$
 with $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$

- In terms of spin variables
 - Computational basis of **H** $|\phi\rangle = |b_0 \ b_1 \ ... \ b_{K-1}\rangle$ with $b_i \in \{0, 1\}$
 - Vector of spin variables: $\mathbf{s} = [(-1)^{b_i} \ \forall i \in V]$

The eigenvalue of
$$\mathbf{H}$$
 reads $\mathcal{F}_{\mathrm{Ising}} = \sum_{i \in V} h_i s_i + \sum_{(i,j) \in E} J_{ij} s_i s_j = \mathbf{s}^T \mathbf{h} + \mathbf{s}^T \mathbf{J} \mathbf{s}$
with $\mathbf{h} = [h_i \ \forall i \in V]$ & $\mathbf{J} = [J_{ij} \ \forall (i,j) \in E]$ User programmable $|\phi_0\rangle = \arg\min_{\phi} \langle \phi | \mathbf{H} | \phi \rangle$ $\mathbf{s} = \arg\min_{\mathbf{s}'} \mathcal{F}_{\mathrm{Ising}}(\mathbf{s}'; \mathbf{h}, \mathbf{J})$ parameters

- In terms of binary variables
 - Vector of binary variables $\mathbf{b} = [b_i \ \forall i \in V]$
 - Spin-binary variable transformation $s_i = 2b_i 1 : \{0,1\} \rightarrow \{-1,1\}$ & property $b_i^2 = b_i$

$$\mathcal{F}_{\text{Ising}} = \sum_{i \in V} h_i s_i + \sum_{(i,j) \in E} J_{ij} s_i s_j \qquad \mathcal{F}_{\text{QUBO}} = \sum_{(i,j) \in E \cup \{(i,i) \forall i \in V\}} A_{ij} b_i b_j = \mathbf{b}^T \mathbf{A} \mathbf{b}$$

$$|\pmb{\phi}_0\rangle = \arg\min_{\pmb{\phi}} \langle \pmb{\phi} | \mathbf{H} \, | \pmb{\phi} \rangle \qquad \qquad \mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A}) \qquad \qquad \text{User programmable parameters}$$

Set of PDEs to be solved

- Strong form Weak form:
$$\nabla \cdot \sigma(x) + b_0(x) = \mathbf{0} \qquad \int_V \sigma(x) : \nabla \otimes^s \delta u(x) dV = \int_V b_0 \cdot \delta u dV + \int_{\partial_N V} \mathbf{n} \cdot \sigma \cdot \delta u d\partial V$$

Constitutive model:

$$\sigma(x,t) = \sigma\big(\nabla \otimes^{\scriptscriptstyle S} u(x,t); \mathbf{q}(x,t)\big) \quad \text{with evolution law} \qquad \mathcal{Q}\big(\sigma(x,t), \mathbf{q}(\nabla \otimes^{\scriptscriptstyle S} u(x,\tau); \tau \leq t)\big) = \mathbf{0}$$

Set of PDEs to be solved

- Strong form Weak form:
$$\nabla \cdot \sigma(x) + b_0(x) = 0 \qquad \int_V \sigma(x) : \nabla \otimes^s \delta u(x) dV = \int_V b_0 \cdot \delta u dV + \int_{\partial_N V} n \cdot \sigma \cdot \delta u d\partial V$$

Constitutive model:

$$\sigma(x,t) = \sigma(\nabla \otimes^s u(x,t); \mathbf{q}(x,t))$$
 with evolution law $Q(\sigma(x,t), \mathbf{q}(\nabla \otimes^s u(x,\tau); \tau \leq t)) = \mathbf{0}$

Finite element formulation

Displacement field at quadrature point E from nodal displacements vector U

$$\boldsymbol{u}(\Xi) = N_a(\Xi)\boldsymbol{U}_a$$



$$\boldsymbol{u}(\Xi) = N_a(\Xi)\boldsymbol{U}_a$$

$$\boldsymbol{\varepsilon}(\Xi) = \boldsymbol{\nabla} \otimes^s \boldsymbol{u}(\Xi) = \boldsymbol{B}_a(\Xi)\boldsymbol{U}_a$$

- Resulting non-linear system of equations on time interval $[t_n \ t_{n+1}]$

$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}, t) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV + \int_{\partial_{N} V} \boldsymbol{n} \cdot \boldsymbol{\sigma} \cdot \boldsymbol{\delta u} d\partial V$$

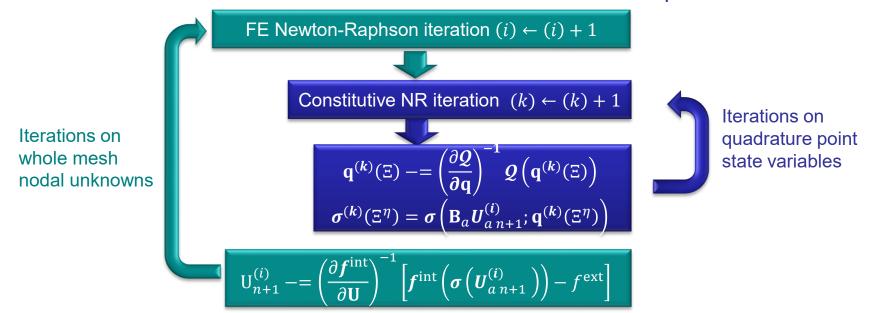
$$\delta \boldsymbol{U}_{\boldsymbol{b}}^{\mathrm{T}} \cdot \sum_{\Xi} \mathbf{B}_{\boldsymbol{b}}^{\mathrm{T}}(\Xi) \, \boldsymbol{\sigma}((\Xi)) \omega^{\Xi} = \delta \boldsymbol{U}_{\boldsymbol{b}}^{\mathrm{T}} \cdot \sum_{\Xi} N_{\boldsymbol{b}}(\Xi) \, \boldsymbol{b}_{0}(\Xi) \omega^{\Xi}$$

Omitting surface tractions

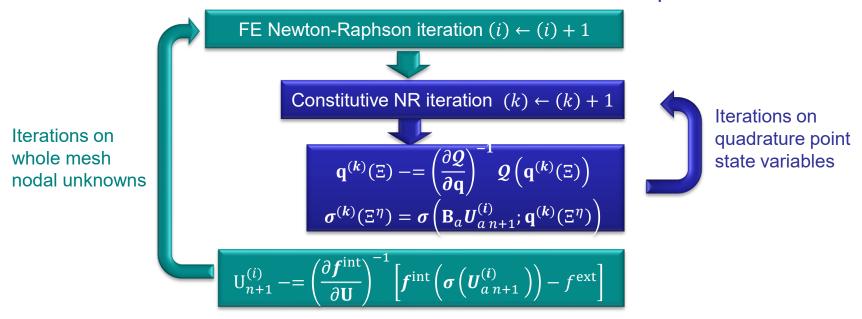
$$\boldsymbol{f}_b^{\text{int}} = \sum_{\Xi} \mathbf{B}_b^{\text{T}}(\Xi) \, \boldsymbol{\sigma}(\Xi) \omega^{\Xi} = \sum_{\Xi} N_b(\Xi) \, \boldsymbol{b}_0(\Xi) \omega^{\Xi} = \boldsymbol{f}_b^{\text{ext}}$$

with
$$\begin{cases} \boldsymbol{\sigma}(\Xi,t_{n+1}) = \boldsymbol{\sigma}\big(\mathbf{B}_a(\Xi)\boldsymbol{U}_{a\;n+1};\mathbf{q}(\Xi,t_{n+1})\big) \\ \\ \boldsymbol{Q}\big(\boldsymbol{\sigma}(\Xi,t_{n+1}),\mathbf{q}(\Xi,t_{n+1}),\mathbf{q}(\Xi,t_n)\big) = \mathbf{0} \end{cases}$$

Consider classical finite element resolution on Quantum Computers?



Consider classical finite element resolution on Quantum Computers?



- What can be solved on a Quantum Computer?
 - Optimization problems can be solved (Actually Quantum Annealers look for a ground state)
 - · Some operations can be achieved efficiently on classical computers like assembly
- Do we need the same resolution structure?
 - Do we need intricated NR loops?
 - Do we even need to use the discretized form of the weak form?

$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV \qquad \qquad \boldsymbol{f}_{b}^{\text{int}} = \sum_{\Xi} \mathbf{B}_{b}^{\text{T}}(\Xi) \boldsymbol{\sigma}(\Xi) \omega^{\Xi} = \boldsymbol{f}_{b}^{\text{ext}}$$

Non-linear finite element resolution on Quantum Computers?

- Weak form:
$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV$$

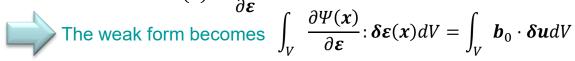
- Assuming non-linear elasticity
 - Existence of a free energy $\Psi(\varepsilon(x))$ with $\varepsilon(x) = \nabla \otimes^s u(x)$
 - Stress results from $\sigma(x) = \frac{\partial \Psi}{\partial \varepsilon}$

The weak form becomes
$$\int_{V} \frac{\partial \Psi(x)}{\partial \varepsilon} : \delta \varepsilon(x) dV = \int_{V} b_{0} \cdot \delta u dV$$

Non-linear finite element resolution on Quantum Computers?

- Weak form:
$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV$$

- Assuming non-linear elasticity
 - Existence of a free energy $\Psi(\varepsilon(x))$ with $\varepsilon(x) = \nabla \otimes^s u(x)$
 - Stress results from $\sigma(x) = \frac{\partial \Psi}{\partial \varepsilon}$



Introduction of a functional

The weak form results from nulling the Gâteaux derivative

$$\Phi'\left(\boldsymbol{u}(V);\delta\boldsymbol{u}(V)\right) = \int_{V} \boldsymbol{\sigma}(\boldsymbol{x}): \nabla \otimes^{s} \boldsymbol{\delta}\boldsymbol{u}(\boldsymbol{x})dV - \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta}\boldsymbol{u}dV = \boldsymbol{0}$$

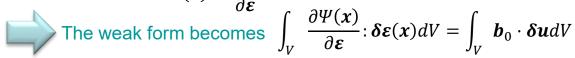


The solution of the weak form minimizes the energy: $u(V) = \arg\min_{u'(V)} \Phi(u'(V))$

Non-linear finite element resolution on Quantum Computers?

- Weak form:
$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV$$

- Assuming non-linear elasticity
 - Existence of a free energy $\Psi(\varepsilon(x))$ with $\varepsilon(x) = \nabla \otimes^s u(x)$
 - Stress results from $\sigma(x) = \frac{\partial \Psi}{\partial \varepsilon}$



Introduction of a functional

The weak form results from nulling the Gâteaux derivative

$$\Phi'\left(\boldsymbol{u}(V);\delta\boldsymbol{u}(V)\right) = \int_{V} \boldsymbol{\sigma}(\boldsymbol{x}): \nabla \otimes^{s} \boldsymbol{\delta}\boldsymbol{u}(\boldsymbol{x})dV - \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta}\boldsymbol{u}dV = \boldsymbol{0}$$



The solution of the weak form minimizes the energy: $u(V) = \arg\min_{u'(V)} \Phi(u'(V))$

- We are looking for the solution of a minimization problem
 - The potential is convex
 - But it is not quadratic
 - Quid inelastic materials?

- Non-linear finite element resolution on Quantum Computers?
 - Inelastic materials
 - with $\boldsymbol{\varepsilon}(x) = \nabla \otimes^s \boldsymbol{u}(x)$ Existence of a Helmholtz free energy $\Psi(\varepsilon(x), \mathbf{q}(x))$
 - Dissipation \mathcal{D} and Clausius-Duhem inequality

•
$$\mathcal{D} = \boldsymbol{\sigma} : \dot{\boldsymbol{\varepsilon}} - \dot{\boldsymbol{\Psi}} \ge 0$$
 with $\dot{\boldsymbol{\Psi}} = \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} + \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{q}} \cdot \dot{\boldsymbol{q}}$

• Equality holds in case of a reversible transformation

$$\boldsymbol{\sigma} = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} \qquad \text{for an irreversible process:} \quad \mathcal{D} = \mathbf{Y} \cdot \dot{\mathbf{q}} \ge 0 \quad \text{with} \quad \mathbf{Y} = -\frac{\partial \Psi}{\partial \mathbf{q}}$$

Postulate the existence of a pseudo-potential $\Theta(\dot{\mathbf{q}})$ and its convex dual $\Theta^*(\mathbf{Y})$

•
$$\theta(\dot{\mathbf{q}}) = \max_{\mathbf{Y}} [\mathbf{Y} \cdot \dot{\mathbf{q}} - \theta^*(\mathbf{Y})]$$
 $\dot{\mathbf{q}} = \frac{\partial \theta^*(\mathbf{Y})}{\partial \mathbf{Y}}$ & $\mathbf{Y} = \frac{\partial \theta(\dot{\mathbf{q}})}{\partial \dot{\mathbf{q}}}$



- Non-linear finite element resolution on Quantum Computers?
 - Inelastic materials
 - Existence of a Helmholtz free energy $\Psi(\varepsilon(x), \mathbf{q}(x))$ with $\varepsilon(x) = \nabla \otimes^s \mathbf{u}(x)$
 - Dissipation \mathcal{D} and Clausius-Duhem inequality

•
$$\mathcal{D} = \boldsymbol{\sigma} : \dot{\boldsymbol{\varepsilon}} - \dot{\boldsymbol{\Psi}} \ge 0$$
 with $\dot{\boldsymbol{\Psi}} = \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} + \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\sigma}} \cdot \dot{\boldsymbol{q}}$

Equality holds in case of a reversible transformation

$$\sigma = \frac{\partial \Psi}{\partial \varepsilon} \qquad \text{for an irreversible process:} \quad \mathcal{D} = \mathbf{Y} \cdot \dot{\mathbf{q}} \ge 0 \quad \text{with} \quad \mathbf{Y} = -\frac{\partial \Psi}{\partial \mathbf{q}}$$

Postulate the existence of a pseudo-potential $\Theta(\dot{\mathbf{q}})$ and its convex dual $\Theta^*(\mathbf{Y})$

•
$$\theta(\dot{\mathbf{q}}) = \max_{\mathbf{Y}} [\mathbf{Y} \cdot \dot{\mathbf{q}} - \theta^*(\mathbf{Y})]$$
 $\dot{\mathbf{q}} = \frac{\partial \theta^*(\mathbf{Y})}{\partial \mathbf{Y}}$ & $\mathbf{Y} = \frac{\partial \theta(\dot{\mathbf{q}})}{\partial \dot{\mathbf{q}}}$

- Power functional \mathcal{E}
 - New independent variables $(\dot{\varepsilon}, \dot{q})$

•
$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) = \dot{\boldsymbol{\Psi}} + \boldsymbol{\Theta}(\dot{\mathbf{q}}) = \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} - \mathbf{Y} \cdot \dot{\mathbf{q}} + \boldsymbol{\Theta}(\dot{\mathbf{q}})$$

$$\frac{\partial \mathcal{E}}{\partial \dot{\mathbf{q}}} = -\mathbf{Y} + \frac{\partial \mathcal{O}(\dot{\mathbf{q}})}{\partial \dot{\mathbf{q}}} = \mathbf{0}$$
 \(\mathcal{\mathcal{E}}\) has to be minimized with respect to internal state

- Effective power functional* $\mathcal{E}^{\mathrm{eff}}(\dot{\boldsymbol{\varepsilon}}) = \min_{\dot{\mathbf{q}}} \mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}})$ with $\boldsymbol{\sigma} = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} = \frac{\partial \mathcal{E}^{\mathrm{eff}}}{\partial \dot{\boldsymbol{\varepsilon}}}$
- The constitutive model is also a minimization problem

*Radovitzky, R. Ortiz M, CMAME 1999 Ortiz, M., Stainier, L., CMAME 1999

- Non-linear finite element resolution on Quantum Computers?
 - In elasticity we had

•
$$u(V) = \arg\min_{u'(V)} \Phi(u'(V))$$
 with $\Phi(u(V)) = \int_{V} \Psi(\nabla \otimes^{s} u(x)) dV - W^{\text{ext}}(u(x))$

- Double minimization problem in inelasticity
 - Power functional \mathcal{E}

$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} - \mathbf{Y} \cdot \dot{\mathbf{q}} + \Theta(\dot{\mathbf{q}}) \qquad & \mathcal{E}^{\text{eff}}(\dot{\boldsymbol{\varepsilon}}) = \min_{\dot{\mathbf{q}}} \mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) \qquad & \boldsymbol{\sigma} = \frac{\partial \mathcal{E}^{\text{eff}}}{\partial \dot{\boldsymbol{\varepsilon}}}$$

Volume power functional

$$\Phi(\dot{\boldsymbol{u}}(V), \dot{\mathbf{q}}(V)) = \int_{V} \mathcal{E}(\nabla \otimes^{S} \dot{\boldsymbol{u}}, \dot{\mathbf{q}}) dV - \dot{W}^{\text{ext}}(\dot{\boldsymbol{u}}(V))$$



- Non-linear finite element resolution on Quantum Computers?
 - In elasticity we had

•
$$u(V) = \arg\min_{u'(V)} \Phi(u'(V))$$
 with $\Phi(u(V)) = \int_{V} \Psi(\nabla \otimes^{s} u(x)) dV - W^{\text{ext}}(u(x))$

- Double minimization problem in inelasticity
 - Power functional \mathcal{E}

$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} - \mathbf{Y} \cdot \dot{\mathbf{q}} + \Theta(\dot{\mathbf{q}}) \qquad & \mathcal{E}^{\text{eff}}(\dot{\boldsymbol{\varepsilon}}) = \min_{\dot{\mathbf{q}}} \mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) \qquad & \boldsymbol{\sigma} = \frac{\partial \mathcal{E}^{\text{eff}}}{\partial \dot{\boldsymbol{\varepsilon}}}$$

Volume power functional

$$\Phi(\dot{\boldsymbol{u}}(V), \dot{\mathbf{q}}(V)) = \int_{V} \mathcal{E}(\nabla \otimes^{S} \dot{\boldsymbol{u}}, \dot{\mathbf{q}}) dV - \dot{W}^{\text{ext}}(\dot{\boldsymbol{u}}(V))$$

• Incremental volume energy functional on time interval $[t_n \ t_{n+1}]^*$

$$\Delta \Phi(\boldsymbol{u}_{n+1}, \boldsymbol{q}_{n+1}) = \int_{V} \Delta \mathcal{E}(\nabla \otimes^{s} \boldsymbol{u}_{n+1}, q_{n+1}) \, dV - \Delta W^{\text{ext}}(\boldsymbol{u}_{n+1})$$
 with
$$\Delta \mathcal{E}(\nabla \otimes^{s} \boldsymbol{u}_{n+1}, \boldsymbol{q}_{n+1}) = \int_{t_{n}}^{t_{n+1}} \mathcal{E}(\nabla \otimes^{s} \dot{\boldsymbol{u}}, \dot{\boldsymbol{q}}) \, dV \quad \& \quad \Delta \mathcal{E}^{\text{eff}}(\boldsymbol{\varepsilon}) = \min_{\boldsymbol{q}} \Delta \mathcal{E}(\boldsymbol{\varepsilon}, \boldsymbol{q}) \quad , \quad \boldsymbol{\sigma} = \frac{\partial \Delta \mathcal{E}^{\text{eff}}}{\partial \boldsymbol{\varepsilon}}$$

*Ortiz, M., Stainier, L., CMAME 1999



- Non-linear finite element resolution on Quantum Computers?
 - In elasticity we had

•
$$u(V) = \arg\min_{u'(V)} \Phi(u'(V))$$
 with $\Phi(u(V)) = \int_{V} \Psi(\nabla \otimes^{s} u(x)) dV - W^{\text{ext}}(u(x))$

- Double minimization problem in inelasticity
 - Power functional \mathcal{E}

$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} - \mathbf{Y} \cdot \dot{\mathbf{q}} + \Theta(\dot{\mathbf{q}}) \qquad & \mathcal{E}^{\text{eff}}(\dot{\boldsymbol{\varepsilon}}) = \min_{\dot{\mathbf{q}}} \mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) \qquad & \boldsymbol{\sigma} = \frac{\partial \mathcal{E}^{\text{eff}}}{\partial \dot{\boldsymbol{\varepsilon}}}$$

· Volume power functional

$$\Phi(\dot{\boldsymbol{u}}(V), \dot{\mathbf{q}}(V)) = \int_{V} \mathcal{E}(\nabla \otimes^{s} \dot{\boldsymbol{u}}, \dot{\mathbf{q}}) - \dot{W}^{\text{ext}}(\dot{\boldsymbol{u}}(V))$$

• Incremental volume energy functional on time interval $[t_n \ t_{n+1}]^*$

$$\begin{split} \Delta \Phi(\boldsymbol{u}_{n+1}, \mathbf{q}_{n+1}) &= \int_{V} \Delta \mathcal{E}(\nabla \otimes^{s} \boldsymbol{u}_{n+1}, q_{n+1}) dV - \Delta W^{\mathrm{ext}}(\boldsymbol{u}_{n+1}) \\ \text{with } \Delta \mathcal{E}(\nabla \otimes^{s} \boldsymbol{u}_{n+1}, \mathbf{q}_{n+1}) &= \int_{t_{n}}^{t_{n+1}} \mathcal{E}(\nabla \otimes^{s} \dot{\boldsymbol{u}}, \dot{\mathbf{q}}) dV \quad \& \quad \Delta \mathcal{E}^{\mathrm{eff}}(\boldsymbol{\varepsilon}) = \min_{\mathbf{q}} \Delta \mathcal{E}(\boldsymbol{\varepsilon}, \mathbf{q}) \quad , \quad \boldsymbol{\sigma} = \frac{\partial \Delta \mathcal{E}^{\mathrm{eff}}}{\partial \boldsymbol{\varepsilon}} \end{split}$$

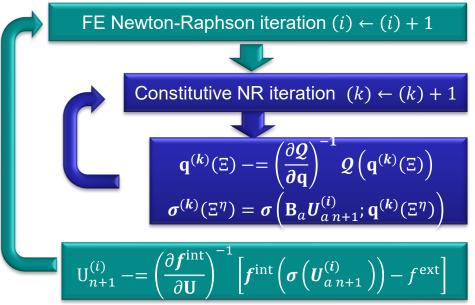
The problem solution reads

$$\mathbf{q}_{n+1} = \arg\min_{\mathbf{q}'} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')$$

$$\Delta \Phi^{\mathrm{eff}}(\mathbf{u}_{n+1}) = \min_{\mathbf{q}'} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}') = \int_{V} \Delta \mathcal{E}^{\mathrm{eff}}(\nabla \otimes^{s} \mathbf{u}_{n+1}) dV - \Delta W^{\mathrm{ext}}$$

$$\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \mathrm{admissible}} \Delta \Phi^{\mathrm{eff}}(\mathbf{u}')$$
*Ortiz, M., Stainier, L., CMAME 1999

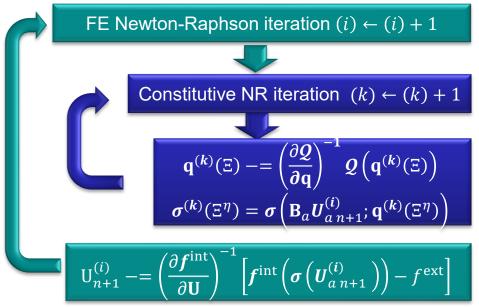
Classical finite element resolution



Finite element as a double-minimization problem

```
Loop until convergence \mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}'); \Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}') \mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}') Internal variables can be constrained (e.g. \mathbf{N}: \mathbf{N} = \frac{3}{2}, \Delta \gamma \geq 0)
```

Classical finite element resolution



Finite element as a double-minimization problem

```
Loop until convergence \mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}'); \Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}') \mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}') Internal variables can be constrained (e.g. \mathbf{N}: \mathbf{N} = \frac{3}{2}, \Delta \gamma \geq 0)
```

- Quantum annealers: ground state of an Ising-Hamiltonian
 - No need for Jacobians
 - No problem of convergence (but needs to be noise-contained)
- But how to make the optimisation problem solvable by quantum annealing?



- Finite element as a double-minimization problem
 - Finite element problem

Loop until convergence
$$\mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');$$

$$\Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')$$

$$\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')$$

- Ising Hamiltonian for Quantum annealing
 - Goal: finding the ground state of a Hamiltonian H: $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in F} J_{ij} \mathbf{Z}_{ij}$ $|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$
 - Problem reformulated in terms of binary variables $\mathbf{b} = [b_i \ \forall i \in V]$ with $b_i \in \{0, 1\}$
 - QUBO optimisation problem $\mathcal{F}_{\text{QUBO}} = \sum_{(i,j) \in E \cup \{(i,i) \forall i \in V\}} A_{ij} b_i b_j = \mathbf{b}^T \mathbf{A} \mathbf{b}$ $\mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A}) \quad \text{User programmable parameters}$

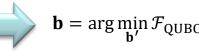
- Finite element as a double-minimization problem
 - Finite element problem

Loop until convergence
$$\mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');$$

$$\Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')$$

$$\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')$$

- Ising Hamiltonian for Quantum annealing
 - Goal: finding the ground state of a Hamiltonian H: $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in F} J_{ij} \mathbf{Z}_{ij}$ $|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi|\mathbf{H}|\phi\rangle$
 - Problem reformulated in terms of binary variables $\mathbf{b} = [b_i \ \forall i \in V]$ with $b_i \in \{0, 1\}$
 - QUBO optimisation problem $\mathcal{F}_{\text{QUBO}} = \sum_{(i,j) \in E \cup \{(i,i) \forall i \in V\}} A_{ij} b_i b_j = \mathbf{b}^T \mathbf{A} \mathbf{b}$ $\mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A}) \quad \text{User programmable parameters}$



- Steps to follow
 - Transform the constrained minimization problem into an unconstrained one
 - Transform the general unconstrained optimization problem into a series of quadratic ones
 - Transform each continuous quadratic optimization problem into a binarized one
 - Apply the double-minimization framework



- Transform the constrained minimization problem into an unconstrained one
 - Constrained multivariate minimization problem
 - $\min_{\mathbf{w}} f(\mathbf{w})$ with $\mathbf{w}^{\min} \le \mathbf{w} \le \mathbf{w}^{\max}$
 - Under constraints $h(\mathbf{w}) = 0$ & $l(\mathbf{w}) \le 0$
 - Augmented minimization problem

•
$$f_{\text{aug}}(\mathbf{v}) = f_{\text{aug}}(\mathbf{w}, \lambda) = f(\mathbf{w}) + c^h (h(\mathbf{w}))^2 + c^l (l(\mathbf{w}) + \lambda)^2$$
 with $\mathbf{v} = \{\mathbf{w}, \lambda \ge 0\}$

- Unconstrained minimization problem
 - $\min_{\mathbf{v}} f_{\text{aug}}(\mathbf{v})$ with $\mathbf{v}^{\min} \leq \mathbf{v} \leq \mathbf{v}^{\max}$
 - Bounds will be enforced during the binarization process

- Transform the constrained minimization problem into an unconstrained one
 - Constrained multivariate minimization problem
 - $\min_{\mathbf{w}} f(\mathbf{w})$ with $\mathbf{w}^{\min} \le \mathbf{w} \le \mathbf{w}^{\max}$
 - Under constraints $h(\mathbf{w}) = 0$ & $l(\mathbf{w}) \le 0$
 - Augmented minimization problem

•
$$f_{\text{aug}}(\mathbf{v}) = f_{\text{aug}}(\mathbf{w}, \lambda) = f(\mathbf{w}) + c^h(h(\mathbf{w}))^2 + c^l(l(\mathbf{w}) + \lambda)^2$$
 with $\mathbf{v} = \{\mathbf{w}, \lambda \ge 0\}$

- Unconstrained minimization problem
 - $\min_{\mathbf{v}} f_{\text{aug}}(\mathbf{v})$ with $\mathbf{v}^{\min} \leq \mathbf{v} \leq \mathbf{v}^{\max}$
 - Bounds will be enforced during the binarization process
- Definition of the double-unconstrained minimization problem

```
Loop until convergence \mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');
\Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')
\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')
```



```
Loop until convergence \mathbf{q}_{n+1}, \lambda = \arg\min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}', \lambda'); \Delta \Phi^{\mathrm{eff}} = \min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}', \lambda') \boldsymbol{u}_{n+1} = \arg\min_{\mathbf{u}' \mathrm{admissible}} \Delta \Phi^{\mathrm{eff}}(\mathbf{u}')
```



- Transform the optimization problem into a series of quadratic ones
 - Unconstrained optimization problem

•
$$\min_{\mathbf{v}} f_{\mathrm{aug}}(\mathbf{v})$$
 with $\mathbf{v}^{\min} \leq \mathbf{v} \leq \mathbf{v}^{\max}$

Taylor's expansion
• $f_{\mathrm{aug}}(\mathbf{v} + \mathbf{z}) \simeq f_{\mathrm{aug}}(\mathbf{v})$
• $f_{\mathrm{aug}}(\mathbf{v} + \mathbf{z}) \simeq f_{\mathrm{$

- New series of optimization problems
 - Iterate on **z** with: $\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}'; f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}})$

- Transform the optimization problem into a series of quadratic ones
 - Unconstrained optimization problem
 - $\min_{\mathbf{v}} f_{\text{aug}}(\mathbf{v})$ with $\mathbf{v}^{\min} \leq \mathbf{v} \leq \mathbf{v}^{\max}$ $\begin{aligned}
 &\underset{\mathbf{v}}{\min} f_{\text{aug}}(\mathbf{v}) \quad \text{with} \quad \mathbf{v}^{\text{min}} \leq \mathbf{v} \leq \mathbf{v}^{\text{max}} \\
 &\text{aylor's expansion} \quad QF(\mathbf{z}; f_{\text{aug},\mathbf{v}}, f_{\text{aug},\mathbf{vv}}) \\
 &\cdot f_{\text{aug}}(\mathbf{v} + \mathbf{z}) \simeq f_{\text{aug}}(\mathbf{v}) \quad \mathbf{z}^{\text{T}} f_{\text{aug},\mathbf{v}} + \frac{1}{2} \mathbf{z}^{\text{T}} f_{\text{aug},\mathbf{vv}} \mathbf{z}
 \end{aligned}$ $f_{\text{aug},\mathbf{v}} = \frac{\partial f_{\text{aug}}}{\partial v_i} \Big|_{\mathbf{v}}$ $f_{\text{aug},\mathbf{v}} = \frac{\partial^2 f_{\text{aug}}}{\partial v_i \partial v_j} \Big|_{\mathbf{v}}$ $f_{\text{aug},\mathbf{v}} = \frac{\partial^2 f_{\text{aug}}}{\partial v_i \partial v_j} \Big|_{\mathbf{v}}$ Taylor's expansion
 - New series of optimization problems
 - Iterate on **z** with: $\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}'; f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}})$
 - Application to the double minimisation problem

```
Loop until convergence
             \mathbf{q}_{n+1}, \lambda = \arg\min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\mathbf{u}_{n+1}, \mathbf{q}', \lambda');
             \Delta \Phi^{\text{eff}} = \min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\text{aug}}(\mathbf{u}_{n+1}, \mathbf{q}', \lambda')
             \overline{\mathbf{u}_{n+1}} = \arg \min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')
```

Allow contain the noise!!!

Loop until convergence Loop on $u_{n+1} \leftarrow u_{n+1} + \Delta u$ $\Delta u = \arg \min_{\Delta u' \text{admissible}} \Delta u'^{\text{T}} \Delta \Phi_{,\mathbf{u}}^{\text{eff}} + \frac{1}{2} \Delta u'^{\text{T}} \Delta \Phi_{,\mathbf{u}\mathbf{u}}^{\text{eff}} \Delta u'$ **Loop on** $q_{n+1} \leftarrow q_{n+1} + \Delta q$, $\lambda \leftarrow \lambda + \Delta \lambda$

 $\Delta \mathbf{q}, \Delta \lambda = \arg \min_{\{\Delta \mathbf{q}' \Delta \lambda'\}} \left[\Delta \mathbf{q'}^{\mathrm{T}} \Delta \lambda' \right] \Delta \Phi_{\mathrm{aug},\{\mathbf{q},\lambda\}} + \frac{1}{2} \left[\Delta \mathbf{q'}^{\mathrm{T}} \Delta \lambda' \right] \Delta \Phi_{\mathrm{aug},\{\mathbf{q},\lambda\}} \left[\Delta \mathbf{q'}^{\mathrm{T}} \Delta \lambda' \right]^{\mathrm{T}}$

 $\Delta \Phi^{\text{eff}} = \Delta \Phi_{\text{aug}}(\boldsymbol{u}_{n+1}, \overline{\boldsymbol{q}}_{n+1}, \lambda)$

- Transform each continuous quadratic optimization problem into a binarized one
 - Optimization problems to be solved
 - $\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}', f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}})$ & $\mathrm{QF}(\mathbf{z}; f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}}) = \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{v}} + \frac{1}{2} \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{vv}} \mathbf{z}$
 - With bounds: $v_{min} \le v + z \le v_{max}$
 - Binarization of $z \in \mathbb{R}^N$ into $N \times L$ qubits

 - $b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^T \mathbf{b}_i$ $\mathbf{z}_1 = \mathbf{z}_i^{\min} + \epsilon_i \boldsymbol{\beta}^T \mathbf{b}_i$ $\mathbf{z} = \mathbf{a} + \mathbf{D}(\boldsymbol{\epsilon}) \mathbf{b}$ with the bounds defining $\mathbf{a} = \mathbf{z}^{\min}$ & the scale $\boldsymbol{\epsilon} = \frac{\mathbf{z}^{\max} \mathbf{z}^{\min}}{2^L 1}$

- Transform each continuous quadratic optimization problem into a binarized one
 - Optimization problems to be solved
 - $\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}', f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}}) \qquad \qquad \& \ \mathrm{QF}(\mathbf{z}; f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}}) = \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{v}} + \frac{1}{2} \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{vv}} \mathbf{z}$
 - With bounds: $v_{min} \le v + z \le v_{max}$
 - Binarization of $z \in \mathbb{R}^N$ into $N \times L$ qubits

•
$$b_{L-1} \dots b_0 \equiv \sum_{j=0} b_j \ 2^j = \boldsymbol{\beta}^T \mathbf{b_i}$$
 $\sum_{j=0} z_1 = z_i^{\min} + \epsilon_i \boldsymbol{\beta}^T \mathbf{b_i}$

• $b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^T \mathbf{b_i}$ $z_1 = z_i^{\min} + \epsilon_i \boldsymbol{\beta}^T \mathbf{b_i}$ • $\mathbf{z} = \mathbf{a} + \mathbf{D}(\boldsymbol{\epsilon})\mathbf{b}$ with the bounds defining $\mathbf{a} = \mathbf{z}^{\min}$ & the scale $\boldsymbol{\epsilon} = \frac{\mathbf{z}^{\max} - \mathbf{z}^{\min}}{2^L - 1}$

$$QF(\mathbf{z}; f_{\text{aug,v}}, f_{\text{aug,vv}}) = \frac{1}{2} \mathbf{b}^{\text{T}} \mathbf{D}^{\text{T}} f_{\text{aug,vv}} \mathbf{D} \mathbf{b} + \mathbf{b}^{\text{T}} \mathbf{D}^{\text{T}} (f_{\text{aug,v}} + f_{\text{aug,vv}} \mathbf{a}) + \frac{1}{2} \mathbf{a}^{\text{T}} (f_{\text{aug,vv}} \mathbf{a} + f_{\text{aug,vv}})$$

$$\mathcal{F}_{\text{QUBO}}(\mathbf{b}; \mathbf{A})$$

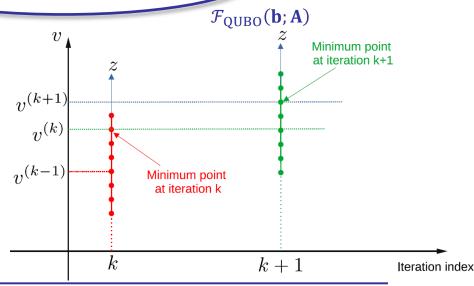
- Transform each continuous quadratic optimization problem into a binarized one
 - Optimization problems to be solved
 - $\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}', f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}}) \qquad \qquad \& \ \mathrm{QF}(\mathbf{z}; f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}}) = \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{v}} + \frac{1}{2} \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{vv}} \mathbf{z}$
 - With bounds: $v_{min} \le v + z \le v_{max}$
 - Binarization of $z \in \mathbb{R}^N$ into $N \times L$ qubits

•
$$b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^T \mathbf{b_i}$$
 $\mathbf{z}_1 = z_i^{\min} + \epsilon_i \boldsymbol{\beta}^T \mathbf{b_i}$

• $b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^T \mathbf{b_i}$ $z_1 = z_i^{\min} + \epsilon_i \boldsymbol{\beta}^T \mathbf{b_i}$ • $\mathbf{z} = \mathbf{a} + \mathbf{D}(\boldsymbol{\epsilon})\mathbf{b}$ with the bounds defining $\mathbf{a} = \mathbf{z}^{\min}$ & the scale $\boldsymbol{\epsilon} = \frac{\mathbf{z}^{\max} - \mathbf{z}^{\min}}{2^L - 1}$

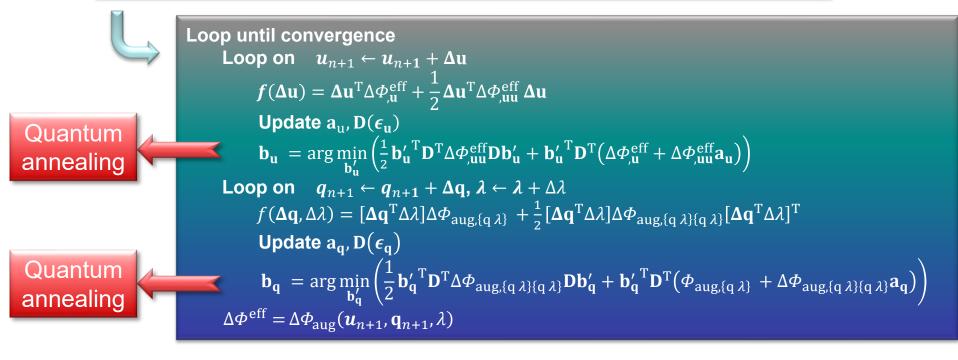
$$QF(\mathbf{z}; f_{\text{aug,}\mathbf{v}}, f_{\text{aug,}\mathbf{v}}) = \frac{1}{2} \mathbf{b}^{\text{T}} \mathbf{D}^{\text{T}} f_{\text{aug,}\mathbf{v}} \mathbf{D} \mathbf{b} + \mathbf{b}^{\text{T}} \mathbf{D}^{\text{T}} (f_{\text{aug,}\mathbf{v}} + f_{\text{aug,}\mathbf{v}} \mathbf{a}) + \frac{1}{2} \mathbf{a}^{\text{T}} (f_{\text{aug,}\mathbf{v}} \mathbf{a} + f_{\text{aug,}\mathbf{v}})$$

- Minimization
 - Bound $\mathbf{a} = \mathbf{z}^{\min}$
 - Scale $\epsilon = \frac{\mathbf{z}^{\max} \mathbf{z}^{\min}}{2^L 1}$
 - Updated when building the QUBO



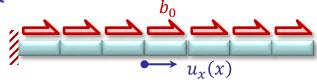
Application to the double-minimization problem

```
Loop until convergence  \begin{array}{l} \text{Loop on} \quad u_{n+1} \leftarrow u_{n+1} + \Delta \mathbf{u} \\ \Delta u = \arg \min_{\Delta \mathbf{u}' \text{ admissible}} \Delta \mathbf{u'}^{\mathsf{T}} \Delta \Phi_{,\mathbf{u}}^{\text{eff}} + \frac{1}{2} \Delta \mathbf{u'}^{\mathsf{T}} \Delta \Phi_{,\mathbf{u}\mathbf{u}}^{\text{eff}} \quad \Delta \mathbf{u'} \\ \text{Loop on} \quad q_{n+1} \leftarrow q_{n+1} + \Delta \mathbf{q}, \ \lambda \leftarrow \lambda + \Delta \lambda \\ \Delta \mathbf{q}, \Delta \lambda = \arg \min_{\{\Delta \mathbf{q}', \Delta \lambda'\}} \left[ \Delta \mathbf{q'}^{\mathsf{T}} \Delta \lambda' \right] \Delta \Phi_{\text{aug}, \{\mathbf{q} \ \lambda\}} + \frac{1}{2} \left[ \Delta \mathbf{q'}^{\mathsf{T}} \Delta \lambda' \right] \Delta \Phi_{\text{aug}, \{\mathbf{q} \ \lambda\} \{\mathbf{q} \ \lambda\}} \left[ \Delta \mathbf{q'}^{\mathsf{T}} \Delta \lambda' \right]^{\mathsf{T}} \\ \Delta \Phi^{\text{eff}} = \Delta \Phi_{\text{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}_{n+1}, \lambda) \end{array}
```

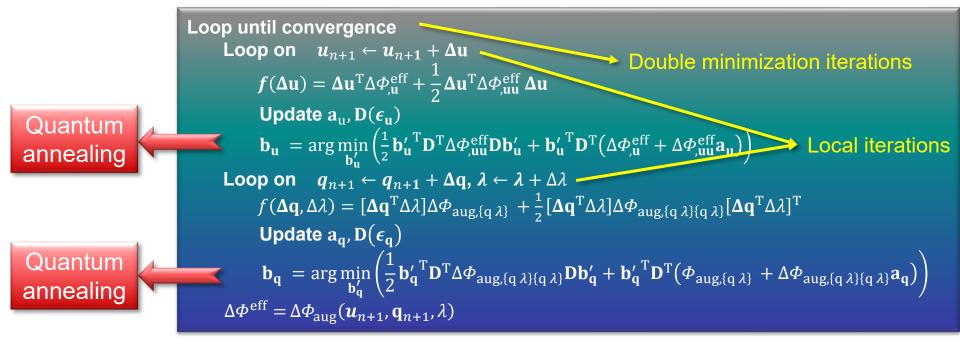


Application on 1D problems

Uniaxial-strain test

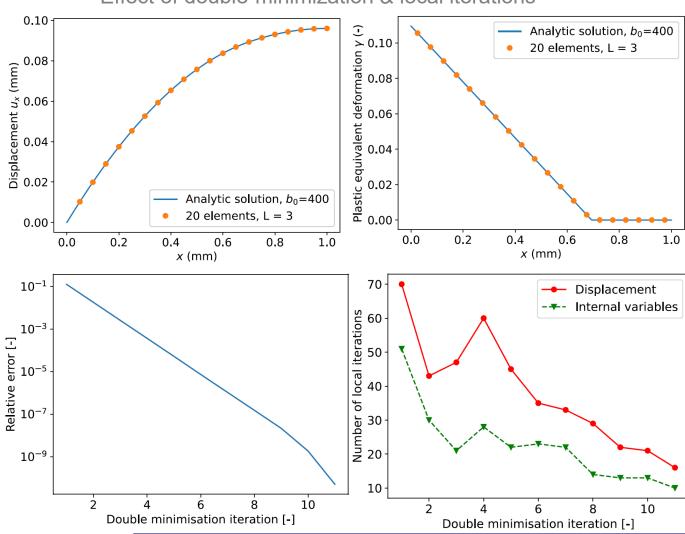


- Elasto-plastic case
 - Double minimization
 - Binarizations L of each nodal displacement and internal variable: $b_{L-1} \dots b_0 \equiv \sum_{i=0}^{L} b_i \ 2^j = \boldsymbol{\beta}^T \mathbf{b}_i$
 - Resolution by quantum annealing on DWave Advantage QPU



Application on 1D problems

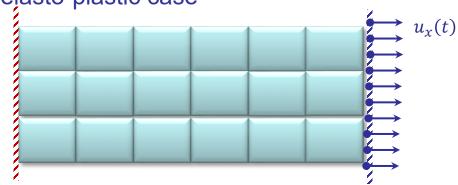
- Uniaxial-strain test
- Elasto-plastic case
 - Effect of double-minimization & local iterations

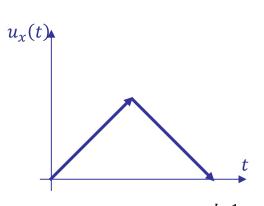


The number of local iterations decreases as the double minimisation iterations proceed

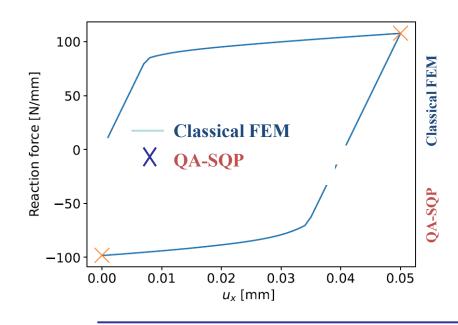
Application on 2D problems

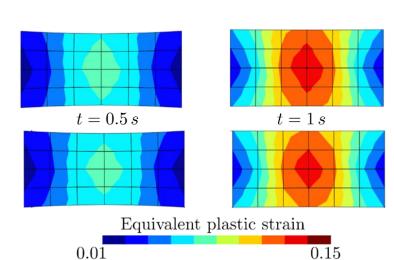
2D-elasto-plastic case





- Double minimization
 - Binarizations L of each nodal displacement and internal variable: $b_{L-1} \dots b_0 \equiv \sum_{i=1}^{L-1} b_i 2^j = \boldsymbol{\beta}^T \mathbf{b}_i$
- Resolution by quantum annealing on DWave Advantage QPU





Conclusions

Application of QC to FEM

- FE resolution needs to be rethought
- It will probably stay advantageous to solve part of the problem on classical computers
- Binarization remains a limitation

Quantum annealing

- Real annealers can now be used
- Efficient to solve optimization problem.... FEM is actually a minimization problem
- Main current limitation is the number of connected qubits

Publication

V. D. Nguyen, F. Remacle, L. Noels. A quantum annealing-sequential quadratic programming assisted finite element simulation for non-linear and history-dependent mechanical problems. *European Journal of Mechanics – A/solids* 105, 105254 10.1016/j.euromechsol.2024.105254

Data and code on

Doi: 10.5281/zenodo.10451584

