



A 3-scale computational homogenisation strategy for sheet moulded compounds using material network surrogates

5th International Conference on Computational Methods for Multi-scale, Multi-uncertainty and Multi-physics Problems
CM3P 2025
July 1-4, 2025, Porto, Portugal

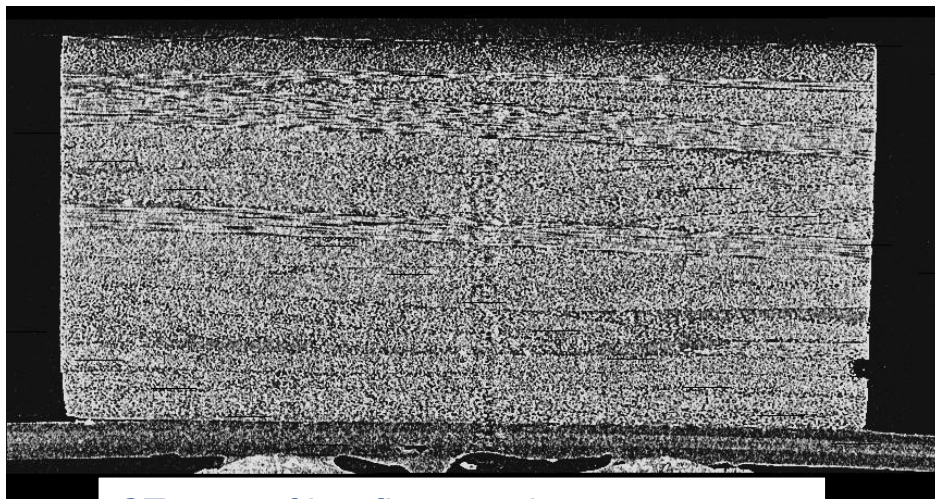
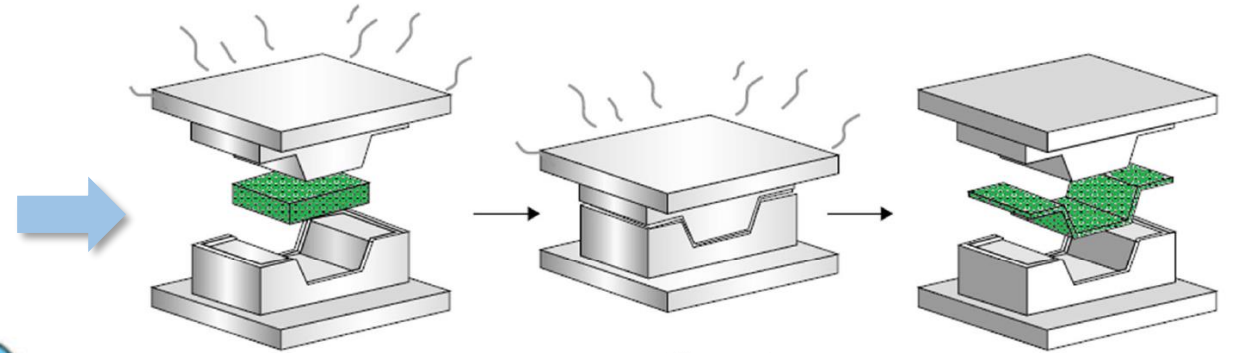
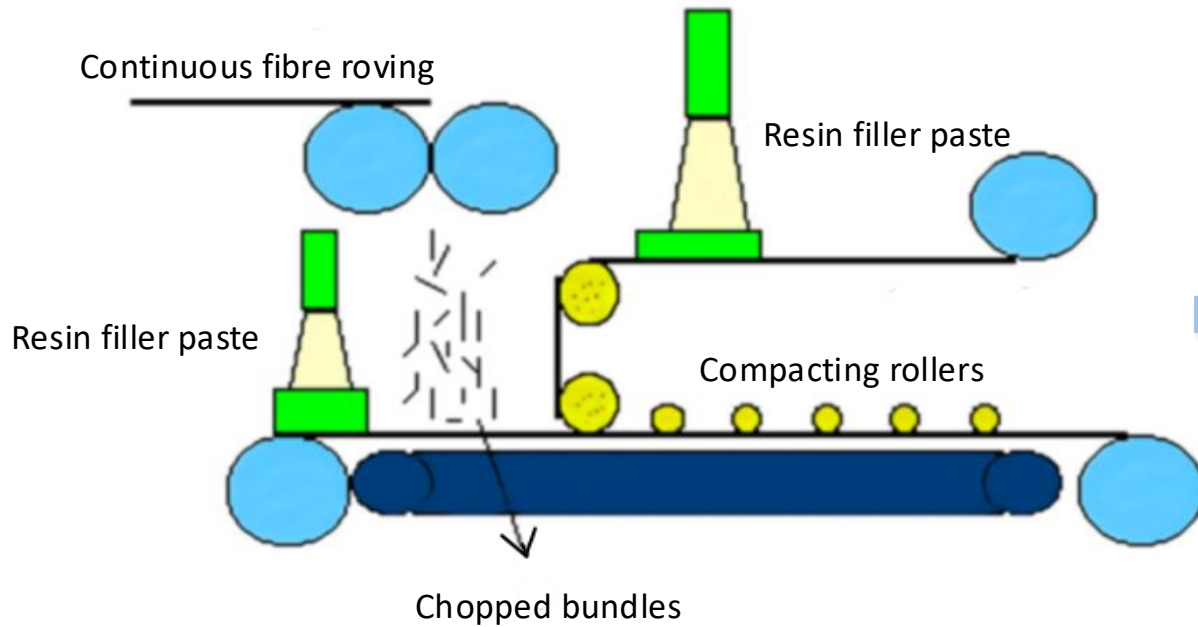
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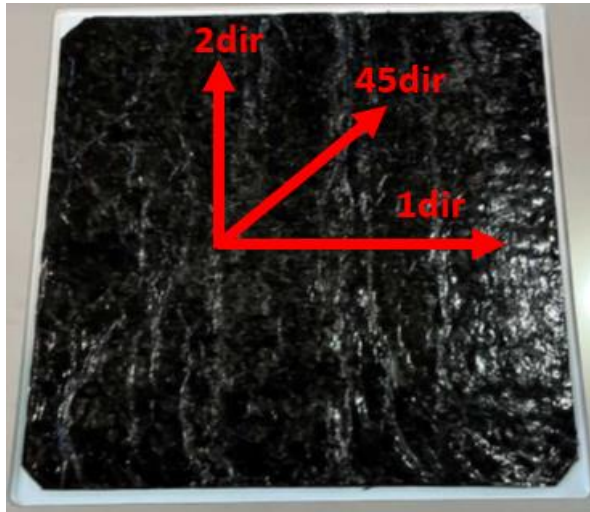
Sheet Moulding Compound (SMC)



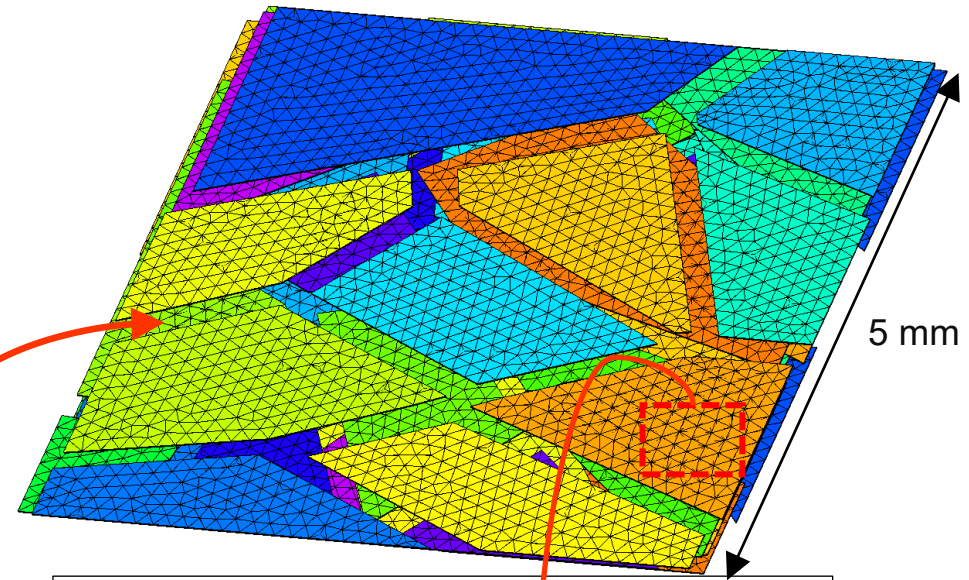
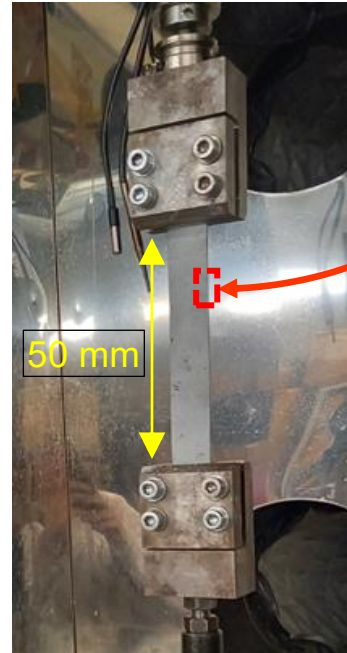
CT-scan of low flow specimen [Zulueta 2024]

- Mitsubishi STR120N131 SMC - Vinyl ester carbon fibre 58-42% by vol. [Fidler 2024]
- Process dependant microstructure
- Low flow – random (only) in-plane orientation of fibre bundles

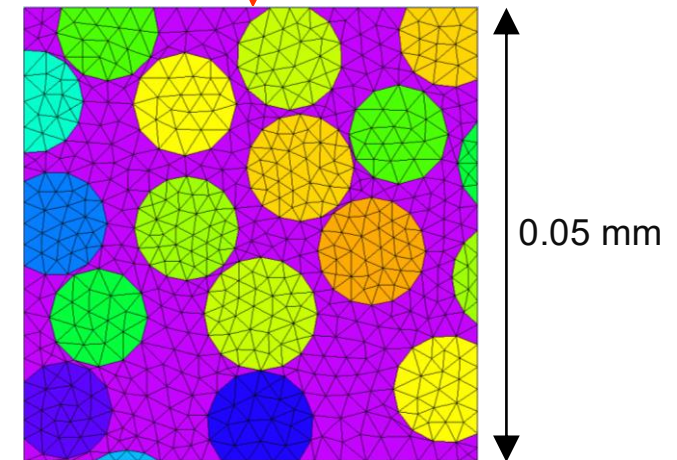
3 scale thermomechanical FE³ strategy for SMC



ISO 527 Sample – Flow aligned



Mesoscale RVE – Oriented Bundles in matrix

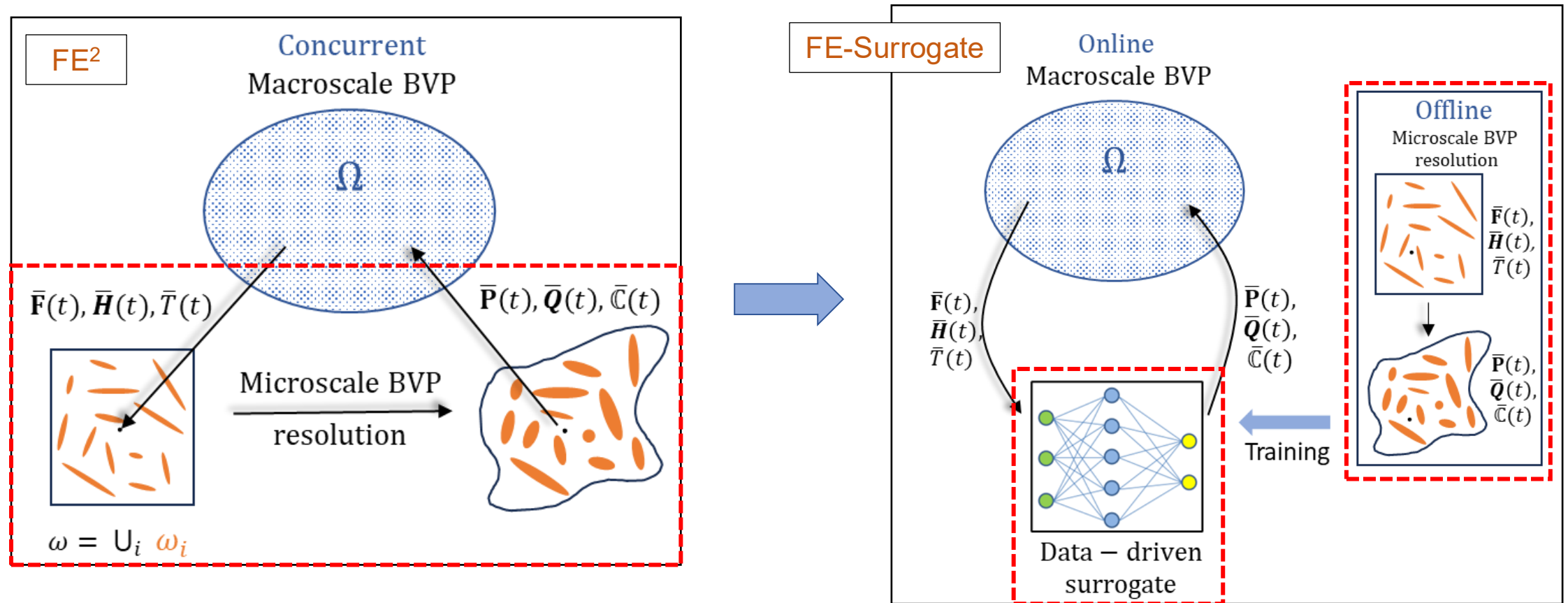


Microscale RVE – Unidirectional fibres in matrix
- 62.1% VF fibre (12 μm diameter)

Objectives

- Fast thermomechanical homogenisation using data-driven surrogates
- Extension of mesoscale surrogacy for local orientations

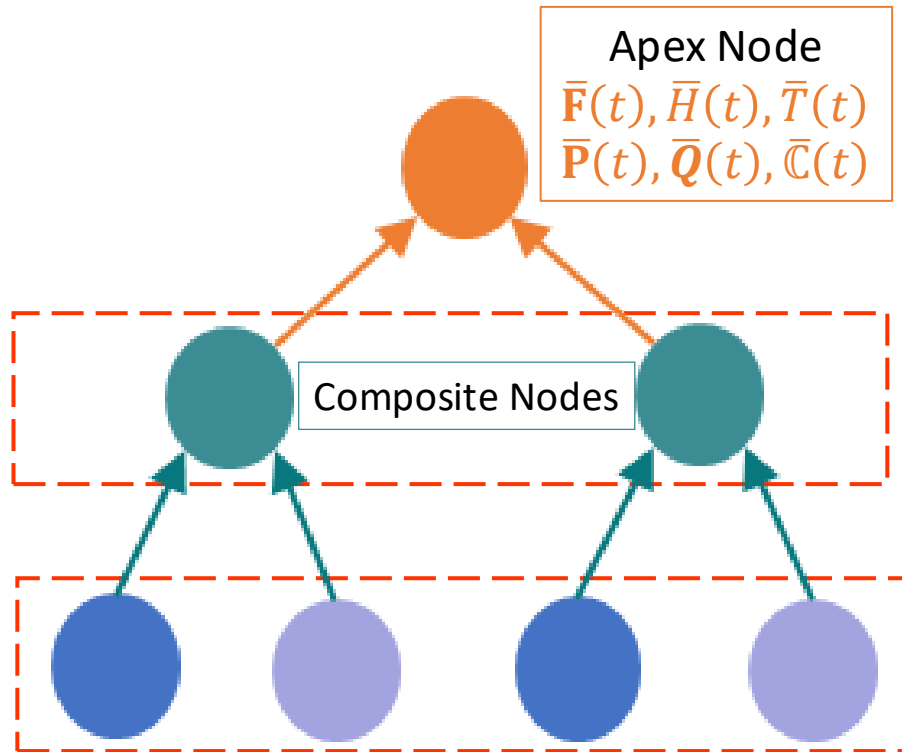
Data-driven analysis for a 2-scale thermomechanical problem



- FE computationally expensive for complex RVEs
- Replace lower scale BVP with data-driven surrogate. E.g. Deep Neural Networks (DNN), Reduced Order Models (ROM)
- DNNs cannot extrapolate, ROMs only for specific cases

Higher scale variables
 $\bar{\mathbf{F}}$ - deformation gradient
 $\bar{\mathbf{H}}$ - temperature gradient
 \bar{T} - temperature
 $\bar{\mathbf{P}}$ - 1st PK stress
 $\bar{\mathbf{Q}}$ - heat flux
 $\bar{\mathbb{C}}$ - Constitutive matrix

Deep Material Network (DMN) [Liu 2019]



Material Nodes – **Fibre** & **matrix**

$$\left\{ \begin{array}{l} \mathbf{P}^i(\mathbf{F}^i(t), T^i(t), z(\tau \leq t)) \\ \mathbf{Q}^i(\mathbf{F}^i(t), \mathbf{H}^i(t), T^i(t), z(\tau \leq t)) \end{array} \right.$$

$(\cdot)^i$ - Lower scale variables
 z - Internal variables

How does it work?

- Simplest form – A perfect binary tree
- Phase constitutive laws at the **material nodes** - $\mathbb{C}_i^{l=0}$
- At the k^{th} **composite node** – Recursive calls to lower nodes

$$\mathbb{C}_k^{l=j} = \text{DMN}(\mathbb{C}_i^{l=j-1}, \Lambda^3)$$

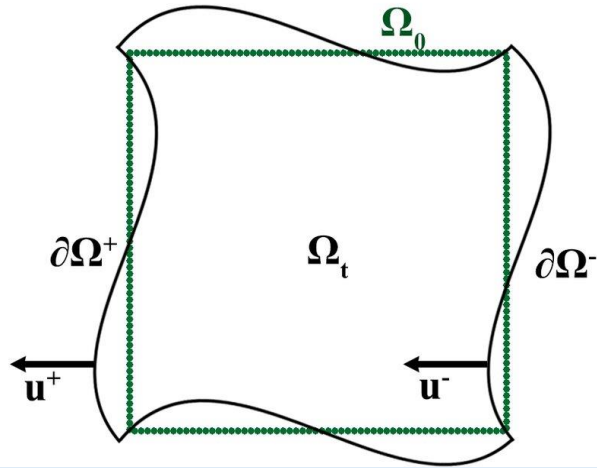
where Λ^3 is the set of trainable parameters

- Homogenised response at the **apex node**

Thermodynamically consistent and extrapolative!

[Liu 2019, Nguyen 2022]

Lower scale BVP



Main Elements of the 2-scale thermomechanical problem

- 1st order expansion of \mathcal{F} in $x_\mu \in \bar{\Omega}$, for $\mathcal{F} = [\mathbf{F}, \mathbf{H}^T]^T$

$$\mathcal{F}_\mu(x_\mu) = \bar{\mathcal{F}} + \nabla \odot \alpha'(x_\mu)$$

where α' is the microstructure incompatibility

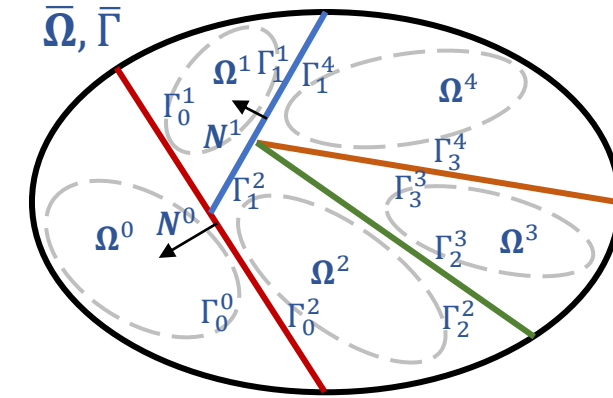
Note: $T_\mu(x_\mu) = \bar{T}$ in 1st order homogenisation

- The Hill-Mandel condition with $\mathcal{P} = [\mathbf{P}, \mathbf{Q}^T]^T$

$$\bar{\mathcal{P}} \cdot \delta \bar{\mathcal{F}} = \frac{1}{\bar{V}} \int_{\bar{V}} \mathcal{P}_\mu \cdot \delta \mathcal{F}_\mu d\bar{V}$$



Material Network



Translated to interfacial interpretation [Wu 2025]

- Fluctuations across $K = 0, 1, \dots, k$ interfaces with $i = 0, 1, \dots, P$ phases

$$\mathcal{F}_i = \bar{\mathcal{F}} + \frac{1}{V_i} \sum_{\forall \Gamma_k^i \neq \emptyset} s_{i,k} N_k \odot \alpha'$$

where $s_{i,k}$ is the surface coefficient, N_k is the normal to the interface and α' is the 4-dimensional DOF

- Weak form of the Hill-Mandel condition

$$\left[\sum_k \left(\sum_i v_i \mathcal{P}_i s_{i,k} \right) \cdot N_k \right] \cdot \delta \alpha' = 0$$

DMN for a 2-scale problem with 2 phases

- For 2 solid phases **A** and **B** in local frames, $s_{A,B} = -s_{B,A}$ akin to laminate theory [Liu 2019], the strains:

$$\mathcal{F}_A = \bar{\mathcal{F}} + \frac{1}{v_A} N_A \odot \hat{\alpha} \quad \vdots \quad \mathcal{F}_B = \bar{\mathcal{F}} - \frac{1}{v_B} N_A \odot \hat{\alpha}$$

where $\hat{\alpha} = \frac{s_{A,B}}{\bar{V}} \alpha'$.

- Solution to incompatibility DOF from weak form of Hill-Mandel
– solve with Newton-Raphson

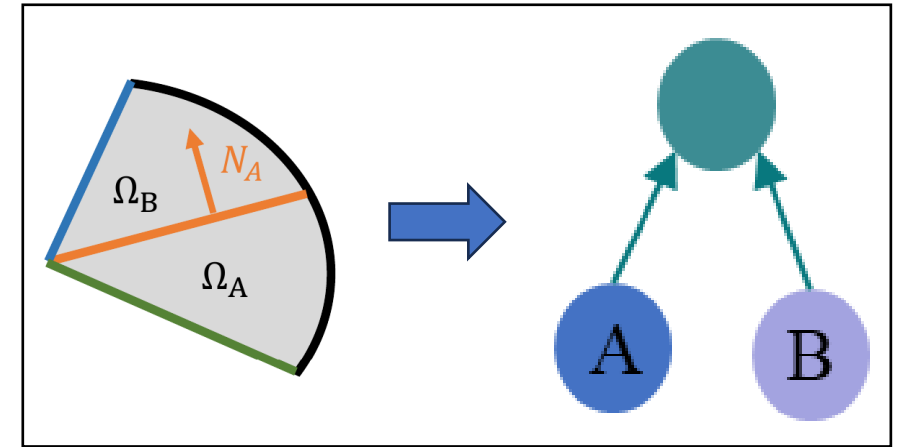
$$\Delta \hat{\alpha} = (\mathbb{K}^{-1} \mathbb{F}) \cdot \Delta \bar{\mathcal{F}} + (\mathbb{K}^{-1} \mathbb{T}) \Delta \bar{T}$$

- Homogenised tangent operators

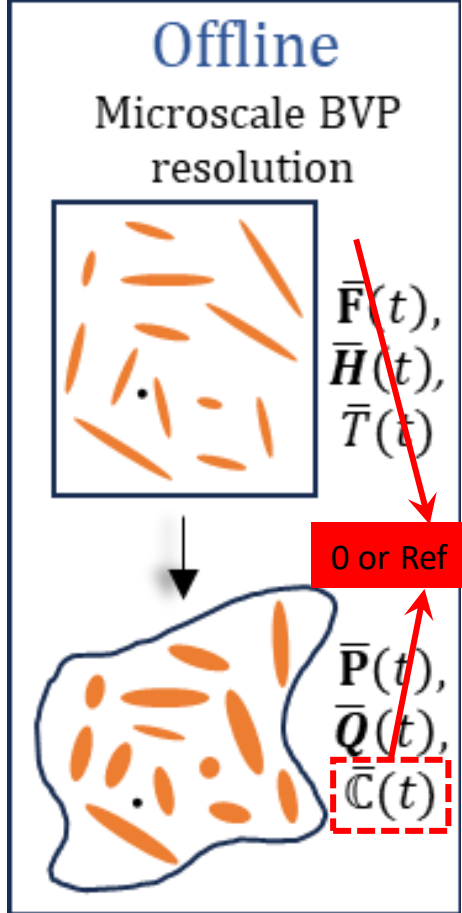
$$\partial \bar{\mathcal{P}} = \mathcal{L}(\mathbb{C}_A, \mathbb{C}_B, \mathbb{K}^{-1} \mathbb{F}) \cdot \partial \bar{\mathcal{F}} + \mathcal{L}_T(\mathbb{C}_A, \mathbb{C}_B, \mathbb{K}^{-1} \mathbb{T}) \partial \bar{T}$$

The matrices \mathbb{K} , \mathbb{F} and \mathbb{T} are functions $\mathbb{C}_A, \mathbb{C}_B$, v_A and N_A (Note: $v_B = 1 - v_A$ and N_A , the 3D normal, requires 2 angles)

∴ Trainable Topological Parameters are $\Lambda^3 = \{v_A, N_A(\theta_A, \phi_A)\}$



DMN training protocol



Linear Elastic Training for a given RVE at 0 strains

- Generate 'n' homogenised tangents (train + test) for random material parameters of 2 phases using **DNS** [Nguyen 2017]

$$\bar{\mathbb{C}}_{s=0,\dots,N}^{\text{DNS}} = \text{DNS}(\mathbb{C}_{s=0,\dots,N}^{i=0,1})$$

- Material tensor evaluation at the **apex node** ($l = 0$) for 2 phases

$$\bar{\mathbb{C}}_{s=0,\dots,N}^{\text{DMN}} = \text{DMN}(l = 0, \mathbb{C}_{s=0,\dots,N}^{i=0,1}; \Lambda^3)$$

- Identify topological parameters from minimisation of loss function, knowing total phase volume fractions ($v_{i=0,1}$) – uses gradient descent from PyTorch

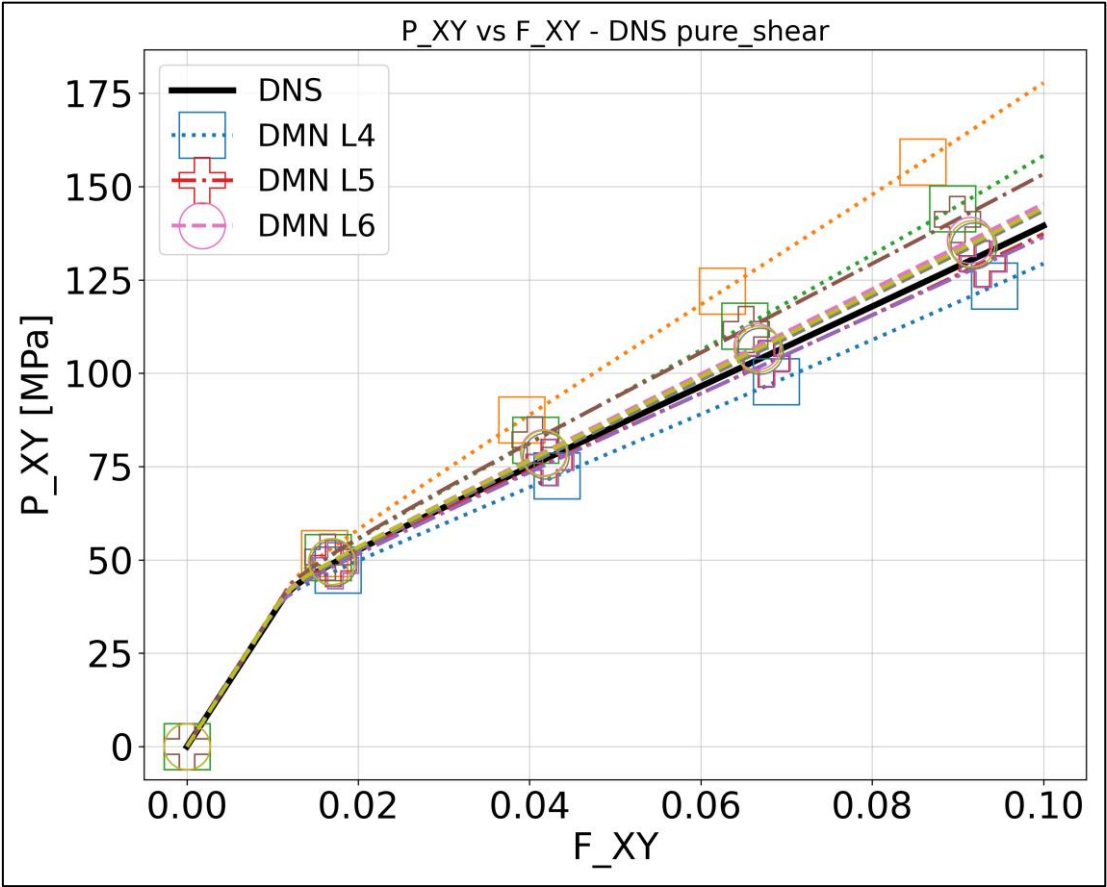
$$\text{Loss}(\bar{\mathbb{C}}^{\text{DNS}}, \bar{\mathbb{C}}^{\text{DMN}}) = \frac{1}{n} \sum_n \frac{\|\bar{\mathbb{C}}^{\text{DNS}} - \bar{\mathbb{C}}_s^{\text{DMN}}(\dots; \Lambda^3)\|}{\|\bar{\mathbb{C}}^{\text{DNS}}\|}$$

Homogenised stacked tangent with relative scaling ($\lambda_1, \lambda_2, \lambda_3$)

$$\bar{\mathbb{C}} \equiv \begin{bmatrix} \frac{\partial \bar{\mathbf{P}}}{\partial \bar{\mathbf{F}}} & \frac{\partial \bar{\mathbf{P}}}{\partial \bar{\mathbf{H}}} & \lambda_1 \frac{\partial \bar{\mathbf{P}}}{\partial \bar{\mathbf{T}}} \\ \frac{\partial \bar{\mathbf{Q}}}{\partial \bar{\mathbf{F}}} & \frac{\partial \bar{\mathbf{Q}}}{\partial \bar{\mathbf{H}}} & \lambda_3 \frac{\partial \bar{\mathbf{Q}}}{\partial \bar{\mathbf{T}}} \end{bmatrix}$$

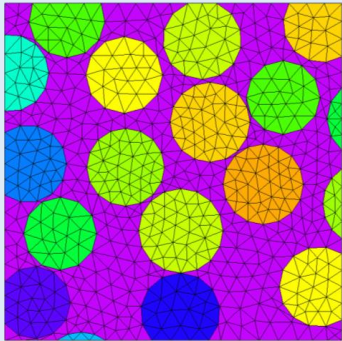
Note: All terms in matrix form.

2 phase microscale DMN surrogate vs DNS 1

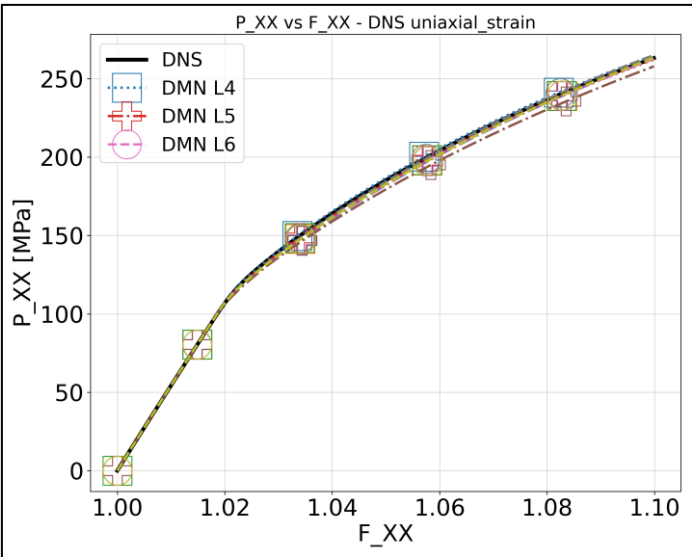
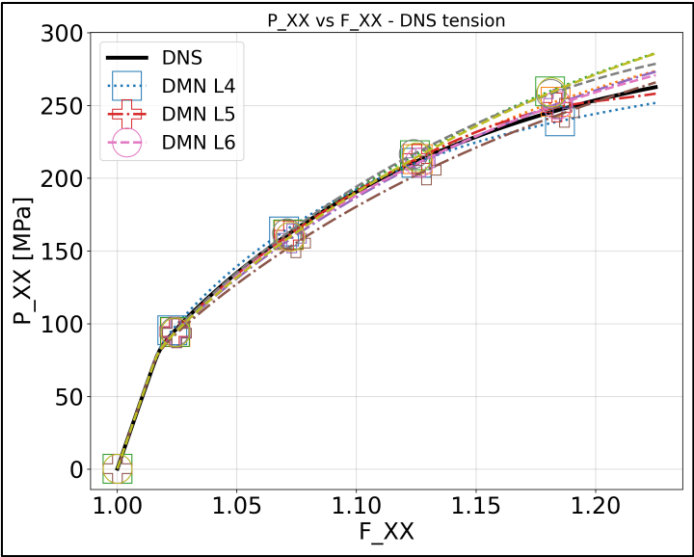


DNS on elastic fibre and J2 elasto-plastic resin UD composite RVE with PBC [Nguyen 2017] vs. Linear elastically trained **DMN** (same strain-path)

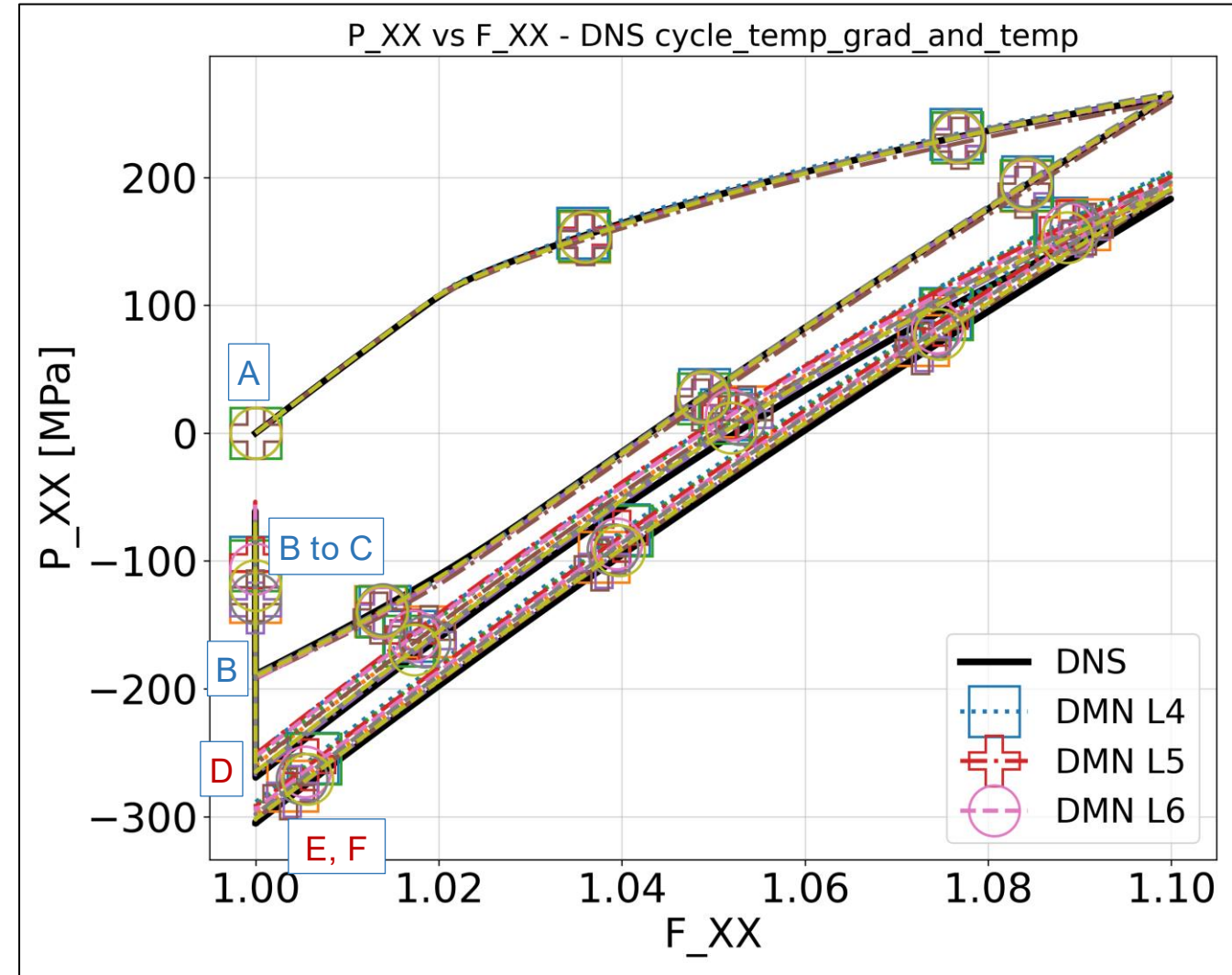
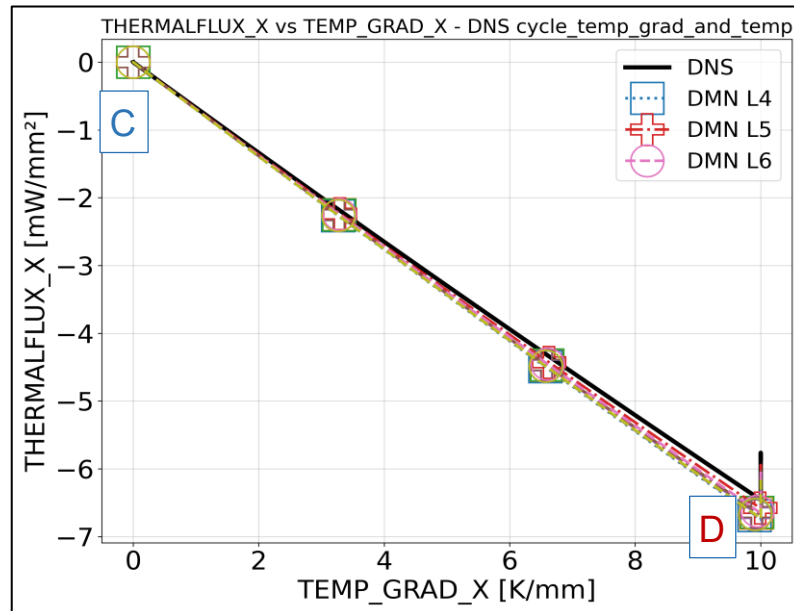
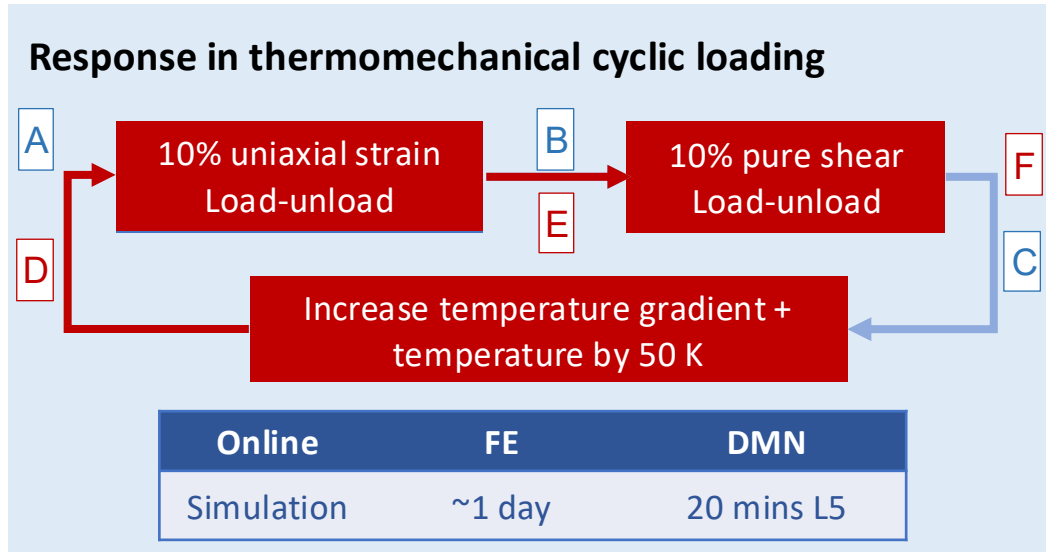
Offline Stage		
Data generation	30 mins/25 samples	
DMN Training	5 hours/1000 epochs L5	
Online	FE	DMN
Simulation	6 hours ~ 10% strain	5 mins L5



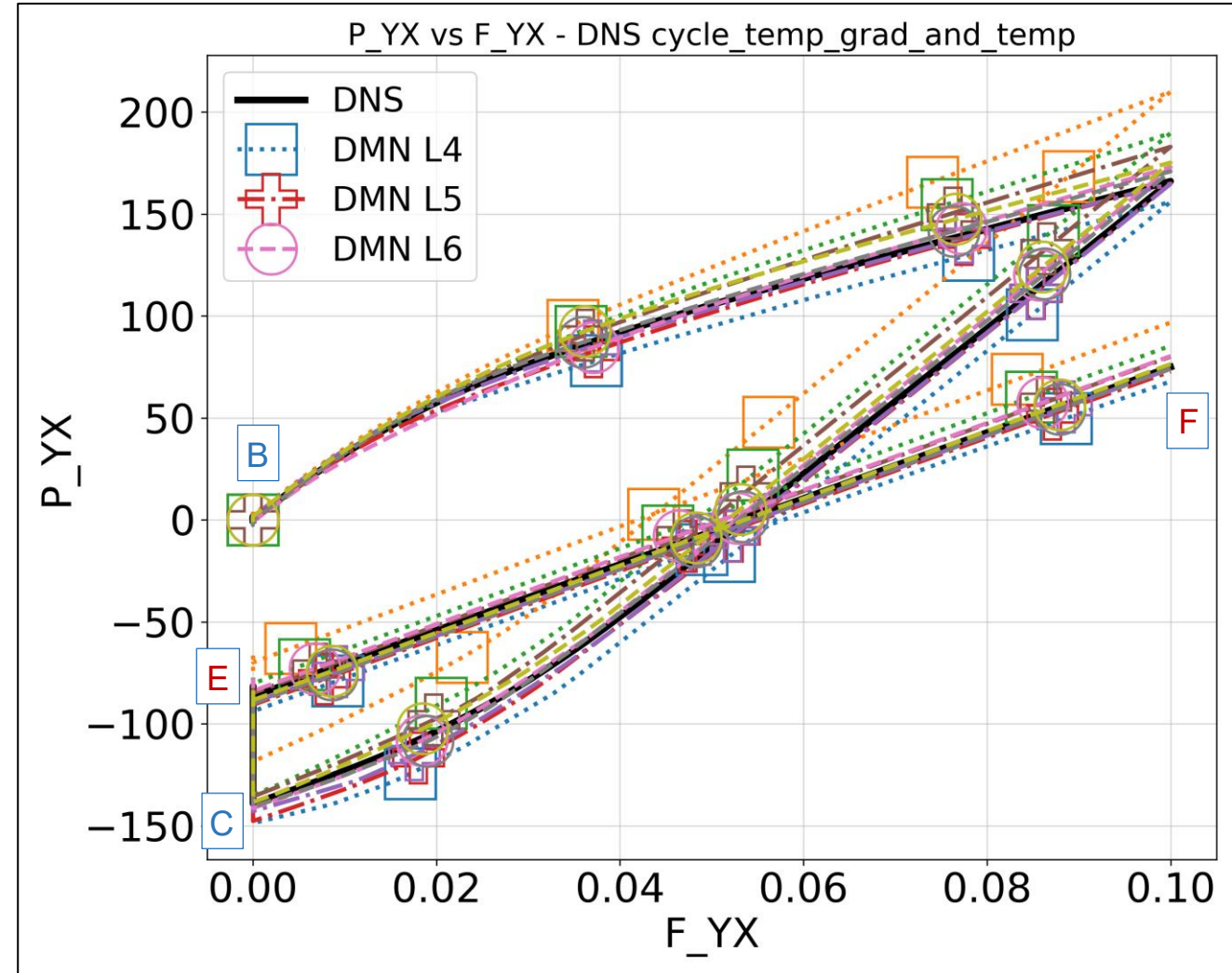
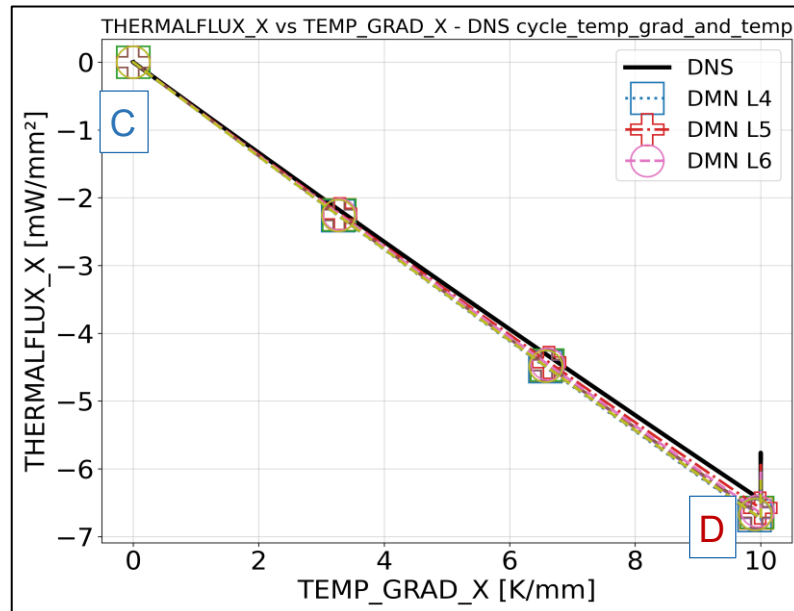
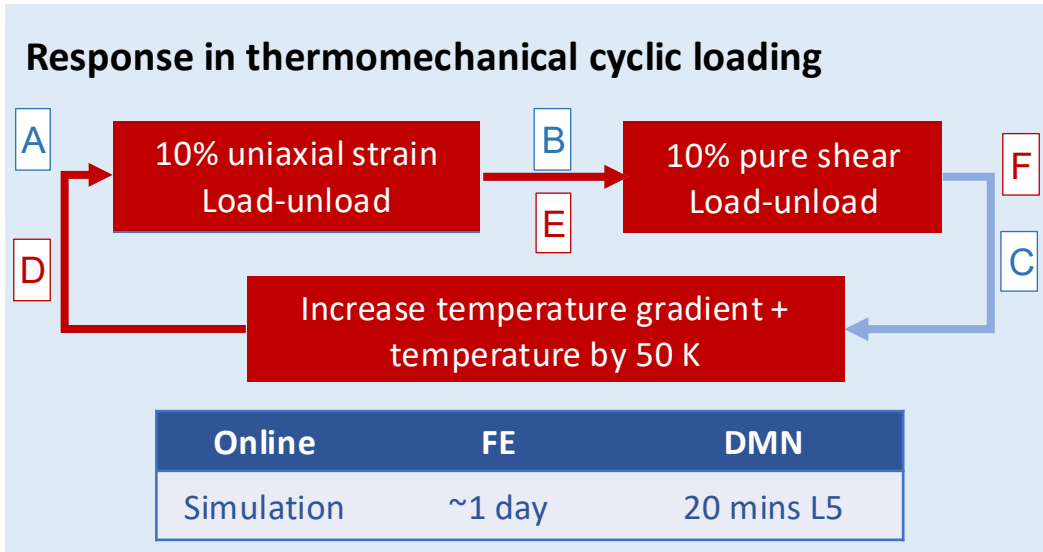
Note: Time per CPU



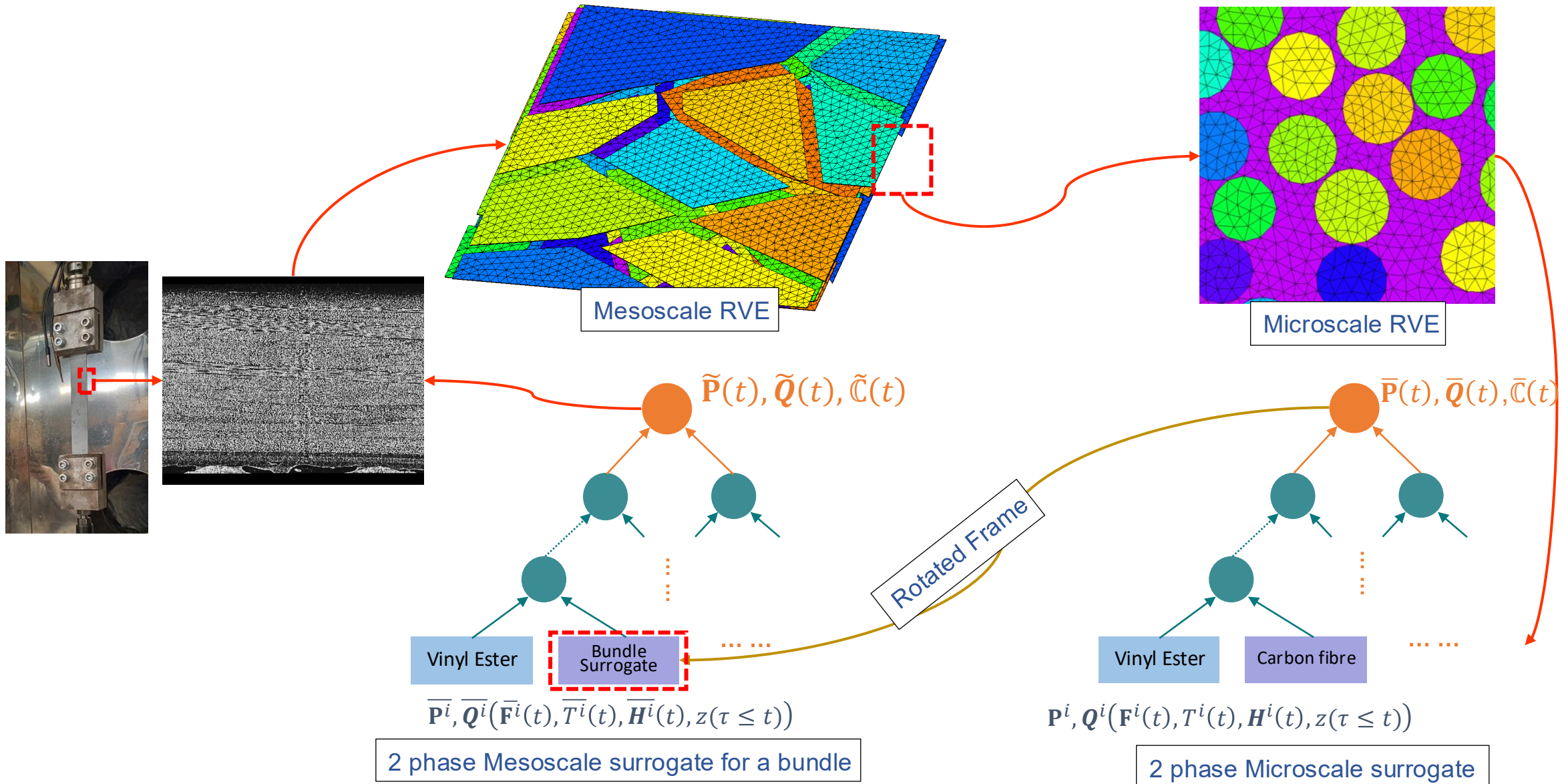
2 phase microscale DMN surrogate vs. DNS 2



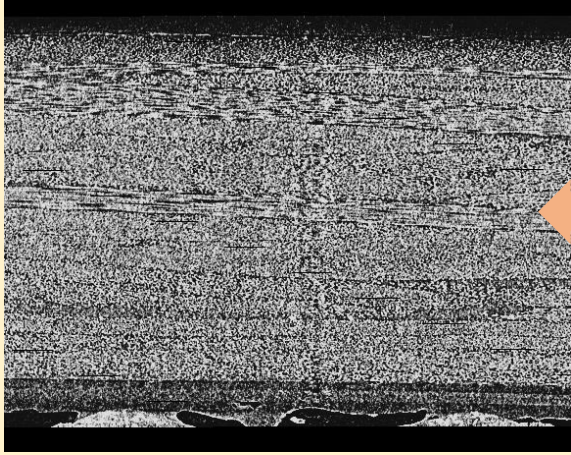
2 phase microscale DMN surrogate vs. DNS 2



3 scale SMC problem with DMN surrogates

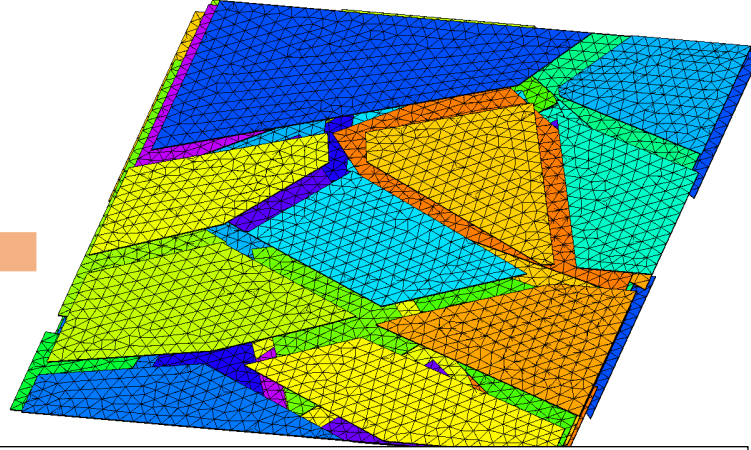


2-phase DMN with a locally oriented phase (under development)

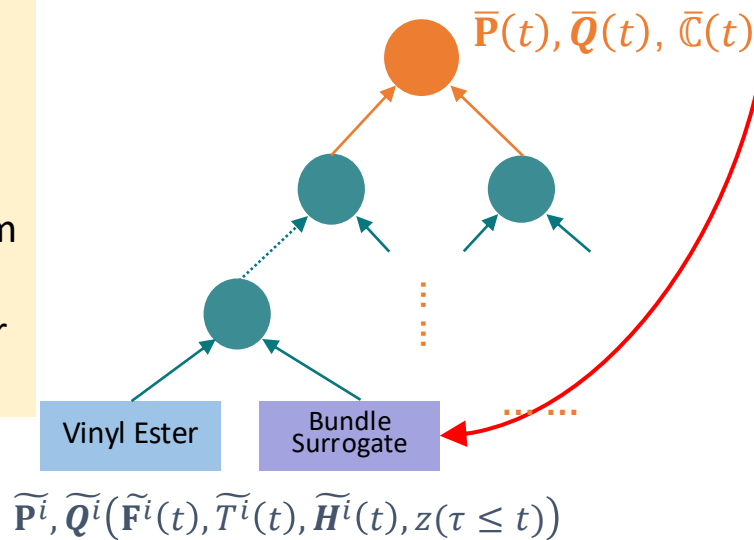


$$\mathbf{A} = \begin{bmatrix} 0.55 & 0 & 0 \\ 0 & 0.45 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Orientation vectors sampled from reconstructed ODF [Zulueta 2024] from 2nd order orientation tensor [Mohamedou 2019]



Each bundle has an orientation vector \vec{e}_r



Modified Training Protocol

- Random train + test data with RVE orientations on micro-DMN using **DNS**

$$\tilde{\mathbb{C}}_{S=0,\dots,N}^{\text{DNS}} = \text{DNS} \left(\mathbb{C}_S^0, \mathcal{R}(\bar{\mathbb{C}}_S^{1 \approx \text{DMN}}) \right)$$

where $\mathcal{R} = \mathcal{R}(\vec{e}_r)$ is a rotation operator

- DMN stiffness evaluation by capturing orientation as a microstructural feature

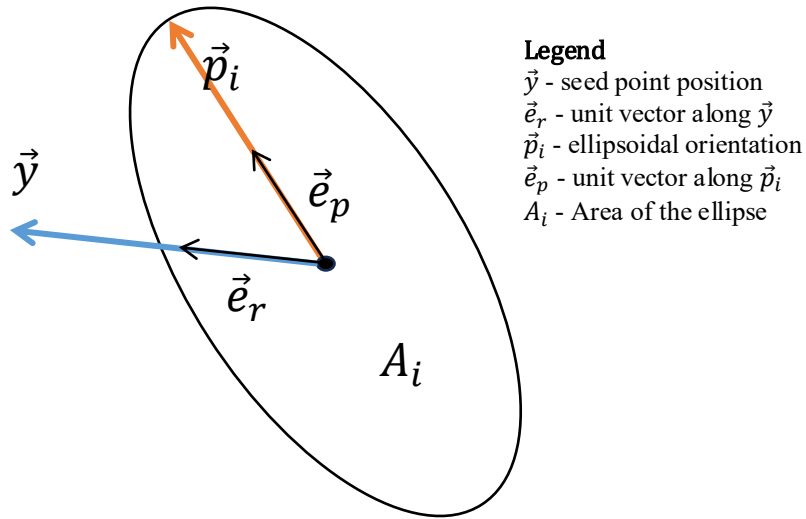
$$\tilde{\mathbb{C}}_{S=0,\dots,N}^{\text{DMN}} = \text{DMN}(\mathbb{C}_S^0, \bar{\mathbb{C}}_S^{1 \approx \text{DMN}}; \Lambda^6)$$

- Extended topological parameters Λ^6 with 3 Euler angles for each Bundle surrogate node

$$\therefore \Lambda^6 = \{v_A, N_A(\theta_A, \phi_A), \mathcal{R}(\alpha, \beta, \gamma)\}$$

where \mathcal{R} is a reduced set of \mathcal{R}

Mesoscale RVE using anisotropic Voronoi algorithm

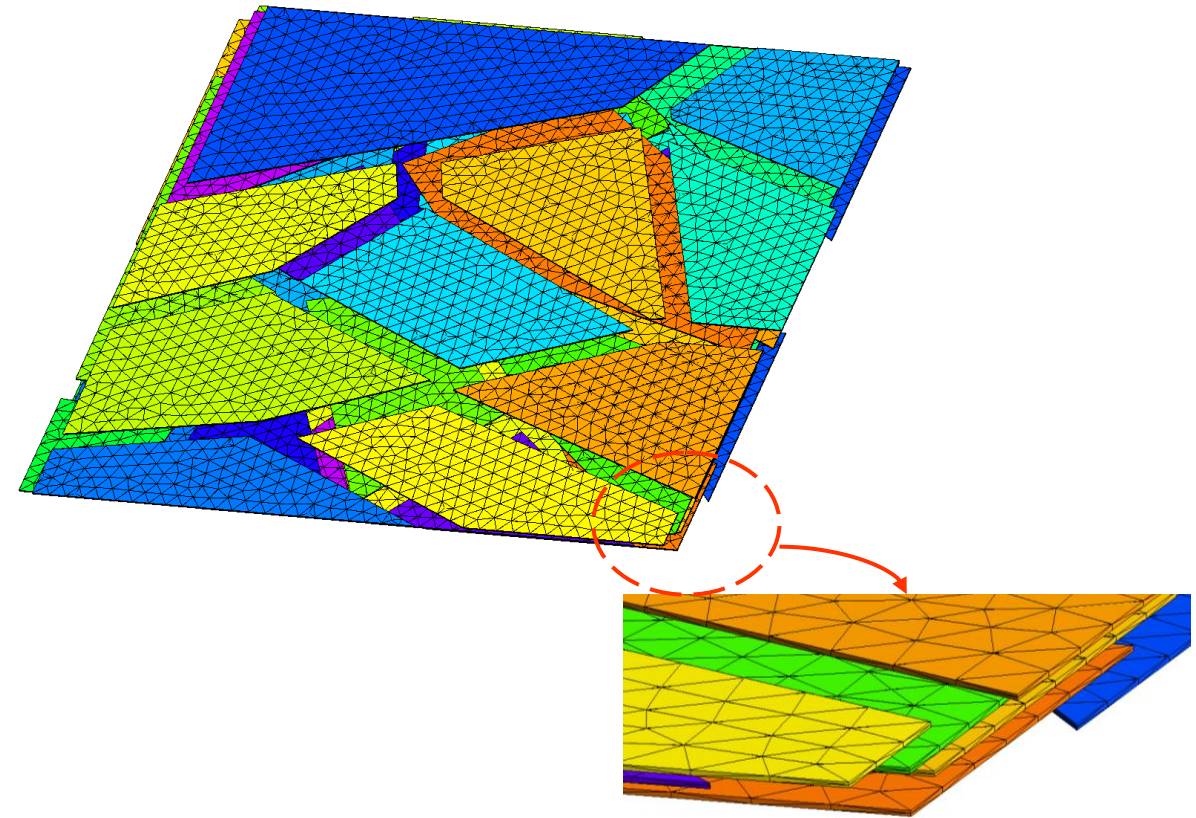


2D ellipsoidal field [Nuland 2021]

Ellipsoidal velocity field in 2D

$$v_i(\vec{y}) = \sqrt{\frac{A_i}{\pi \|\vec{p}_i\|}} \left[1 + \left(\frac{1}{\|\vec{p}_i\|^2} - 1 \right) (\vec{e}_p \cdot \vec{e}_r)^2 \right]^{-\frac{1}{2}}$$

- Boundaries based on growth times – radial distance
- Anisotropy from orientation and aspect ratio – Applied to SMC bundles



Anisotropic Voronoi Cells

- Random seeds using Poisson disk sampling
- Convex polygonisation using convex-hull algorithm
- Shrunk and stacked to create layered structure (resin fills the gaps – not shown)

Conclusions and Perspectives

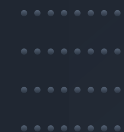
- Generalized Deep Material Network methodology for thermomechanical coupling – Shown to work!
- Extension to DMNs with local phase orientations – New training protocol!
- Incorporation of viscous and dissipative effects
- Incorporation of non-local damage at the micro level with thermal effects

References

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Thank you for your attention!

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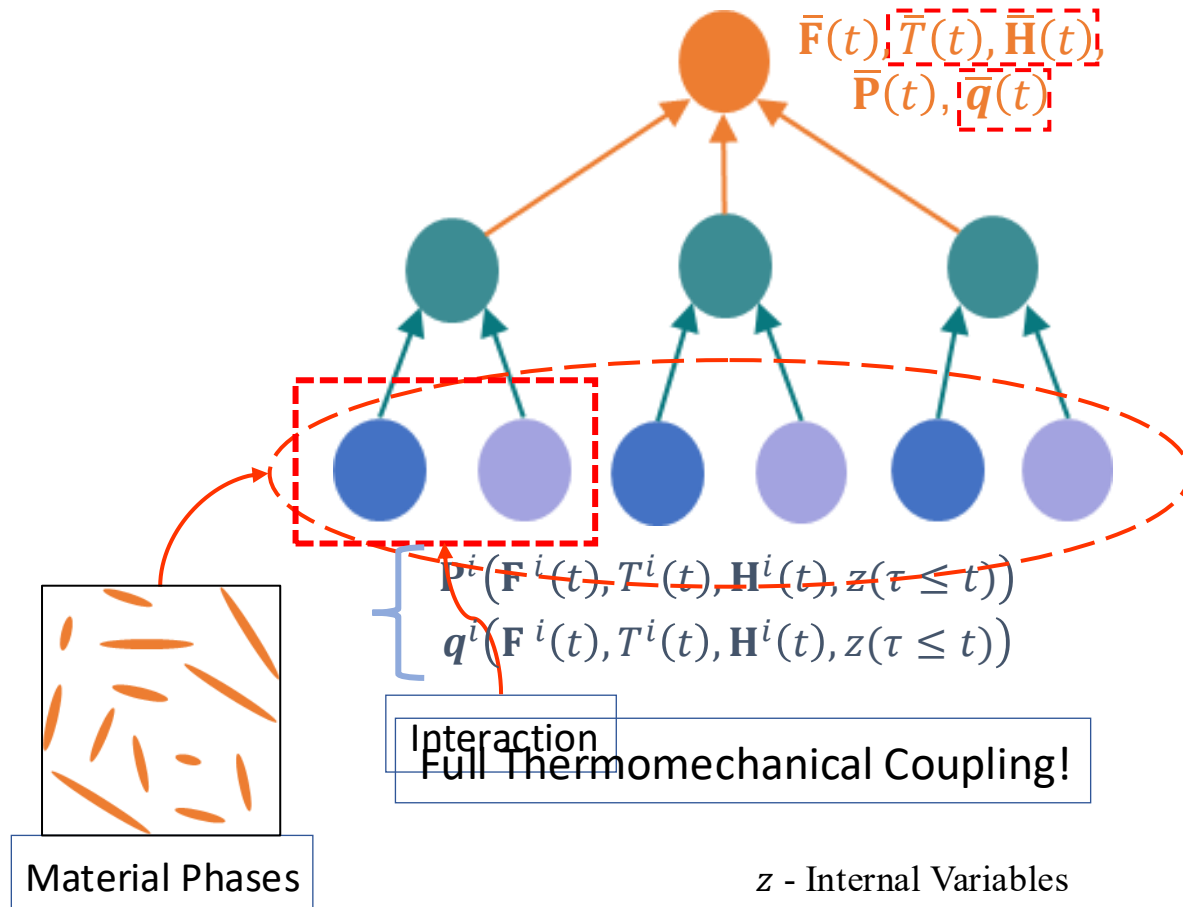
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Appendix - Deep Material Network (DMN)

Deep Material Network (DMN)



State of the art

- [Liu 2019] Isothermal finite-strain
- [Gajek 2021-22] Thermomechanical small-strain, isothermal application to real structure
- [Nguyen 2021-22] Interaction based, Isothermal finite-strain (developed in CM3)
- [Wu 2025] Stoichiometric, Interface interpretation, Isothermal small-strain (developed in CM3)

Lack of finite-strain thermomechanical DMN surrogate modelling!

Appendix - Interface-based Interpretation of DMN

- Link homogenised combined gradient to nodes
 - $\mathcal{F} = [F, H^T]^T$ in the mapping
- $\bar{\mathcal{F}} + \sum_{k=0}^{M-1} \alpha^{i,k} \mathbf{a}^k \otimes \mathbf{N}^k = \mathcal{F}^i, \quad i = 0 \dots 9$
- $\bar{T} = T^i$ limitation of 1st order homogenisation
- Weak form of Thermomechanical Hill-Mandel Condition

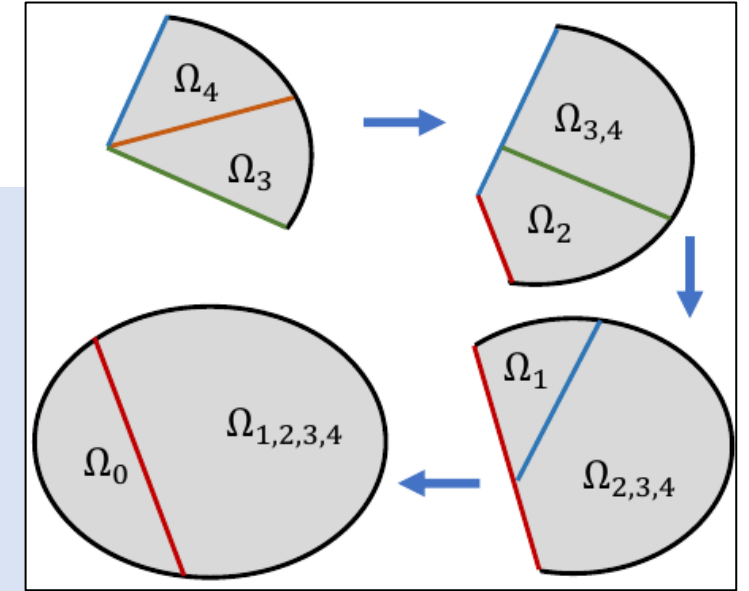
- $\mathcal{P} = [P \ q^T]^T$

$$\bar{\mathcal{P}} : \delta \bar{\mathcal{F}} = \sum_i W^i \mathcal{P}^i : \delta \mathcal{F}^i \quad \Rightarrow \quad \left[\sum_k \left(\sum_i W^i \mathcal{P}^i \alpha^{i,k} \right) \cdot \mathbf{N}^k \right] \cdot \delta \mathbf{a}^k = 0$$

\Rightarrow Constitutive behaviours: $\mathcal{P}^p(t) = \mathcal{P}^p(\mathcal{F}^i(t), T(t); \mathbf{Z}(\tau \leq t))$
 if node $i \in$ phase p for material $p=0$ or $p=1$

- Homogenized dependant set from volumetric averaging

$$\bar{\mathcal{P}} = \sum_i W^i \mathcal{P}^i$$



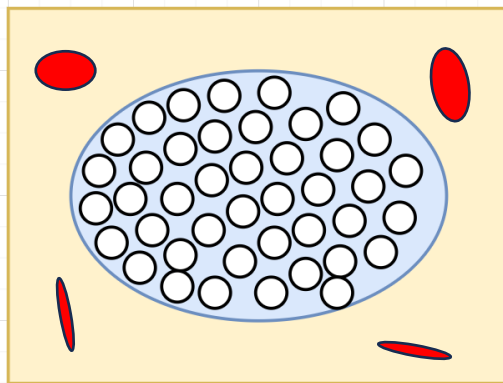
Network of 2-phase interfaces [Wu 2025]

Appendix - DMN Training

Thermomechanical homogenisation of composite systems

- **Offline training**
 - > TVE - Random generation of \mathbb{C}
 - > TVP - Random generation of stress vs. strain loading paths
- Fitting parameters as Microstructural descriptors
- Training to minimise a loss function using gradient descent (PyTorch)

RVE

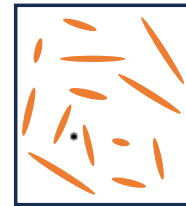


Bundle Microstructure

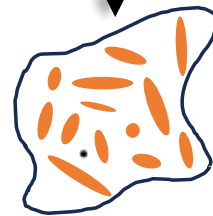


Offline

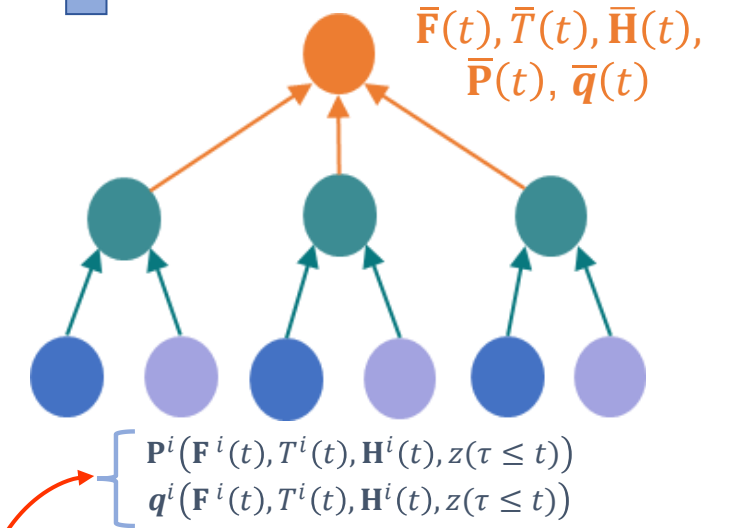
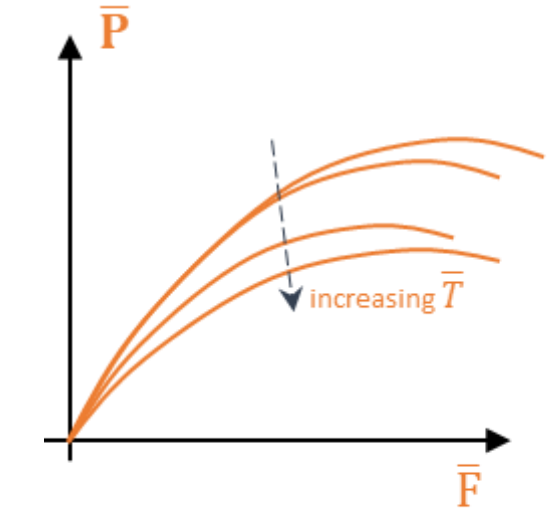
Microscale BVP
resolution



$\bar{\mathbf{F}}(t),$
 $\bar{T}(t),$
 $\bar{\mathbf{H}}(t)$

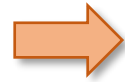
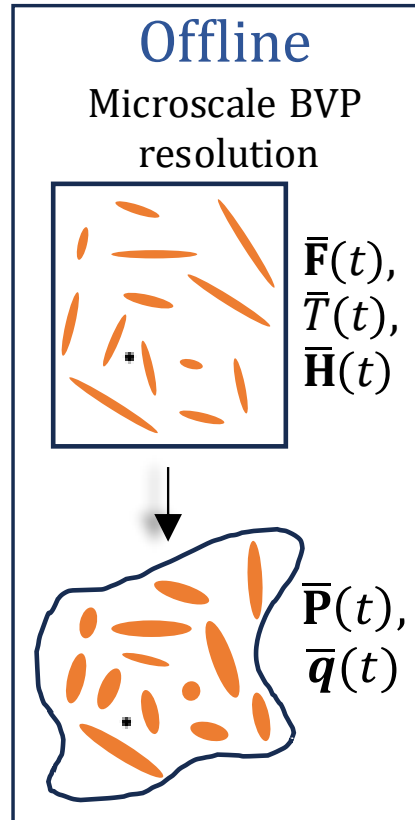


$\bar{\mathbf{P}}(t),$
 $\bar{\mathbf{q}}(t)$



Constitutive Material Laws

Appendix - Thermomechanical Tangents in DMN



Offline Data

- Constitutive behaviour for the combined “stress” at initialisation:

$$\Delta \mathcal{P} = \Delta \mathcal{P}(\Delta \mathcal{F}, \Delta T)$$

- Homogenised stacked tangent (with relative scaling) for training:

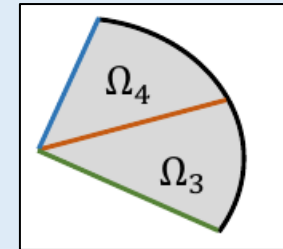
$$\left[\frac{\partial \bar{\mathcal{P}}}{\partial \bar{\mathcal{F}}}, \frac{\partial \bar{\mathcal{P}}}{\partial T} \right] \equiv \begin{bmatrix} \frac{\partial \bar{\mathcal{P}}}{\partial \bar{\mathcal{F}}} & \frac{\partial \bar{\mathcal{P}}}{\partial \bar{H}} & \frac{\partial \bar{\mathcal{P}}}{\partial \bar{T}} \\ \frac{\partial \bar{q}}{\partial \bar{\mathcal{F}}} & \frac{\partial \bar{q}}{\partial \bar{H}} & \frac{\partial \bar{q}}{\partial \bar{T}} \end{bmatrix}$$

- To train the DMN parameters:

$\alpha^{i,k}$ - interface coefficients

\mathbf{N}^k - interface normal

W^i - weights \sim volume fractions

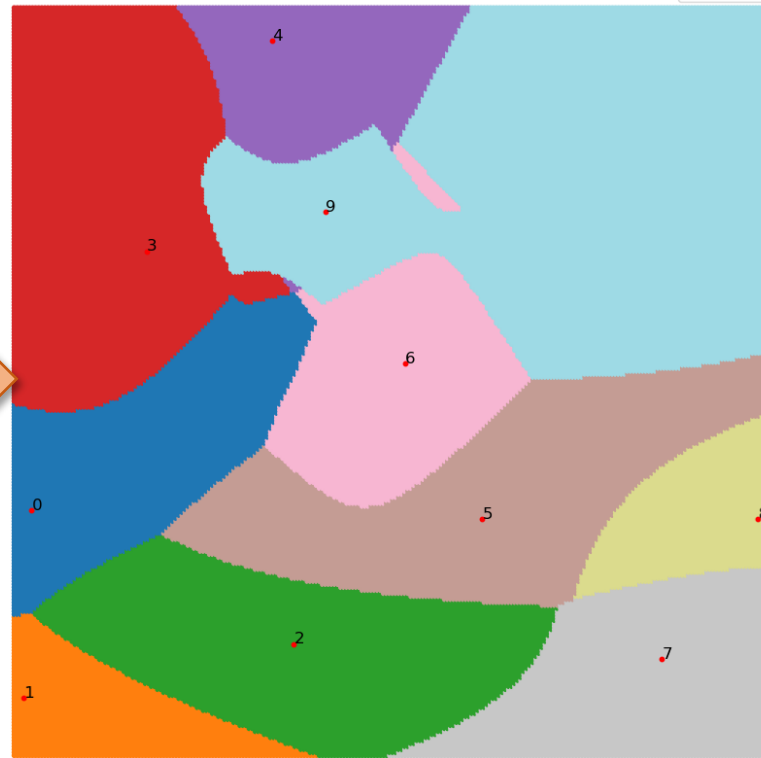


Appendix - Anisotropic Voronoi algorithm 1

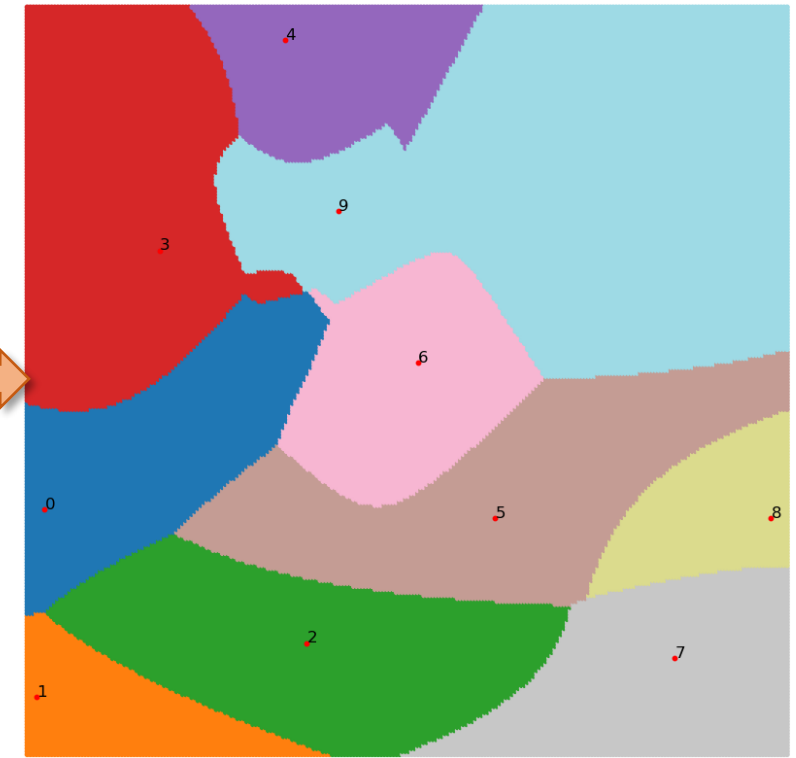
- Robust Methodology for Domain Refinement



Initial assignment using Ellipsoidal growth field causes islandification.



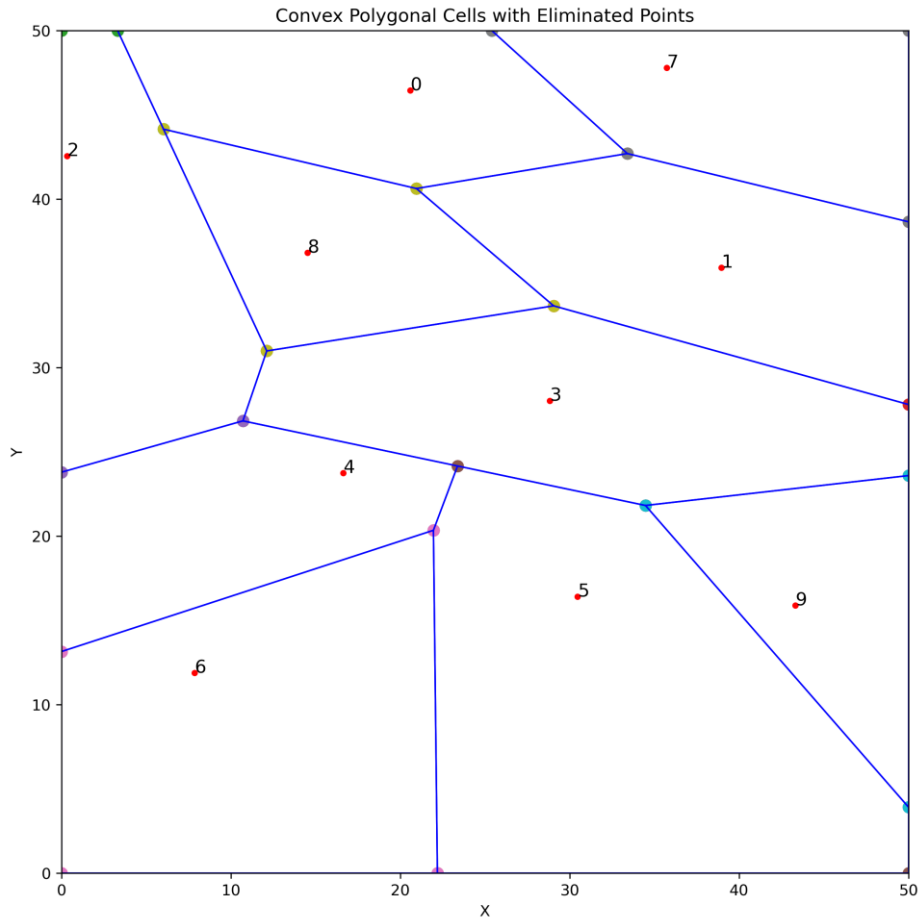
Reassignment 1 - Identify islands by KD Tree split-planes and reassign using distance from domain centre of mass.



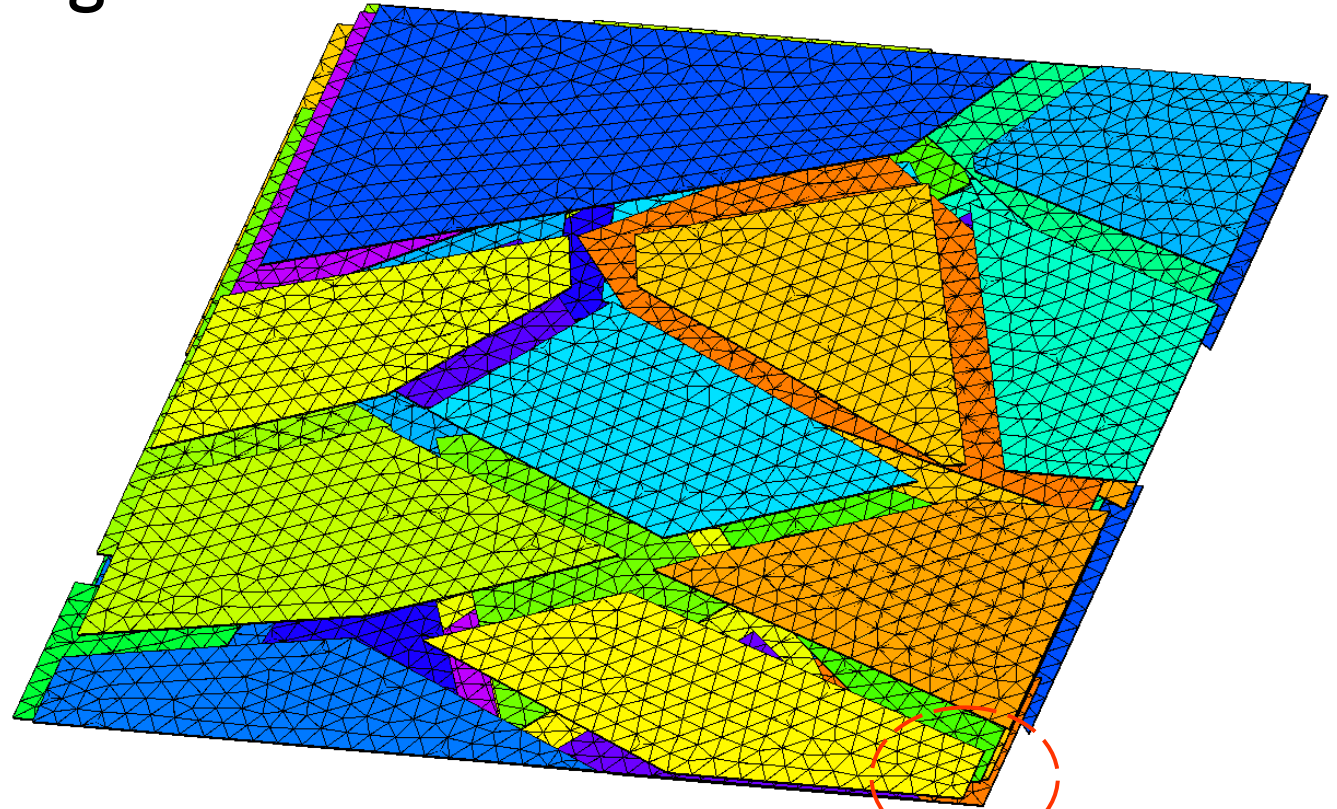
Reassignment 2 - Re-identify islands by KD and re-reassign to domain of the closest seed to parent.

Appendix - Anisotropic Voronoi Algorithm 2

- Polygonisation and layered stacking



Polygonisation - Find domain junctions and form polygons using Convex Hull algorithm.



Stack - extrude and shrink cells, stack layers, Boolean to form a negative space for polymer (not shown).

