

Controlling liquid landscape with 3D-printed spines: A tool for micromanipulation



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CONTEXT

GRAVITY wins over **SURFACE TENSION** and keeps the water level flat and horizontal, even when tilting the container

> Except in the few millimeters of a **CAPILLARY MENISCI**

. . .

SUPERPOSITION OF MENISC

• Liquid elevation around one meniscus: $z(r) = QK_0\left(\frac{r}{r}\right)$

With the constant integration, also called the capillary charge

 $Q = (R - h an lpha) \cos(heta + lpha)$

And λ , the capillary length, the distance over which surface tension overcomes gravity

Menisci can SUPERIMPOSE when the distance is smaller or around λ h_v



Let's challenge this!

$$z(x,y) = \sum_{k,\ell} Q_{k,\ell} K_0igg(rac{|ec{r}-ec{r}_{k,\ell}|}{\lambda}igg)$$



Liquid elevation inside **3D-printed arrays of spines** with varying lattice constant and symmetry



LIQUID SLOPES AND SLIDES

Let's swap the physics : Think about a desired interface and find the corresponding lattice









Model is valid when $a > 4(R - h \tan \alpha)$

MANIPULATION

This device serves as a great tool to transport floating particles into programmable paths !

- Heavy particles: fall down a meniscus (W > B)
- Light particles: rise up along a meniscus (B > W)

3-directional transport



Trajectory of an 800 µm bead:





ART

1 Found a nice image

2 Check our GitHub for the code that transforms your image into a specially engineered array of spines 3 3D-print the provided STL file 4 Deep it into water and enjoy!







PERSPECTIVES







Study the particular dynamics of object into our device

« Controlling liquid landscape with 3D-printed spines: A tool for micromanipulation », M.Delens, A.Franckart, and N. Vandewalle, In Review Preprint: https://doi.org/10.21203/rs.3.rs-3467162/v1

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International meeting in memory of Yves Couder: Self-Organization in physics and biology, morphogenesis, turbulence, walking droplets and non-linear physics Paris 4th-7th June 2024