

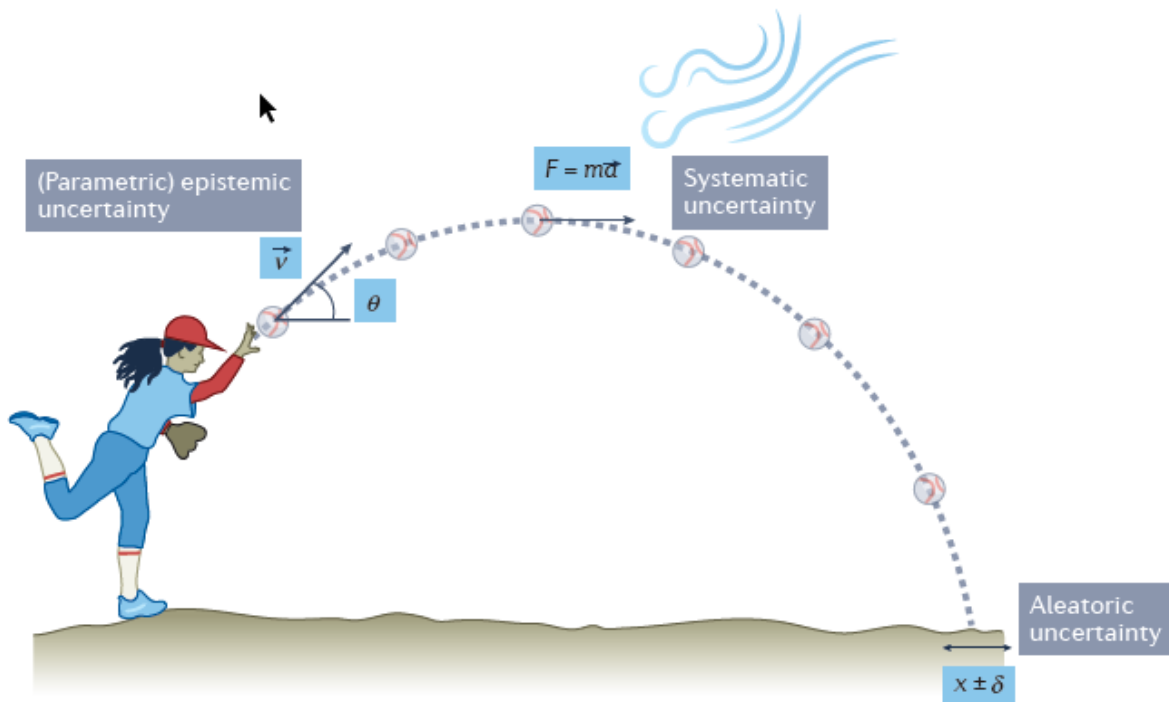
# Simulation-based inference for the physical sciences

Grenoble Artificial Intelligence for Physical Sciences

May 29, 2024

Gilles Louppe

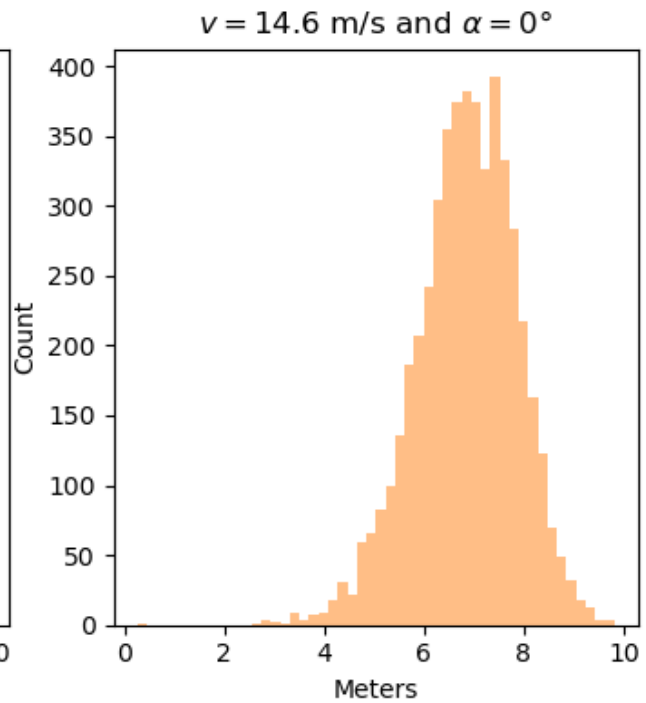
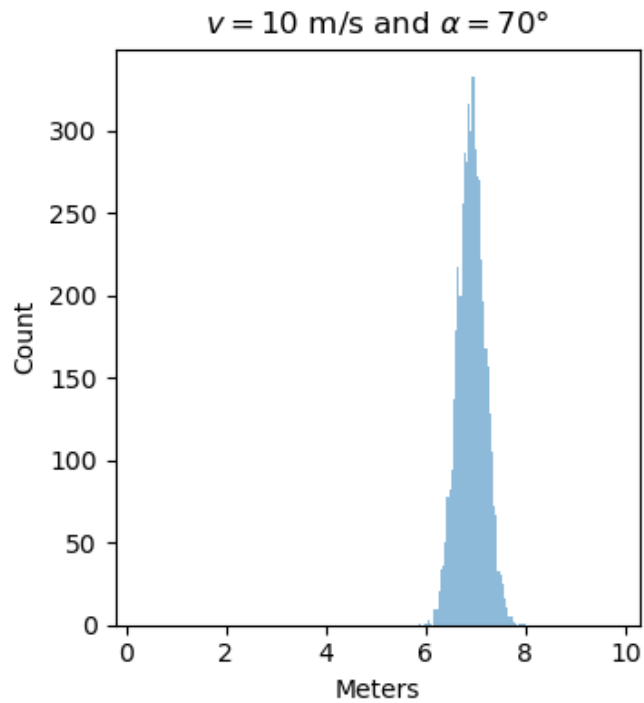
[g.louppe@uliege.be](mailto:g.louppe@uliege.be)



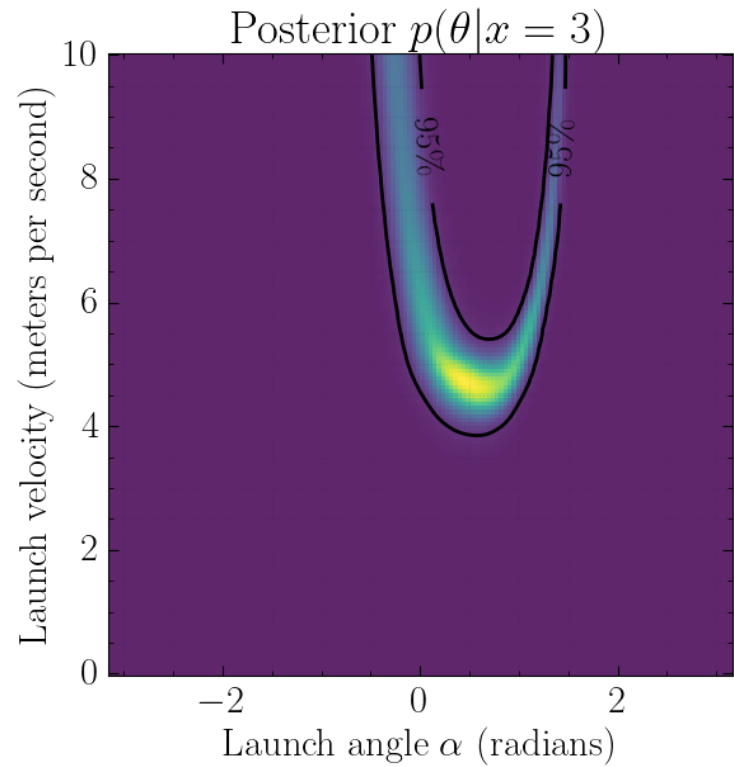
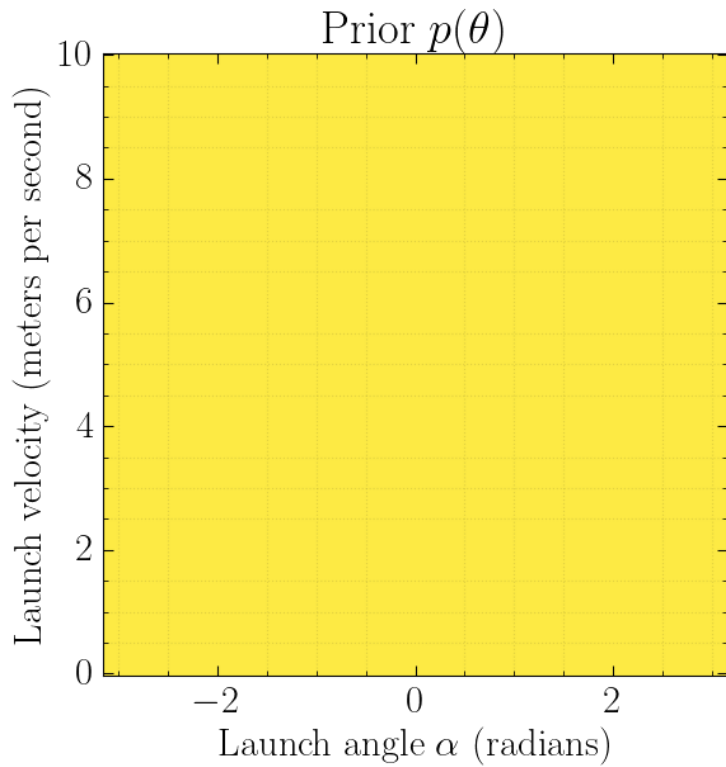
$$v_x = v \cos(\alpha), \quad v_y = v \sin(\alpha),$$

$$\frac{dx}{dt} = v_x, \quad \frac{dy}{dt} = v_y, \quad \frac{dv_y}{dt} = -G.$$

```
def simulate(v, alpha, dt=0.001):  
    v_x = v * np.cos(alpha) # x velocity m/s  
    v_y = v * np.sin(alpha) # y velocity m/s  
    y = 1.1 + 0.3 * random.normal()  
    x = 0.0  
  
    while y > 0: # simulate until ball hits floor  
        v_y += dt * -G # acceleration due to gravity  
        x += dt * v_x  
        y += dt * v_y  
  
    return x + 0.25 * random.normal()
```



What parameter values  $\theta$  are the most plausible?



# Simulation-based inference

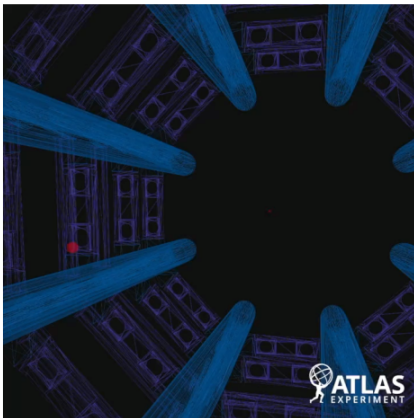


# Simulators as generative models

A simulator prescribes a generative model that can be used to simulate data  $\mathbf{x}$ .

## Collider data

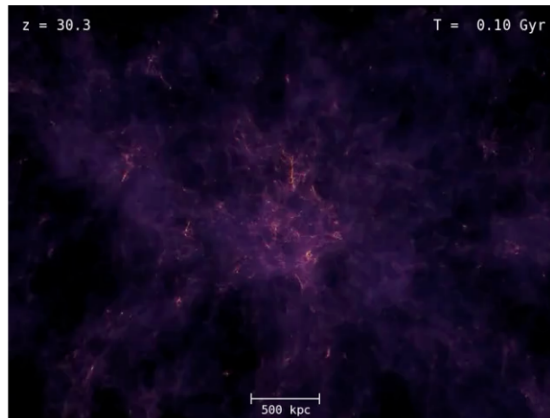
particles  $\sim p(\text{particles})$



[C. Cesarotti with ATLAS]

## Cosmology data

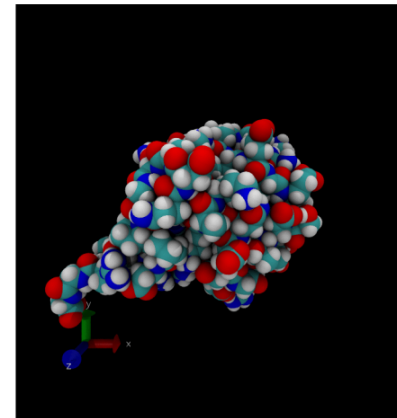
particles  $\sim p(\text{particles})$



[Aquarius simulation]

## Molecular dynamics

configurations  $\sim p(\text{configurations})$



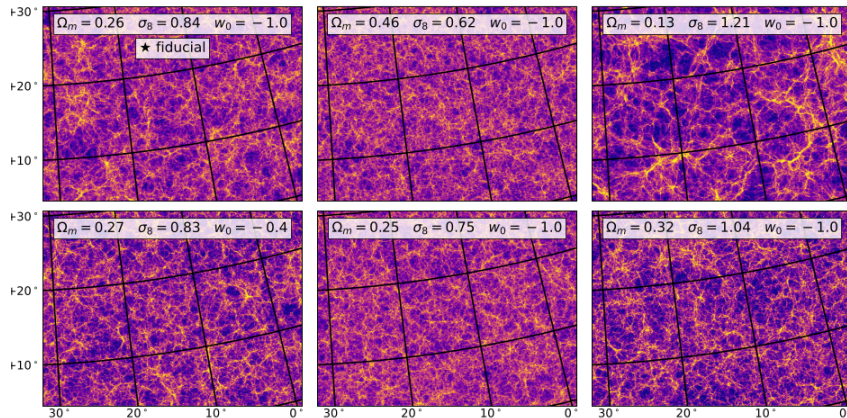
[E. Cances et al]

# Conditional simulators

A conditional simulator prescribes a way to sample from the likelihood  $p(\mathbf{x}|\theta)$ , where  $\theta$  is a set of conditioning variables or parameters.

## Cosmology data

$$\text{map} \sim p(\text{map} \mid \{\Omega_m, \sigma_8, w_0\})$$



[Kacprzak et al 2022]

$$x \sim p(x; \mathcal{M})$$

Model

or

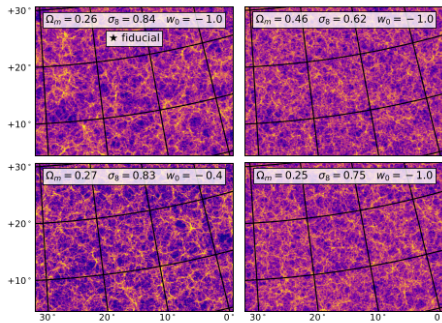
$$x \sim p(x \mid \theta)$$

Model parameters

# What can we do with generative models?

Produce samples and make predictions

$$\mathbf{x} \sim p(\mathbf{x}|\theta)$$

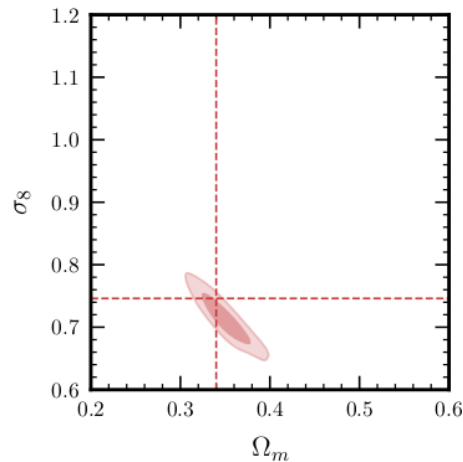


[Kacprzak et al 2022]

Evaluate densities

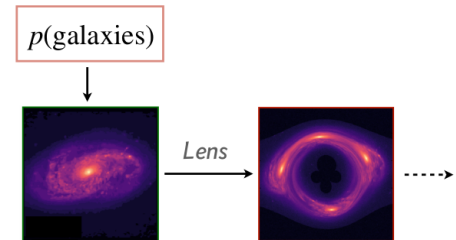
$$p(\mathbf{x}|\theta)$$

$$p(\theta|\mathbf{x}) = \frac{p(\mathbf{x}|\theta)p(\theta)}{p(\mathbf{x})}$$

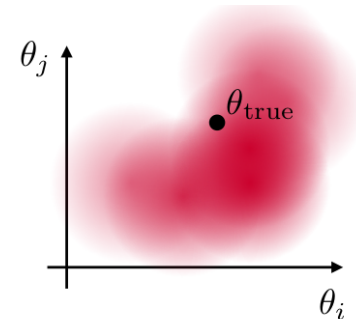
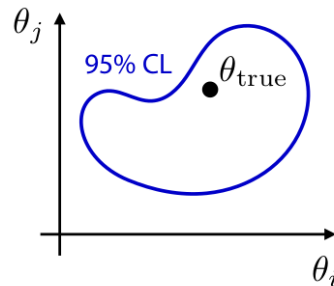
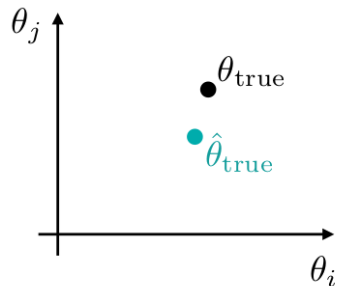


Encode complex priors

$$p(\mathbf{x})$$



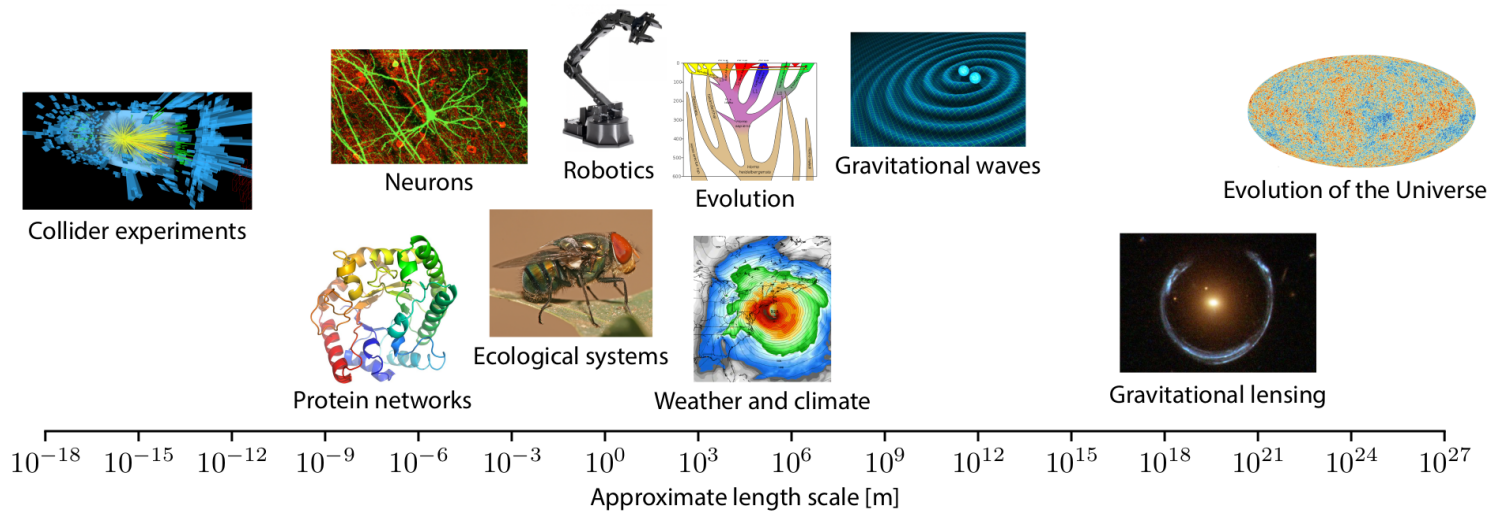
# Inference



- Frequentist inference: find the parameters  $\hat{\theta}$  that maximizes the likelihood  $p(\mathbf{x}|\theta)$  or build a confidence interval thereof.
- Bayesian inference: compute the posterior distribution

$$p(\theta|\mathbf{x}) = \frac{p(\mathbf{x}|\theta)p(\theta)}{p(\mathbf{x})}$$

of the parameters  $\theta$  given the data  $\mathbf{x}$ .



## Examples of inference problems across the physical sciences

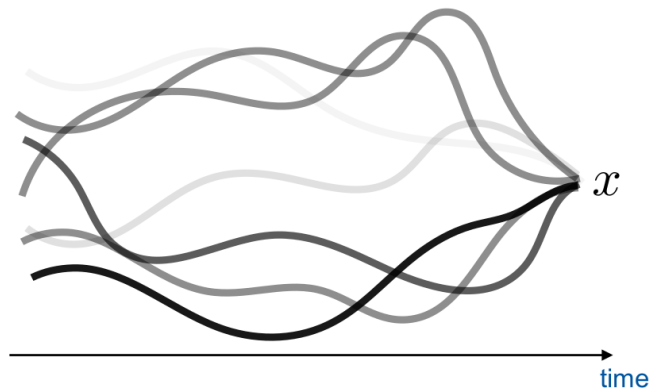
- Discovering new particles in high-energy physics
- Data assimilation in weather forecasting
- Estimating gravitational wave parameters
- Retrieving atmospheric properties of exoplanets
- Constraining cosmological models from galaxy surveys

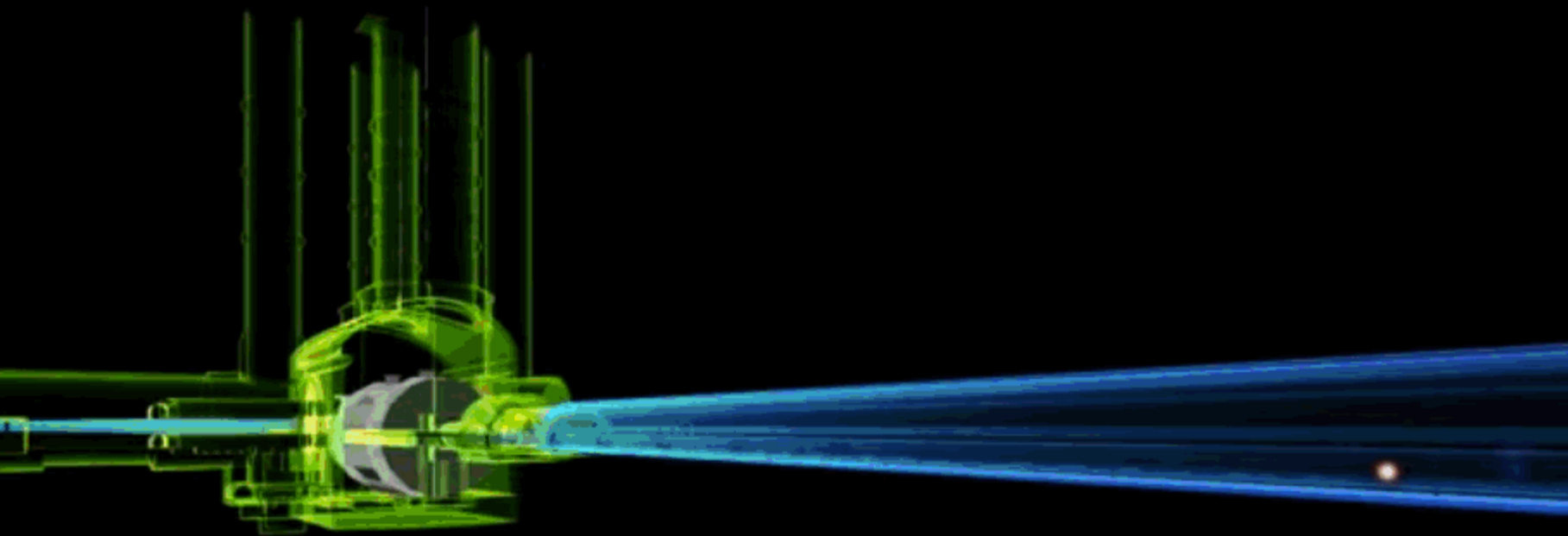
## Intractable likelihoods

The (modeled) data generating process may involve additional latent variables  $\mathbf{z}$  that are not observed, leading to likelihoods

$$p(\mathbf{x}|\theta) = \int p(\mathbf{x}, \mathbf{z}|\theta) d\mathbf{z}.$$

In this case, evaluating the likelihood becomes intractable.





$$p(\mathbf{z}_p | \theta)$$

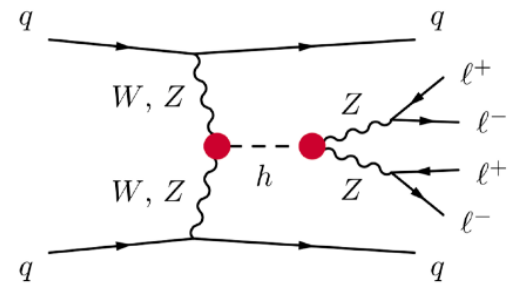
Latent variables

Parameters  
of interest

Parton-level  
momenta

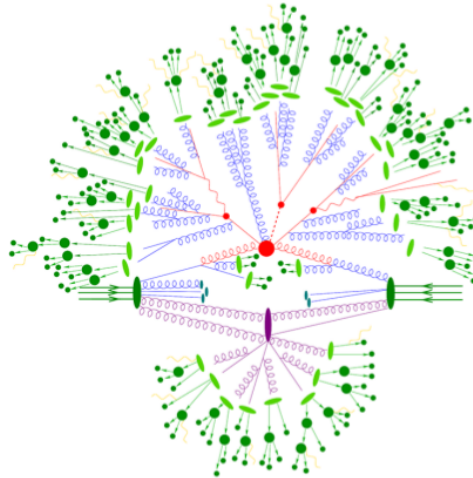
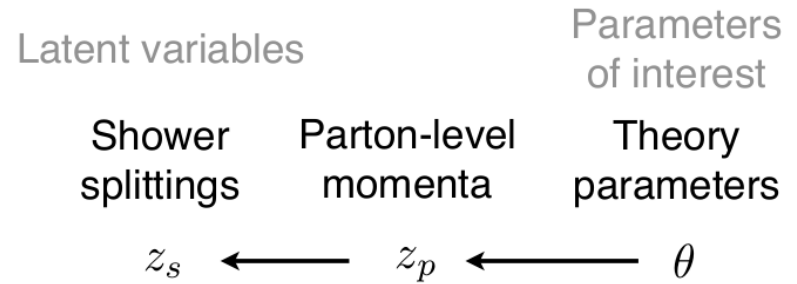
Theory  
parameters

$$z_p \longleftarrow \theta$$





$$p(\mathbf{z}_s | \theta) = \int p(\mathbf{z}_p | \theta) p(\mathbf{z}_s | \mathbf{z}_p) d\mathbf{z}_p$$



$$p(\mathbf{z}_d|\theta) = \iint p(\mathbf{z}_p|\theta)p(\mathbf{z}_s|\mathbf{z}_p)p(\mathbf{z}_d|\mathbf{z}_s)d\mathbf{z}_pd\mathbf{z}_s$$

Latent variables

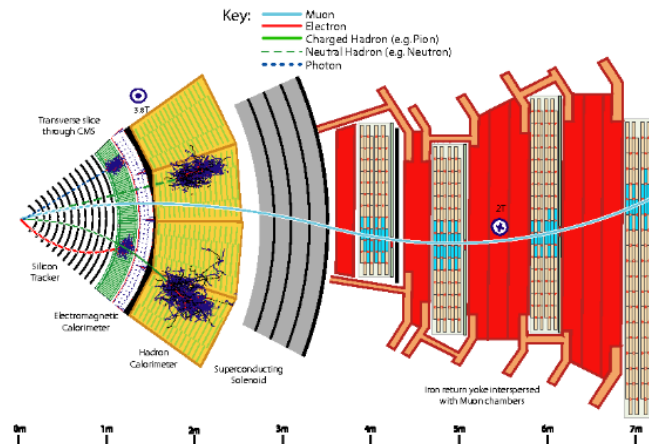
Parameters of interest

Detector interactions

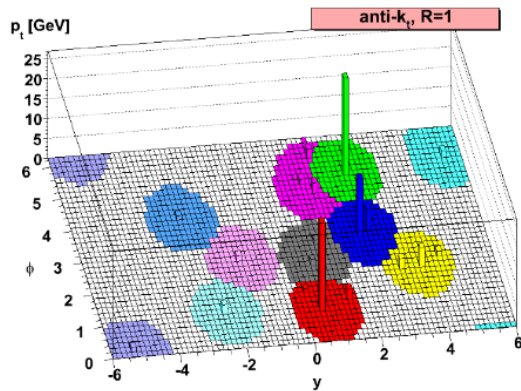
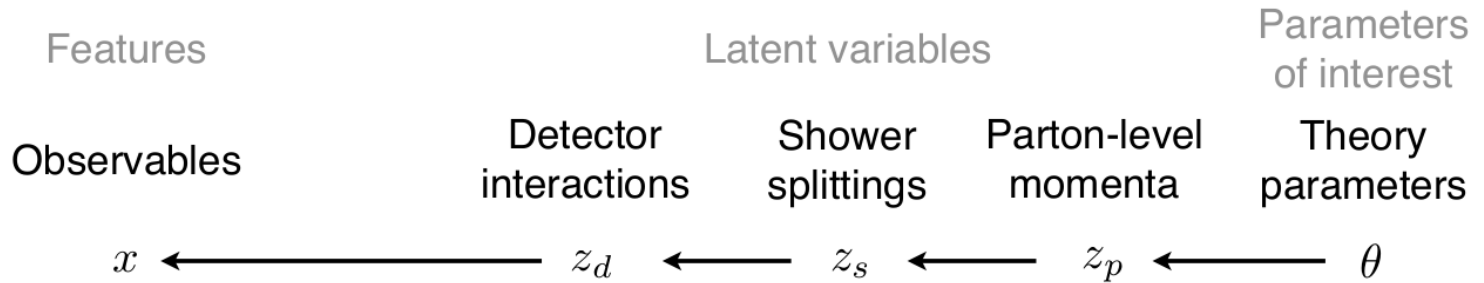
Shower splittings

Parton-level momenta

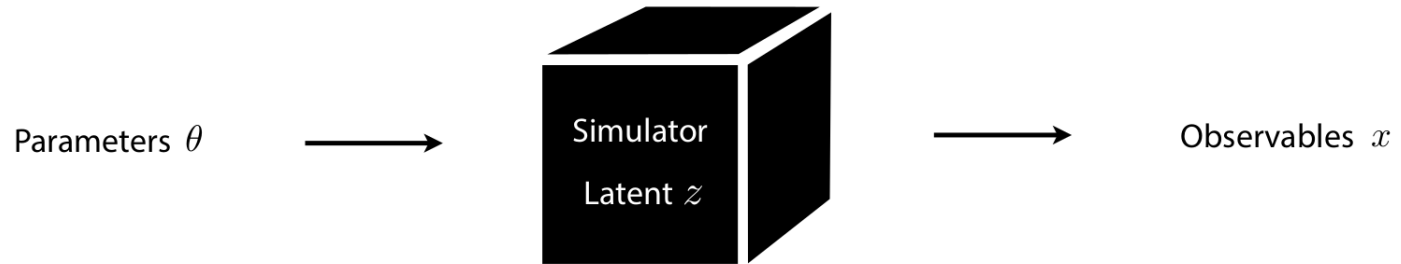
Theory parameters



$$p(\mathbf{x}|\theta) = \underbrace{\iiint}_{\text{yikes!}} p(\mathbf{z}_p|\theta)p(\mathbf{z}_s|\mathbf{z}_p)p(\mathbf{z}_d|\mathbf{z}_s)p(\mathbf{x}|\mathbf{z}_d)d\mathbf{z}_p d\mathbf{z}_s d\mathbf{z}_d$$



[Image source: M. Cacciari, G. Salam, G. Soyez 0802.1189]



- Prediction:
- Well-motivated mechanistic, causal model
  - Simulator can generate samples  $x \sim p(x|\theta)$

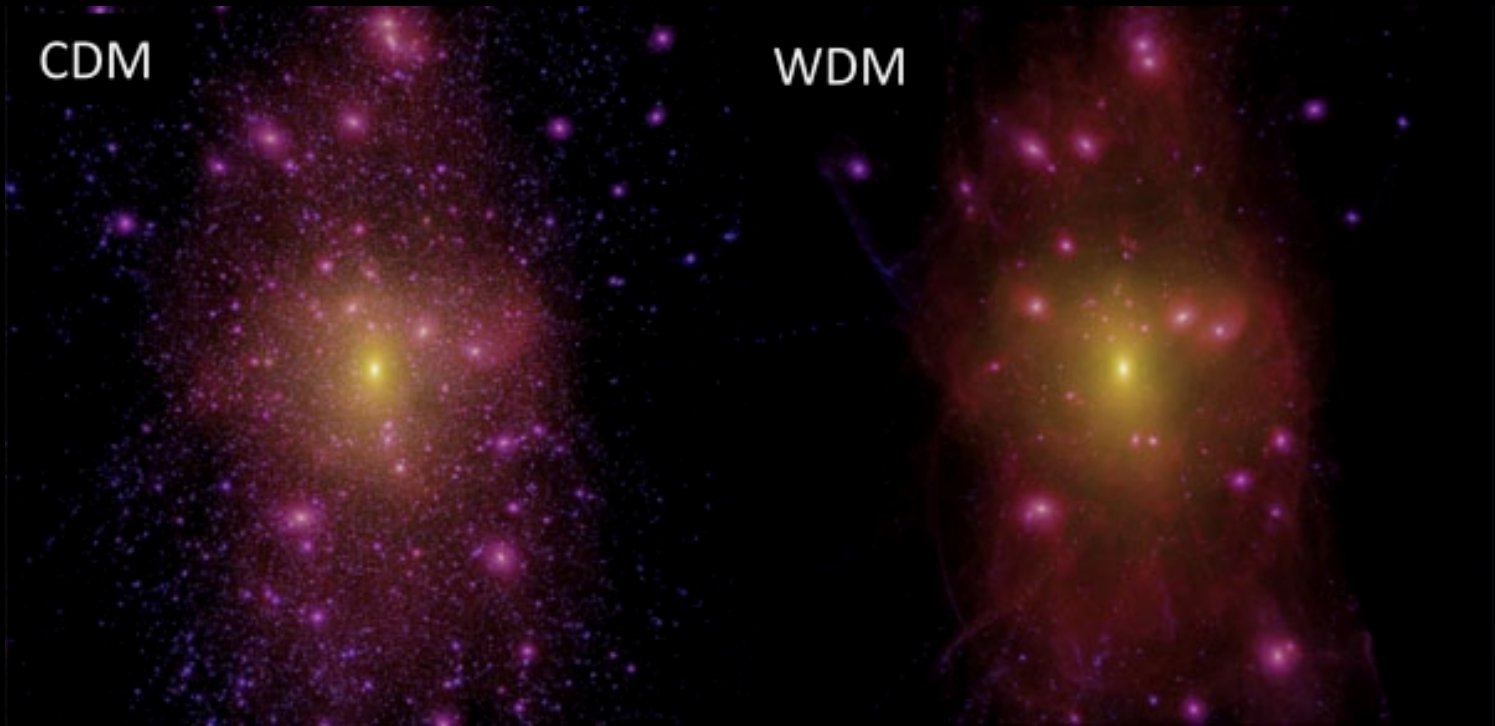
- Inference:
- Interactions between low-level components lead to challenging inverse problems
  - Likelihood  $p(x|\theta) = \int dz p(x, z|\theta)$  is intractable

Statistical inference becomes challenging when the likelihood  $p(\mathbf{x}|\theta)$  is implicit or intractable. **Simulation-based inference algorithms are needed.**



# A case study

Hermans et al, "Constraining dark matter with stellar streams", 2021.



Can we constrain the nature of dark matter from cosmological observations?

# Constraining dark matter with stellar streams

## Palomar 5 (Pal5) stream

Pal5 was discovered in 2001 as the first thin stream formed from a globular cluster. Its current orbit takes it far over the galactic center.

## Globular clusters

These hives typically hold 100,000 stars or fewer and give rise to long, thin streams.

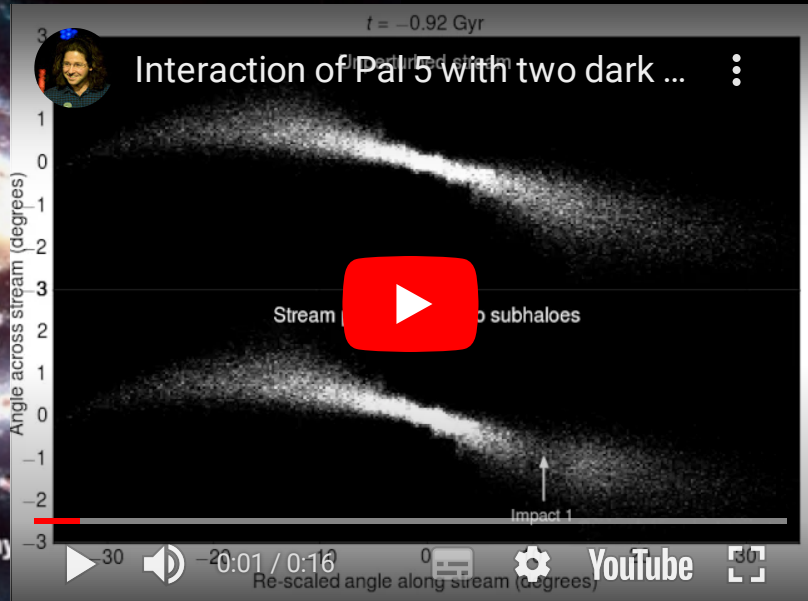
Gap

Sun

## GD1 stream

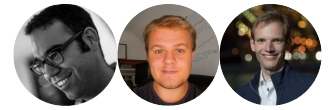
Discovered in 2006, GD1 is the longest known thin stream, stretching across more than half the northern sky. It contains a gap that could be the scar of a dark matter collision 500 million years ago.

Milky Way



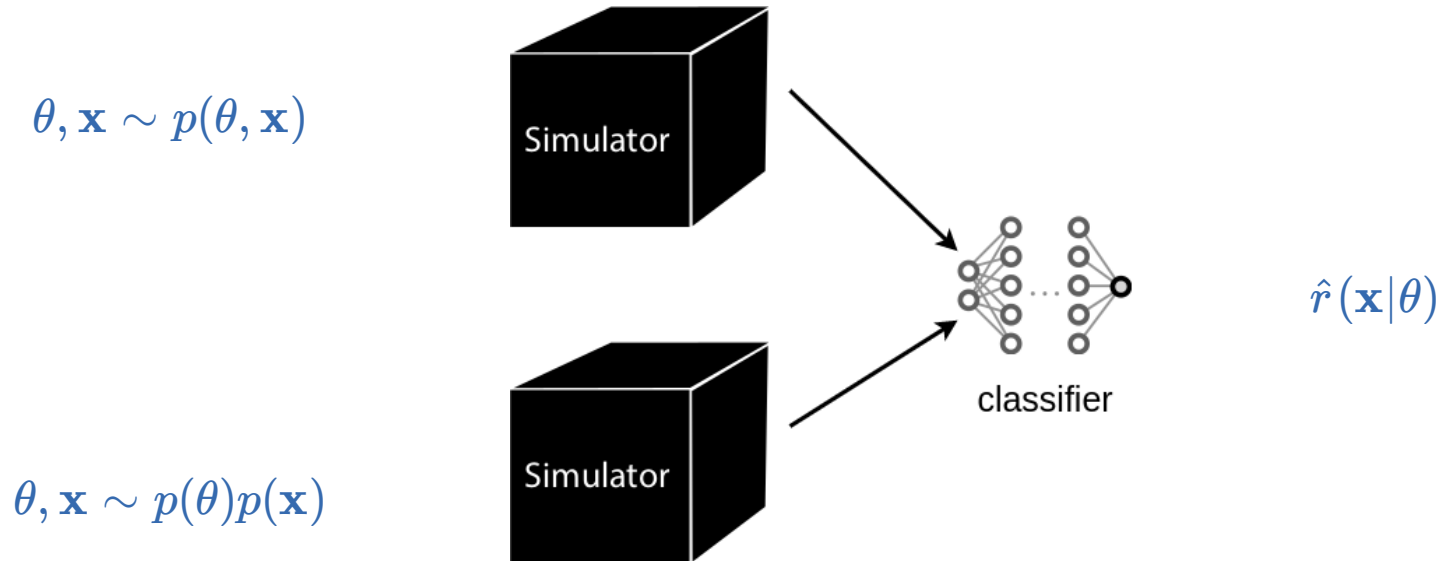
$$p(m_{\text{WDM}}, t_{\text{age}} | \text{GD1}) = \frac{p(\text{GD1} | m_{\text{WDM}}, t_{\text{age}}) p(m_{\text{WDM}}, t_{\text{age}})}{p(\text{GD-1})}$$

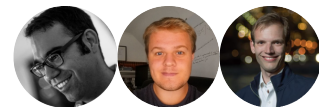




## Neural ratio estimation (NRE)

The likelihood-to-evidence  $r(\mathbf{x}|\theta) = \frac{p(\mathbf{x}|\theta)}{p(\mathbf{x})} = \frac{p(\theta, \mathbf{x})}{p(\theta)p(\mathbf{x})}$  ratio can be estimated from a binary classifier  $d(\theta, \mathbf{x})$ , even if neither the likelihood nor the evidence can be evaluated.



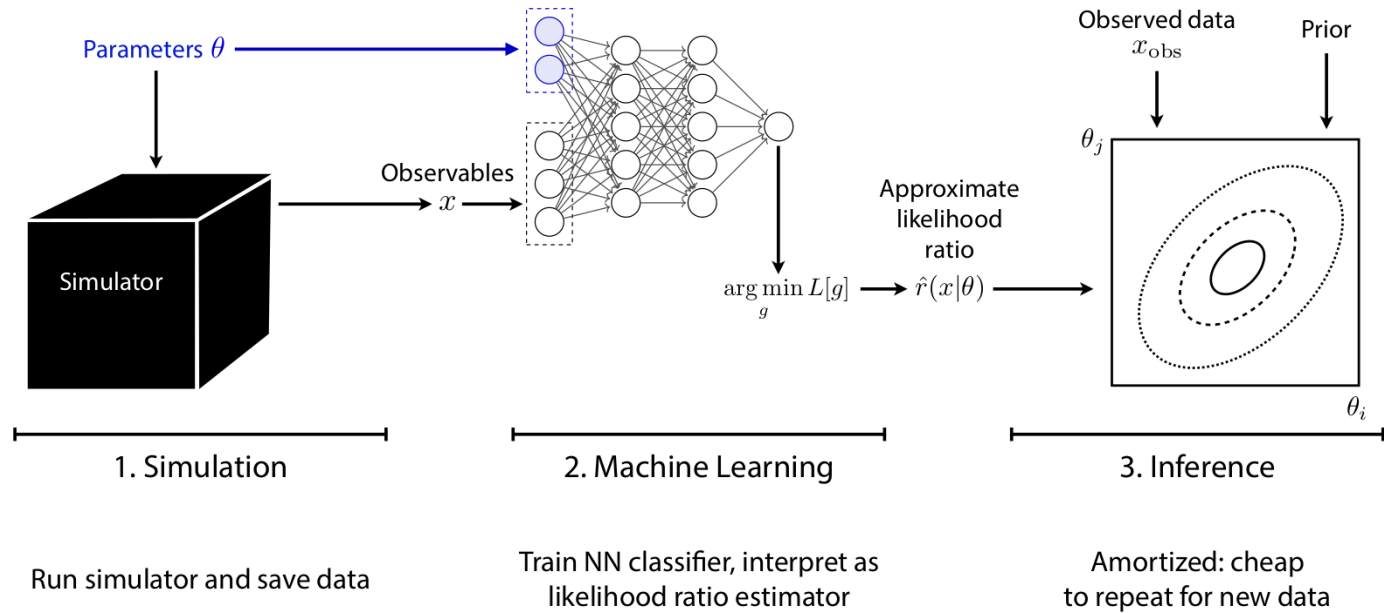


The solution  $d$  found after training approximates the optimal classifier

$$d(\theta, \mathbf{x}) \approx d^*(\theta, \mathbf{x}) = \frac{p(\theta, \mathbf{x})}{p(\theta, \mathbf{x}) + p(\theta)p(\mathbf{x})}.$$

Therefore,

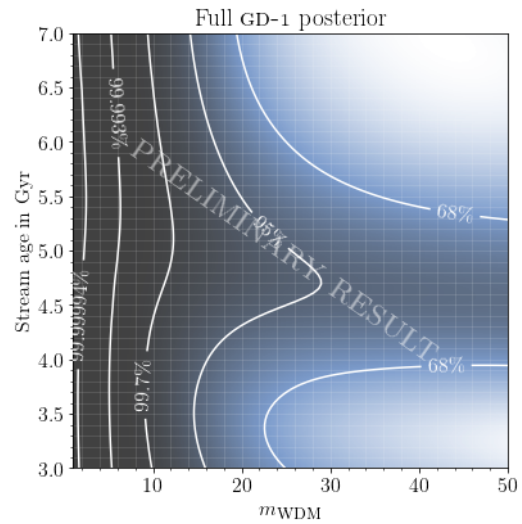
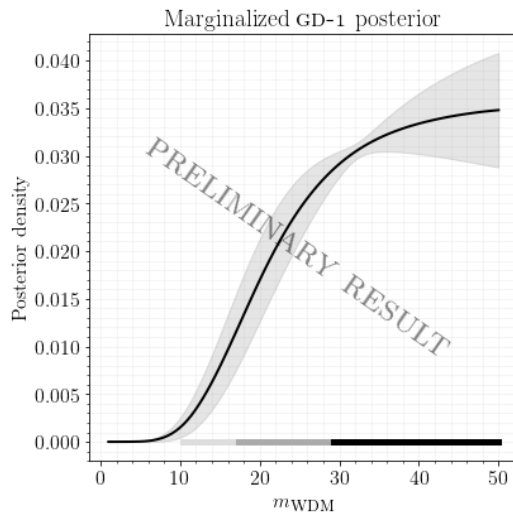
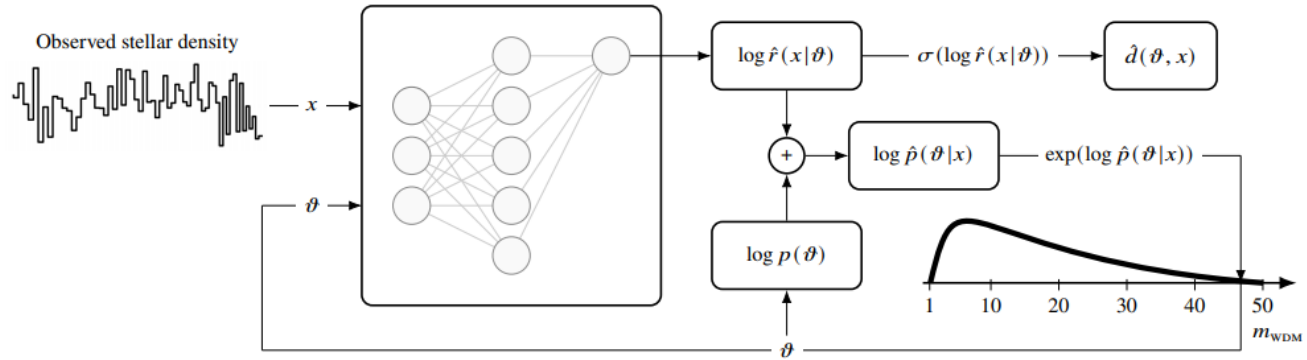
$$r(\mathbf{x}|\theta) = \frac{p(\mathbf{x}|\theta)}{p(\mathbf{x})} = \frac{p(\theta, \mathbf{x})}{p(\theta)p(\mathbf{x})} \approx \frac{d(\theta, \mathbf{x})}{1 - d(\theta, \mathbf{x})} = \hat{r}(\mathbf{x}|\theta).$$

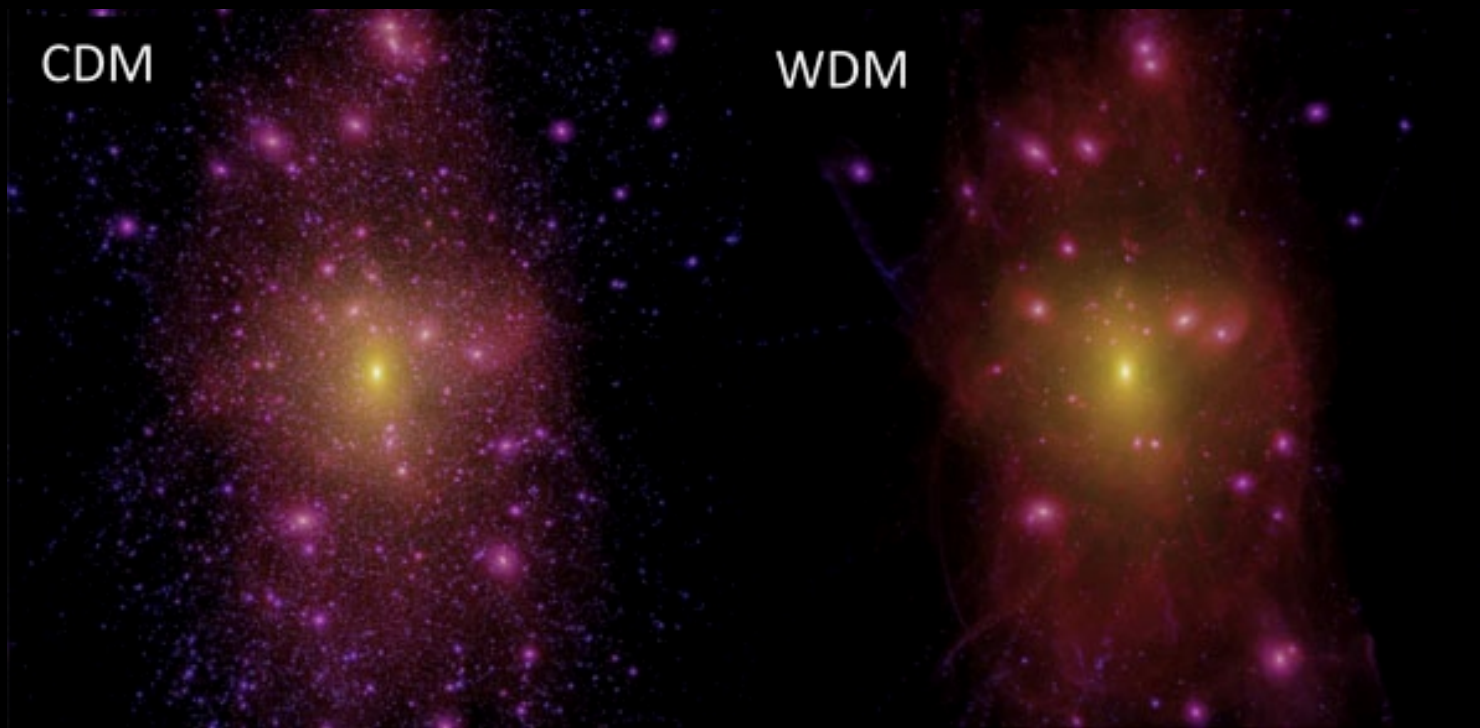


$$p(\theta|\mathbf{x}) \approx \hat{r}(\mathbf{x}|\theta)p(\theta)$$



# NRE for stellar streams





Preliminary results for GD-1 suggest a preference for CDM over WDM.

Wait a minute Gilles...  
I can't claim that in a paper!  
Your neural network must be wrong!

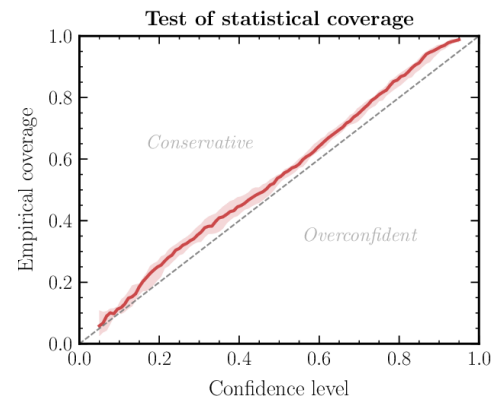
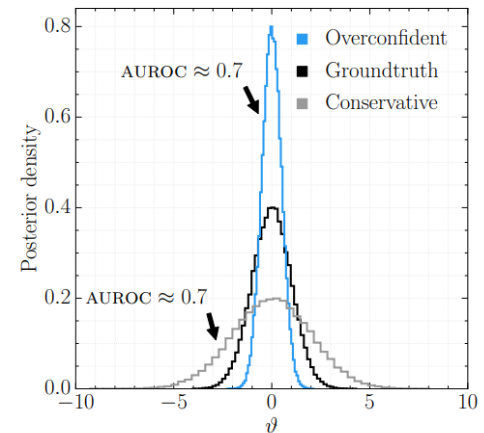


## Expected coverage

$$EC(\hat{p}, \alpha) = \mathbb{E}_{p(\theta, \mathbf{x})} [\theta \in \Theta_{\hat{p}(\theta|\mathbf{x})}(\alpha)]$$

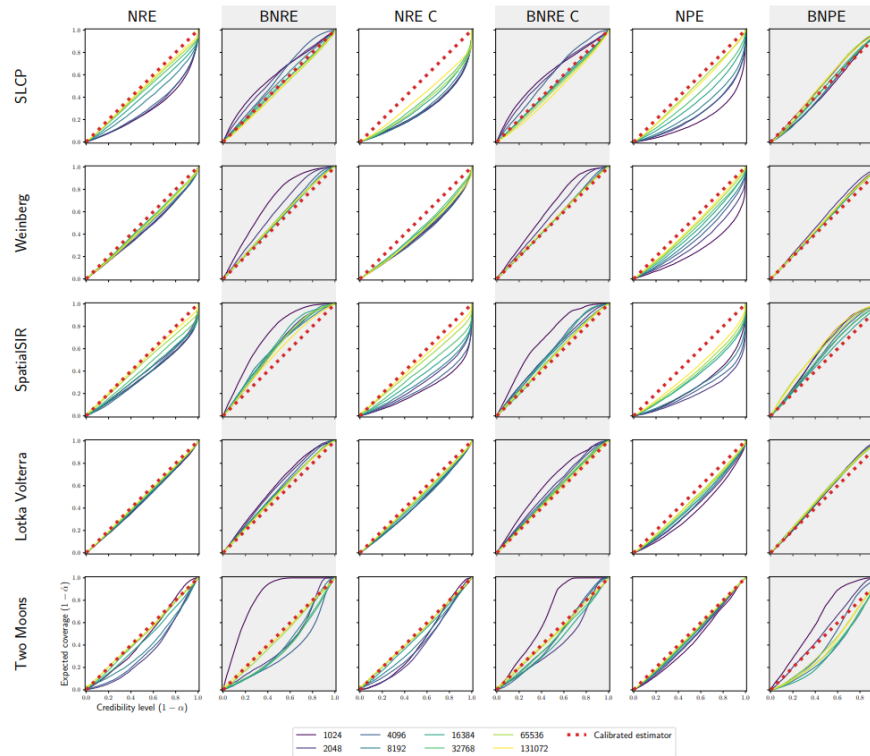
If the expected coverage is close to the nominal coverage probability  $\alpha$ , then the approximate posterior  $\hat{p}$  is calibrated.

- If  $EC < \alpha$ , then the posterior is underdispersed and overconfident.
- If  $EC > \alpha$ , then the posterior is overdispersed and conservative.





# Balancing inference for conservative posteriors



Conservative posteriors can be obtained by enforcing  $d$  to be balanced, i.e. such that  $\mathbb{E}_{p(\theta, \mathbf{x})} [d(\theta, \mathbf{x})] = \mathbb{E}_{p(\theta)p(\mathbf{x})} [1 - d(\theta, \mathbf{x})]$ .



# Summary

Simulation-based inference is a major evolution in the statistical capabilities for science, as it enables the analysis of complex models and data without simplifying assumptions.

Obstacles remain to be overcome, such as the curse of dimensionality, the need for large amounts of data, or the necessary robustness of the inference network.