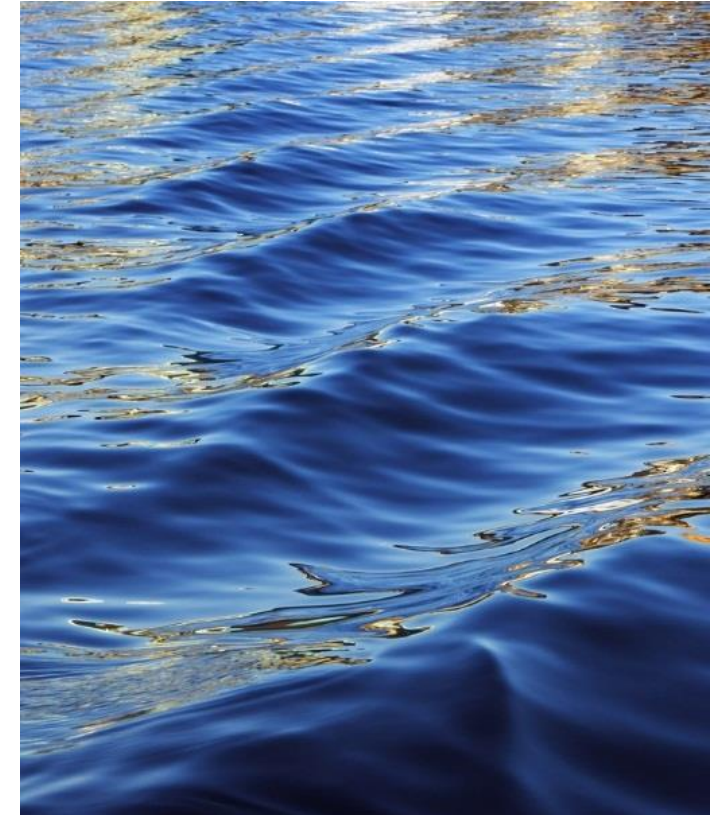


A creep survey: from creep mechanisms to macroscopic and microscopic models

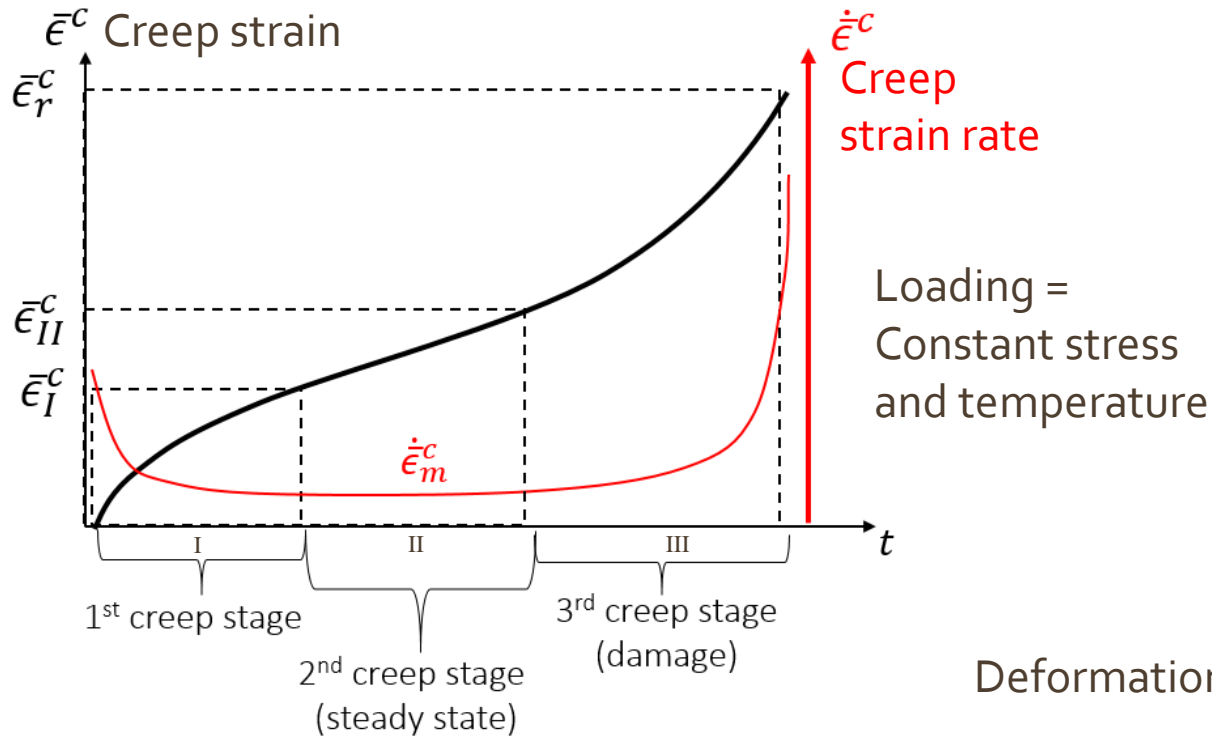
AM Habraken,
G. Bryndza, F. Chen, L. Duchêne, A. Mertens,
C. Rojas, J. Tchuindjang



Toward sustainability
A good design reduces energy consumption, saves raw material

What is creep?

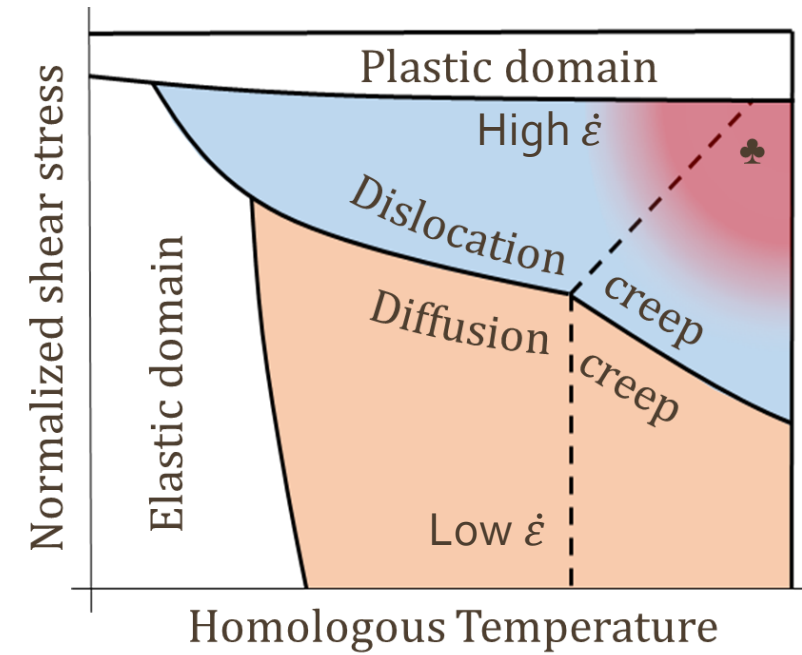
Schematic Deformation Mechanism Map
4 Regions



Typical creep curves

Deformation Mechanism Map

Deformation-Mechanism Maps, The Plasticity and Creep of Metals and Ceramics, by Harold J Frost, Dartmouth College, USA, and Michael F Ashby, Cambridge University, UK
<https://defmech.engineering.dartmouth.edu/>



\clubsuit : Dynamic recrystallization (DRX)

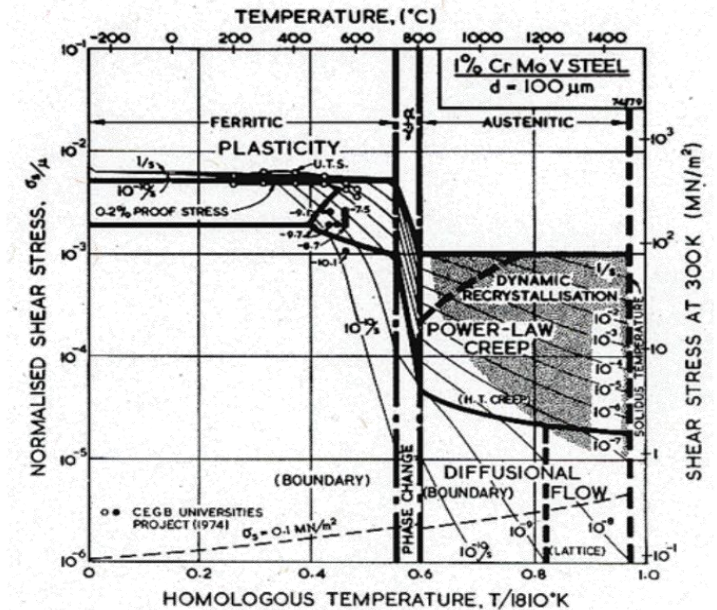


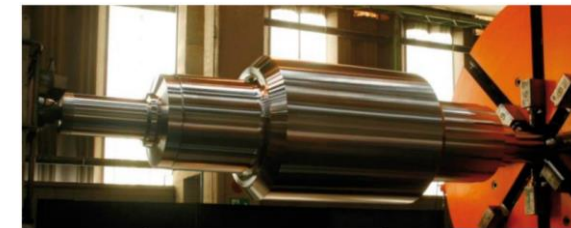
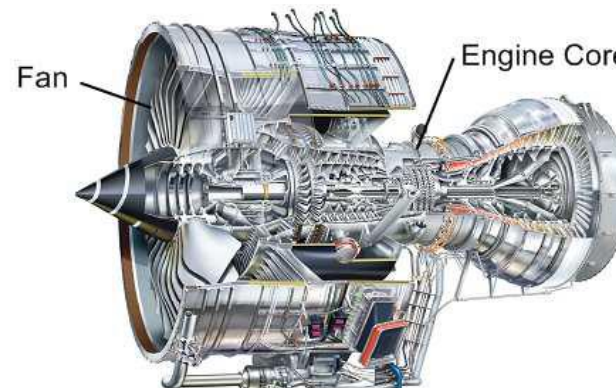
Fig. 8.7. A 1% Cr-Mo-V steel, of grain size 100 μm , showing data.

Why is creep studied ?

- Many sectors have creep issues
- Modeling creep
 - Correct design of parts
 - Optimal industrial maintenance and investment plan
 - Reduce product development time (validation tests)
- Understanding creep mechanism → Optimal design of alloy composition, heat treatments



PETROCHEMICAL industry



Contents

- Introduction
- **Phenomenological** approaches
 - Scalars
 - Larson Miller etc...
 - Curves and constitutive laws FE
 - Norton
 - Graham Wales
- **Micro** physical based approaches
 - The basis
 - Incoloy 718 application
- **Fatigue-Creep**, Dwell effect and FE Morch constitutive macro law
- **Nitriding** effect
- **AID4Greenest** EU project ...

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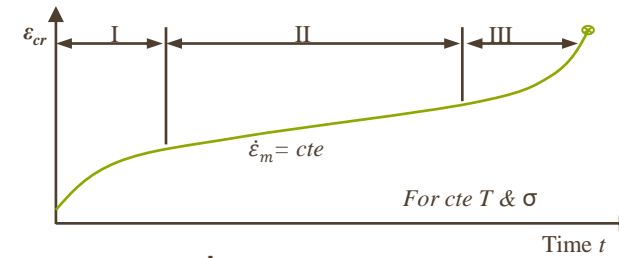
- The basis
- Incoloy 718 application

- **Fatigue-Creep**, Dwell effect and FE Morch constitutive macro law

- **Nitriding** effect

- **AID₄Greenest** EU project ...

About master curves, Larsen-Miller Parameter LMP



Stationary creep (power law):

$$\dot{\epsilon} = B\sigma^n e^{-\frac{\Delta H}{kT}}$$

B and n are material constants
 ΔH is activation energy
 n is normally between 3 and 8

Larson and Miller formulation:

$$\dot{\epsilon} = A e^{-\frac{\Delta H}{kT}}$$

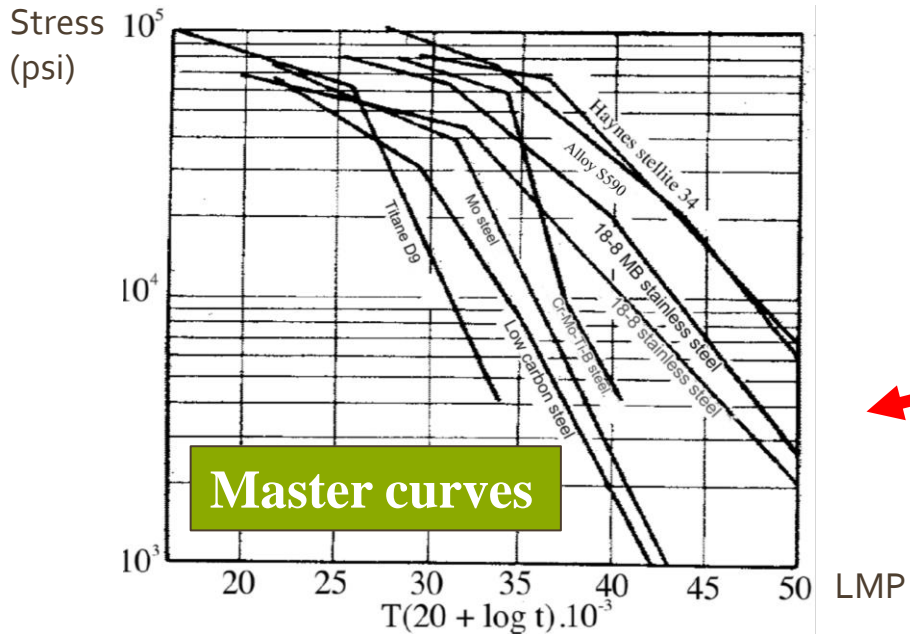
A is a constant
 ΔH is activation energy

$$\ln\left(\frac{\epsilon}{t}\right) = \ln\left(A e^{-\frac{\Delta H}{kT}}\right)$$

$$\ln(t) = \ln\left(\frac{\epsilon}{A}\right) + \frac{\Delta H}{kT}$$

$$Const = T(\ln(t) + C_1)$$

For most of the alloys $35 < C_1 < 60$



Rupture stress is plotted as a function of a parameter (x) = t_R or $\dot{\epsilon}_m$
 $T(\ln(x) + C_1)$

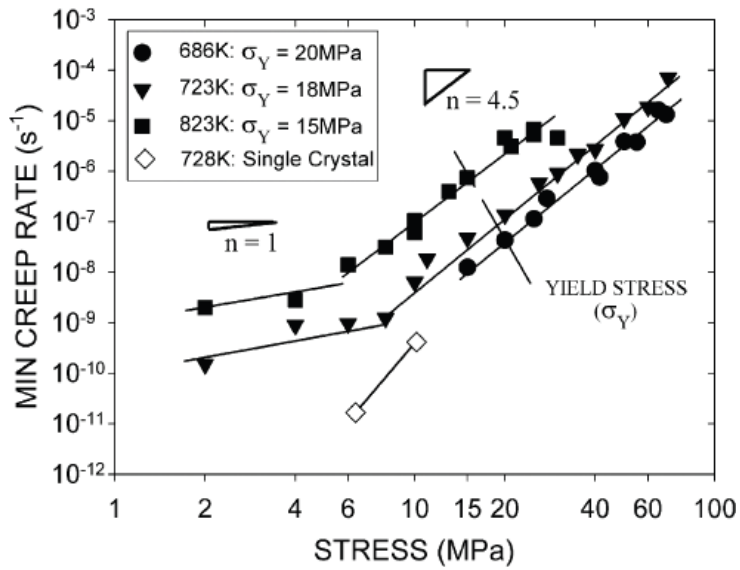
As $\dot{\epsilon}_m \cdot t_r = cte$
 Monkman-Grant*

Link σ to T and t_R or $\dot{\epsilon}_m$

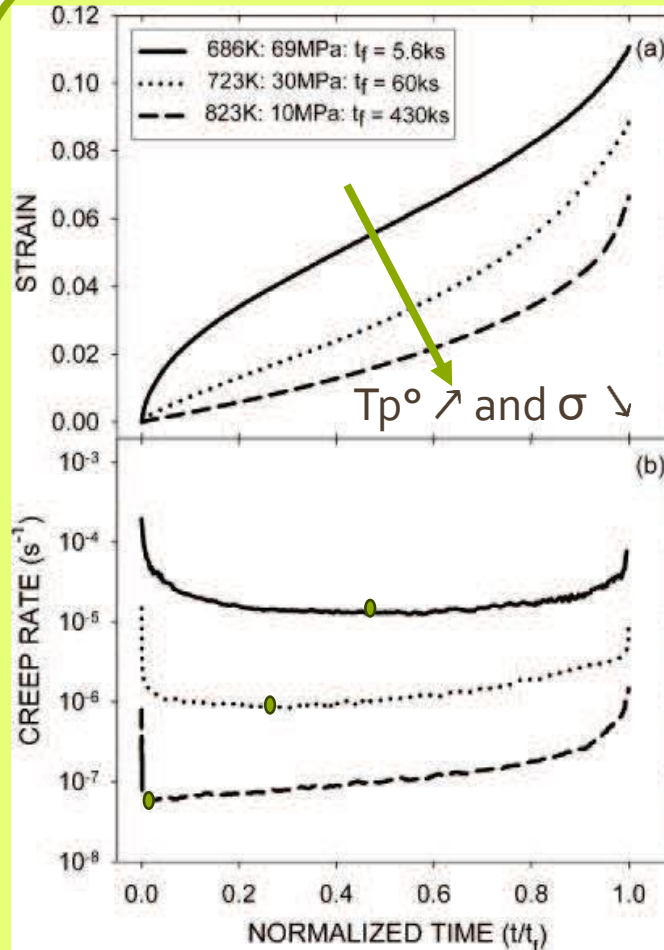
OK for microstructure = cte

FR Larson, J. Miller, Transactions of the ASME (1954)

GE Dieter, "Mechanical Metallurgy," McGraw-Hill Book Company (1988)



≠ n with "no" physical meaning



Experimental creep observations

If $T_p^\circ \nearrow$ and $\sigma \searrow$

Creep state II $\dot{\epsilon}_m^c \searrow$
earlier

From power-law analysis there is no indication that creep behavior changes in the higher stress regime.

LMP does not point the correct position of mechanism change
diffusion \rightarrow dislocation

No effect of yield stress

No info on **creep curves**

($\sigma = \text{cte}$ $T = \text{cte}$)

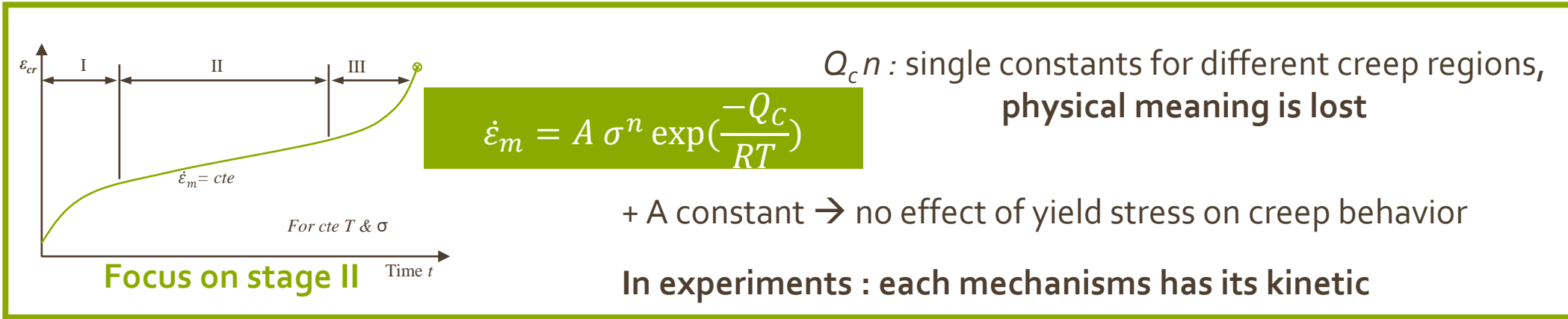
$\epsilon = f(\sigma, T, t)$



Wilshire introduced the use of σ/σ_Y

And focuses on stage I and III

Issues of LMP approach and exponential function (Norton)



Wilshire equations (focus on stage I and III)
 Based on relative stress = σ/σ_{UTS}

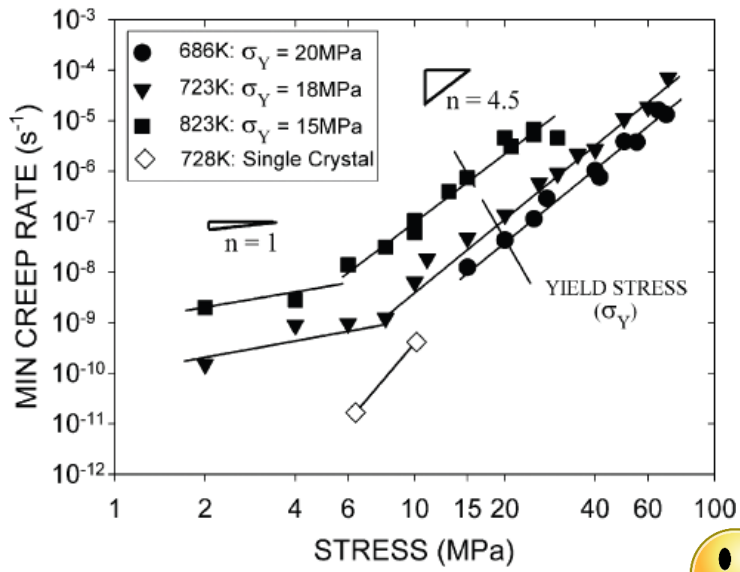
$\rightarrow Q_c^*$ related to different physical mechanism depending on creep region

\neq equations \neq mechanisms $\rightarrow t_r$ or $\dot{\epsilon}_m^c$

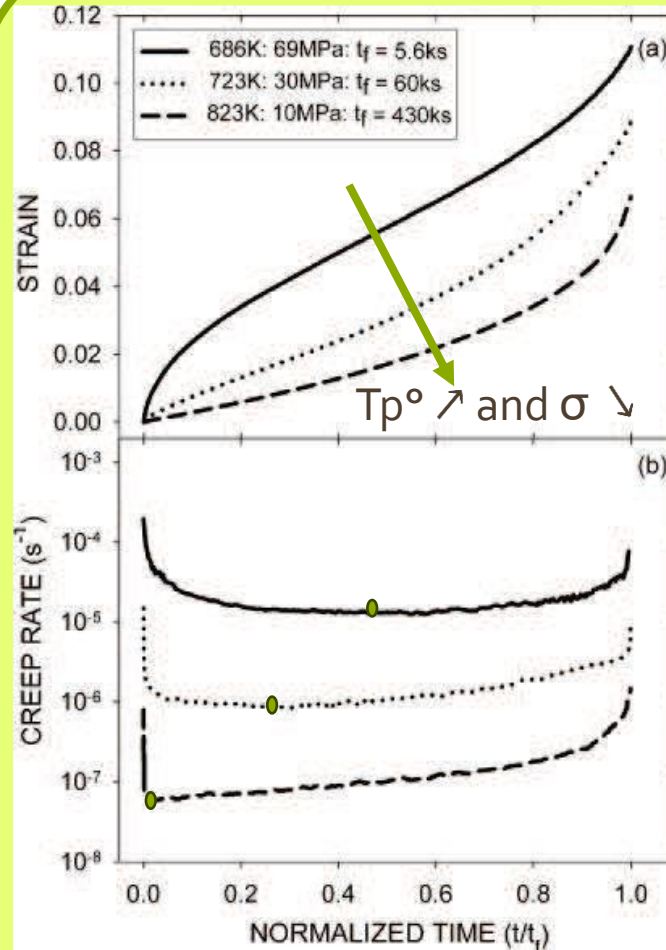
$\dot{\epsilon}_m \cdot t_r = cte$ Monkman-Grant allows to pass from 1- \rightarrow 2

$$\left\{ \begin{array}{l} \sigma/\sigma_{UTS} = \exp \{ -k_u [t_r \exp(-Q_c^*/RT)]^u \} \quad (1) \\ \sigma/\sigma_{UTS} = \exp \{ -k_v [\dot{\epsilon}_m \exp(-Q_c^*/RT)]^v \} \quad (2) \end{array} \right.$$

Whole curve parameters k_w , w = functions of strain $\rightarrow \sigma/\sigma_{UTS} = \exp \{ -k_w [t_\epsilon \cdot \exp(-Q_c^*/RT)]^w \}$



Norton approach $\rightarrow \neq n$

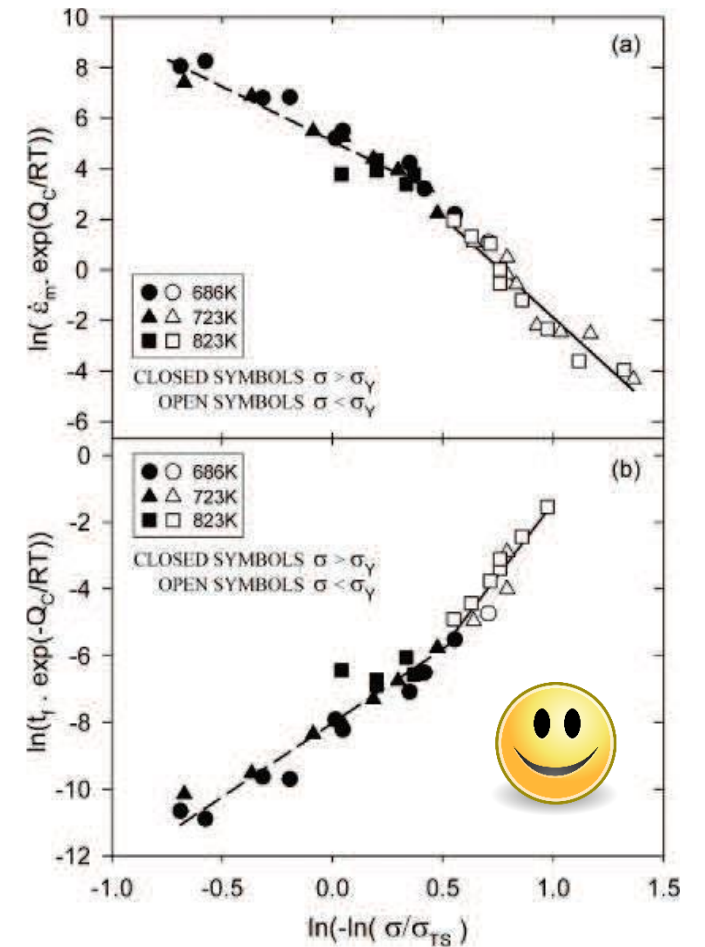


Experimental creep observations

If $T_p^\circ \nearrow$ and $\sigma \searrow$

Creep state II \searrow

earlier



Wilshire equations

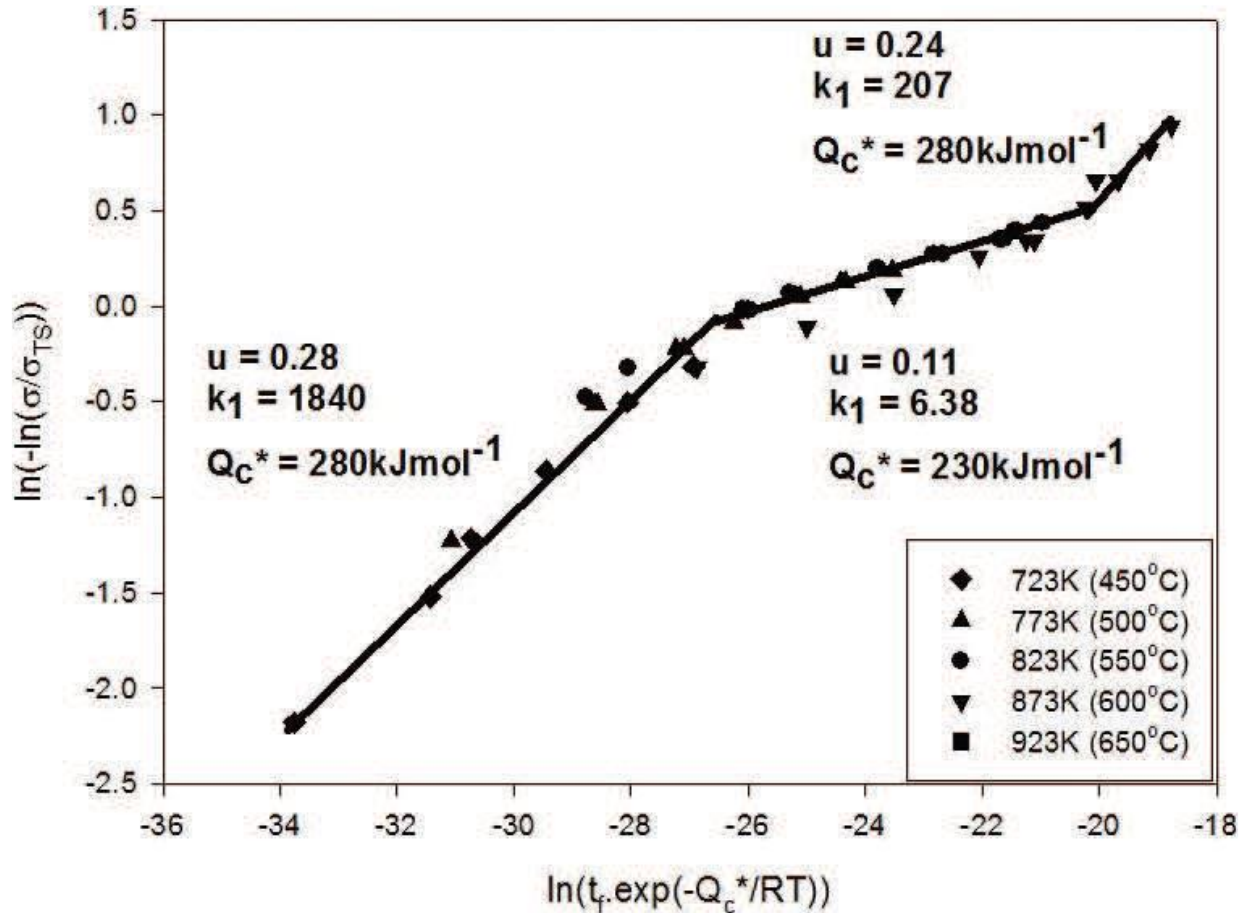
Q_c^* = cte = grain boundary diffusion

$k_i, u, v \neq$ for $\sigma < \sigma_y$ and $\sigma > \sigma_y$

$$\sigma/\sigma_{UTS} = \exp \left\{ -k_u \left[t_f \cdot \exp(-Q_c^*/RT) \right]^u \right\}$$

$$\sigma/\sigma_{UTS} = \exp \left\{ -k_v \left[\dot{\epsilon}_m \exp(-Q_c^*/RT) \right]^v \right\}$$

Issues of Wilshire approach



Gr 22 tube
2.25 CR - 1Mo - NIMS data

Wilshire equations

$Q_c^*, k_i, u, v \neq$ multiple ctes

3 Different mechanisms

For 2.25 CR - 1Mo

- High T and long t : bainite degradation \rightarrow ferrite
- Low σ : mainly GB effect
- High σ : increase of dislocation density

$$\sigma/\sigma_{UTS} = \exp \{ -k_u [t_f \cdot \exp(-Q_c^*/RT)]^u \}$$

$$\sigma/\sigma_{UTS} = \exp \{ -k_v [\dot{\epsilon}_m \exp(-Q_c^*/RT)]^v \}$$



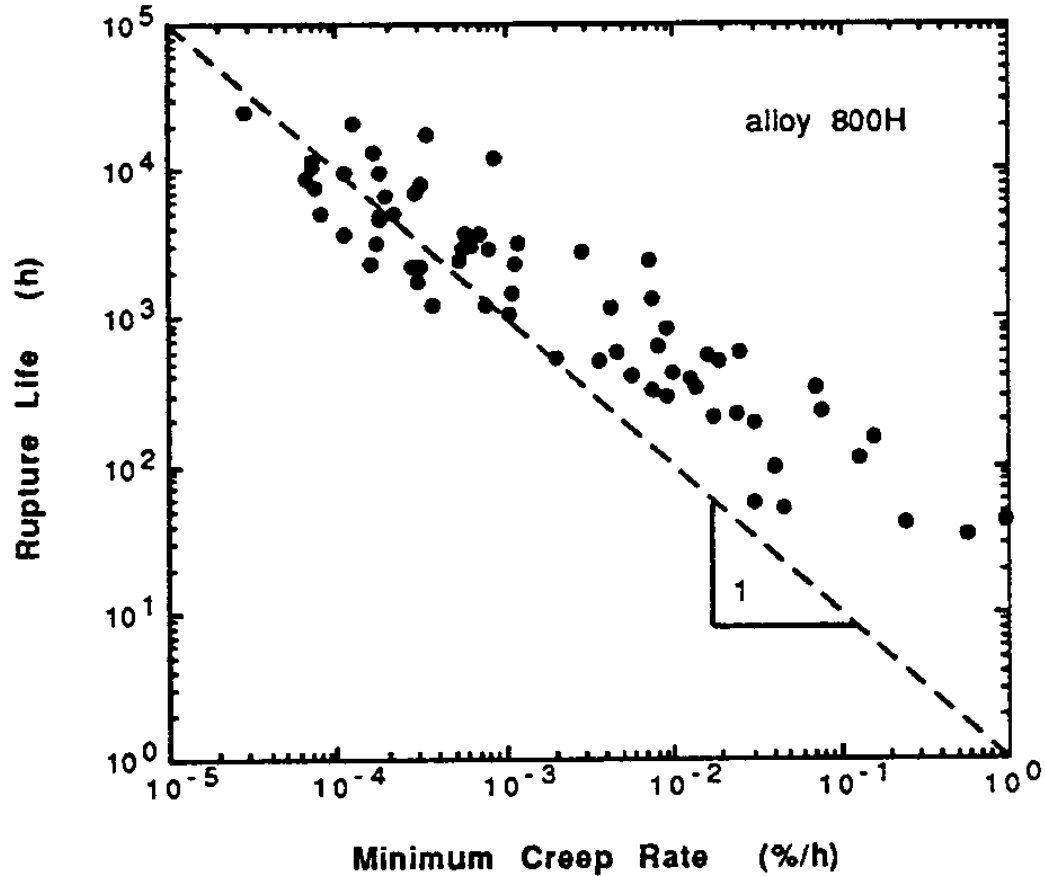
Needs many data

Just scalars t_R or $\dot{\epsilon}_m$ identified

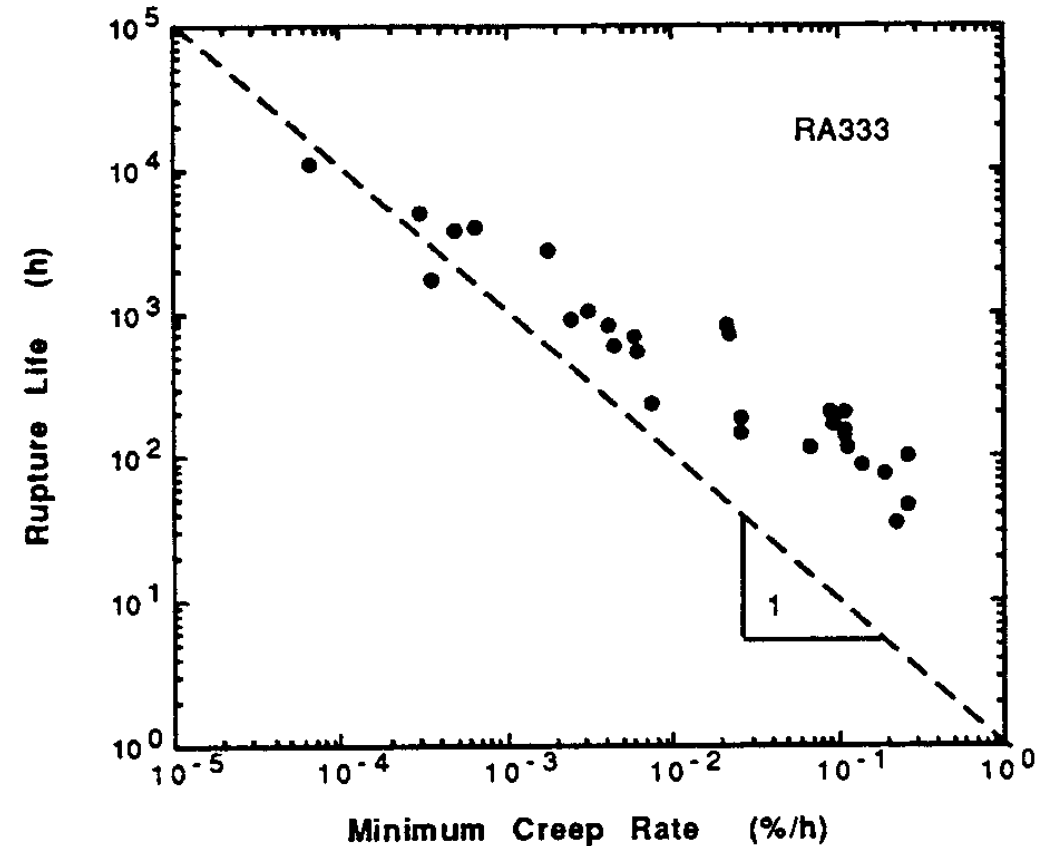
Strong effect of microstructure evolution

**Need to chose correct functions
integrating all information
for FE simulations to model creep
under variable T, σ and long t**

Issue in Monkman-Grant assumption of $\dot{\epsilon}_m \cdot t_r = cte$



Austenitic Incoloy alloy (Fe-Ni-Cr)



Ni-Cr alloy with solid solution strengthening

Issues in Design of piping and support components in high-temperature fluidized bed combustor systems

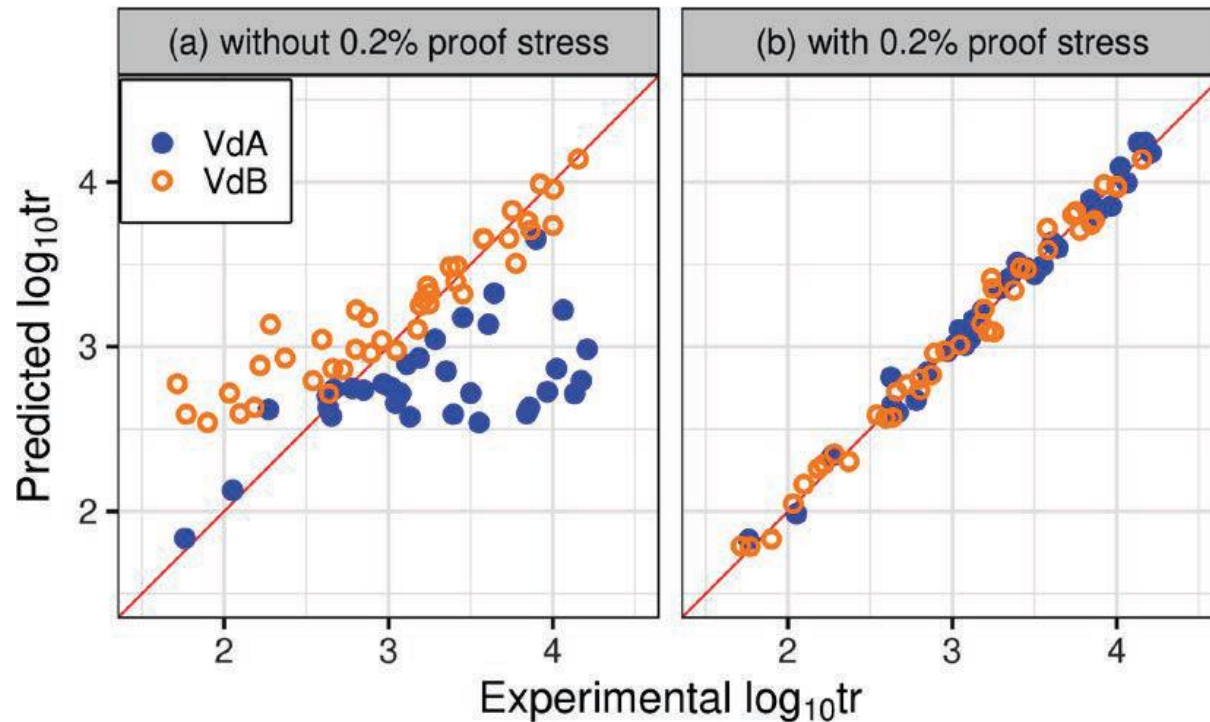
Machine learning to predict t_r

Data base used : 27 compositions (ferritic heat resistant steel) a total of 212 creep curves
from carbon steel to low-alloy and high-alloy steels (Fe+ Pe, Fe+Pe+Ba, Ma+Ba) , 0 to 9%Cr

Input: **composition**, test condition (T, σ) + **yield stress σ_y** (to express process manufacturing difference)

Output: $\log_{10} t_r$

Validation with or
without yield stress
included in the
training

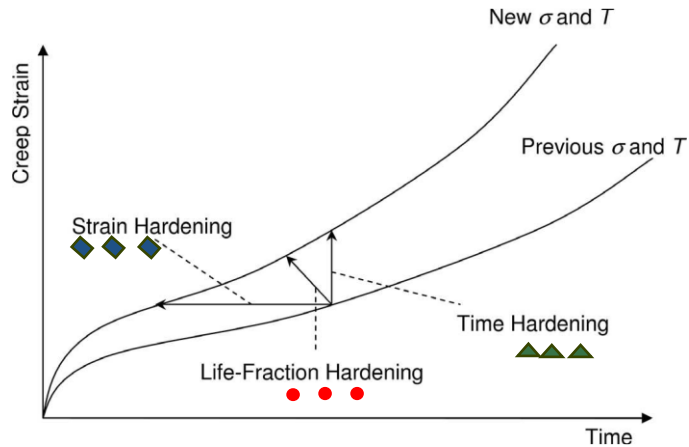


Model developed
on a single family
Fe+ Pe,
Fe+Pe+Ba,
Ma+Ba had
no higher accuracy than
the global model on the
whole data set

similar results in
Nakamura et al.
Materials Today Com 2023,
With σ_y replaced by Hv

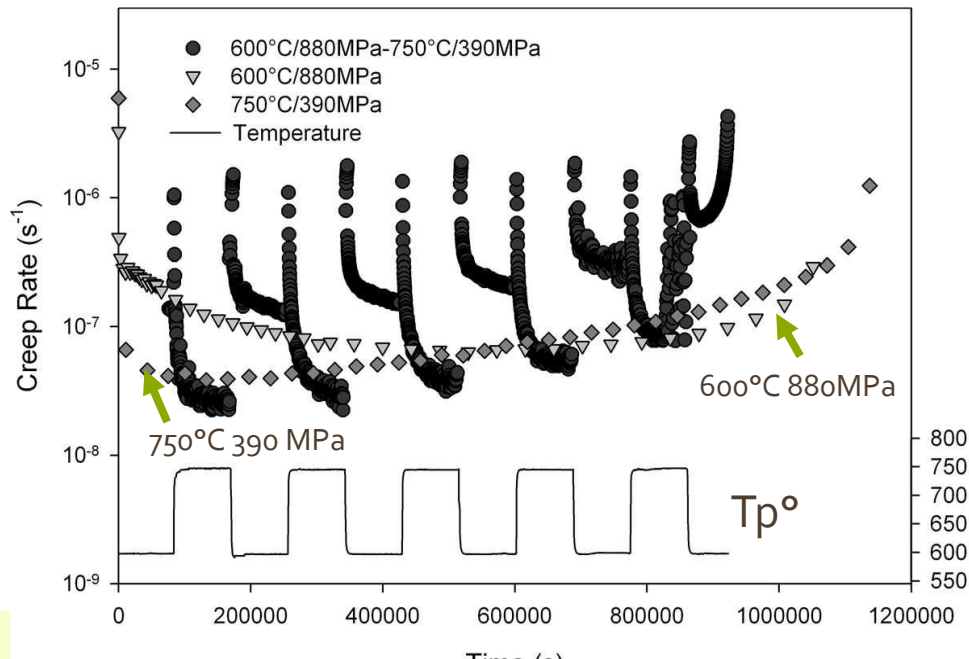
Accuracy of
support vector regression (SVR) > random forest (RF) or gradient tree boosting (GTB) methods

Extrapolation ...from these "scalars" toward FE



1. Define a **constitutive law** with internal variables
 1. Use of them to jump between 1D reference curves $\epsilon = f(\sigma, T, t)$ (1 curve for $\sigma = \text{cte}$ $T = \text{cte}$)
- The use of state variables is better than horizontal or vertical shift

Experiments Creep under TP° and stress jump

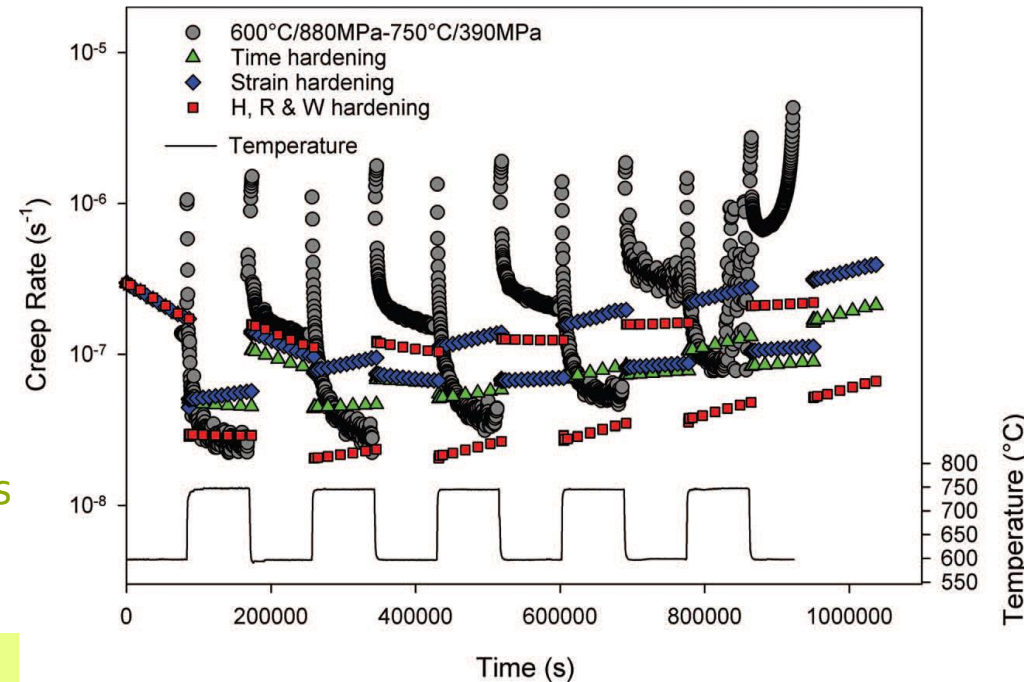


Waspaloy

Harrison et al. in
Tanski · 2018
IntechOpen

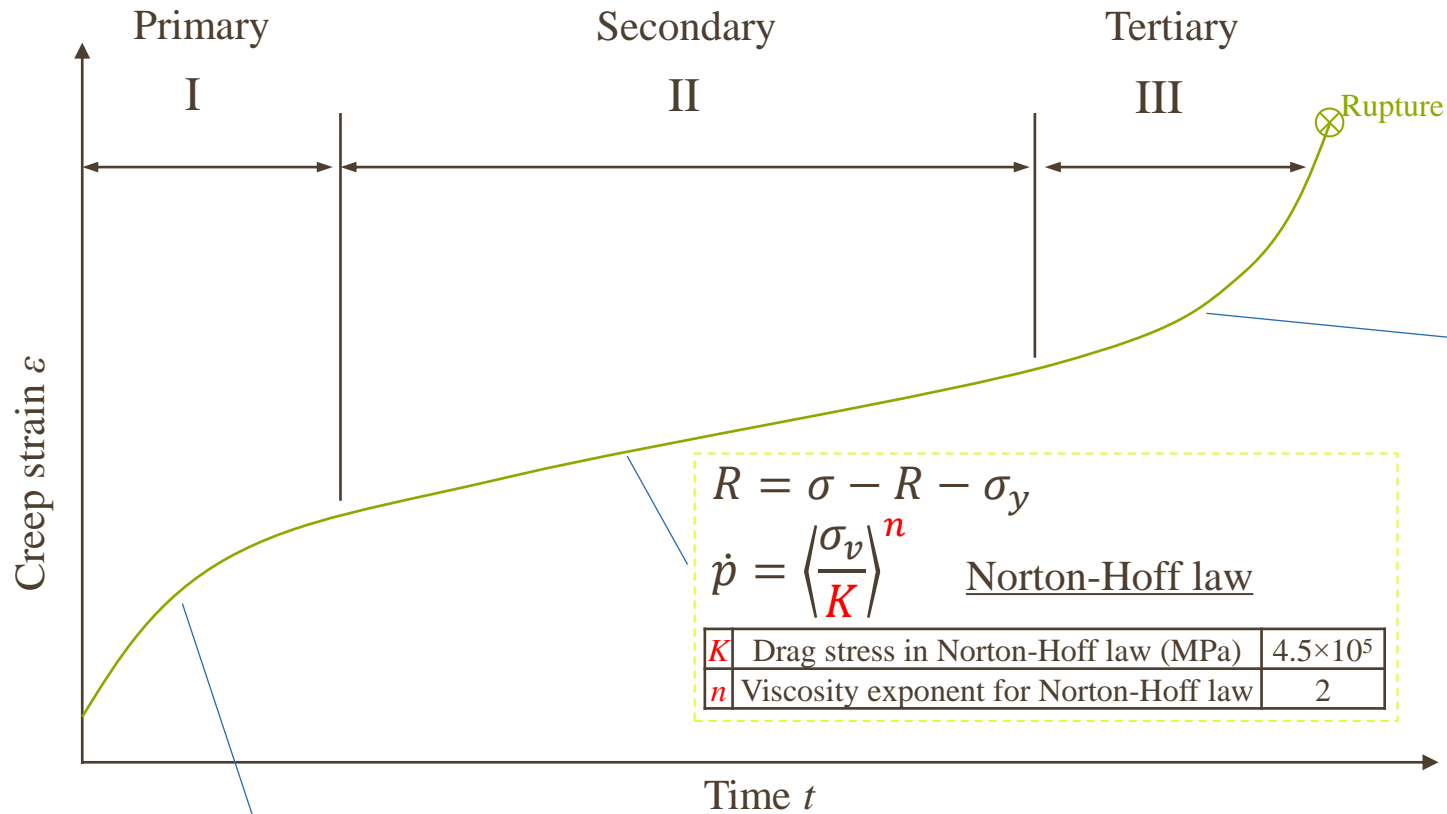
Model
predictions
still far ..

Model Prediction (Experiment in grey)



Elasto-visco-plastic creep damage model

Helene Morch [ULiege Ph.D. 2022 Walloon Region project], Norton type + damage



Isotropic hardening

$$R = Q(1 - e^{-b\dot{p}})$$

b	Rate of isotropic hardening	104
Q	Total isotropic saturation size of the yield surface	100

OPTIM
+ Manual identification

Elasticity

T	Temperature (C°)	550
E	Young's modulus (MPa)	1.7×10^5
ν	Poisson's Ratio	0.3

Damage: Rabotnov-Kachanov equation:

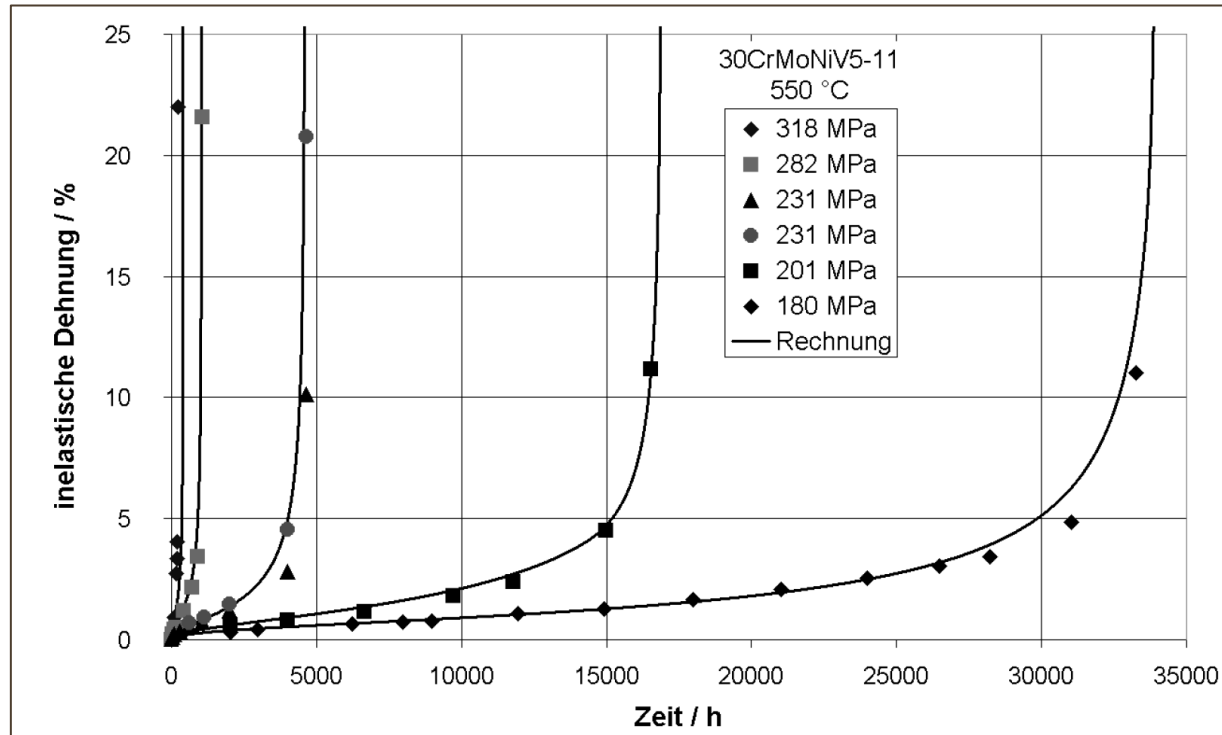
$$\dot{D}_c = k_3 \left(\frac{Y(\sigma^d * k_4)}{S_c} \right)^{s_c} \frac{1}{(1 - D)^k}$$

h	Mico-defects closure parameter	0.2
D_{crit}	Critical damage value (<1)	0.99
τ	Specific time for the appearance of creep	1×10^5
k_3	Global safety coefficient on creep damage	1
k_4	Safety coefficient applied to stress level on creep damage	1
S_c	Creep damage parameter	38.00
s_c	Creep damage exponent	3.50
k_c	Kachanov creep damage exponent	4.00

Law identified for 30CrMoNiV5-11



Used Creep curves from literature for 30CrMoNiV5-11



Schemmel J. Beschreibung des Verformungs-, 2003.

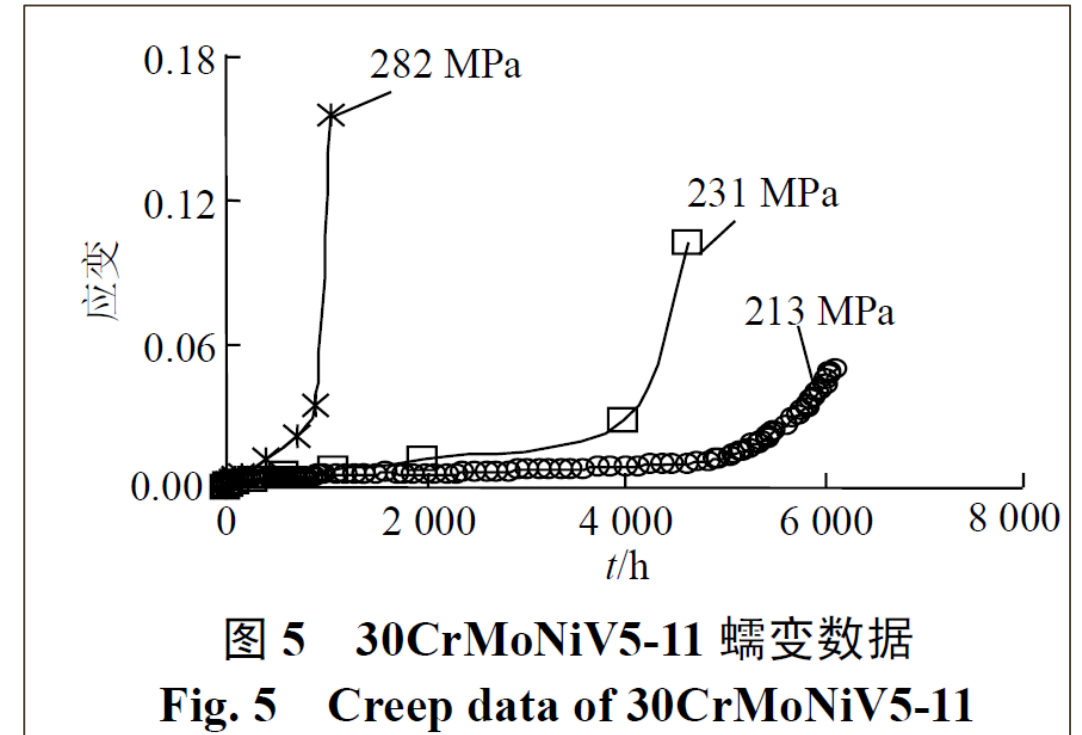
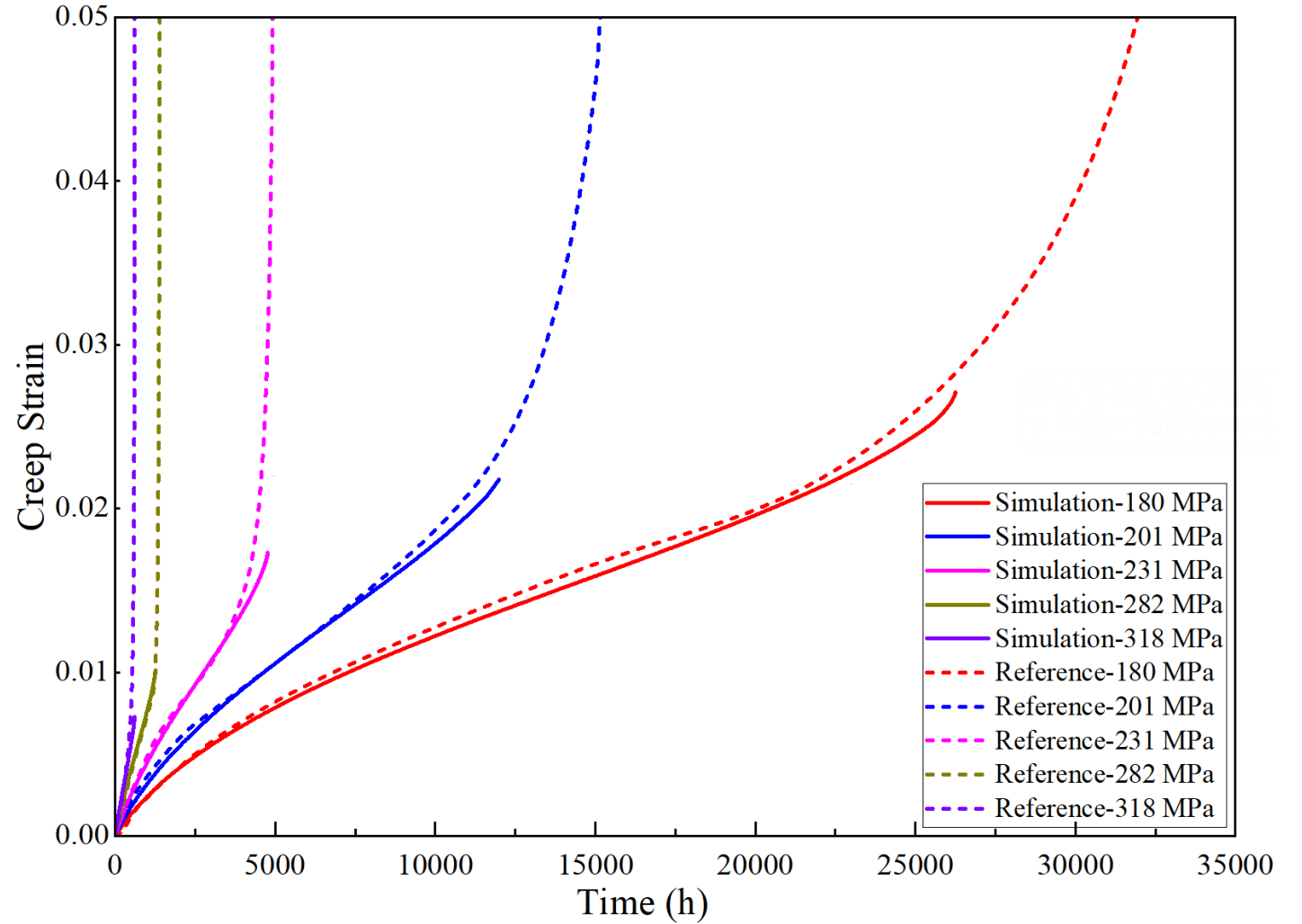
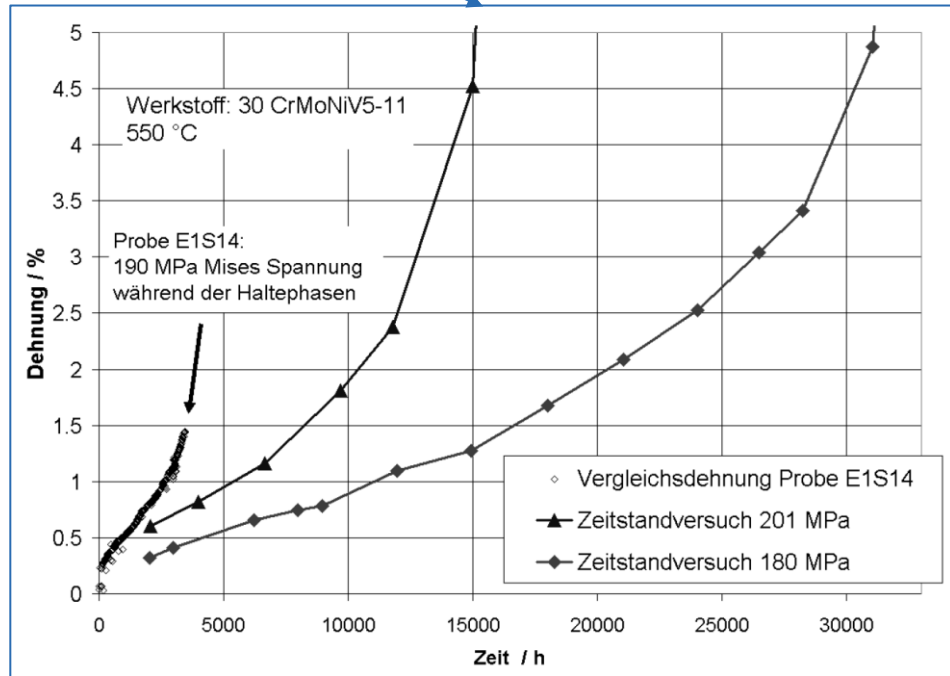
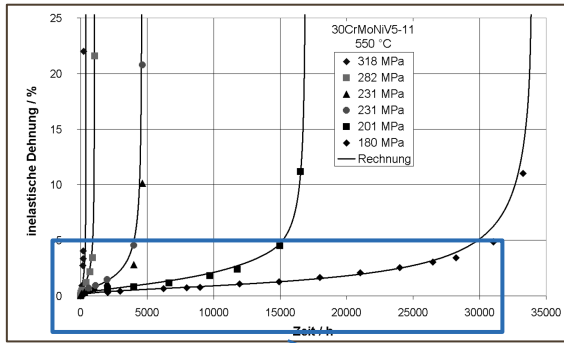


图 5 30CrMoNiV5-11 蠕变数据
Fig. 5 Creep data of 30CrMoNiV5-11

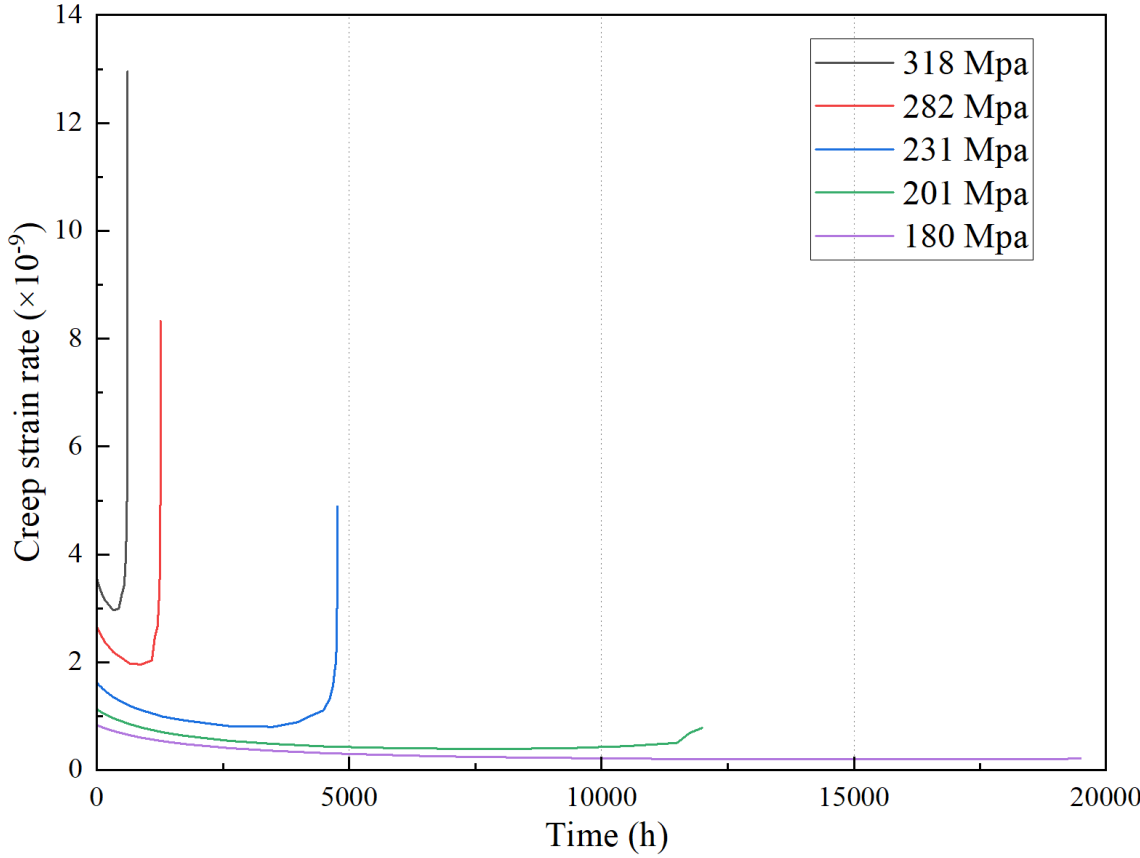
徐鸿,倪永中,王树东. 中国电机工程学报,2009,29(32):88-91.

Single element test (performed by ULiege Lagamine)

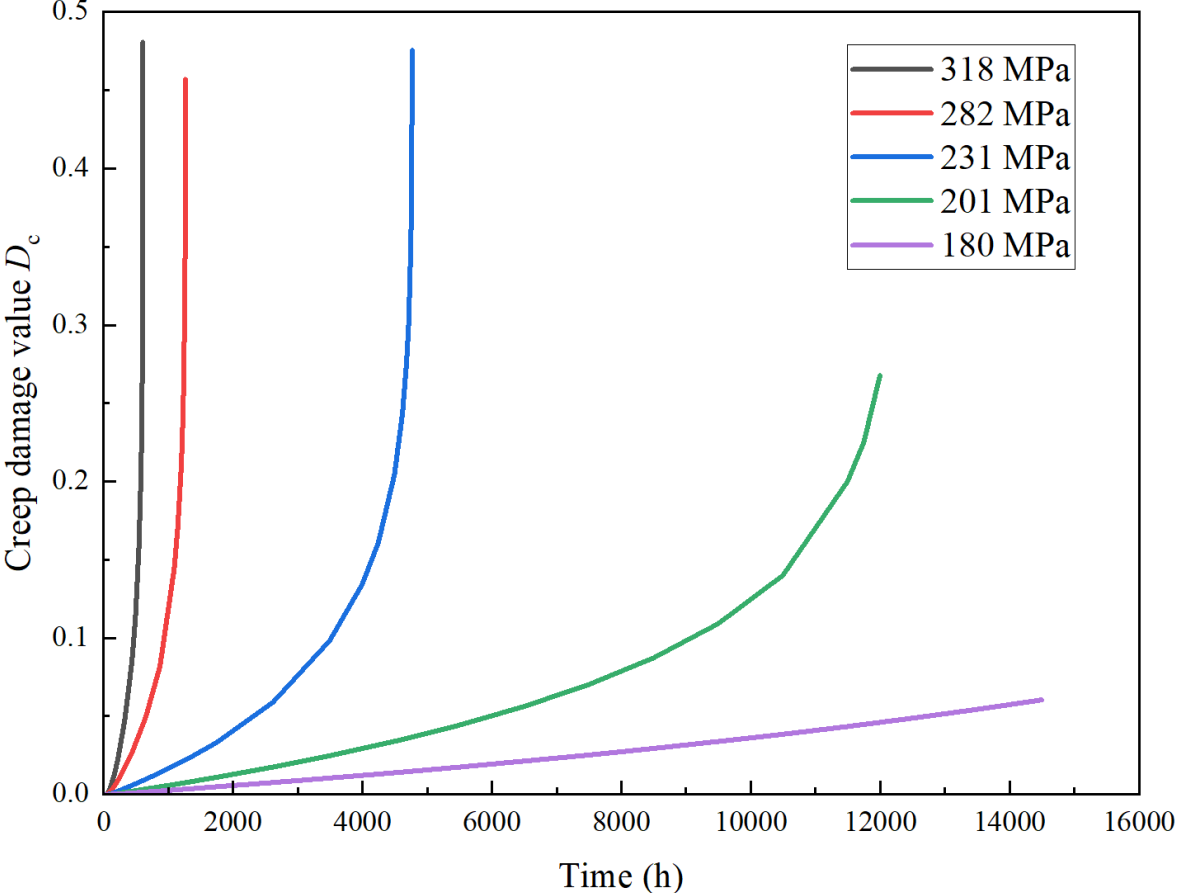


Single element test (Creep strain rate & Damage value-time)

Creep strain rate



Creep damage value



(performed by ULiege Lagamine)

$$\tilde{\sigma} = \frac{\sigma}{1 - hD}$$

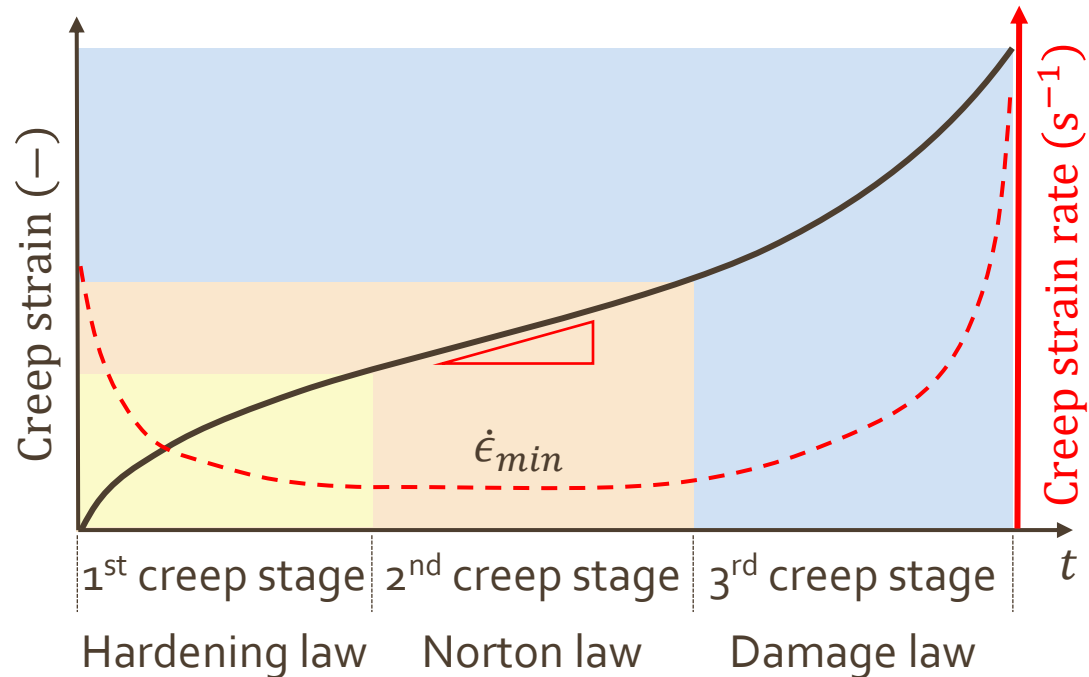
- Microdefects closure h
- Creep damage D

Creep modeling issues with Norton type law

Norton viscosity function

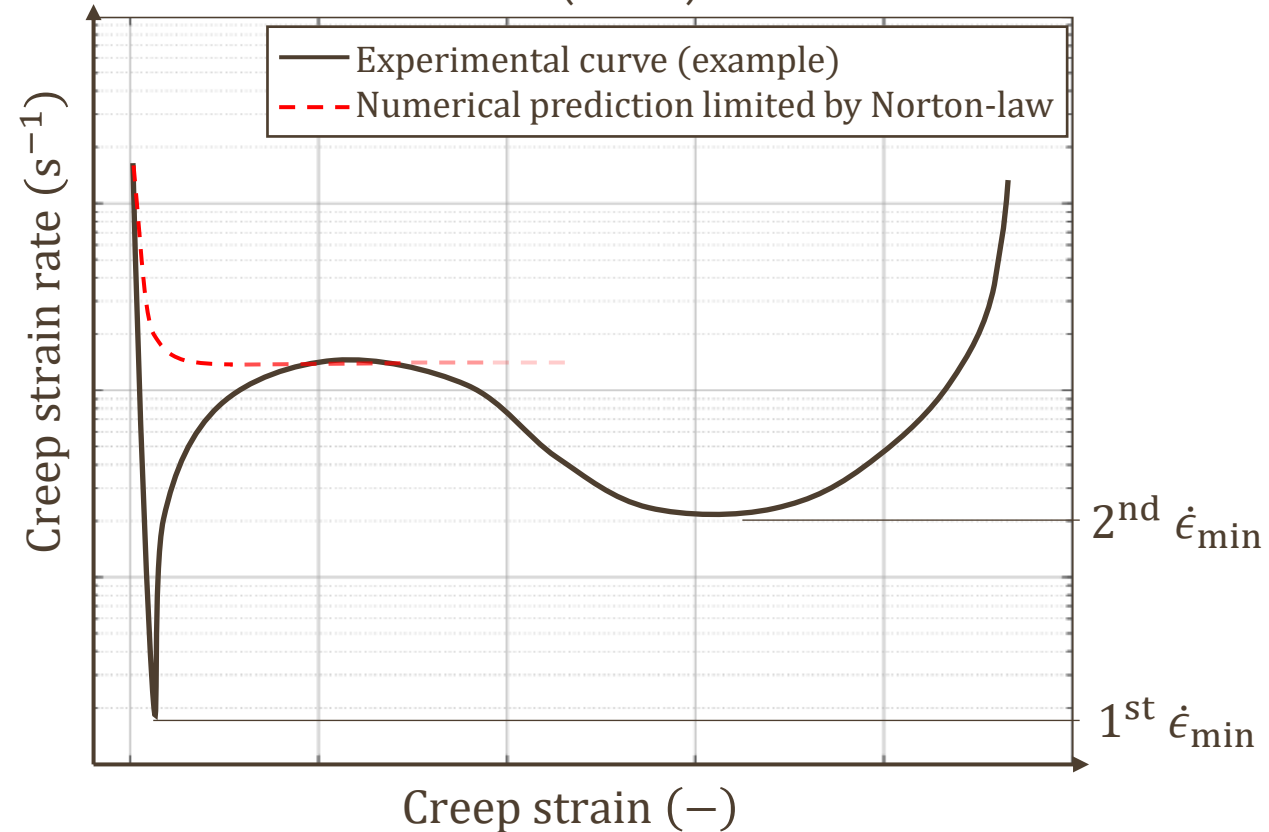
$$\dot{p} = \left\langle \frac{\sigma_v}{K} \right\rangle^n$$

OK for classic creep behavior:



~~OK~~ for materials with non-classical creep

Non-classical creep response: 2-step creep rate minima (800H)



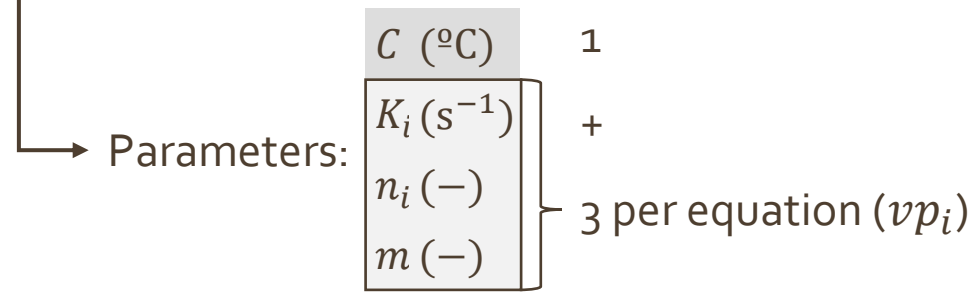
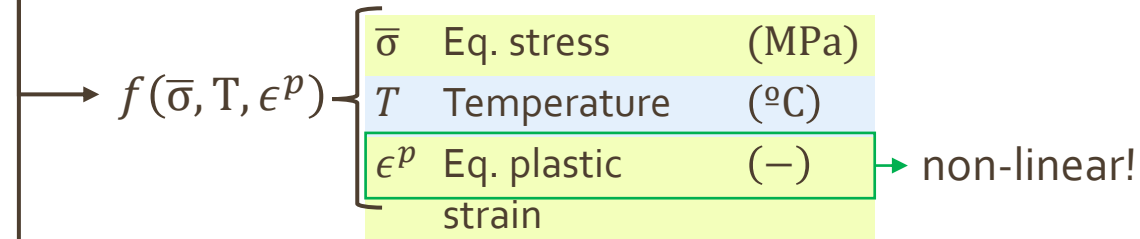
*: Experimental curves after (V. Gutmann & R. Bürgel, 1983)

Graham-Walles viscosity function

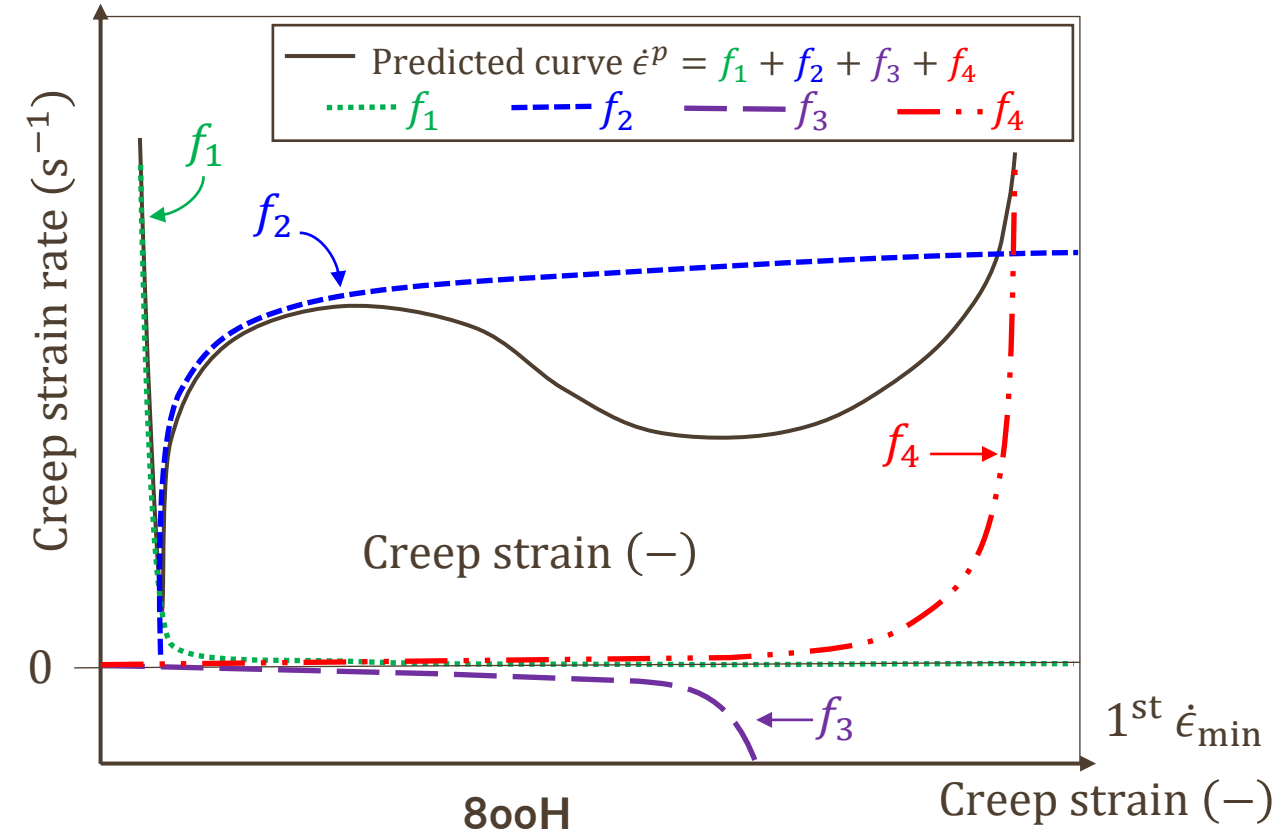
→ higher flexibility

Non-conventional approach, addition of i functions, implemented in Lagamine FE code

$$\dot{\epsilon}^p = \sum_{i=1}^{vp_i} K_i \exp\left(\frac{T}{C}\right) [\bar{\sigma}]^{n_i} (\epsilon^p)^{m_i}$$



Possible to model non-classical creep response:
2-step creep rate minima



Graham-Walles viscosity function

$$\dot{\epsilon}^p = \sum_{i=1}^{vp_i} K_i \exp\left(\frac{T}{C}\right) (\bar{\sigma})^{n_i} (\epsilon^p)^{m_i}$$

$f(\bar{\sigma}, T, \epsilon^p)$

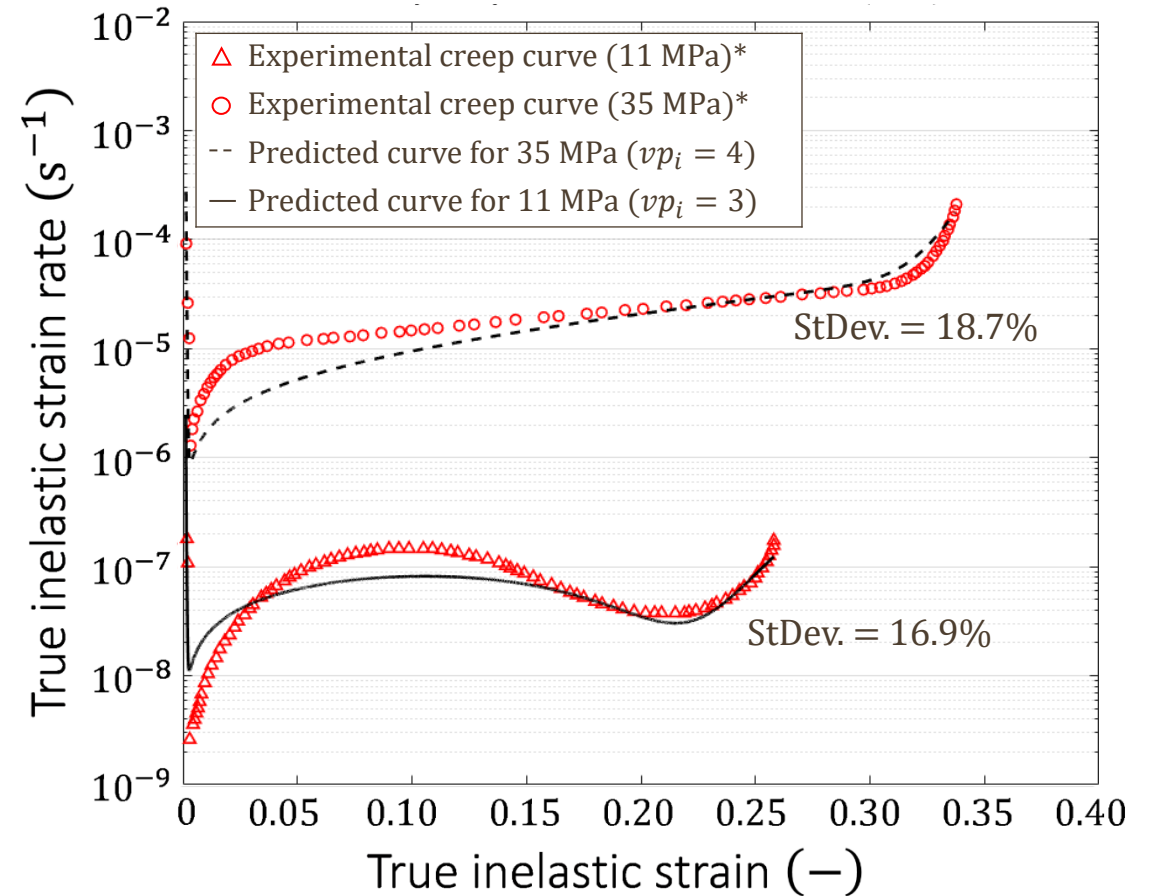
$\bar{\sigma}$	Eq. stress	(MPa)
T	Temperature	(°C)
ϵ^p	Eq. plastic strain	(-)

→ non-linear!

Parameters:

C (°C)	1
K_i (s ⁻¹)	+
n_i (-)	3 per equation (vp_i)
m_i (-)	

Case study: creep response of 800H alloy at 1000°C

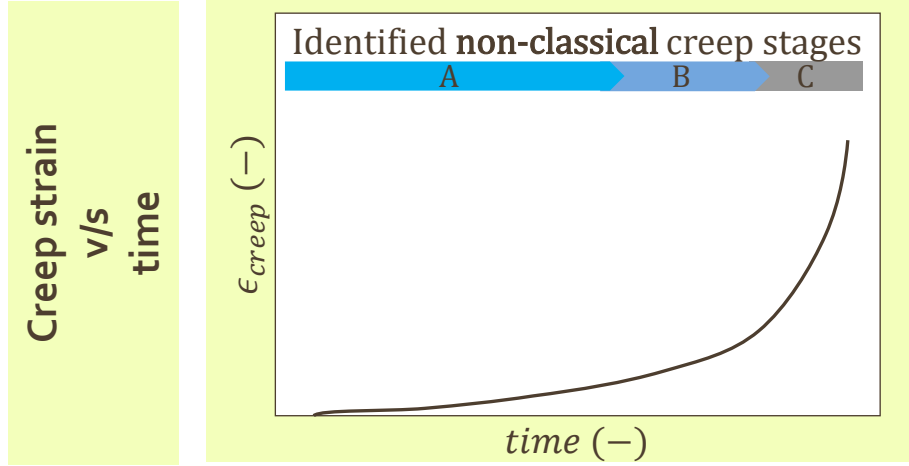


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- **AID4Greenest** EU project ...

Classical curve (low microstructure evolution)



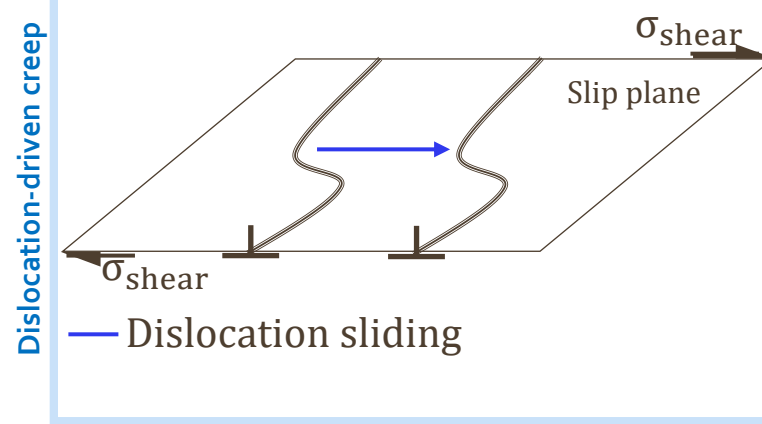
Time effect

A

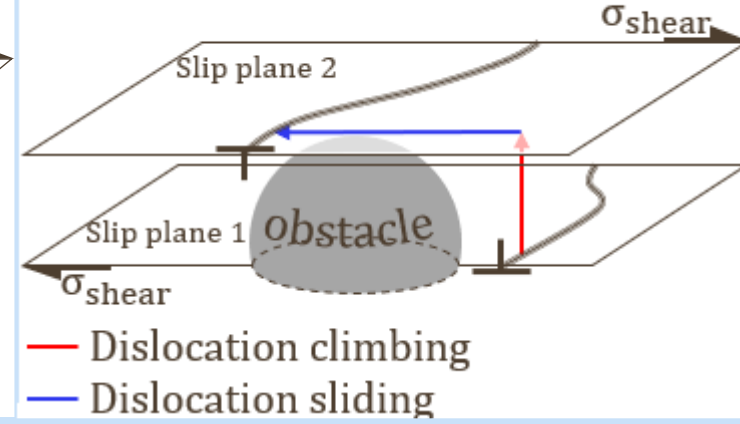
B

Creep mechanisms

Low tp° and high stress (1)

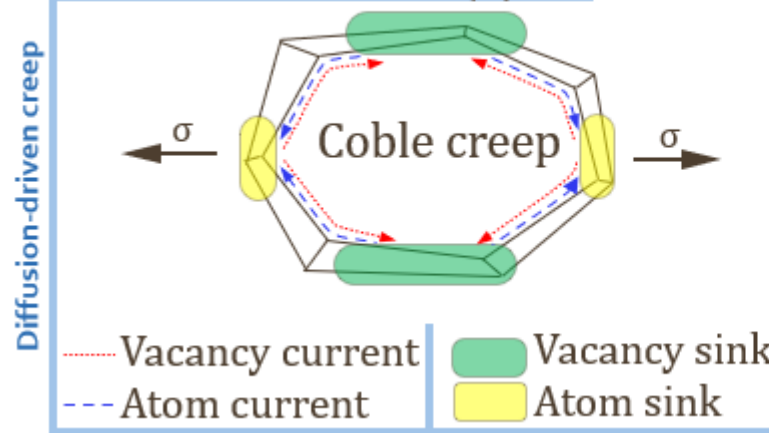


High tp° high stress (2)

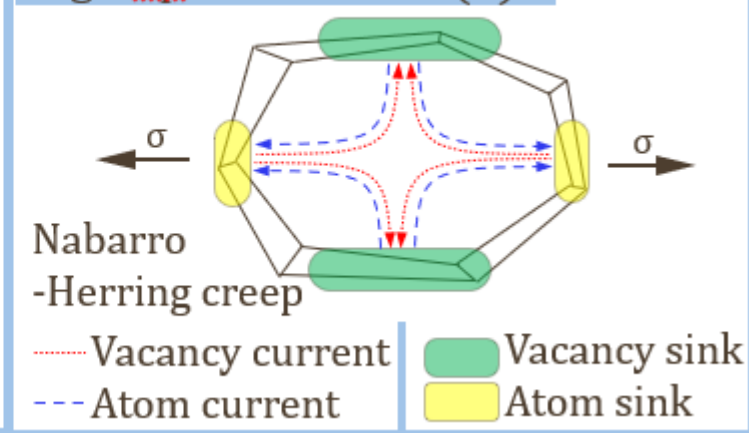


Dislocation glide, shearing or looping around obstacles, are freed by vacancy diffusion \rightarrow generation intra granular deformation

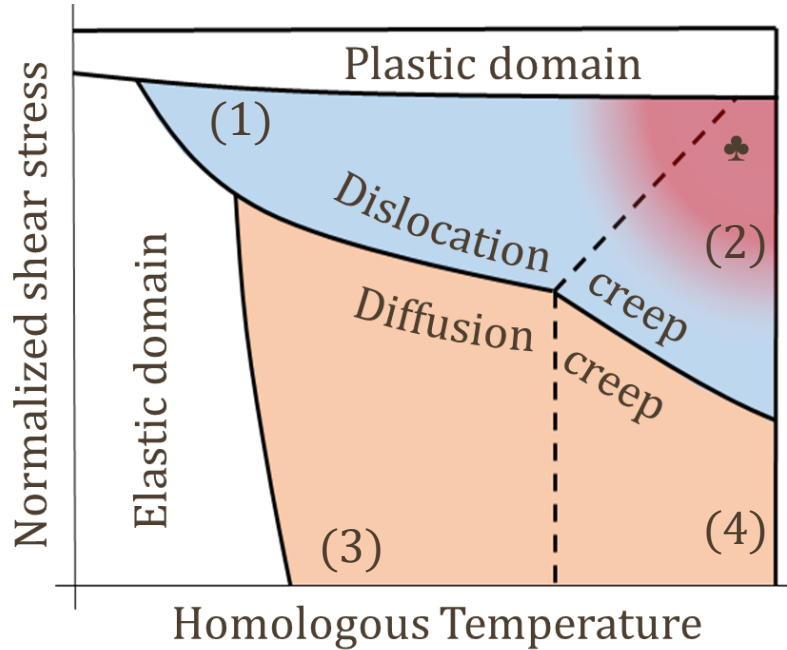
Low tp° low stress (3)



High tp° Low stress (4)



Diffusion : along GB inside the grain \rightarrow GB sliding



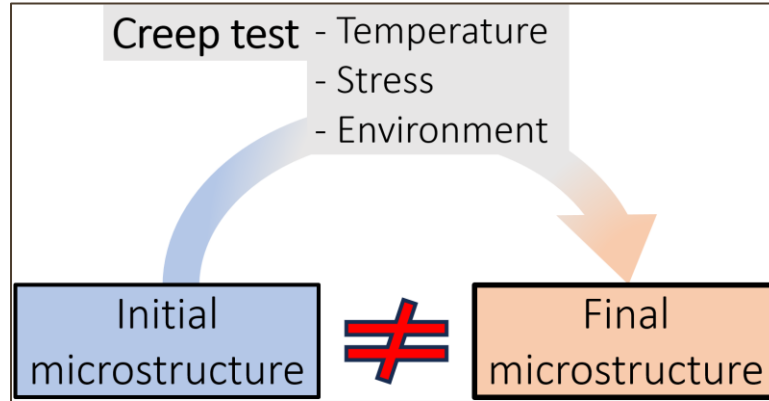
♣: Dynamic recrystallization (DRX)

Semi-physical creep model → macro FE Coupled approach ?

(S. Mesarovic et al., Springer, 2019)

Creep properties of materials depend on:

- **Permanent** microstructural features
- **Evolving** microstructural features



Accurate creep modeling requires microstructure evolution
Orowan equation to link macro strain and microstructure

$$\dot{\epsilon} = \frac{\rho b v_g}{M}$$

$\dot{\epsilon}$	Creep rate	(s ⁻¹)
ρ	Dislocation density	(m ⁻²)
b	Burger's vector	(m)
v_g	Dislocation glide velocity	(ms ⁻¹)
M	Taylor factor	(-)

	Semi-physical	Phenomenological
• Deterministic	• Statistical	• Empirical
• Nano-scale	• Meso-scale	• Macro-scale
• Complex	• Moderate	• Simplified

A Macro law (used in macro FE simulations)

T, \dot{T}, σ or ϵ loading, q state variables
→ $\dot{\epsilon}$ or $\dot{\sigma}$, updated q state variables

→ Macro law identified through predicted creep curves computed by a creep Meso-scale model

OR

→ Macro law sequentially or continuously updated based on state variable(s) kinetic of reflecting microstructure state computed

- from a set of equations
- from interpolation within in a data base
- from a meso or nano model (phase-field...)

OR

-multi scale ...

Semi-physical creep modeling approach

N.M. Ghoniem et al., 1990 → a comprehensive mean-field model

5 co-dependent non-linear equations.

Each = specific microstructural feature involved in the creep mechanism.

$\dot{\epsilon} = \frac{\rho_m b v_g}{M}$	Creep strain rate
$\dot{\rho}_m = v_g \left[\rho_m^{3/2} + \frac{\beta \rho_s R_{sb}}{h_b^2} - \frac{\rho_m}{2R_{sb}} - \delta_a (\rho_m^2 - \rho_m \rho_s) \right] - 8 \rho_m^{3/2} v_{cm}$	Mobile dislocation density
$\dot{\rho}_s = v_g \left[\frac{\rho_m}{2R_{sb}} - \delta_a \rho_m \rho_s \right] - 8 \frac{\rho_s}{h_b} v_c$	Static (dipole) dislocation density
$\dot{\rho}_b = 8(1 - 2\zeta) \frac{\rho_s}{h_b} v_c - \frac{\rho_b}{R_{sb}} M_{sb} \left[P_{sb} - 2\pi \left(\sum_i r_{p_i}^2 \cdot N_{p_i} \right) \gamma_{sb} \right]$	Boundary dislocation density
$\dot{R}_{sb} = M_{sb} \left[P_{sb} - 2\pi \left(\sum_i r_{p_i}^2 \cdot N_{p_i} \right) \gamma_{sb} \right] - \mu \eta_v K_c R_{sb} \left[(\rho_m + \rho_s)^{1/2} - \frac{K_c}{2R_{sb}} \right] \frac{\Omega D_s}{KT}$	Subgrain radius

Semi-physical creep modeling approach

N.M. Ghoniem et al., 1990 → a comprehensive mean-field model

5 co-dependent non-linear equations.

Each = specific microstructural feature involved in the creep mechanism.

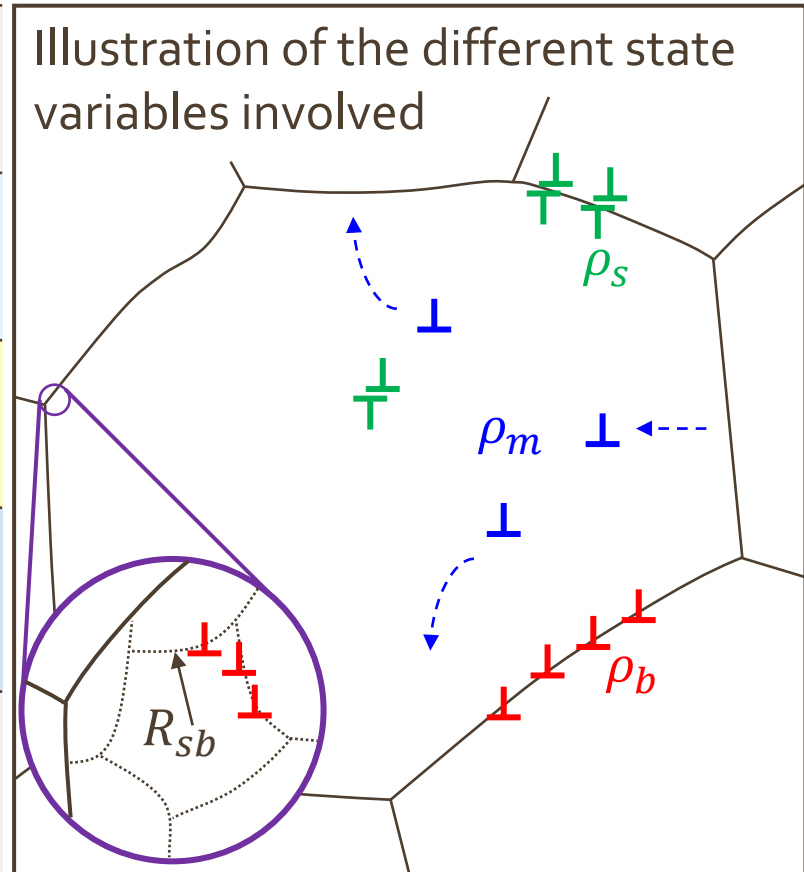
$$\dot{\epsilon} = \frac{\rho_m b v_g}{M}$$

$$\dot{\rho}_m = v_g \left[\rho_m^{3/2} + \frac{\beta \rho_s R_{sb}}{h_b^2} - \frac{\rho_m}{2R_{sb}} - \delta_a (\rho_m^2 - \rho_m \rho_s) \right] - 8 \rho_m^{3/2} v_{cm}$$

$$\dot{\rho}_s = v_g \left[\frac{\rho_m}{2R_{sb}} - \delta_a \rho_m \rho_s \right] - 8 \frac{\rho_s}{h_b} v_c$$

$$\dot{\rho}_b = 8(1 - 2\zeta) \frac{\rho_s}{h_b} v_c - \frac{\rho_b}{R_{sb}} M_{sb} \left[P_{sb} - 2\pi \left(\sum_i r_{p_i}^2 \cdot N_{p_i} \right) \gamma_{sb} \right]$$

$$\dot{R}_{sb} = M_{sb} \left[P_{sb} - 2\pi \left(\sum_i r_{p_i}^2 \cdot N_{p_i} \right) \gamma_{sb} \right] - \mu \eta_v K_c R_{sb} \left[(\rho_m + \rho_s)^{1/2} - \frac{K_c}{2R_{sb}} \right] \frac{\Omega D_s}{KT}$$



C. Rojas ULiege

Semi-physical creep modeling approach

N.M. Ghoniem et al., 1990 → a comprehensive mean-field model

5 co-dependent non-linear equations.

Each = specific microstructural feature involved in the creep mechanism.

$$\dot{\epsilon} = \frac{\rho_m b v_g}{M}$$

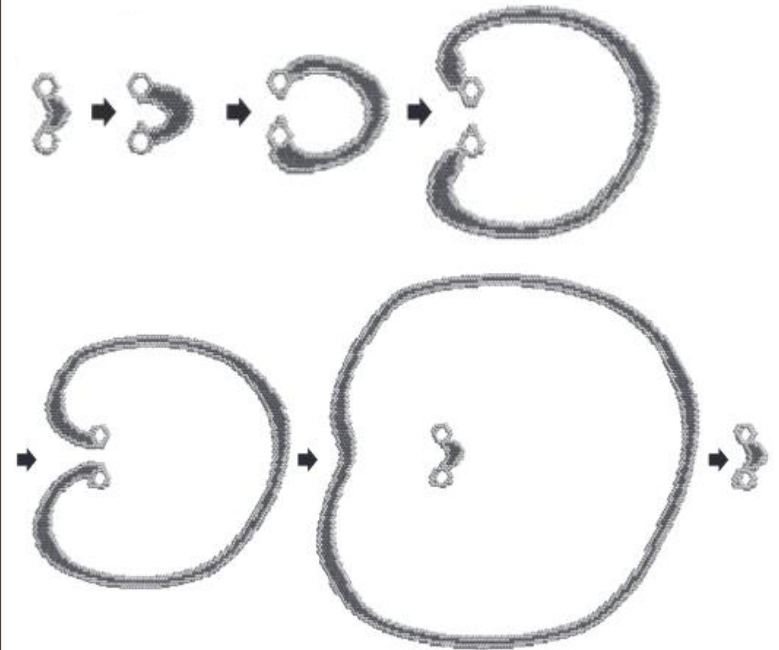
$$\dot{\rho}_m = v_g \left[\rho_m^{3/2} + \frac{\beta \rho_s R_{sb}}{h_b^2} - \frac{\rho_m}{2R_{sb}} - \delta_a (\rho_m^2 - \rho_m \rho_s) \right] - 8 \rho_m^{3/2} v_{cm}$$

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Frank-Read dislocation source



(T. Shimokawa & S. Kitada, 2014)

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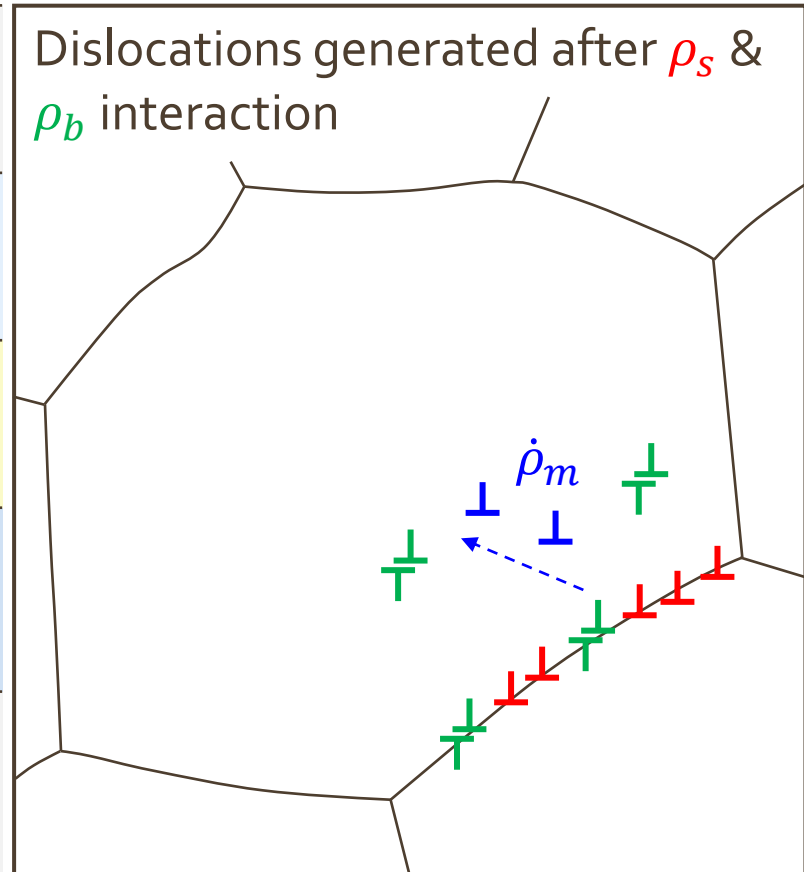
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C. Rojas ULiege

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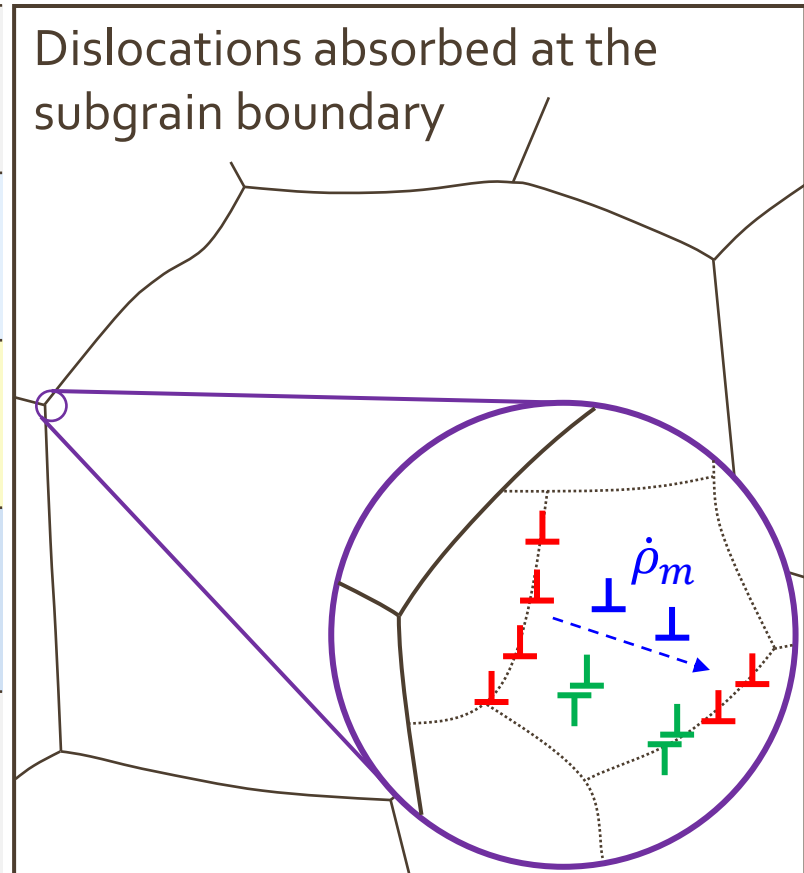
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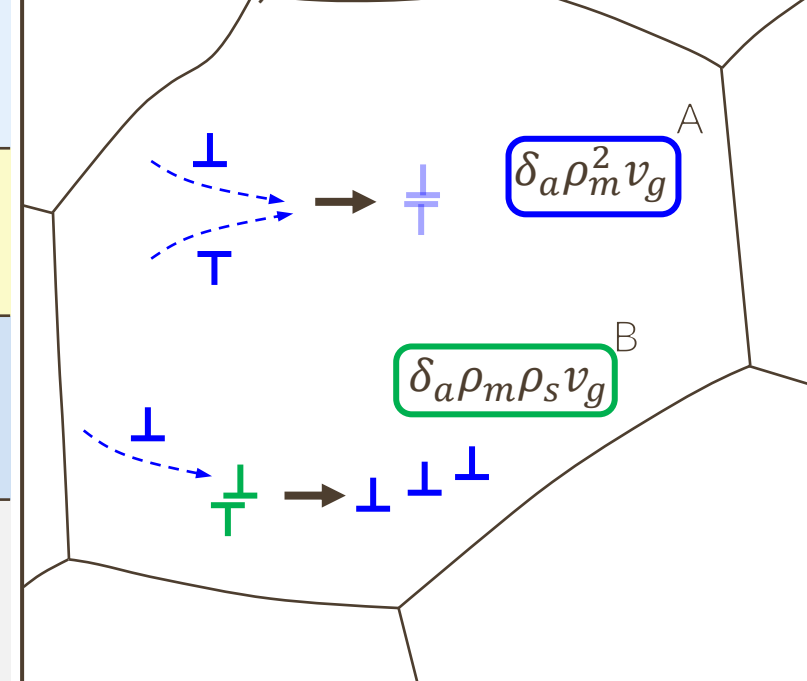
$$\dot{\rho}_m = v_g \left[\rho_m^{3/2} + \frac{\beta \rho_s R_{sb}}{h_b^2} - \frac{\rho_m}{2R_{sb}} - \delta_a(\rho_m^2)^A + \delta_a \rho_m \rho_s^B \right] - 8 \rho_m^{3/2} v_{cm}$$

$$\dot{\rho}_s = v_g \left[\frac{\rho_m}{2R_{sb}} - \delta_a \rho_m \rho_s^B \right] - 8 \frac{\rho_s}{h_b} v_c$$

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Dynamic recovery: Annihilation by **glide** ($\rho_m - \rho_m$ and $\rho_m - \rho_s$ interaction)



C. Rojas ULiege

Semi-physical creep modeling approach

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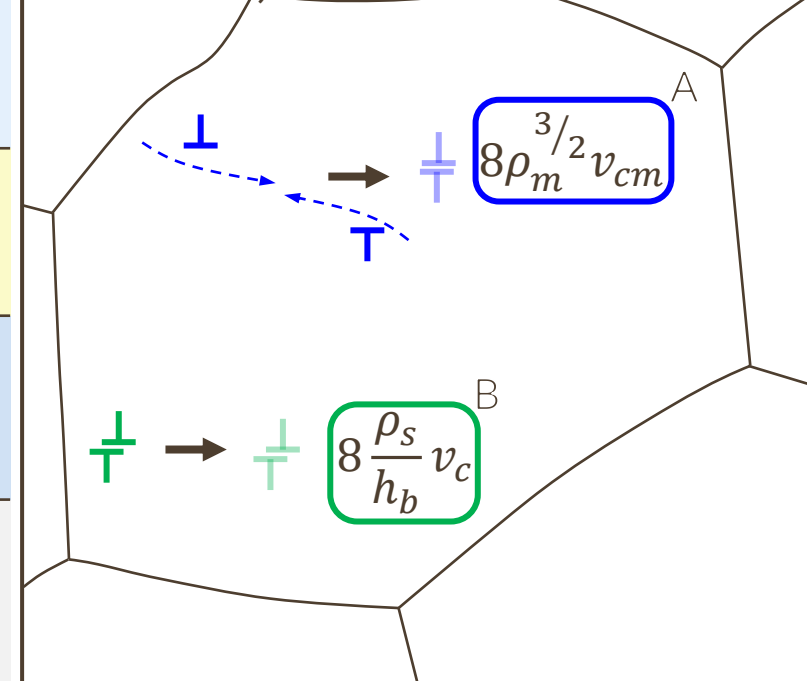
$$\dot{\rho}_m = v_g \left[\rho_m^{3/2} + \frac{\beta \rho_s R_{sb}}{h_b^2} - \frac{\rho_m}{2R_{sb}} - \delta_a (\rho_m^2 - \rho_m \rho_s) \right] - \boxed{8 \rho_m^{3/2} v_{cm}}^A$$

$$\dot{\rho}_s = v_g \left[\frac{\rho_m}{2R_{sb}} - \delta_a \rho_m \rho_s \right] - \boxed{8 \frac{\rho_s}{h_b} v_c}^B$$

$$\dot{\rho}_b = 8(1 - 2\zeta) \frac{\rho_s}{h_b} v_c - \frac{\rho_b}{R_{sb}} M_{sb} \left[P_{sb} - 2\pi \left(\sum_i r_{p_i}^2 \cdot N_{p_i} \right) \gamma_{sb} \right]$$

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Dynamic recovery: Annihilation by **climb** ($\rho_m - \rho_m$ and $\rho_s - \rho_s$ interaction)



C. Rojas ULiege

Semi-physical creep modeling approach

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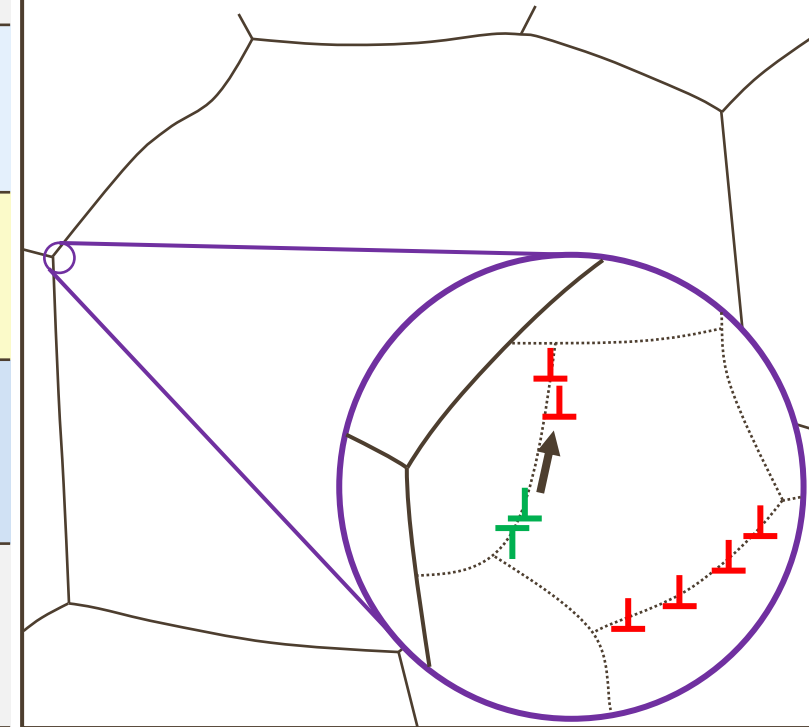
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Share of boundary dislocations produced after ρ_s



C. Rojas ULiege

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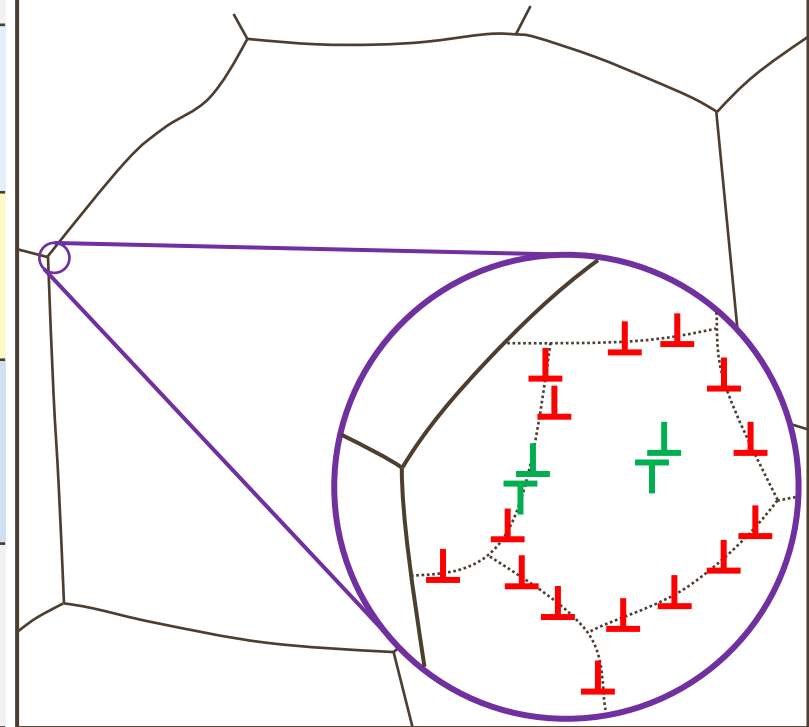
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Subgrain growth

Subgrain nucleation

Evolution of subgrains: growth and nucleation terms

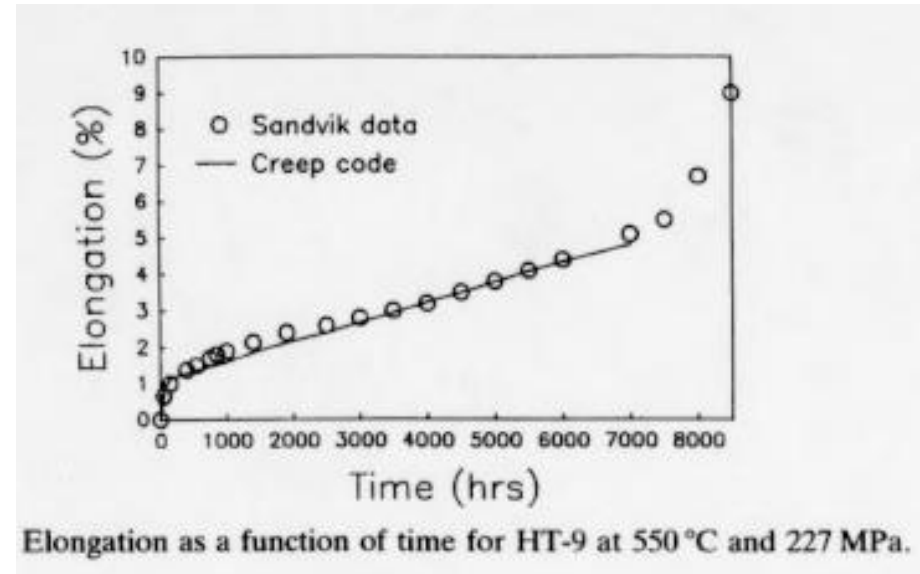


C. Rojas ULiege

Martensitic steel HT9 - Ghoniem model application

Creep curve predictions : validated

- Earlier stage I \rightarrow II transition point if $T \nearrow$
- $\dot{\epsilon}_m \propto \sigma^5$ (steel type forming dislocation cells)
- $T \nearrow \rightarrow \dot{\epsilon} \nearrow$ (recovery and glide velocity \nearrow)
- $\rho \nearrow$ with $\dot{\epsilon}$ until saturation

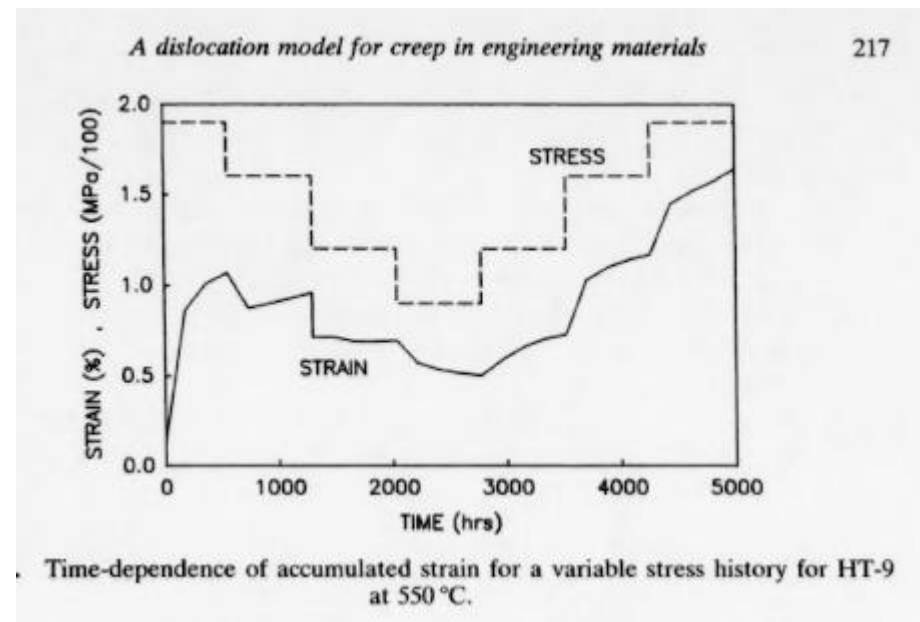


Strain related to stress history is logic

1st stress \searrow $\dot{\epsilon}$ \searrow than \nearrow

Effective stress applied on dislocation \searrow $\dot{\epsilon}$ \searrow

ρ , internal stress readjust, threshold is again reached $\dot{\epsilon} \nearrow$



Semi-physical creep modeling approach

Accommodation of more particles (MX and $M_{23}C_6$) phase effects,
 New functions for Cavitation damage (D_{cav}) **and** precipitate coarsening (D_{ppt})

$$\dot{\epsilon} = \frac{\rho_m b v_g}{M(1 - D_{ppt})(1 - D_{cav})}$$

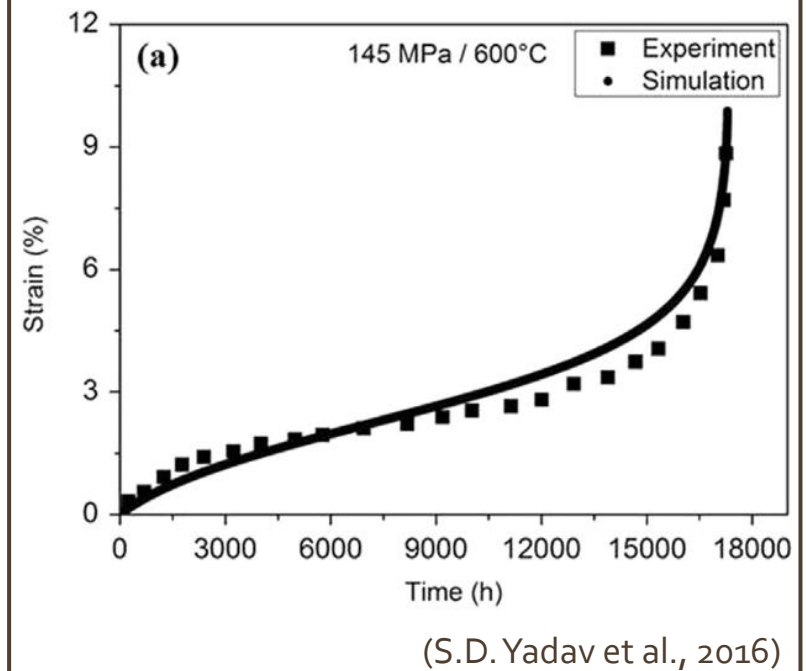
$$\dot{\rho}_m = v_g \left[\rho_m^{3/2} + \frac{\beta \rho_s R_{sb}}{h_b^2} - \frac{\rho_m}{2R_{sb}} - \delta_a (\rho_m^2 - \rho_m \rho_s) \right] - 8 \rho_m^{3/2} v_{cm}$$

$$\dot{\rho}_s = v_g \left[\frac{\rho_m}{2R_{sb}} - \delta_a \rho_m \rho_s \right] - 8 \frac{\rho_s}{h_b} v_c$$

$$\dot{\rho}_b = 8(1 - 2\zeta) \frac{\rho_s}{h_b} v_c - \frac{\rho_b}{R_{sb}} M_{sb} \left[P_{sb} - 2\pi \left(\sum_i r_{p_i}^2 \cdot N_{p_i} \right) \gamma_{sb} \right]$$

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Application on P92 tempered martensitic steel



Semi-physical creep modeling approach

Addition of effective velocity (v_{eff}) calculated as the sum of glide + climb velocity contributions

$$\dot{\epsilon} = \frac{\rho_m b v_{eff}}{M(1 - D_{ppt})(1 - D_{cav})}$$

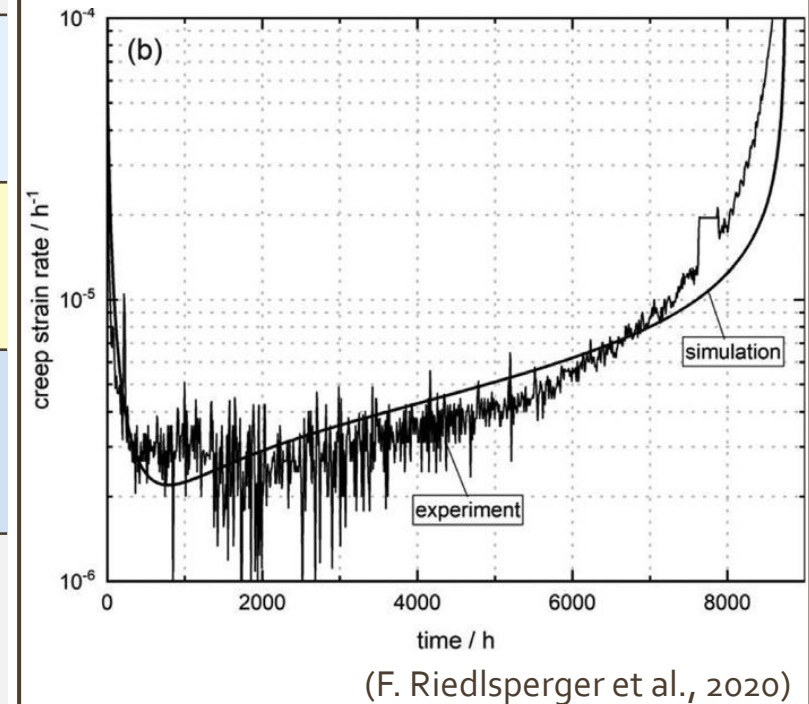
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Application on P91 austenitic-martensitic steel



Semi-physical creep modeling approach

The base model is modified to include more complex intragranular precipitate-dislocation interaction terms, and a **diffusional creep rate term**

$$\dot{\epsilon}_{disl} = \frac{\rho_m b v_g}{M(1 - D_{cav})}$$

$$\dot{\epsilon}_{diff} = A_c \frac{D_{gb} \delta_{gb} \sigma_{app} \Omega}{8R_{sb}^3 K_B T}$$

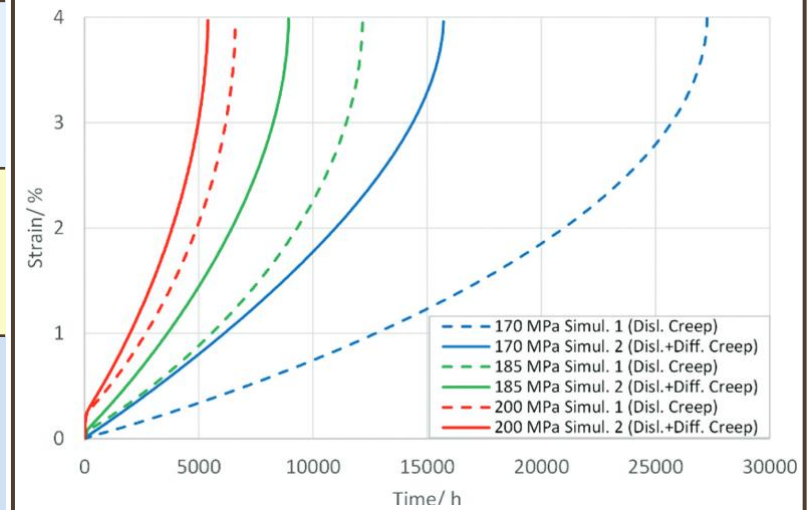
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Application on A617 Ni-based alloy



(F. Riedlsperger et al., 2023)

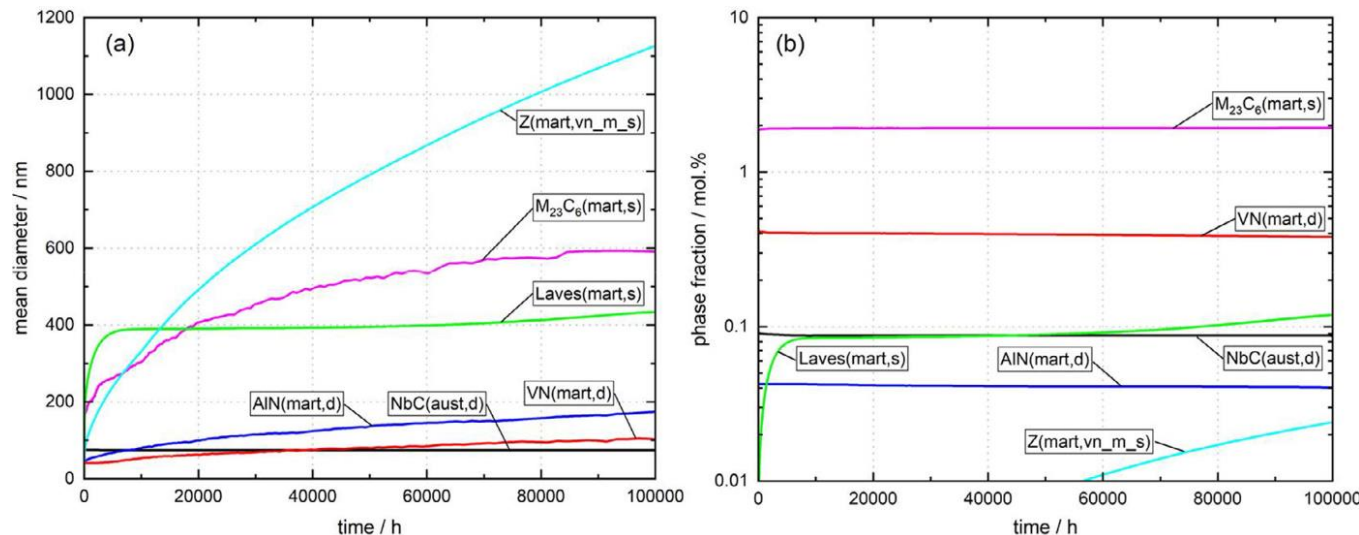
Semi-physical creep modeling approach

Knowledge on the microstructure evolution is mandatory

- Thermodynamic simulations
- Microstructure characterization after (interrupted) tests to validate **precipitate state and kinetic**

- Phase fraction (mol. %)
- Mean diameter (m)
- Nucleation site (dislocation paths, intra- or intergranular,...)?

MatCalc simulations performed for P91 steel



after (F. Riedlsperger et al., 2020)

microstructure evolution by 4 physical variables:

ρ_m	Mobile dislocation density	(m ⁻²)
ρ_s	Static dislocation density	(m ⁻²)
ρ_b	Dynamic dislocation density	(m ⁻²)
R_{sgb}	Sub-grain radius	(m)

creep behavior ($\dot{\epsilon}$) is conditioned by their:

- Growth
- Production
- Annihilation
- Transformation

X. Wu law (Grain Boundary + Intragrain events)

Based on strain decomposition
1 D approach

$$\varepsilon = \left(\frac{\sigma}{E} + \varepsilon_p \right) + \varepsilon_{gbs} + \varepsilon_v$$

Elasticity

GB sliding, dislocation slip and climb in presence of precipitates in GB
Creep stage I and II

Dislocation climb and multiplication, intragranular deformation
Creep State III

$$\varepsilon_v = \frac{1}{M} [\exp(M\dot{\varepsilon}_i t) - 1]$$

"M dislocation multiplier factor?"
→ Taylor factor

Plasticity law for instance

$$\varepsilon_p = K \left(\frac{\sigma}{E} \right)^n$$

$$\varepsilon_{gbs} = \varepsilon_0 + \phi \dot{\varepsilon}_{ss} t + \frac{\sigma}{\beta^2 H_{obs}} \left[1 - \exp \left(- \frac{\beta^2 \phi H_{gbs} \dot{\varepsilon}_{ss} t}{\sigma(\beta - 1)} \right) \right]$$

$$\dot{\varepsilon}_{ss} = \phi(1 - \beta^{-1}) \frac{D\mu b}{kT} \left(\frac{b}{d} \right)^q \left(\frac{l+r}{b} \right)^{q-1} \frac{\sigma(\sigma - \sigma_{ic})}{\mu^2}$$

Each eq. is related to dislocation genesis and movement

β microstructure param

D diffusion constant

b Burgers vector

μ shear modulus

r grain boundary precipitate size,

q GB precipitate distribution (1 none, 2 discrete, 3 continuous)

p stress exponent for GB sliding

Φ shape factor of GB

σ_{ic} threshold value

σ

d grain size

k Boltzman constant

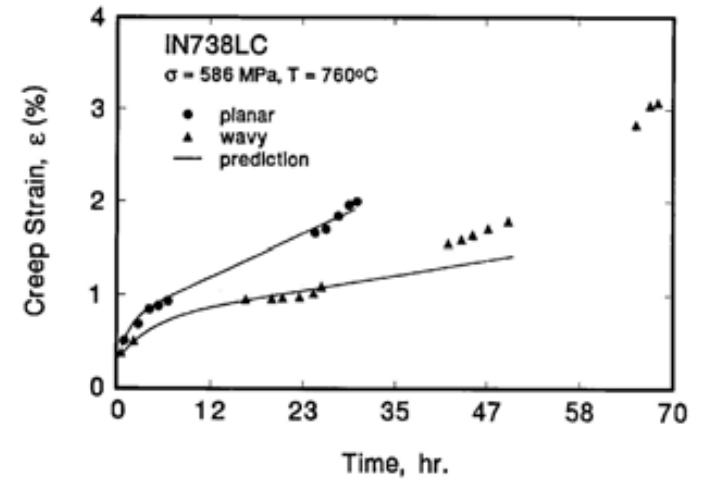
H_{gbs} GB hardening coeff

l grain boundary precipitate spacing

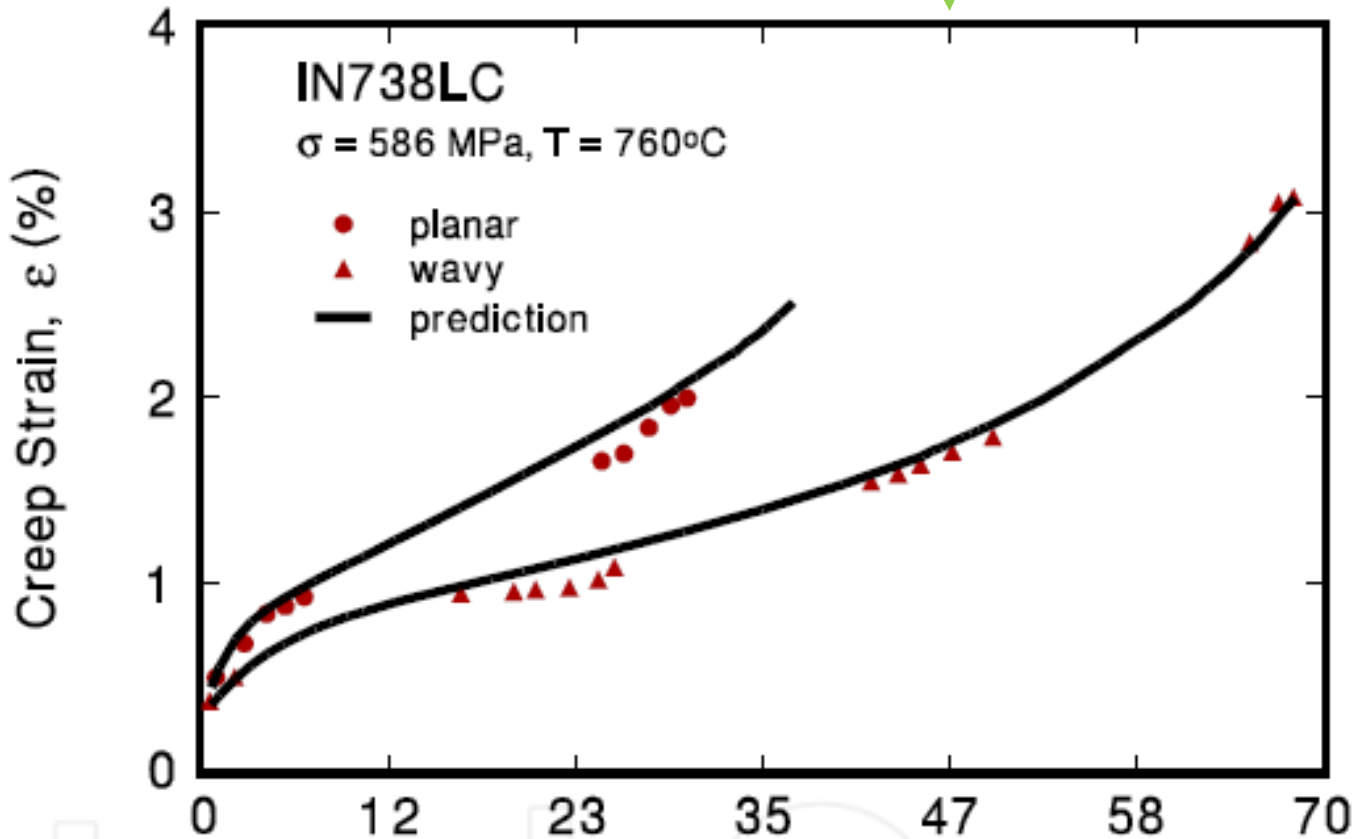
→ effective stress introduced

Application of X.Wu creep law

$$\epsilon = \left(\frac{\sigma}{E} + \epsilon_p \right) + \epsilon_{gbs} + \epsilon_v$$



1. Only GB effect



Wu, X.J. & Koul, A.K. (1996). Modelling creep in complex engineering alloys. In: *Creep and Stress Relaxation in Miniature Structures and Components*, pp. 3-19. The Metallurgical Society, Warrendale, PA.

2. GB effect + precipitate dislocation interaction intra granular

A lack according S. Wu: contribution of creep cavitation (Acta Mat 2022)

→ Deeper in creep mechanism understanding

Additive or Cast & Wrought Incoly 718 → ≠ creep behavior

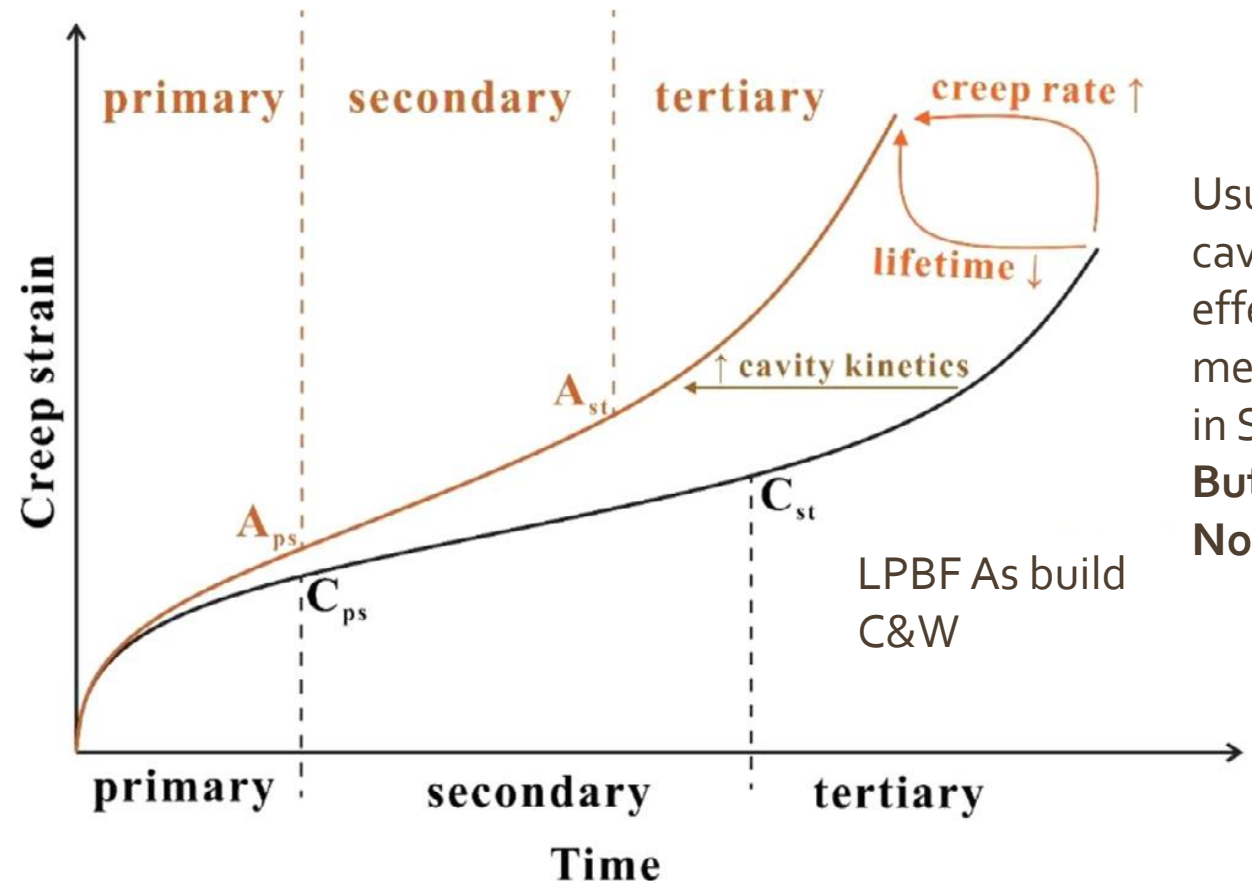
X. Wu, Kock-Mecking-Estrin...

OK for dislocation motion or grain boundary sliding
(if the cavitation kinetics slow)

If cavity density or formation is high,
→ + cavitation creep strain contribution

In AM materials

- High density of vacancies, high porosity
- Compositional inhomogeneity
- Grain anisotropy
- Out of equilibrium microstructure, so evolving with T and t

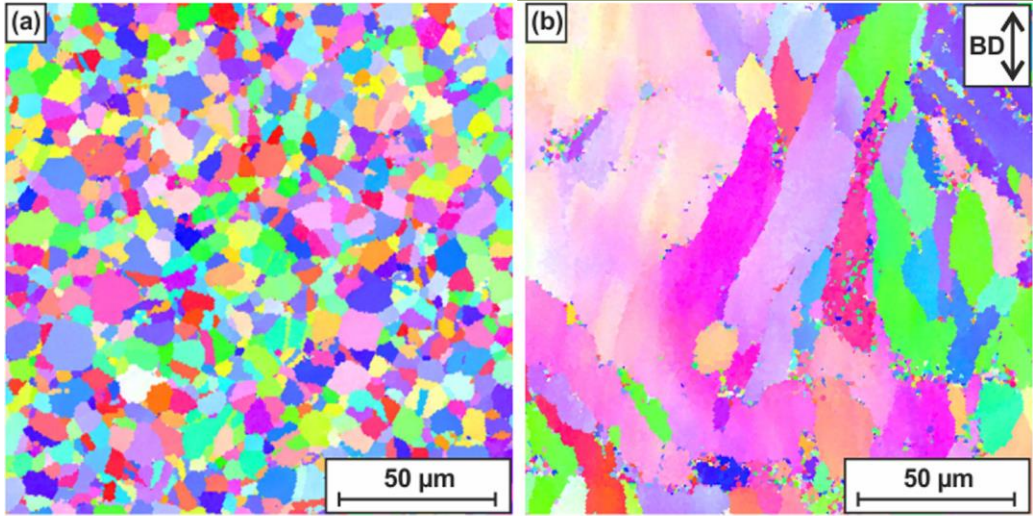


Creep behavior of heat treated Inconel 718 ? Which microstructure ?

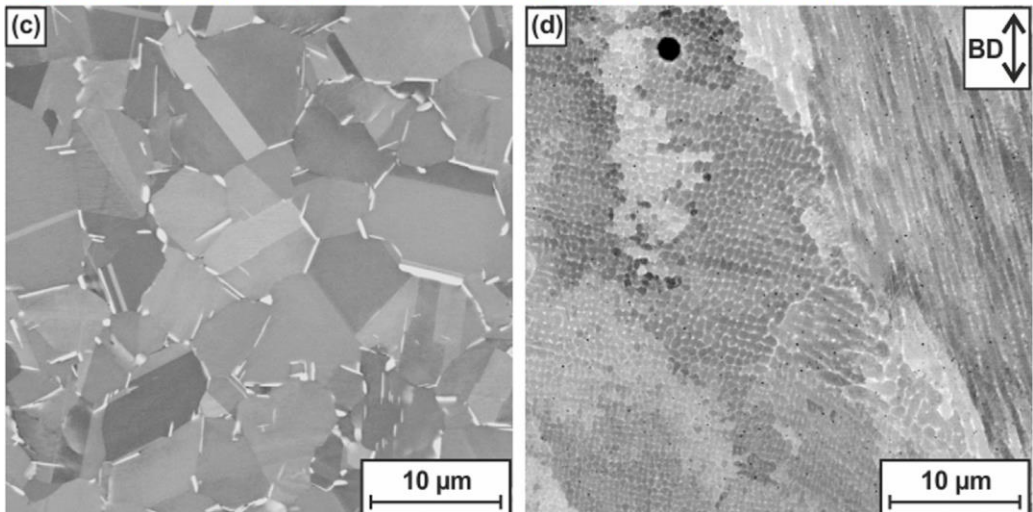
1st example

Cast & Forged (C&W)
+ 1.5h 980°C + Aging

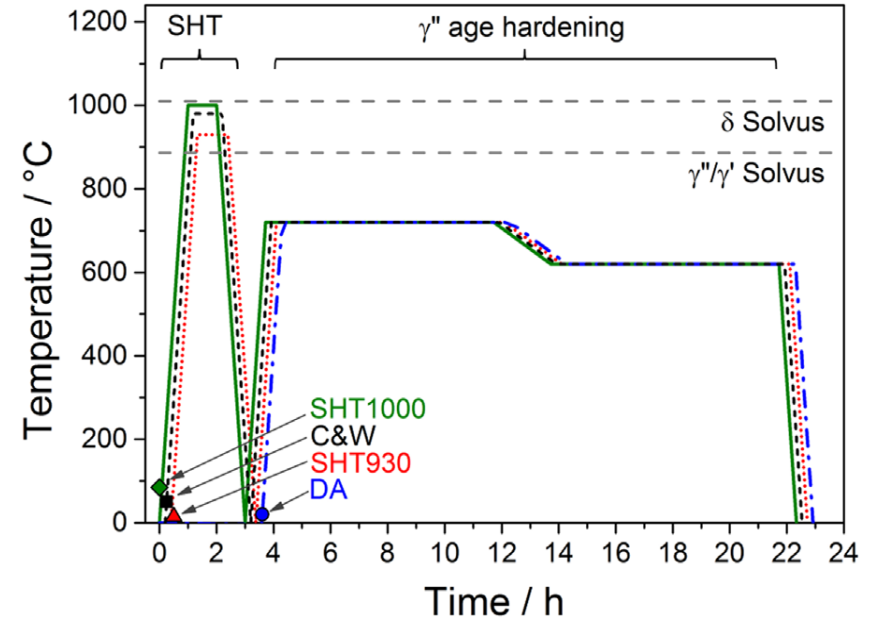
As built LPBF



Large grains (+ subgrains)
Up to 150 μm // building dir.
Up to 30 μm ⊥ building dir.



+



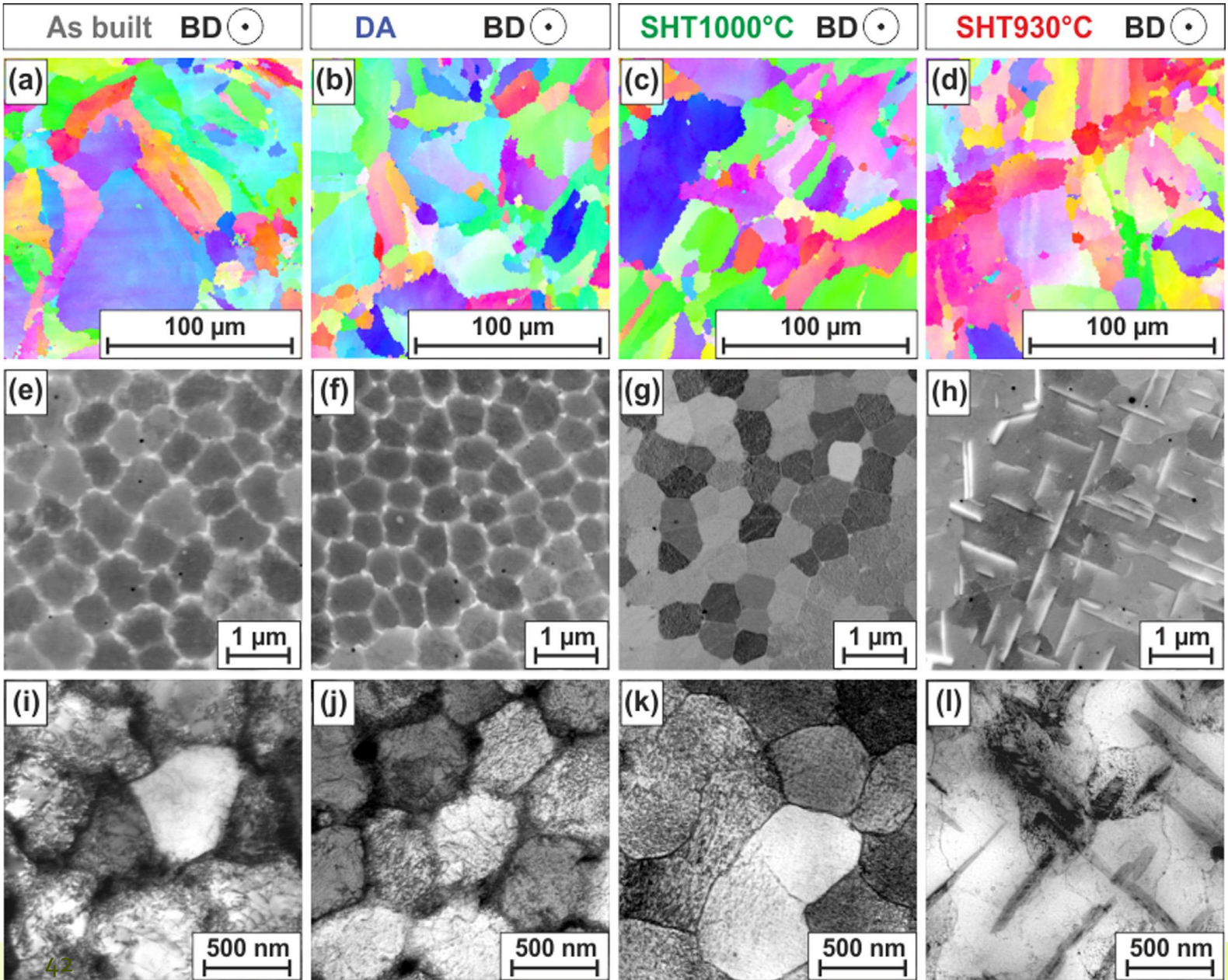
Fine dendrites
with spacing < 1 μm

(SHT Solution Heat Treatment)

Completely recrystallized
Average grain 7 μm

Plate light Bright δ
particules at GB
Formed during forging
3.5%

Inconel 718: Microstructures LPBF + heat treatment



No γ' γ''

AS built

Aged

γ' a lot

$\gamma'' \neq$
amount

SHT 1000°C
+ Aged

SHT 930°C
+ Aged

Interdendritic region
(rich in Nb) + Lave 14
+ High dislocation
density around subgrain
No δ

Nearly no δ

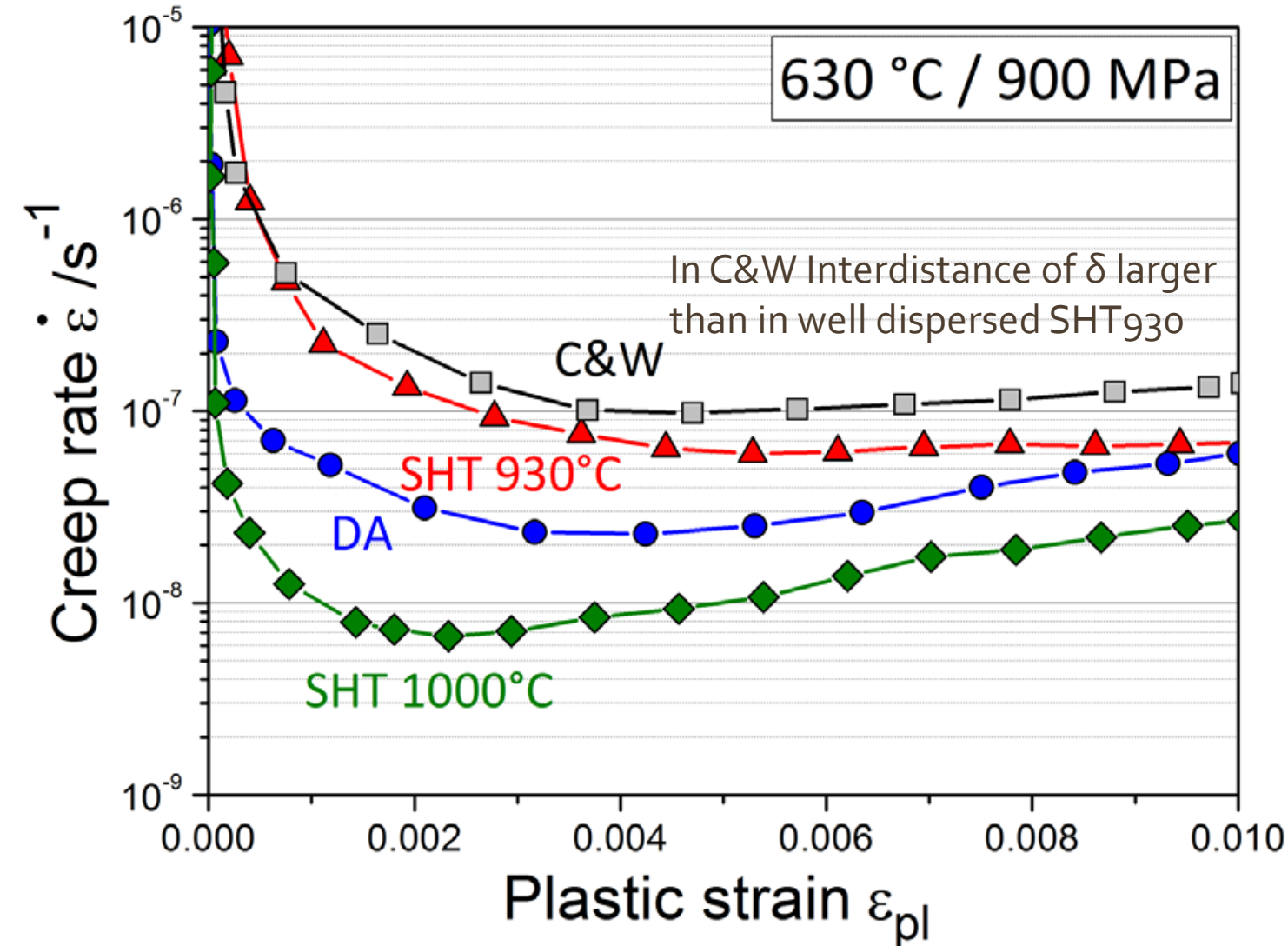
Interdendritic region
+ Lave 14 dissolved
Low dislocation

A lot of δ
Intra granular (fine)
+ in High Angle GB (thicker)

Subgrain size \approx ca 0.6 μ m

Creep behavior of Inconel 718 LPBF + heat treatment

Experiments: compression 630°C
(TP such that no over aging and strong
micro. evolution like recrystallisation)



γ'' --> creep strength
different amount and length

δ (high Nb) \rightarrow less γ' γ''
+Thick $\delta \rightarrow$ vacancy nucleation
 \rightarrow SHT 930 not optimal

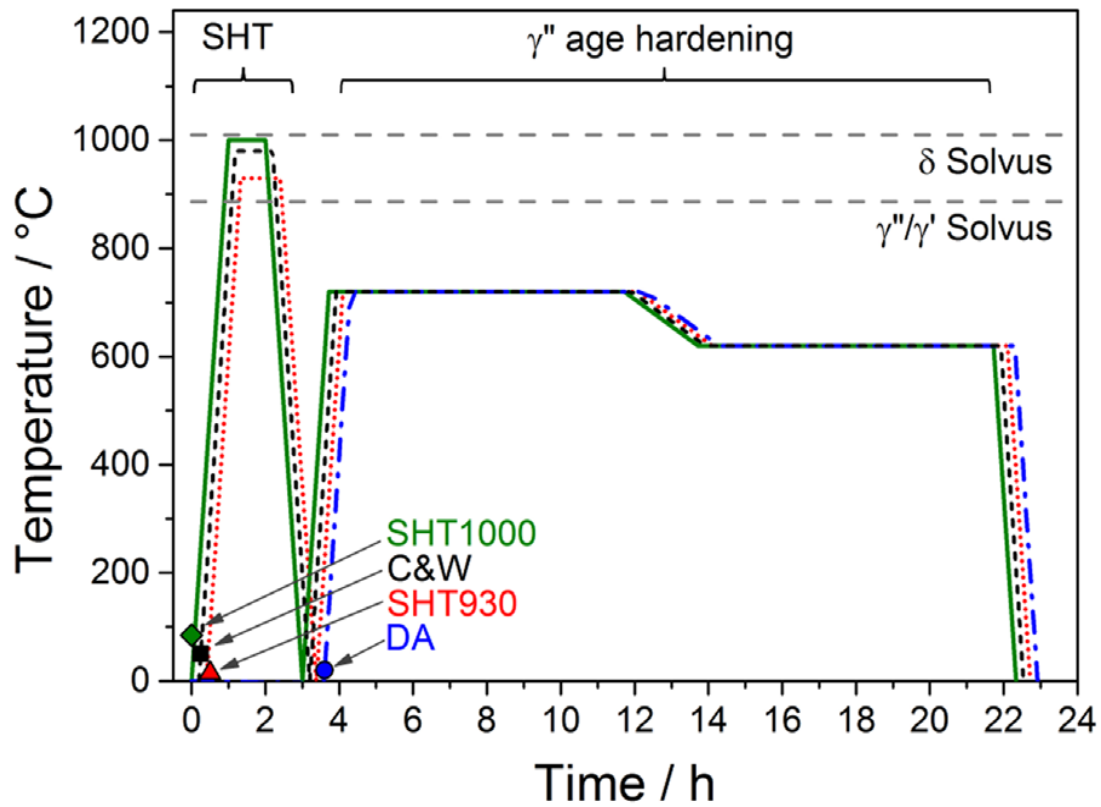
Laves (high Nb)
 \rightarrow less γ' γ'' but higher than SHT 930
 \rightarrow Aged state better

No δ , no Laves, low dislocations
Larger γ'' size in addition to higher volume
But sub grains less stable

LPBF Subgrain size \approx ct at 630°C

Sub grain generated by high creep stress
will be smaller

Creep behavior of Inconel 718 LPBF + Post Heat treatments

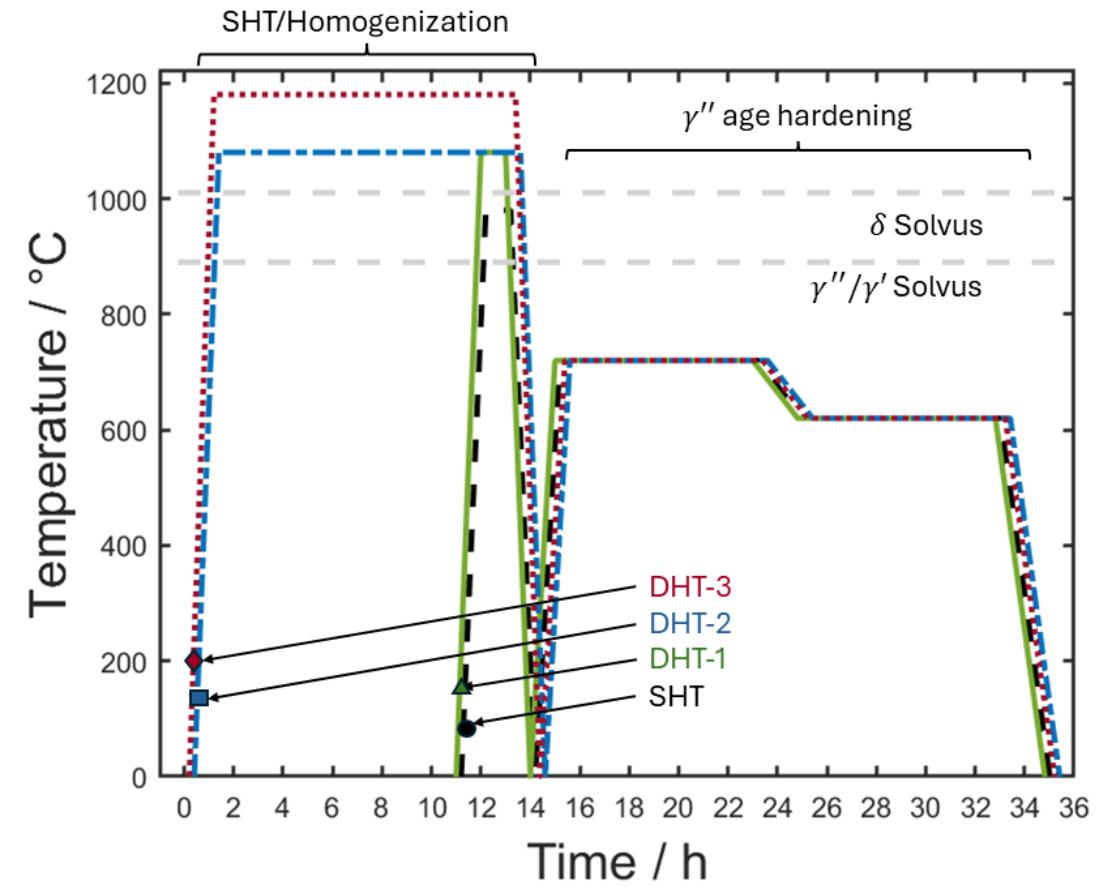


Creep tests
Compression

Pröbstle et al. MSEA 2016
LPBF 175W 620mm/s

2nd example

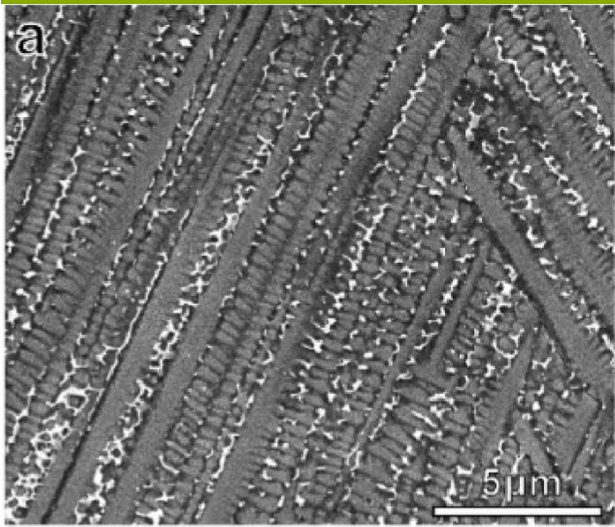
Experiments: tension 630°C
(strong micro. evolution like recrystallisation)



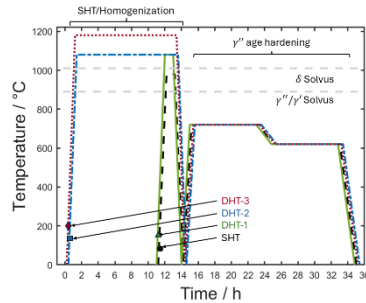
All DHT are performed > 1050°
→ recrystallisation and no more subgrains
according. Zhang MSEA 2015

DHT
designed heat
treatment

Inconel 718: Microstructures LPBF+ Heat Treatment

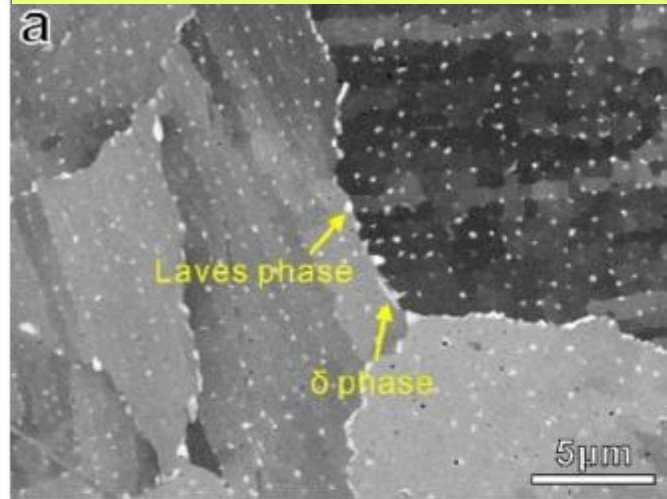


Dendritic structure and inter-dendritic Laves phase
 LPBF manufacturing param: 285 W laser power, 960mm/s scan speed



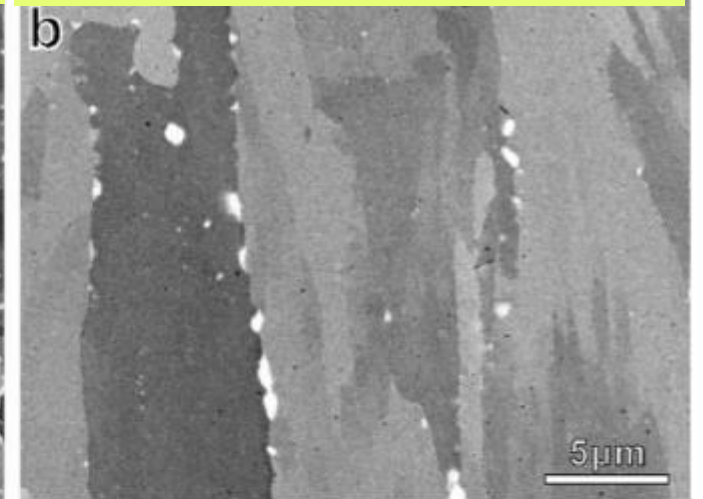
Laves + δ in GB

SHT (980°C° 1h)

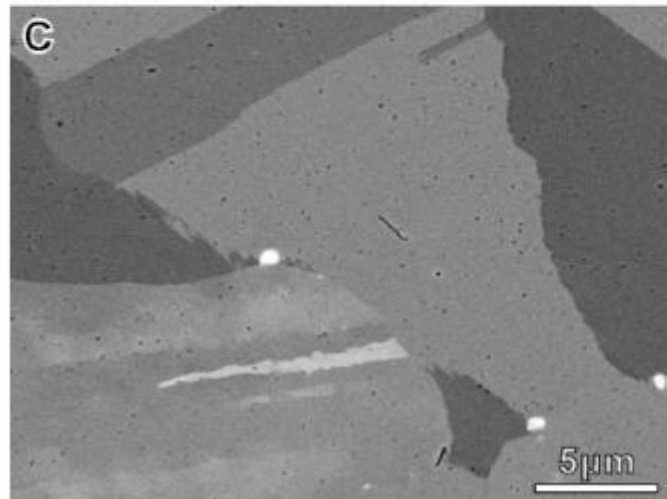
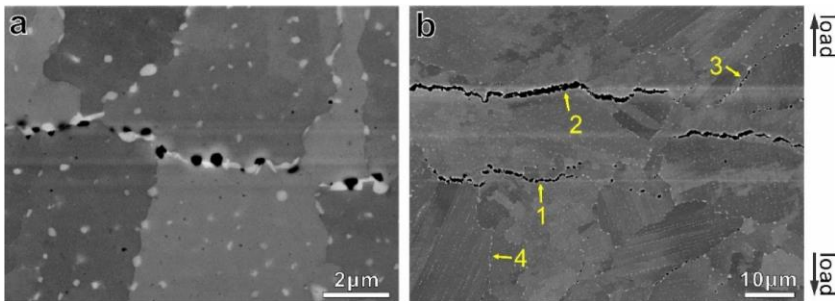


Laves + δ in GB, NbC present,

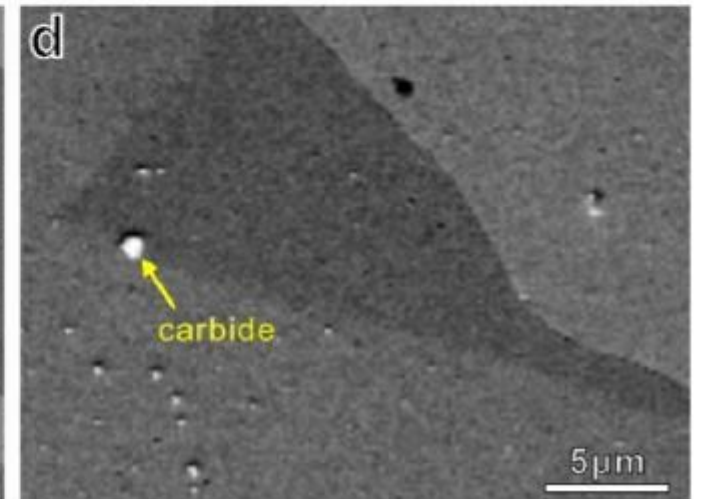
DHT1 (1080 C° 1h)



GB particles dissolution → cavity nucleation
 (mostly in GB ⊥ building dir.)



DHT2 (1080 C° 12h)



DHT3 (1180 C° 1h)

Laves + δ disappear GB, NbC present

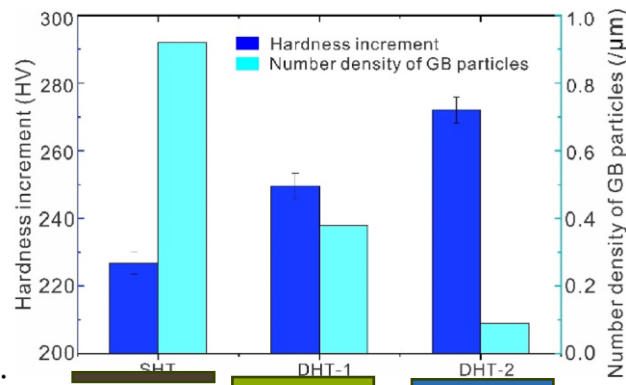
Inconel 718: Microstructures LPBF+ Heat Treatment

SHT, **DHT₁** : columnar grain structure
 low angle GBs
 Grain aspect ratio ≈ 3.26

DHT₂ and **DHT₃** :
 recrystallized equiaxed grains
 high angle GBs
 Grain aspect ratio ≈ 1
 high fraction of annealing twins
 (effect higher for **DHT₂**
 grain growth decreases them)

DHT₂: average grain size $80\mu\text{m}$

DHT₃ : average grain size $280\mu\text{m}$

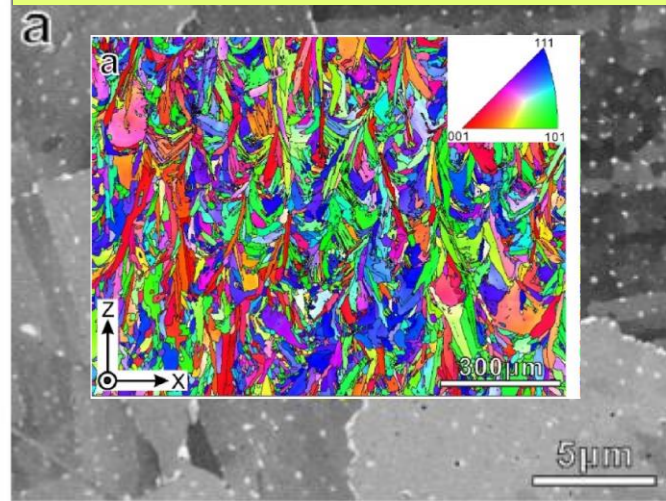


$\gamma'' \propto \text{hardness}$

Related to
 dissolution of GB
 particles

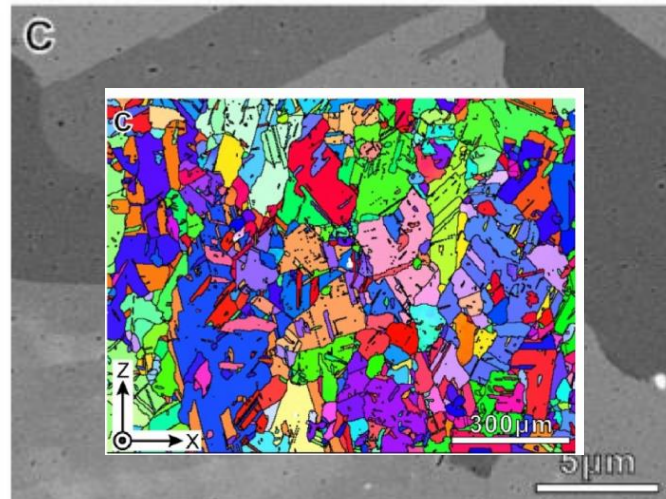
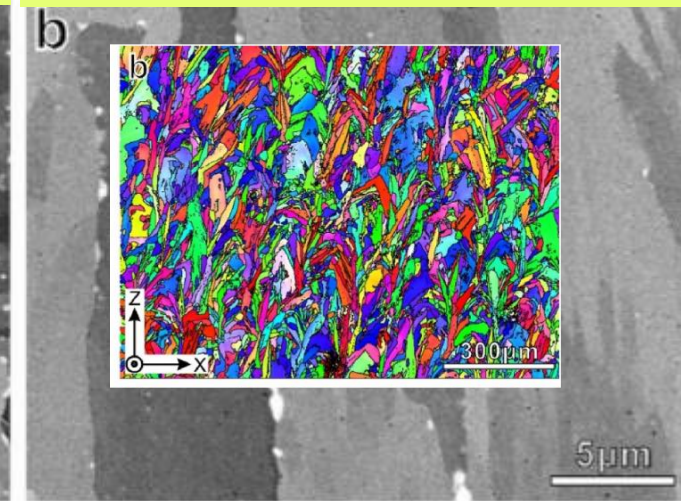
Laves + δ in GB

SHT ($980^\circ\text{C}^\circ 1\text{h}$)

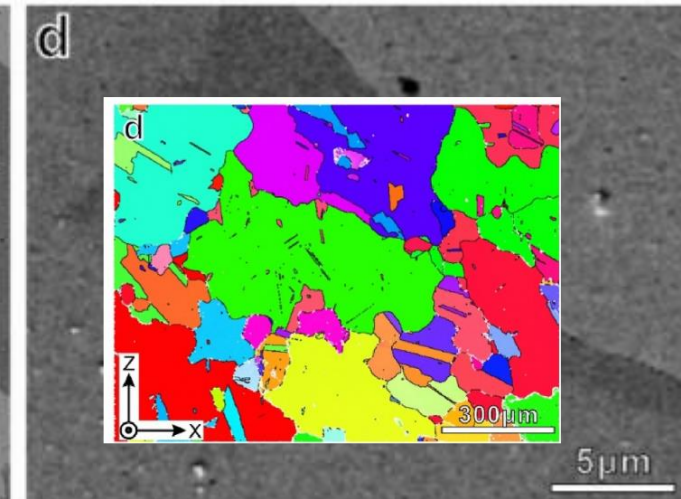


Laves + δ in GB, NbC present,

DHT₁ ($1080^\circ\text{C}^\circ 1\text{h}$)



DHT₂ ($1080^\circ\text{C}^\circ 12\text{h}$)



DHT₃ ($1180^\circ\text{C}^\circ 1\text{h}$)

Laves + δ disappear GB, NbC present

Creep behavior of Inconel 718 : S. Wu model

$$t_r \propto 1/(N_p + N_{gb})$$

N_p potential nucleation site density \approx GB particle density well oriented
 → **grain shape effect !!!**

N_{gb} triple points and GB ledge density
 (identified from difference between SHT and DHT1)

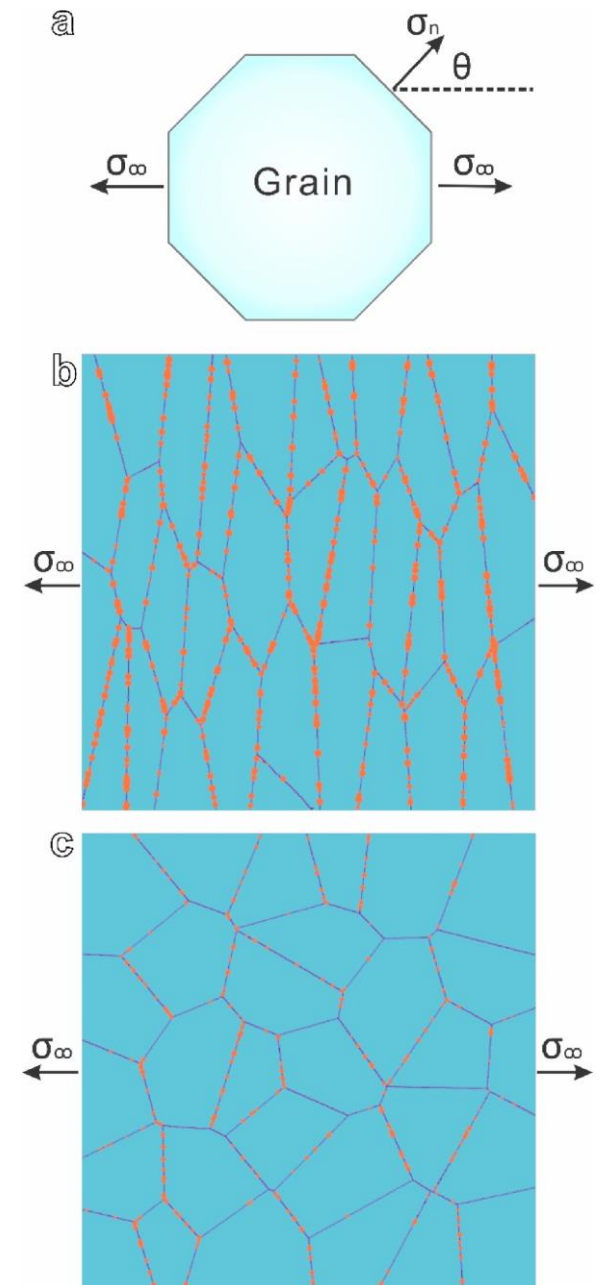
$$\dot{\epsilon}_m^c \propto \frac{\phi_m \lambda_m}{h} \sinh\left(\frac{\sigma b^2 \lambda_m}{MkT}\right)$$

- ϕ_m Volume fraction precipitate
- λ_m Average dislocation glide distance
- h Dislocation climb distance against precipitates
- b Burgers vector
- M Taylor factor

effect of GB particles (SHT > DHT1 > DHT2 & DHT3)

γ'' density - intra granular effect (larger in DHT2 & DHT3 > DHT1 > SHT)

Grain shape (Larger in SHT and DHT1 + anisotropy) as cavitation if orientation of GB OK



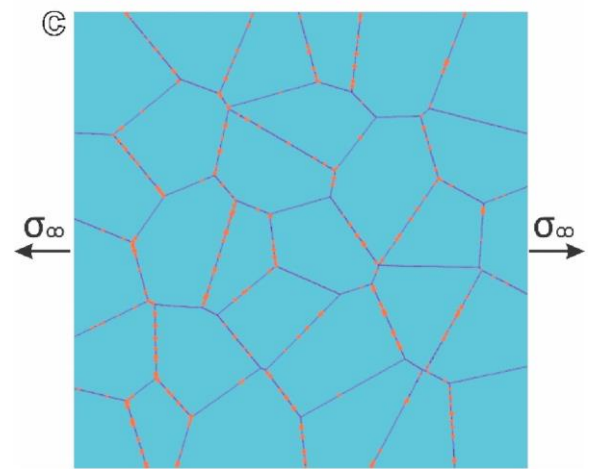
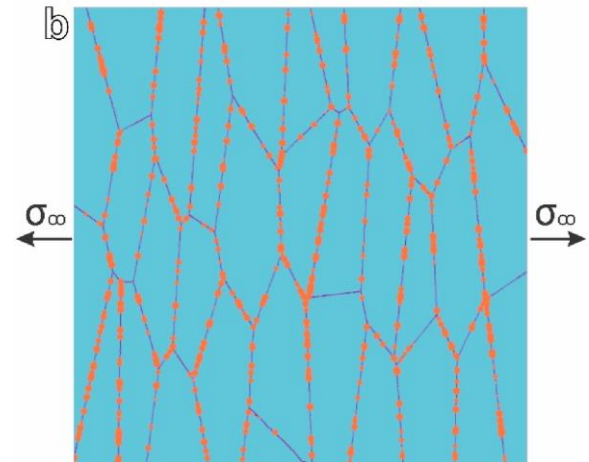
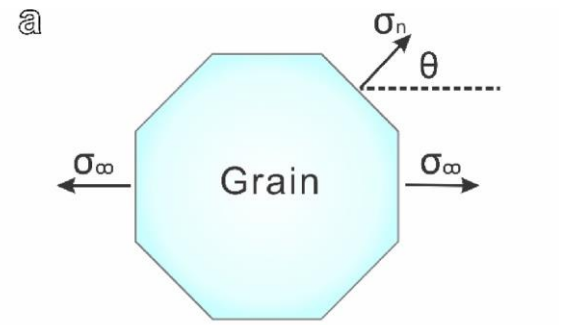
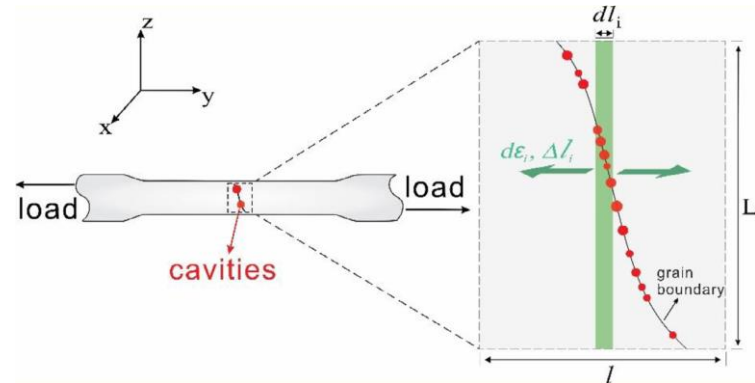
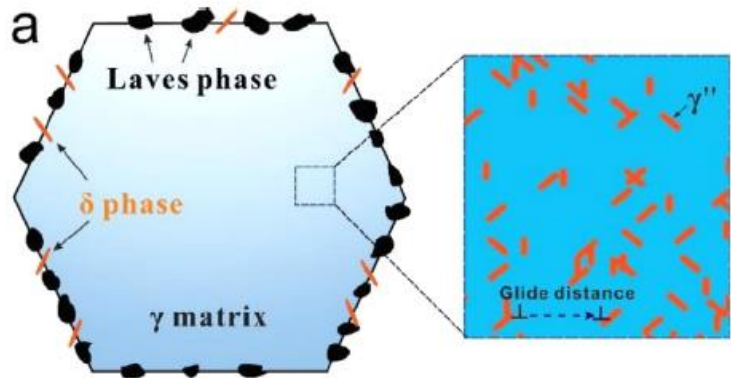
Creep behavior of Inconel 718 : S. Wu model

Total set of equations to model

- Dislocation motion (glide + climb) and GB sliding
- Cavitation kinetics

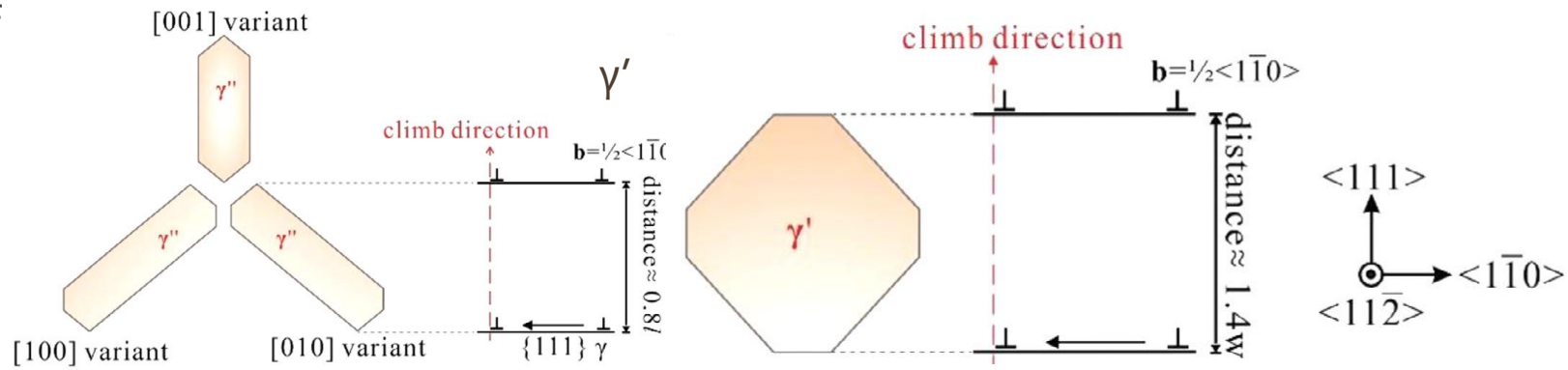
Concept of effective stress due to damage
Idealized Microstructure

2nd example



3 Variants of γ''

Estimation of climb distance for dislocation



Creep behavior of Inconel 718

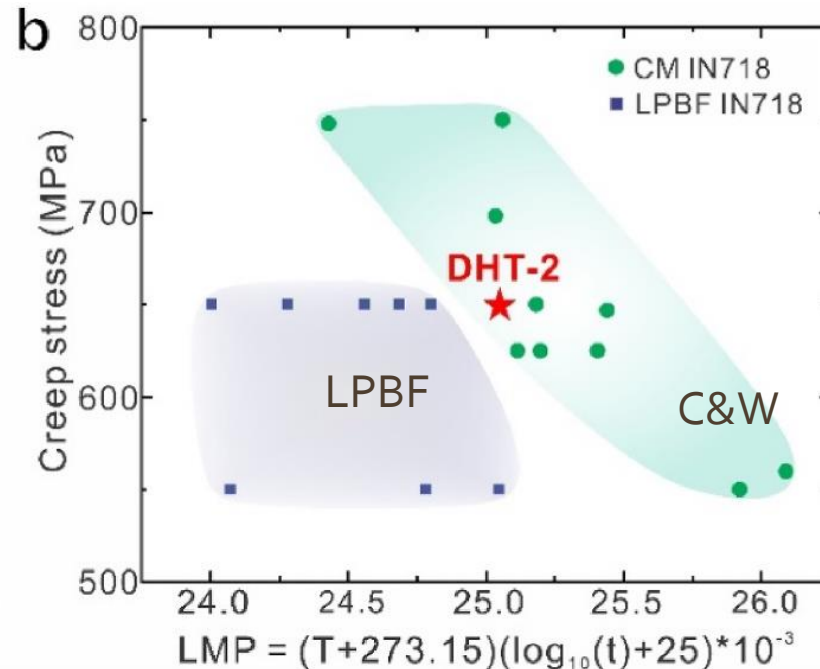
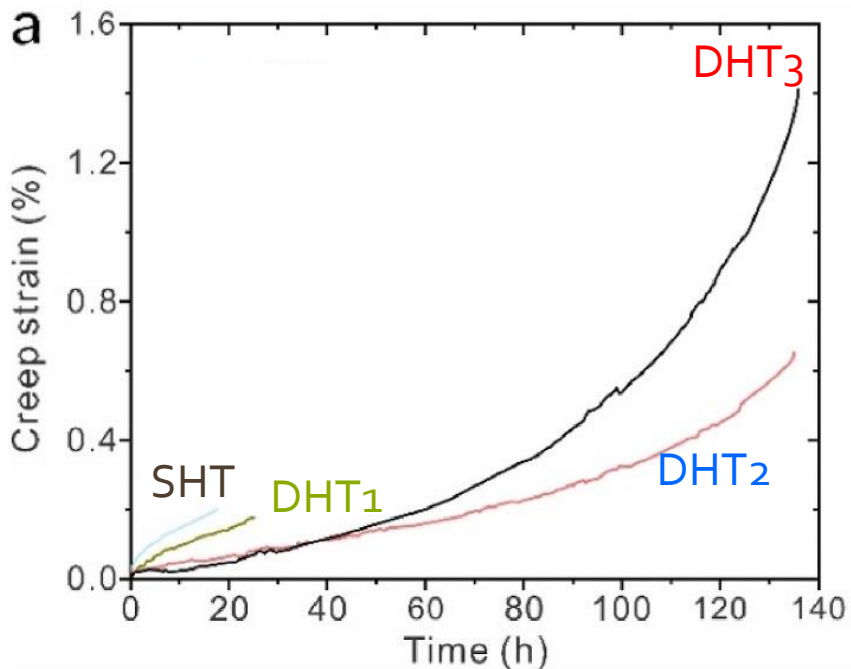
LPBF + heat treatment

Experiments: tension 630°C
(strong micro. evolution like recrystallisation)

Which dominant mechanism?

GB sliding dominant creep mechanism (cavity formation at triple junction points)

Dislocation dominant creep mechanism (cavity formation due to dislo pile up at GB or GB ledge or at subgrains boundary)



T_r of DHT2 = DHT3
→ GB non dominant mechanism
as strong different grain size
80 -> 280 μm

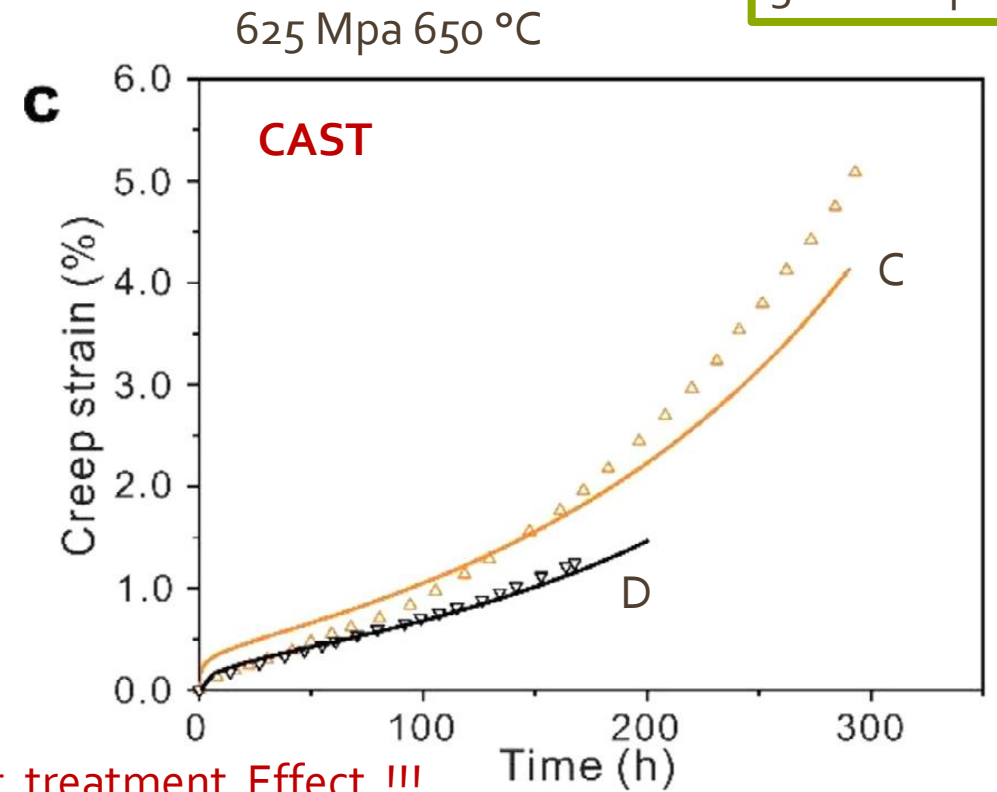
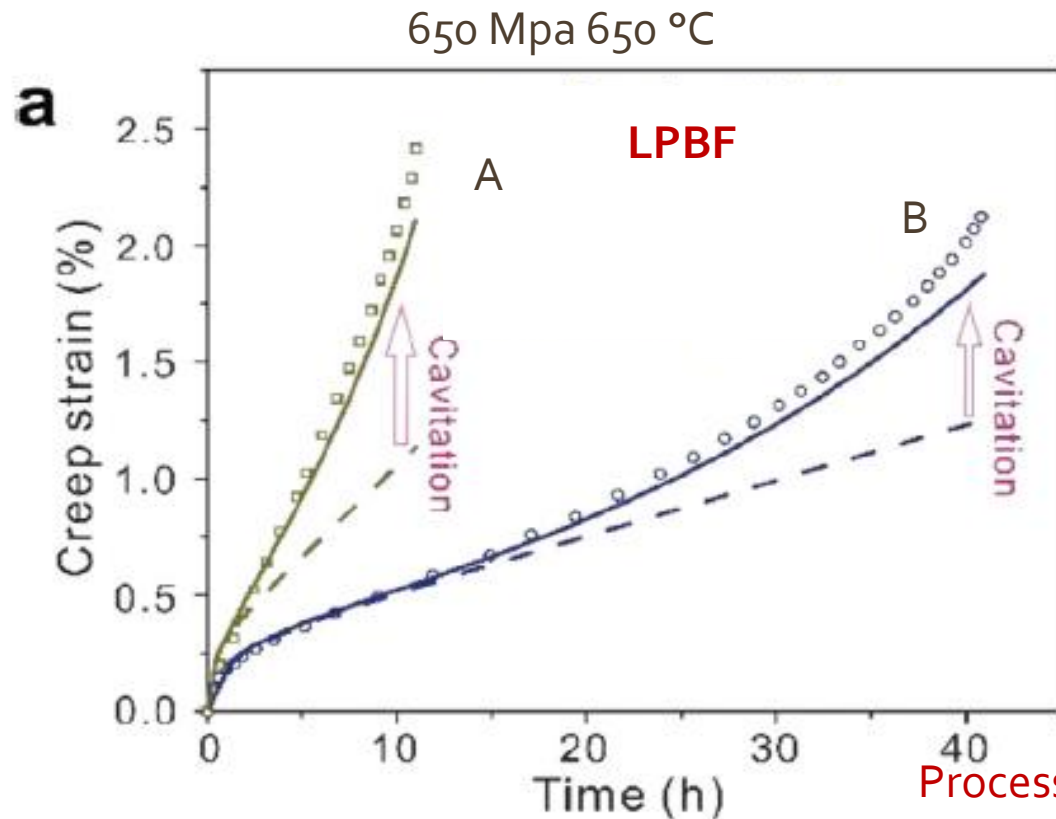
Dislocation glide-climb
=main mechanism

Cavitation \propto GB particle number

SHT > DHT1 > DHT2

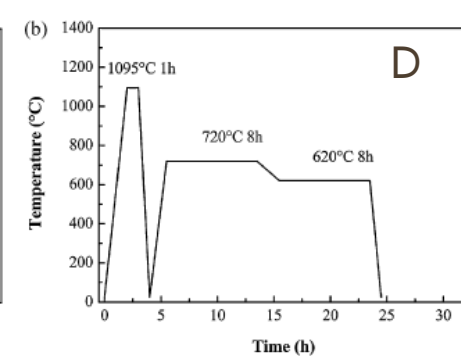
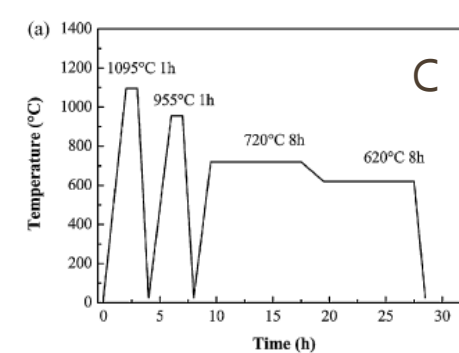
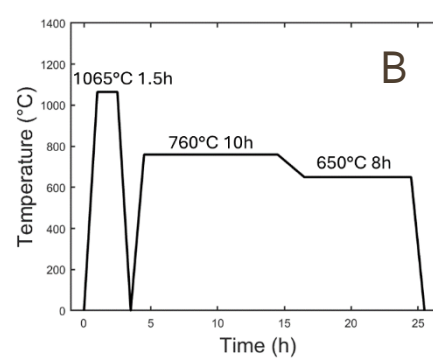
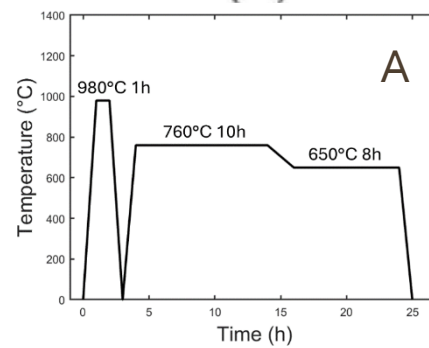
Creep behavior of Inconel 718: S. Wu model's result

3rd example



Process and Heat treatment Effect !!!

Prediction
 --- without cavitation
 — with cavitation
 Experiment ○ ○ ○ ○ ○



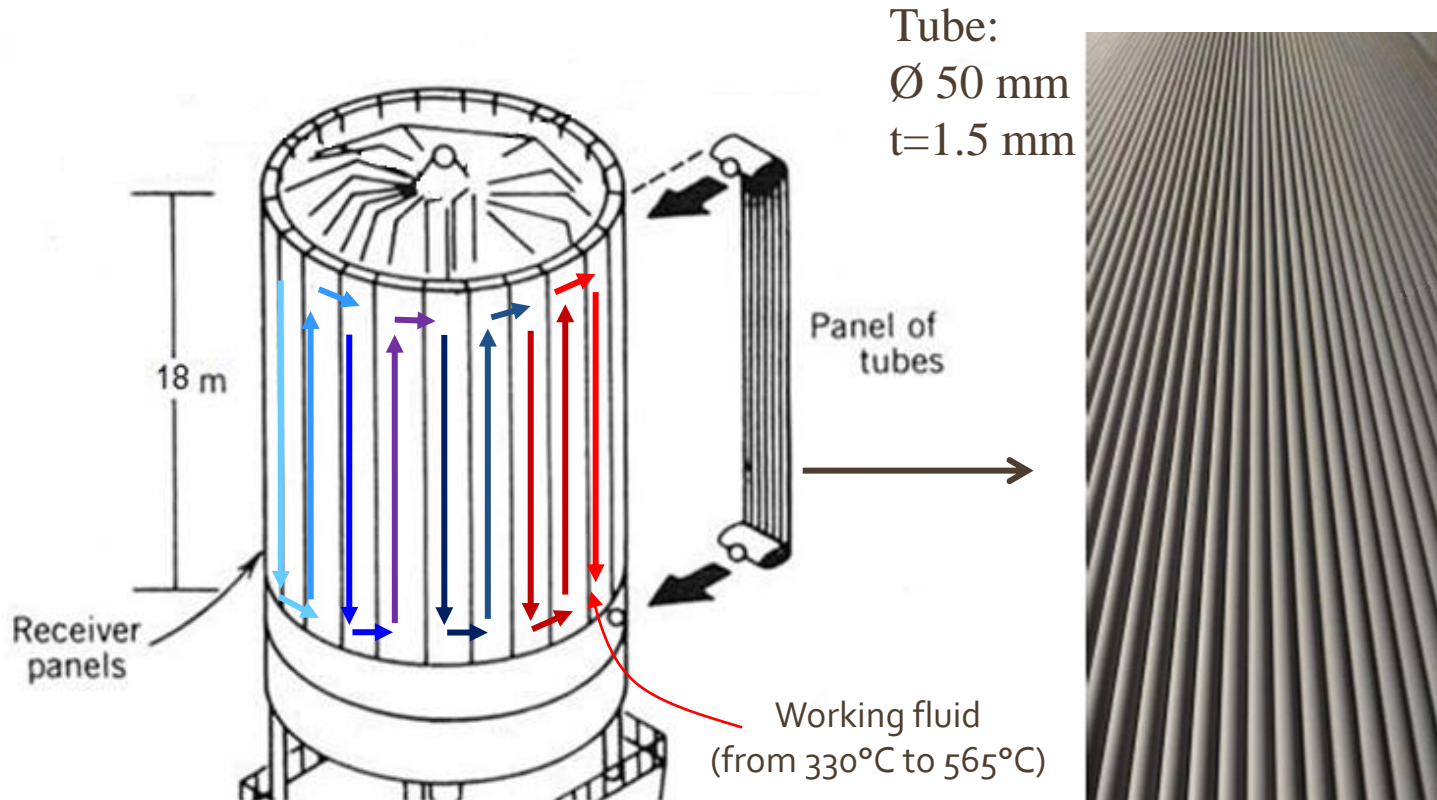
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- **Nitriding** effect
- **AID₄Greenest** EU project ...

Solar receivers - Walloon Region projects (Experiments + Modeling)



RÉGION WALLONNE
DE BELGIQUE



Solar receiver
(source : W.B.Stine, R.W.Harrigan,
Solar Energy Systems Design)

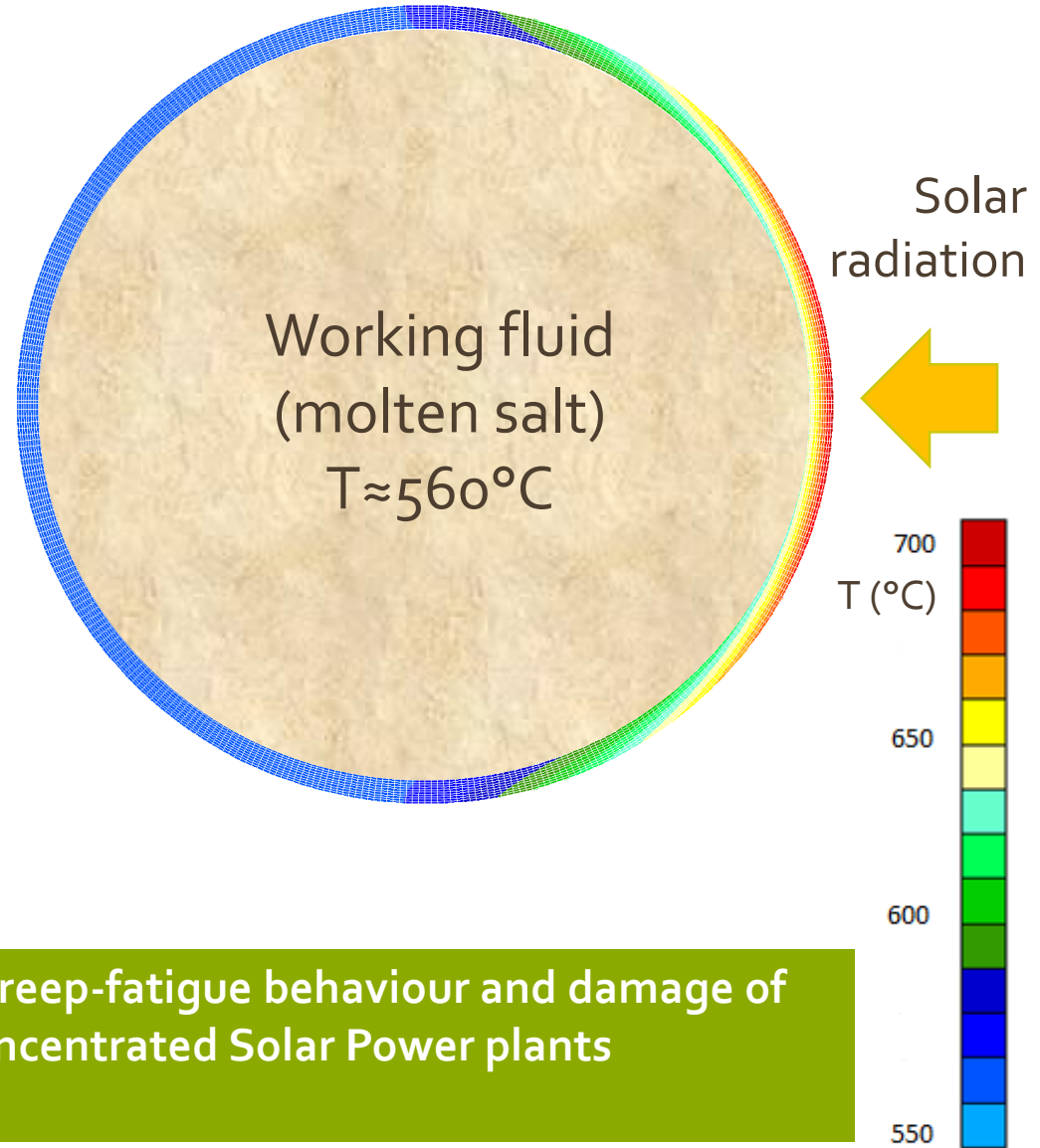
Panel of tubes manufactured from nickel
alloy sheet (Haynes 230)
(source : CMI Solar)

The tubes

Temperature distribution in a tube
(Lagamine FE code)

- **Fatigue + creep**
- **Extreme Thermo-mechanical loading**
(Haynes 230)
- **Advanced model**

Thermomechanical modelling of the creep-fatigue behaviour and damage of Nickel-alloy receiver tubes used in Concentrated Solar Power plants
Morch, H el ene PhD Uliege 2022

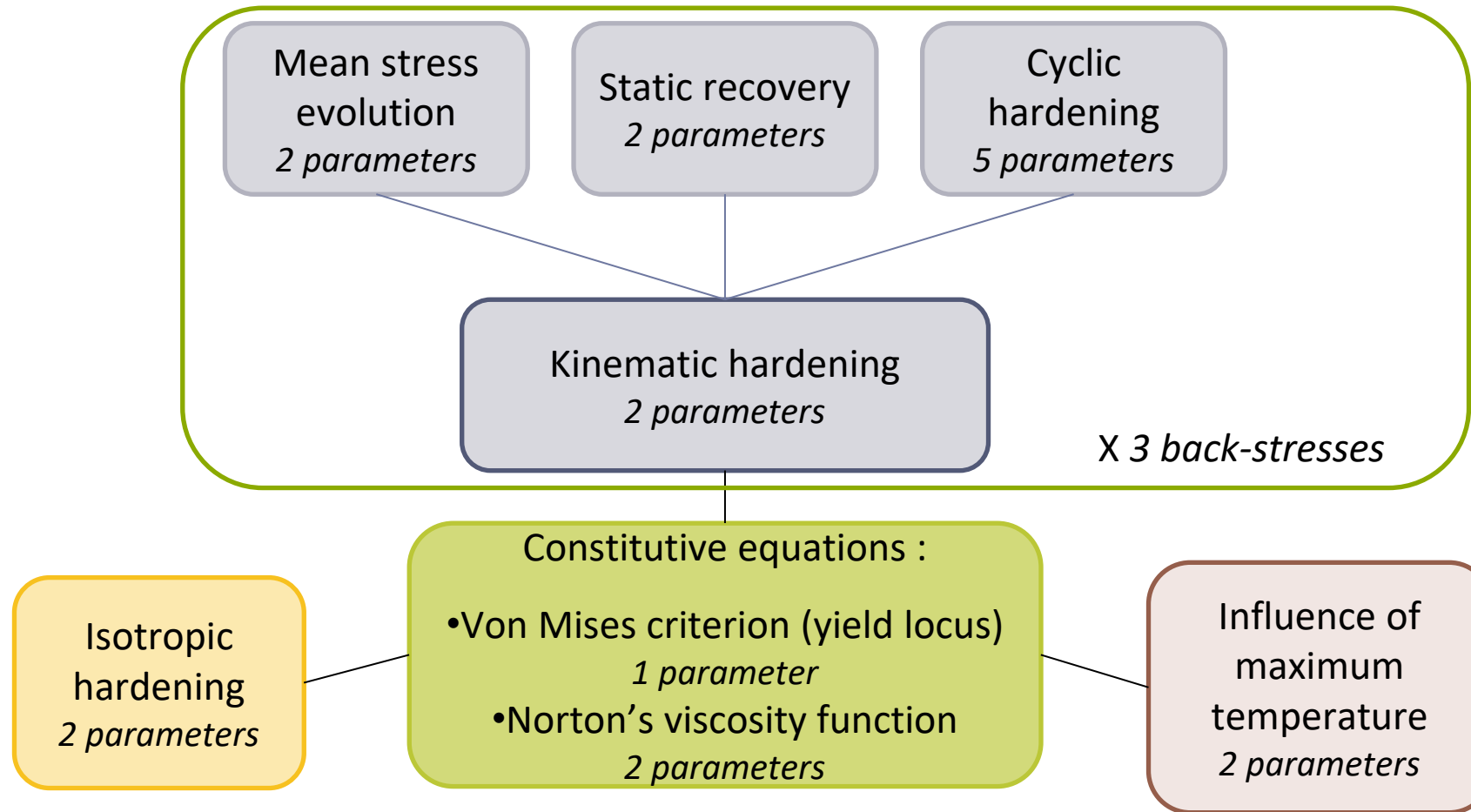


“Morch law”

Advanced damage Chaboche coupled model

Effect of tensile and compressive hold times on the rupture behavior of nickel-based alloy 230 at 700°C submitted... Morch et al.

31 Equations to solve...



→ ²⁸~~40~~ parameters → Efficient temperature dependence of parameters for thermo-mechanical finite element modeling of alloy 230 Morch et al. *European Journal of Mechanics – A/Solids*, 85, p. 104-116

Morch law: 1st version uncoupled, 2nd coupled... $D_{creep} + D_{fatigue}$

Isotropic EVP model

$$\underline{\varepsilon} = \underline{\varepsilon}^{el} + \underline{\varepsilon}^{vp} + \underline{\varepsilon}^{th}$$

$$\underline{\sigma} = \underline{E} : \underline{\varepsilon}^{el}$$

$$\underline{\dot{\sigma}} = \underline{E} : \underline{\dot{\varepsilon}}^{el} + \underline{\dot{E}} : \underline{\varepsilon}^{el}$$

$$f = \|\underline{\sigma} - \underline{X}\| - \sigma_0 - R \leq 0$$

Viscous stress

$$\sigma_v = f > 0$$

Viscosity Norton

$$\dot{p} = \left\langle \frac{\sigma_v}{K} \right\rangle^n$$

$$Avec : \dot{p} = \sqrt{\frac{2}{3} \underline{\varepsilon}^{vp} : \underline{\varepsilon}^{vp}}$$

Or Graham Wales

Kinematic hardening

$$\hat{X} = \sum_{i=1}^{nAF} \hat{X}_i$$

$$\dot{\hat{X}}_i = \frac{2}{3} C_i \underline{\dot{\varepsilon}}^{vp} - \gamma_i (\hat{X}_i - Y_i) \dot{p}$$

Static recovery

$$\dot{\hat{X}}_i = \dots - b_i \|\underline{X}_i\|^{n_i-1} \hat{X}_i$$

TP^o effect

$$\dot{\hat{X}}_i = \dots + \frac{1}{C_i} \frac{\partial C_i}{\partial T} T \hat{X}_i$$

Mean stress Effect

$$\dot{Y}_i = -\alpha_{b,i} \left(\frac{3}{2} Y_{st,i} \frac{\hat{X}_i}{\|\underline{X}_i\|} + Y_i \right) \|\underline{X}_i\|^{r_i}$$

Cyclic Hardening

$$\dot{\gamma}_i = D_{\gamma_i} (\gamma_i^0 - \gamma_i) \dot{p}$$

$$\gamma_i^0 = a_{\gamma_i} + b_{\gamma_i} e^{-c_{\gamma_i} \dot{p}}$$

Isotropic hardening

$$\dot{R} = b(Q - R) \dot{p}$$

Effect of Max tp^o

On cyclic hardening

$$\dot{D}_{\gamma_i} = b_{D_{\gamma_i}} (D_{\gamma_i}^{Tmax} - D_{\gamma_i}) \dot{p}$$

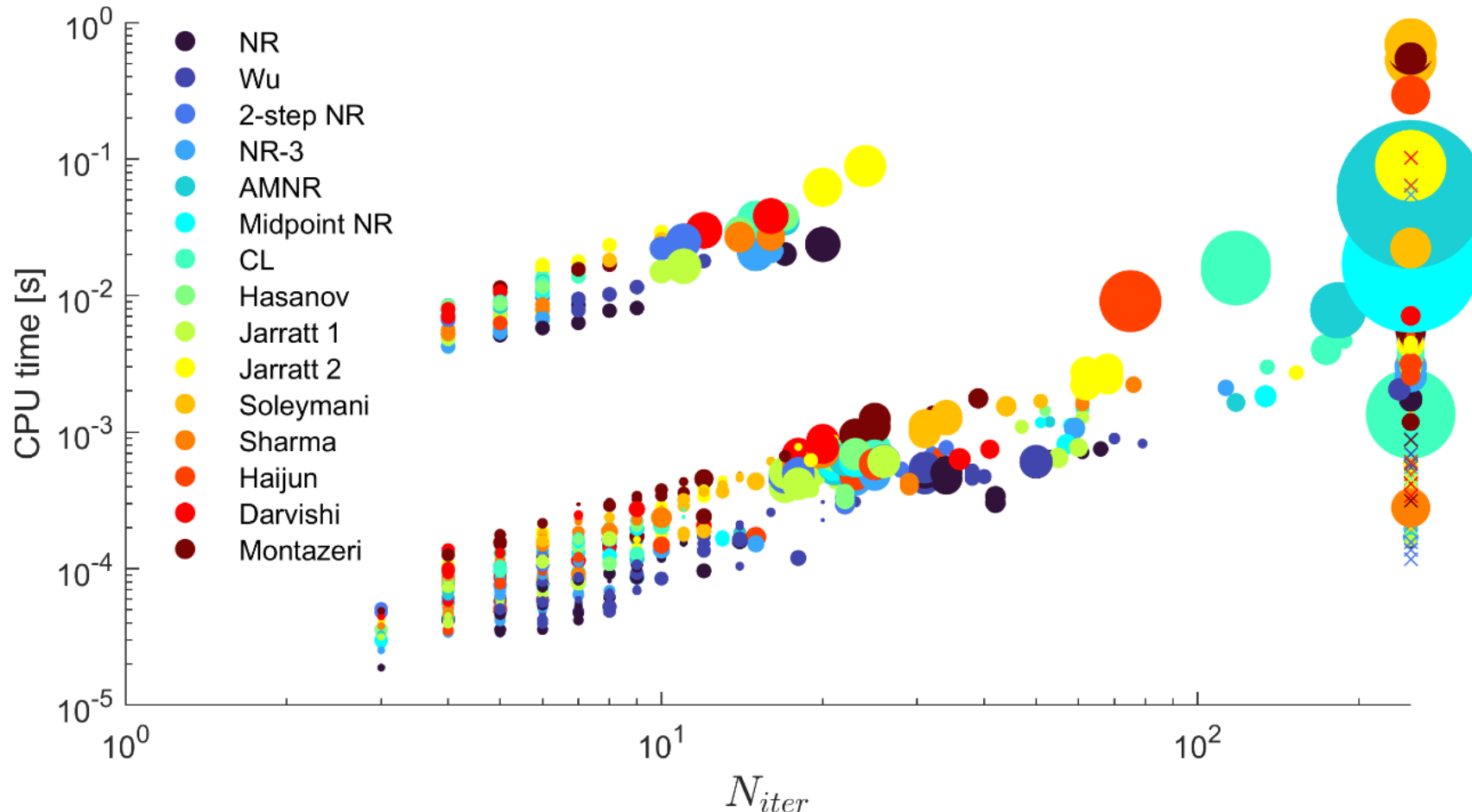
On cyclic hardening

$$E = f_E E + (1 - f_E) E_{Tmax}$$

$$\dot{f}_E = b_E (f_E^S - f_E) \dot{p}$$

Study of optimal resolution → Newton Raphson !!!

Analysis of different resolution approach



A review of higher order Newton type methods and the effect of numerical damping

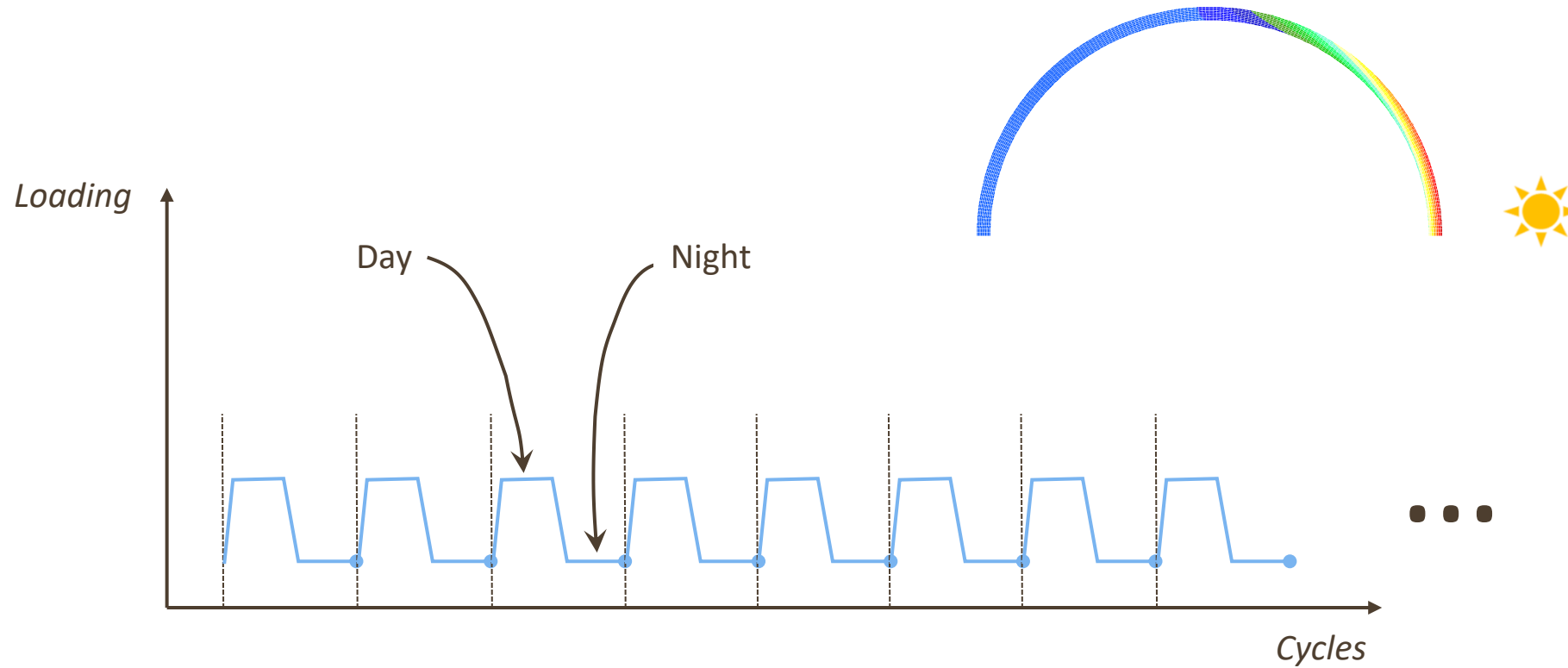
for the solution of

an advanced coupled Lemaitre damage model

Morch et al. *Finite Elements in Analysis and Design*, 209, p. 103801

Iteration number versus CPU time to solve the equation system

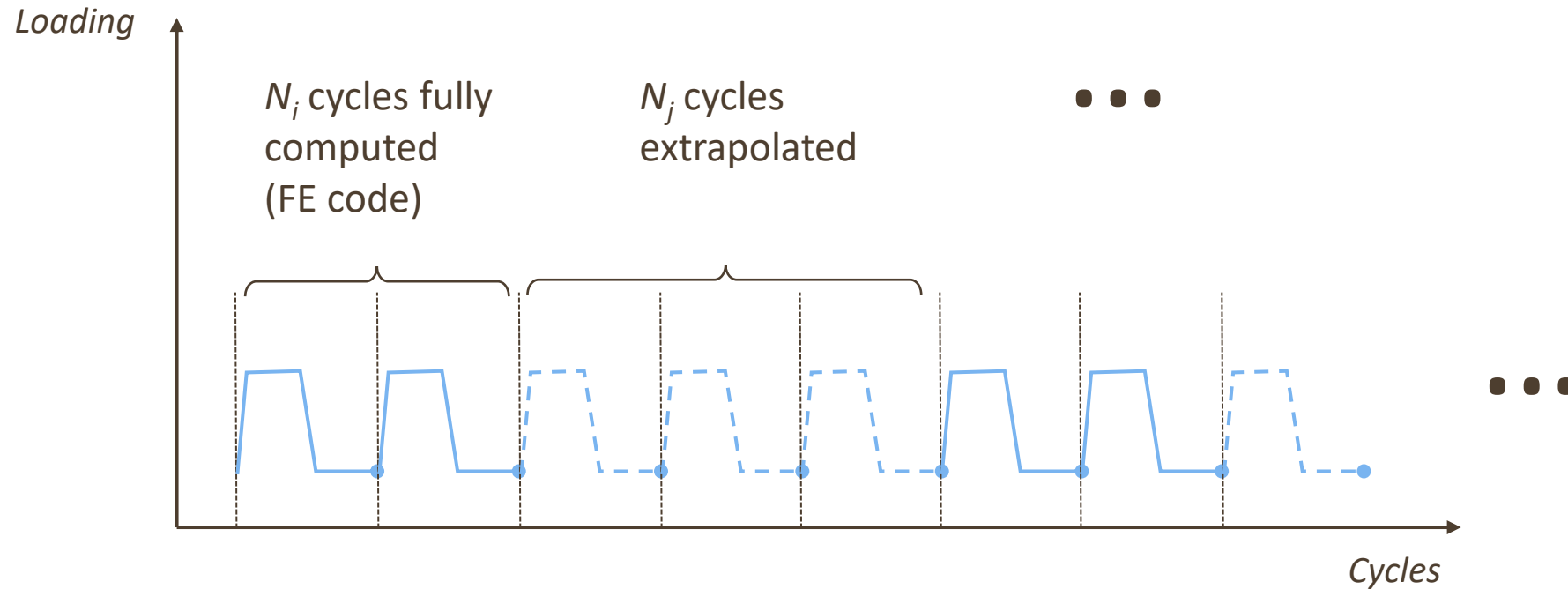
Cycle jump approach



- Target:
- ▶ 10 000 cycles (~25 years)
 - ▶ 18m long tube (~200 000 FE, 10^6 DOFs)

Duchêne et al. ICTP 2023
Conf proc.

Cycle jump approach



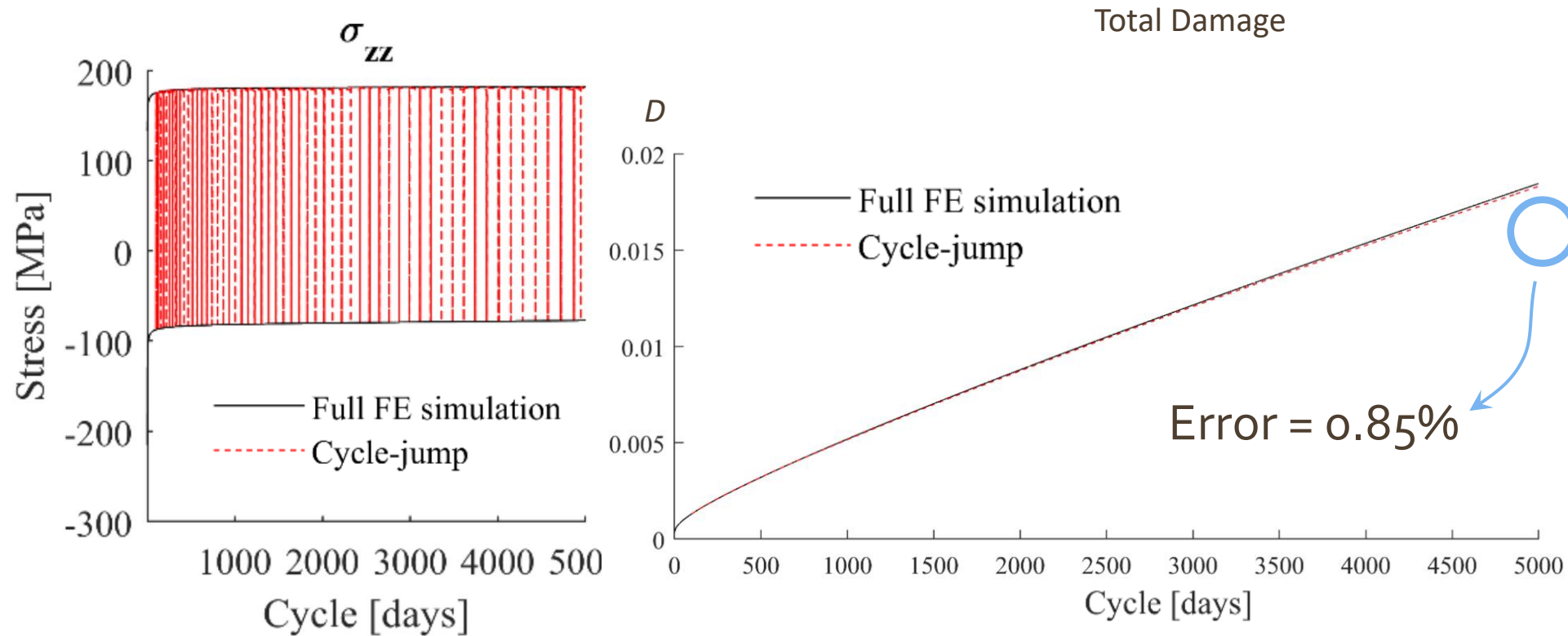
Target: ► 10 000 cycles
(~25 years)

► 18m long tube
(~200 000 FE, 10^6 DOFs)

This study: ► 5 000 cycles

► 1 slice of the tube
(300 FE, ~3000 DOFs)

Cycle jump: optimum parameters



	CPU time (hours)
Full FE computation	104
Optimum Cycle jump	11

- ▶ 5 000 cycles
- ▶ 1 slice of the tube (300 FE, ~3000 DOFs)

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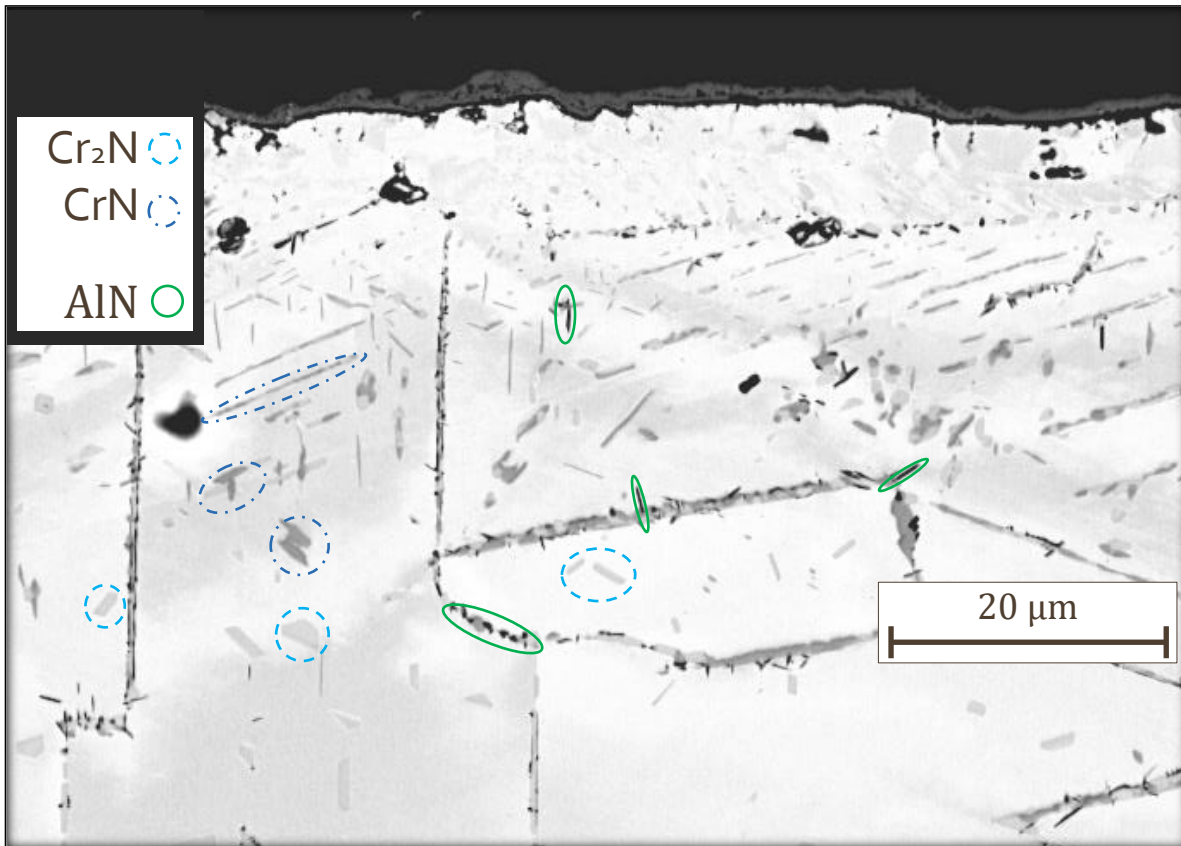
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- **AID4Greenest EU project ...**

Environmental effects on creep: nitridation

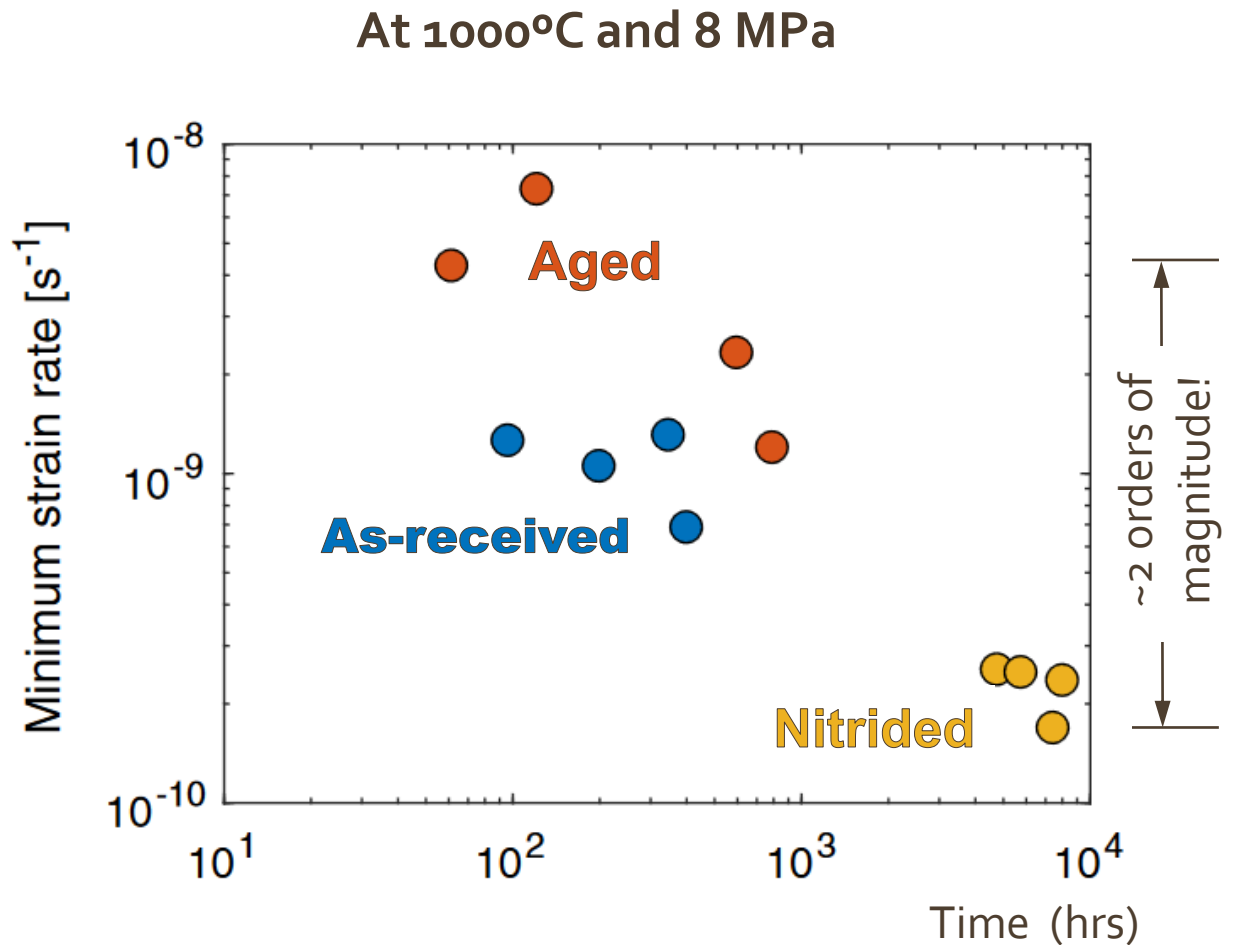
800H

Long-term (>1000h)
high-temperature exposure
high-N₂ environment (e.g., air)

Nitridation
Precipitation of:
AlN, CrN, Cr₂N

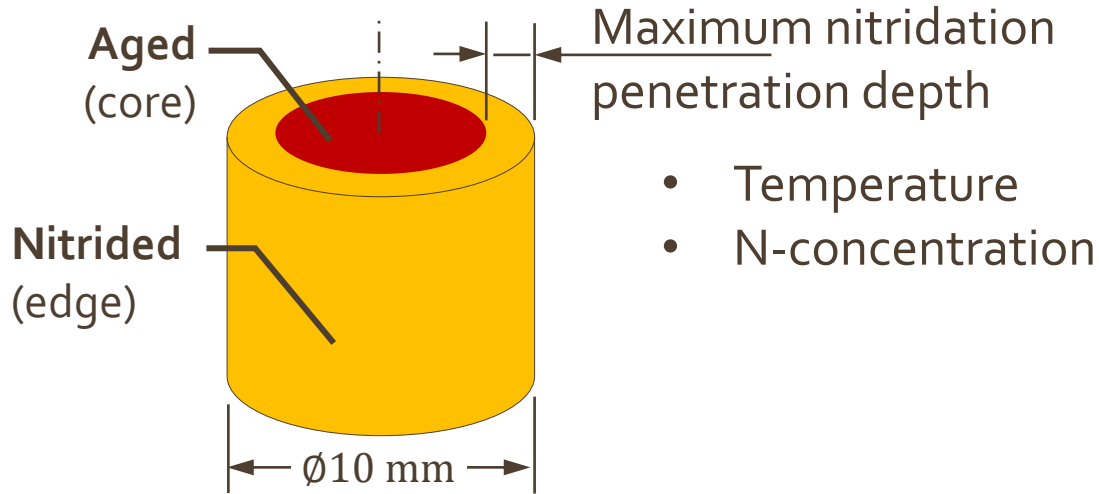


Nitridation → creep hardening



Environmental effects on creep: nitridation

FE simulation of nitridation effect (Lagamine code Uliège)

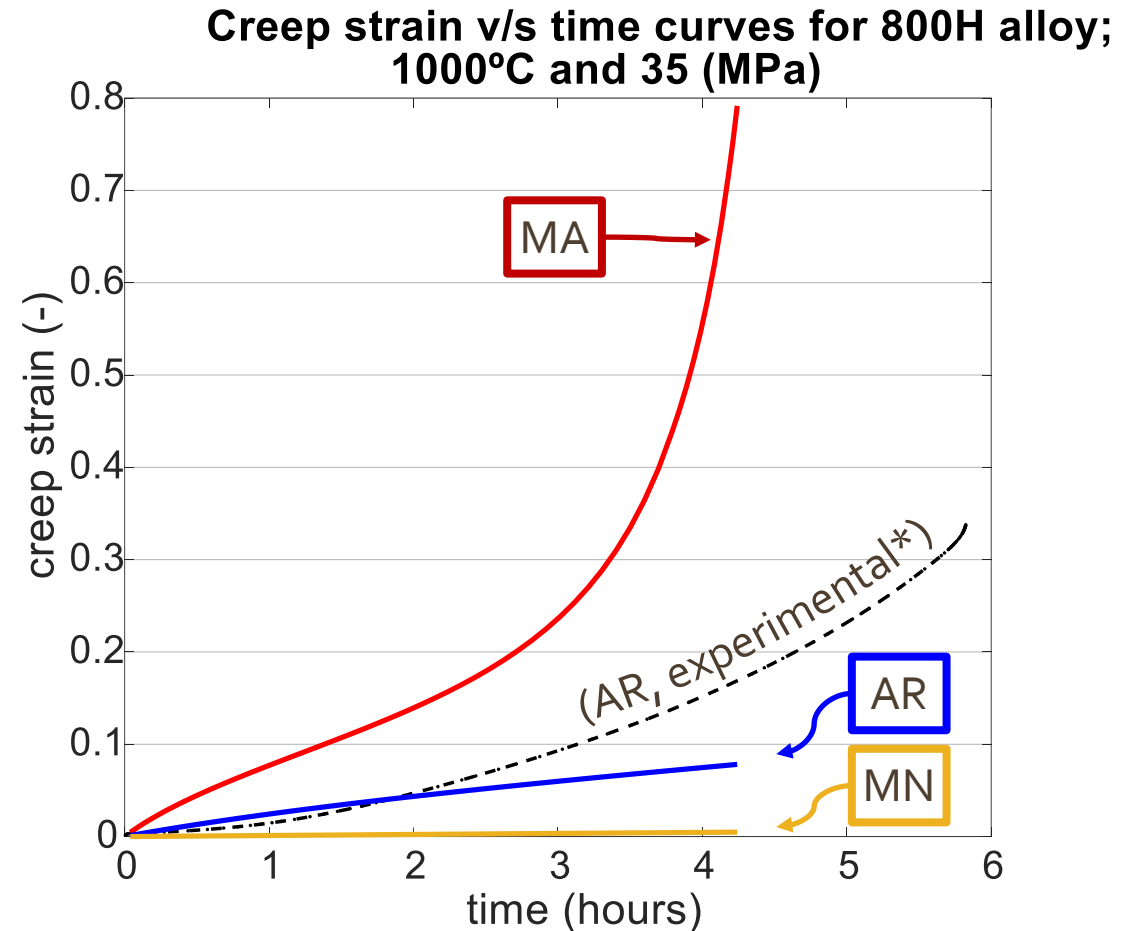


Experiment for identification (A.M. Young et al., 2023):

Parameters	Aged (MA)	As-received (AR)	Nitrided (MN)
Norton law			
k (MPa)	3.10E + 04	7.50E + 04	5.35E + 05
n (-)	1.18	1.22	1.29

$$\dot{p} = \left\langle \frac{\sigma_v}{K} \right\rangle^n$$

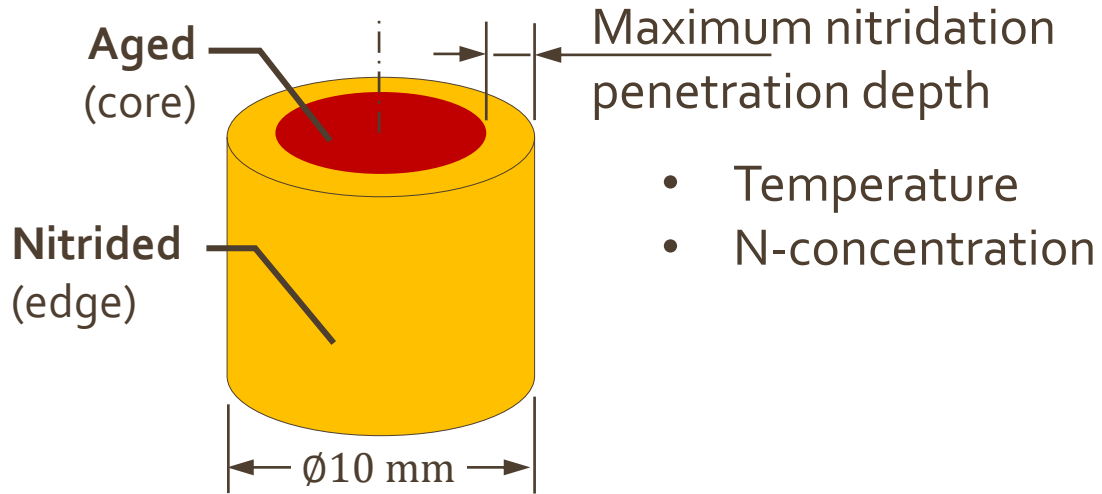
Prediction for homogeneous samples (Norton)



*: Experimental curve after (V. Gutmann & R. Bürgel, 1983)

Environmental effects on creep: nitridation

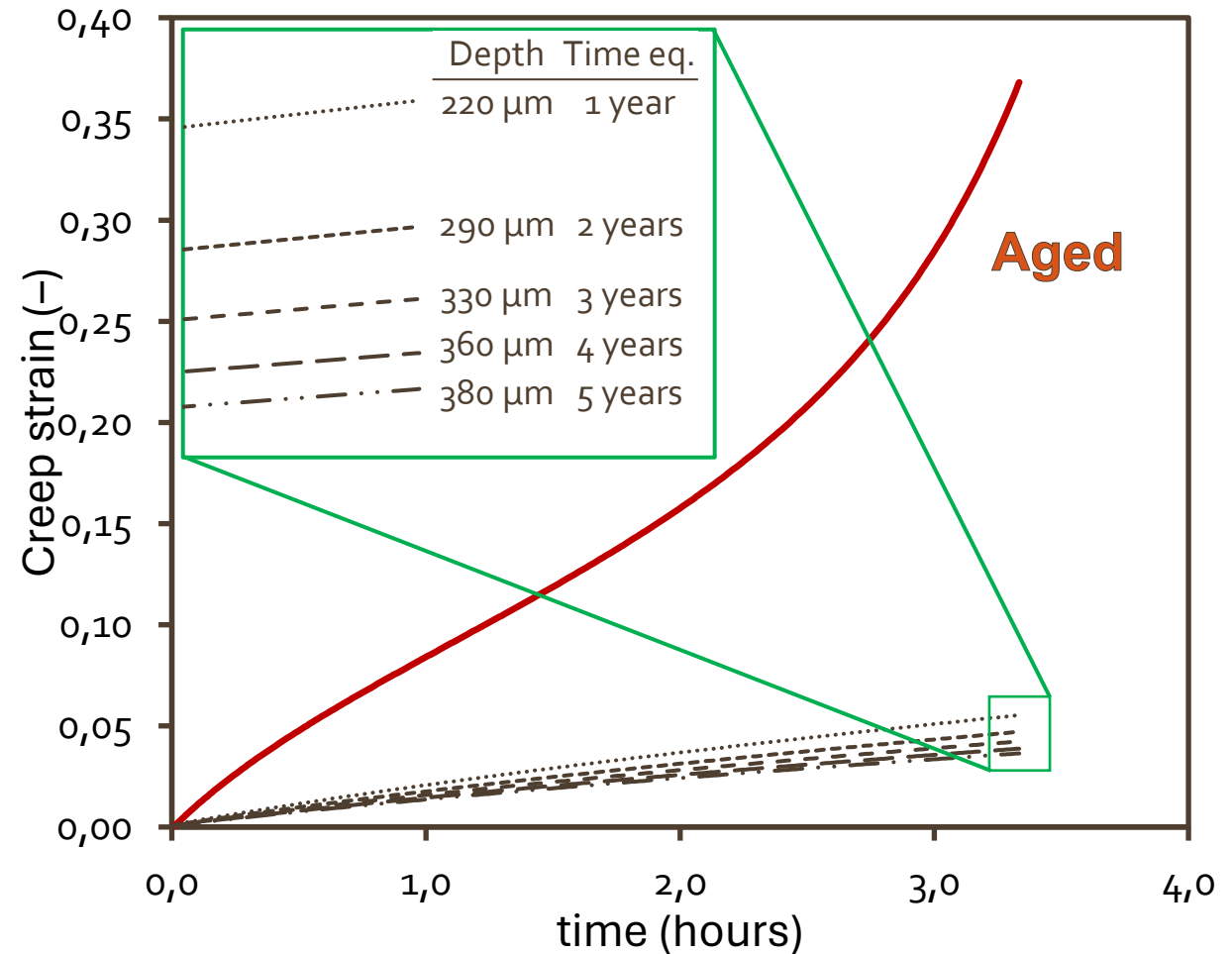
FE simulation of nitridation effect (Lagamine code Uliege)



Using the information from (A.M. Young et al., 2023):

Parameters		Aged (MA)	As-received (AR)	Nitrided (MN)
Norton law $\dot{p} = \left(\frac{\sigma_v}{K}\right)^n$	k (MPa)	3.10E + 04	7.50E + 04	5.35E + 05
	n (-)	1.18	1.22	1.29

Predictions for different aged + nitrided 800H material combinations | 1000°C & 35 MPa



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- Manufacturing of a shaft *Reinosa*
- Characterization and prediction of **microstructure** *Uliege, Oulu, Fraunhofer, MDEA*
- Standard creep test *Uliege*
- 2 Types of Accelerated creep test *IMDEA - Fraunhofer*
- Forging + Cooling simulation *OULO*
- Creep Simulation:
 - Macro** laws (Morch) *Uliege*
 - Micro** law (under development) *Uliege*
 - Machine learning** (under development) *Fraunhofer IMDEA*



Efficient way to predict shaft lifetime

→ Generic tool development



<https://aid4greenest.eu/>

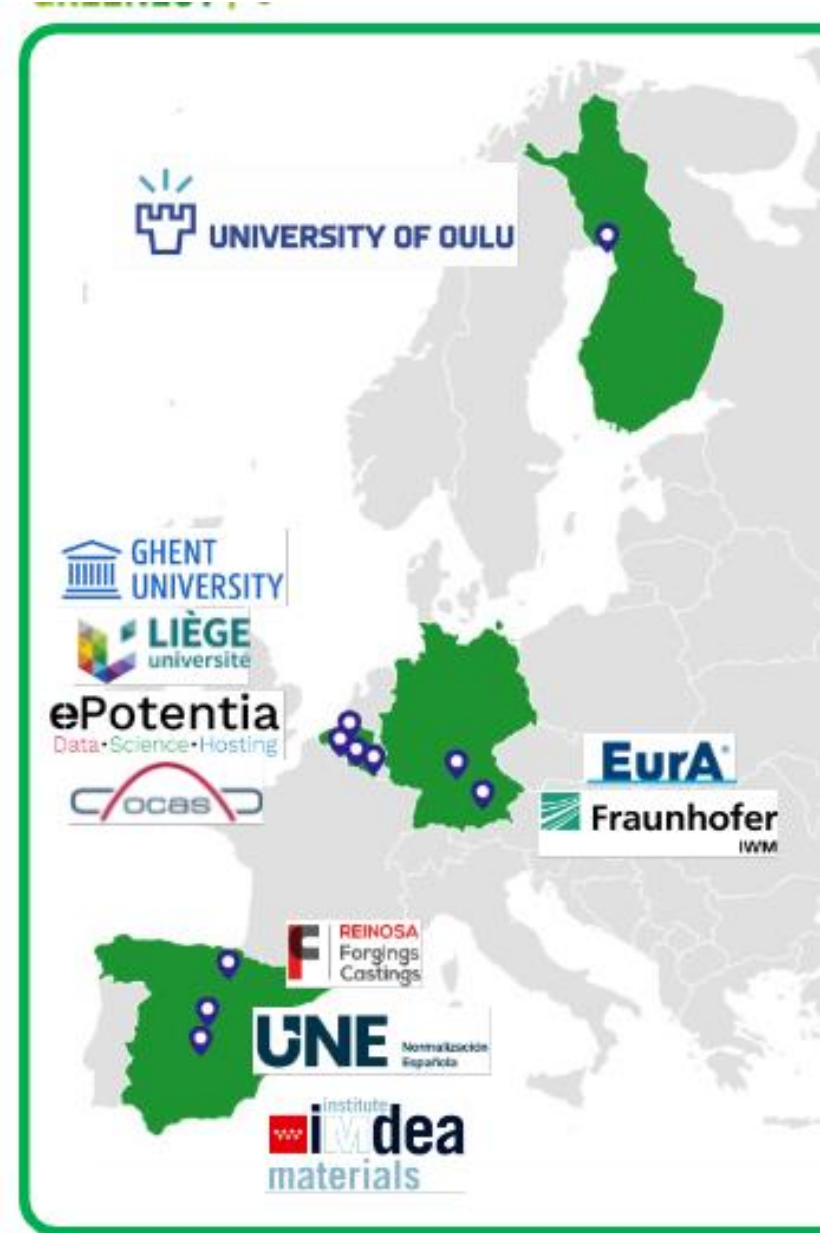


AID4GREENEST Official



Thank you for your attention

Anne. Habraken@uliege.be



<https://aid4greenest.eu/>