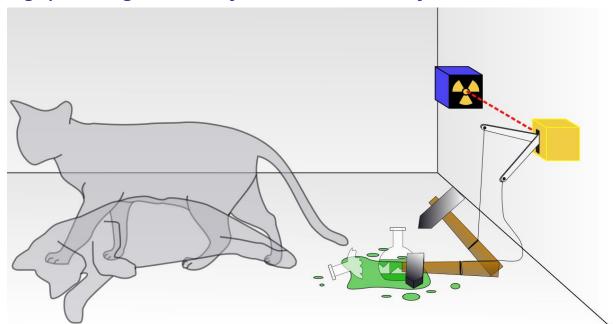
Computational & Multiscale Mechanics of Materials



Introduction to quantum computing and non-linear finite-element (re)formulation for quantum annealing

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Bits vs. Qubits:

- Superposition of states:
 - A quantum bit can be 0 or 1 at the same time



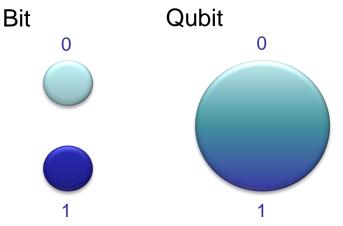
• Computational basis
$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 & $|1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

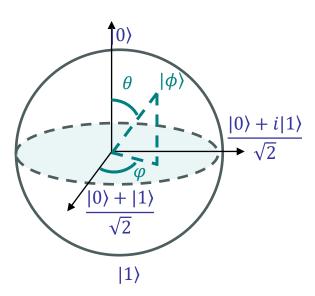
• Notations:
$$\begin{cases} |\phi\rangle = \binom{\alpha}{\beta} = \alpha |0\rangle + \beta |1\rangle \\ |\alpha|^2 + |\beta|^2 = 1 \end{cases}$$
$$|\alpha|^2 + |\beta|^2 = 1$$

Qubit represented on the surface of the Bloch Sphere

$$|\phi\rangle = e^{i\delta} \left(\cos\left(\frac{\theta}{2}\right)|0\rangle + e^{i\varphi}\sin\left(\frac{\theta}{2}\right)|1\rangle\right)$$

- Global phase ${
 m e}^{i\delta}$ has no observable consequence (NB relative phase has consequence)
- At measurement (in the computational basis)
 - Either $|0\rangle$ or $|1\rangle$ with respective probability $|\alpha|^2$ and $|\beta|^2$





Multiple (connected) qubits:

Itiple (connected) qubits:
$$|\phi_0\rangle = \alpha_0|0\rangle + \beta_0|1\rangle$$
 Product state of 2 1-qubit states:
$$|\phi_1\rangle = \alpha_1|0\rangle + \beta_1|1\rangle$$



$$|\pmb{\phi}\rangle = |\phi_0\rangle \otimes |\phi_1\rangle = \alpha_0\alpha_1|00\rangle + \alpha_0\beta_1|01\rangle + \alpha_1\beta_0|10\rangle + \beta_0\beta_1|11\rangle$$

Most general 2-qubit state

$$|\phi\rangle = \alpha_{00}|00\rangle + \alpha_{01}|01\rangle + \alpha_{10}|10\rangle + \alpha_{11}|11\rangle$$



Because of entanglement, a K-qubit state is more general

(it cannot always be written as the product of *K* 1-qubit states)



There is not always *K* equivalent 1-qubit states to a *K*-qubit state, e.g.

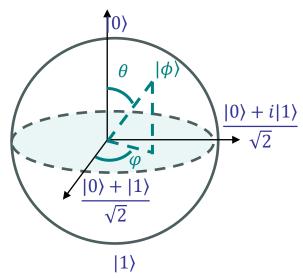
$$|\phi\rangle = \frac{1}{\sqrt{2}}|00\rangle + 0|01\rangle + 0|10\rangle + \frac{1}{\sqrt{2}}|11\rangle$$

- A system of *K* coupled qubits
 - Is a 2^K -state quantum-mechanical system
 - Whose state can be represented by any normalised linear combination of 2^K basis states:

$$|\phi\rangle = \phi_0|0\rangle \otimes |0\rangle \dots \otimes |0\rangle + \phi_1|0\rangle \otimes |0\rangle \dots \otimes |1\rangle + \dots + \phi_{2^K-1}|1\rangle \dots \otimes |1\rangle \otimes |1\rangle$$

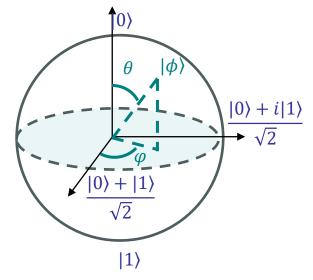
with
$$\sum_{i=0}^{2^{K}-1} |\phi_i|^2 = 1$$

Because of superposition, potentially, a quantum computer with *K* qubits can take 2^K bitstrings of size K in parallel at the same time. A classical computer can only take 1 bitstring of size K



Quantum computers:

- Trapped-ion quantum computer
 - Suspended ions in electromagnetic field
 - Ground state and excited states
 - Interactions controlled by laser
 - E.g. IonQ & Quantinuum
- Photonic quantum computers
 - State corresponds to direction of photon travel
- Superconducting quantum computers
 - Superconducting qubits as artificial atoms (ground state and excited state)
 - Superconducting capacitors and inductors are used to produce a resonant circuit
 - Operate at temperature of 10 mK
 - Qubit state controlled by external microwave signals
 - IBM, D-Wave
- Different platforms (2 different resolution methodologies)
 - IBM
 - 2022: 433-qubit Osprey'
 - 2023: 1121-qubit Condor
 - D-Wave
 - 5000+-qubit Advantage (35000 couplers)
 - Each qubit is only connected to a reduced number of other qubits



Universal gate

- Gate on 1 qubit
 - E.g. Hadamard $\mathbf{H^d} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ $|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $|1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $|0\rangle \boxed{\mathbf{H^d}} \frac{1}{\sqrt{2}} (|0\rangle + |1\rangle)$ $|1\rangle \boxed{\mathbf{H^d}} \frac{1}{\sqrt{2}} (|0\rangle |1\rangle)$
- Gate on 2 qubits

• NB:
$$|01\rangle$$
: $\begin{pmatrix} 1 & \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ 0 & \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{pmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$

• E.g. controlled-not: $\mathbf{C}_{10} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$

$$|x\rangle - |x\rangle - |x\rangle - |x\rangle - |y \oplus x\rangle$$

 $x, y \in \{0,1\}$, the second qubit is flipped if and only if first is 1

E.g. for
$$x = 1$$
 $y = 0$: $|\phi\rangle = 0|00\rangle + 0|01\rangle + 1|10\rangle + 0|11\rangle$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

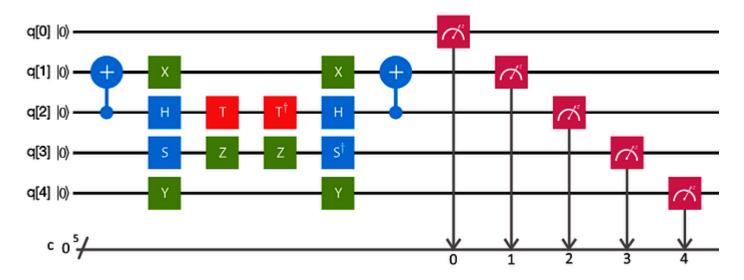
$$|\boldsymbol{\phi}'\rangle = \mathbf{C}_{10}|\boldsymbol{\phi}\rangle = 0|00\rangle + 0|01\rangle + 0|10\rangle + 1|11\rangle$$

Gate on *n* qubits ...



Universal gate

Circuit, e.g. on 5-qubits



Gate-based QC

- Universal approach (like classical computers operations are performed on qubits)
- Highly sensitive to noise difficulty in controlling error
- Error controlled by using control qubits



Quantum annealer

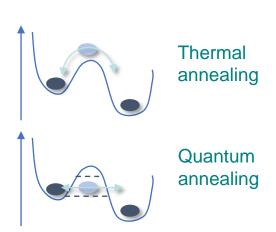
Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$

- Based on quantum adiabatic theorem:
 - Considering a time-varying Hamiltonian $\mathbf{H}_{\mathbf{Q}\mathbf{A}}(t)$ initially at ground state, if its time evolution is slow enough, it is likely to remain at the ground state
- Adiabatic quantum computing:
 - Starts from the ground state of an easy to prepare Hamiltonian H_i
 - Evolves to the ground state of the Hamiltonian H which encodes the sought solution

$$\mathbf{H}_{\mathbf{QA}}(t) = \frac{(t_a - t)}{t_a} \; \mathbf{H}_i + \frac{t}{t_a} \; \mathbf{H}$$

- Quantum annealing
 - Exploits quantum effect such as quantum tunneling
 - Less sensitive to noise than Gate-based QC
 - Less versatile than Gate-based QC



Ising Hamiltonian

Goal: finding the ground state of a Hamiltonian H

$$|\boldsymbol{\phi}_0\rangle = \arg\min_{|\boldsymbol{\phi}\rangle} \langle \boldsymbol{\phi} | \mathbf{H} | \boldsymbol{\phi} \rangle$$

- Some definitions
 - Set of *K* qubits $V = \{0, ... K 1\}$
 - Set of interactions between 2 qubits $E \subset \{(i,j) \mid i \in V, j \in V, i < j\}$
 - Pauli- Z operator $\mathbf{Z} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ and identity $\mathbf{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$
 - Pauli- Z operator applied on qubit i: $\mathbf{Z}_i = \underbrace{\mathbf{I}}_0 \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_i \otimes \mathbf{I} \otimes \cdots \otimes \underbrace{\mathbf{I}}_{K-1}$
 - Pauli- Z operator applied on qubits i and j:

$$\mathbf{Z}_{ij} = \underbrace{\mathbf{I}}_{0} \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_{i} \otimes \mathbf{I} \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_{j} \otimes \mathbf{I} \otimes \cdots \otimes \underbrace{\mathbf{I}}_{K-1}$$

- Ising Hamiltonian represented by an undirected graph (V, E):

•
$$\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$$

• Is a $2^K \times 2^K$ diagonal operator in the computational basis



- Quadratic Unconstrained Binary Optimization (QUBO)
 - Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$
 with $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$

- In terms of spin variables
 - Computational basis of **H** $|\phi\rangle = |b_0 \ b_1 \ ... \ b_{K-1}\rangle$ with $b_i \in \{0, 1\}$
 - We have successively

$$\mathbf{Z} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \qquad \mathbf{Z} |b_i\rangle =$$

$$\mathbf{Z} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \qquad \mathbf{Z} | b_i \rangle = (-1)^{b_i} | b_i \rangle \qquad | 0 \rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad | 1 \rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\mathbf{Z}_i = \underbrace{\mathbf{I}}_0 \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_i \otimes \mathbf{I} \otimes \cdots \otimes \underbrace{\mathbf{I}}_{K-1} \qquad \qquad \mathbf{Z}_i | \boldsymbol{\phi} \rangle = (-1)^{b_i} | \boldsymbol{\phi} \rangle$$



$$\mathbf{Z}_i|\boldsymbol{\phi}\rangle = (-1)^{b_i}|\boldsymbol{\phi}\rangle$$

$$\mathbf{Z}_{ij} = \underbrace{\mathbf{I}}_{0} \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_{i} \otimes \mathbf{I} \otimes \cdots \otimes \mathbf{I} \otimes \underbrace{\mathbf{Z}}_{j} \otimes \mathbf{I} \otimes \cdots \otimes \underbrace{\mathbf{I}}_{K-1} \qquad \mathbf{Z}_{ij} |\boldsymbol{\phi}\rangle = (-1)^{b_{i}} (-1)^{b_{j}} |\boldsymbol{\phi}\rangle$$



$$\mathbf{Z}_{ij}|\boldsymbol{\phi}\rangle = (-1)^{b_i}(-1)^{b_j}|\boldsymbol{\phi}\rangle$$

Defining the vector of spin variables: $\mathbf{s} = [(-1)^{b_i} \ \forall i \in V]$



The eigenvalue of **H** reads $\mathcal{F}_{\text{Ising}} = \sum_{i \in V} h_i s_i + \sum_{(i,j) \in F} J_{ij} s_i s_j = \mathbf{s}^T \mathbf{h} + \mathbf{s}^T \mathbf{J} \mathbf{s}$

with
$$\mathbf{h} = [h_i \ \forall i \in V] \ \& \ \mathbf{J} = [J_{ij} \ \forall (i,j) \in E]$$



$$|\phi_0\rangle = \arg\min_{\phi} \langle \phi | \mathbf{H} | \phi \rangle$$



$$|\phi_0\rangle = \arg\min_{\phi} \langle \phi | \mathbf{H} | \phi \rangle$$
 $\mathbf{s} = \arg\min_{\mathbf{s}'} \mathcal{F}_{\text{Ising}}(\mathbf{s}'; \mathbf{h}, \mathbf{J})$

User programmable parameters

- Quadratic Unconstrained Binary Optimization (QUBO)
 - Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$
 with $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$

- In terms of spin variables
 - Computational basis of **H** $|\phi\rangle = |b_0 \ b_1 \ ... \ b_{K-1}\rangle$ with $b_i \in \{0, 1\}$
 - Vector of spin variables: $\mathbf{s} = [(-1)^{b_i} \ \forall i \in V]$

The eigenvalue of
$$\mathbf{H}$$
 reads $\mathcal{F}_{\mathrm{Ising}} = \sum_{i \in V} h_i s_i + \sum_{(i,j) \in E} J_{ij} s_i s_j = \mathbf{s}^T \mathbf{h} + \mathbf{s}^T \mathbf{J} \mathbf{s}$
with $\mathbf{h} = [h_i \ \forall i \in V]$ & $\mathbf{J} = [J_{ij} \ \forall (i,j) \in E]$ User programmable $|\phi_0\rangle = \arg\min_{\phi} \langle \phi | \mathbf{H} | \phi \rangle$ $\mathbf{s} = \arg\min_{\mathbf{s}'} \mathcal{F}_{\mathrm{Ising}}(\mathbf{s}'; \mathbf{h}, \mathbf{J})$ parameters

- In terms of binary variables
 - Vector of binary variables $\mathbf{b} = [b_i \ \forall i \in V]$
 - Spin-binary variable transformation $s_i = 2b_i 1 : \{0,1\} \rightarrow \{-1,1\}$ & property $b_i^2 = b_i$

$$\mathcal{F}_{\text{Ising}} = \sum_{i \in V} h_i s_i + \sum_{(i,j) \in E} J_{ij} s_i s_j \qquad \mathcal{F}_{\text{QUBO}} = \sum_{(i,j) \in E \cup \{(i,i) \forall i \in V\}} A_{ij} b_i b_j = \mathbf{b}^T \mathbf{A} \mathbf{b}$$

$$|\phi_0\rangle = \arg\min_{\phi} \langle \phi | \mathbf{H} | \phi \rangle \qquad \mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A}) \qquad \text{User programmable parameters}$$

Summary

Goal: finding the ground state of a Hamiltonian H

$$|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$$
 with $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$

- Adiabatic annealing
 - Starts from the ground state of an easy to prepare H_i
 - Evolves to the ground state of the Hamiltonian H

$$\mathbf{H}_{\mathbf{QA}}(t) = \frac{(t_a - t)}{t_a} \; \mathbf{H}_i + \frac{t}{t_a} \; \mathbf{H}$$



Quantum annealing

- Problem reformulated in terms of binary variables
 - **b** = $[b_i \, \forall i \in V]$ with $b_i \in \{0, 1\}$
 - Eigenvalue $\mathcal{F}_{OUBO} = \mathbf{b}^T \mathbf{A} \mathbf{b}$
 - QUBO optimization $\mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A})$

User programmable parameters

- In practice
 - Provide the QUBO matrix A
 - Set the annealing time t_a (typically 20 μ s)
 - One annealing returns a sample of b
 - A single run may not provide the global minimum due to environmental noises, hardware imperfections, pre- and post-processing errors

 requires several reads

Set of PDEs to be solved

- Strong form Weak form:
$$\nabla \cdot \sigma(x) + b_0(x) = 0 \qquad \int_V \sigma(x) : \nabla \otimes^s \delta u(x) dV = \int_V b_0 \cdot \delta u dV + \int_{\partial_N V} n \cdot \sigma \cdot \delta u d\partial V$$

Constitutive model:

$$\sigma(x,t) = \sigma\big(\nabla \otimes^{s} u(x,t); \mathbf{q}(x,t)\big) \quad \text{with evolution law} \quad \mathcal{Q}\big(\sigma(x,t), \mathbf{q}(\nabla \otimes^{s} u(x,\tau); \tau \leq t)\big) = \mathbf{0}$$

Finite element formulation

Displacement field at quadrature point E from nodal displacements vector U

$$\boldsymbol{u}(\Xi) = N_a(\Xi)\boldsymbol{U}_a$$



$$\boldsymbol{u}(\Xi) = N_a(\Xi)\boldsymbol{U}_a$$

$$\boldsymbol{\varepsilon}(\Xi) = \boldsymbol{\nabla} \otimes^s \boldsymbol{u}(\Xi) = \boldsymbol{B}_a(\Xi)\boldsymbol{U}_a$$

Resulting non-linear system of equations on time interval $[t_n \ t_{n+1}]$

$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}, t) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV + \int_{\partial_{N} V} \boldsymbol{n} \cdot \boldsymbol{\sigma} \cdot \boldsymbol{\delta u} d\partial V$$

$$\delta \boldsymbol{U}_{\boldsymbol{b}}^{\mathrm{T}} \cdot \sum_{\Xi} \mathbf{B}_{\boldsymbol{b}}^{\mathrm{T}}(\Xi) \, \boldsymbol{\sigma}((\Xi)) \omega^{\Xi} = \delta \boldsymbol{U}_{\boldsymbol{b}}^{\mathrm{T}} \cdot \sum_{\Xi} N_{\boldsymbol{b}}(\Xi) \, \boldsymbol{b}_{0}(\Xi) \omega^{\Xi}$$

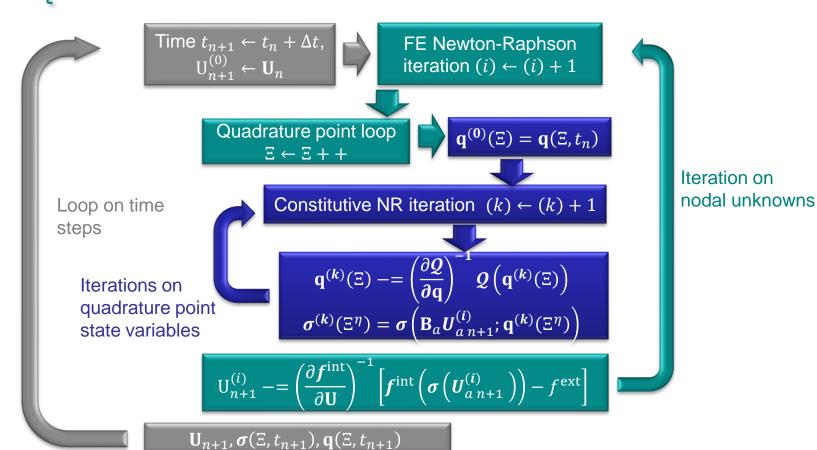
Omitting surface tractions

$$\boldsymbol{f}_b^{\text{int}} = \sum_{\Xi} \mathbf{B}_b^{\text{T}}(\Xi) \, \boldsymbol{\sigma}(\Xi) \omega^{\Xi} = \sum_{\Xi} N_b(\Xi) \, \boldsymbol{b}_0(\Xi) \omega^{\Xi} = \boldsymbol{f}_b^{\text{ext}}$$

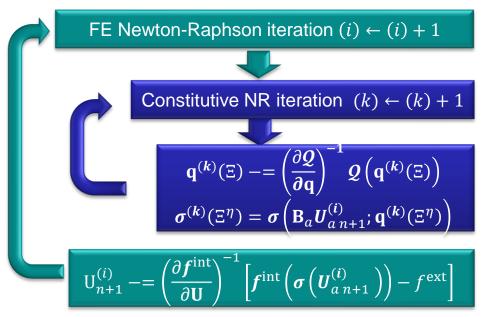
with
$$\begin{cases} \boldsymbol{\sigma}(\Xi, t_{n+1}) = \boldsymbol{\sigma}\big(\mathbf{B}_a(\Xi)\boldsymbol{U}_{a\,n+1}; \mathbf{q}(\Xi, t_{n+1})\big) \\ \boldsymbol{Q}\big(\boldsymbol{\sigma}(\Xi, t_{n+1}), \mathbf{q}(\Xi, t_{n+1}), \mathbf{q}(\Xi, t_n)\big) = \mathbf{0} \end{cases}$$

Finite element formulation

- Resulting non-linear system of equations on time interval $[t_n t_{n+1}]$



Consider classical finite element resolution on Quantum Computers?



- What can be solved on a Quantum Computer?
 - Optimization problems can be solved (Actually Quantum Annealers look for a ground state)
 - Some operations can be achieved efficiently on classical computers like assembly
- Do we need the same resolution structure?
 - Do we need intricated NR loops?
 - Do we even need to use the discretized form of the weak form?

$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV \qquad \qquad \boldsymbol{f}_{b}^{\text{int}} = \sum_{\Xi} \mathbf{B}_{b}^{\text{T}}(\Xi) \boldsymbol{\sigma}(\Xi) \omega^{\Xi} = \boldsymbol{f}_{b}^{\text{ext}}$$



- Linear finite element resolution on Quantum Computers?
 - Assuming linear elasticity
 - Existence of a free energy $\Psi = \frac{1}{2} \varepsilon(x)$: $\mathbb{C}(x)$: $\varepsilon(x)$ with $\varepsilon(x) = \nabla \otimes^s u(x)$
 - Stress results from $\sigma(x) = \frac{\partial \Psi}{\partial \varepsilon} = \mathbb{C}(x)$: $\varepsilon(x) = \mathbb{C}(x)$: $(\nabla \otimes^s u(x))$
 - Finite element form:
 - At quadrature point using nodal shape function derivatives: $\sigma(\Xi) = C(\Xi)B_a(\Xi)U_a$
 - FE equations $f_b^{\text{int}} = \sum_{\Xi} \mathbf{B}_b^{\text{T}}(\Xi) \, \sigma(\Xi) \omega^{\Xi} = f_b^{\text{ext}}$

$$\sum_{\Xi} \mathbf{B}_b^{\mathrm{T}}(\Xi) \mathbf{C}(x) \mathbf{B}_a \omega^{\Xi} \mathbf{U}_a = \mathbf{K}_{ab} \mathbf{U}_a = \mathbf{f}_b^{\mathrm{ext}}$$

Defining the internal energy and work of external forces

$$\Phi = \frac{1}{2} \boldsymbol{U}_b \mathbf{K}_{ab} \boldsymbol{U}_a - W^{\text{ext}}$$
 with $W^{\text{ext}} = \boldsymbol{f}_b^{\text{ext}} \boldsymbol{U}_b$



The solution of the FE equations minimizes the energy

$$\mathbf{U} = \arg\min_{\mathbf{U}'} \left(\frac{1}{2} \mathbf{U'}^{\mathrm{T}} \mathbf{K} \mathbf{U'} - \mathbf{f}^{\mathrm{ext}^{\mathrm{T}}} \mathbf{U'} \right)$$

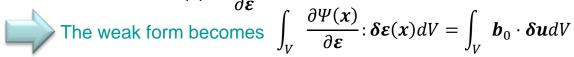
We are looking for the ground state of a Hamiltonian

$$\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in E} J_{ij} \mathbf{Z}_{ij}$$

Non-linear finite element resolution on Quantum Computers?

- Weak form:
$$\int_{V} \boldsymbol{\sigma}(\boldsymbol{x}) : \nabla \otimes^{s} \boldsymbol{\delta u}(\boldsymbol{x}) dV = \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta u} dV$$

- Assuming non-linear elasticity
 - Existence of a free energy $\Psi(\varepsilon(x))$ with $\varepsilon(x) = \nabla \otimes^s u(x)$
 - Stress results from $\sigma(x) = \frac{\partial \Psi}{\partial \varepsilon}$



Introduction of a functional

The weak form results from nulling the Gâteaux derivative

$$\Phi'\left(\boldsymbol{u}(V);\delta\boldsymbol{u}(V)\right) = \int_{V} \boldsymbol{\sigma}(\boldsymbol{x}): \nabla \otimes^{s} \boldsymbol{\delta}\boldsymbol{u}(\boldsymbol{x})dV - \int_{V} \boldsymbol{b}_{0} \cdot \boldsymbol{\delta}\boldsymbol{u}dV = \boldsymbol{0}$$



The solution of the weak form minimizes the energy: $u(V) = \arg\min_{u'(V)} \Phi(u'(V))$

- We are looking for the solution of a minimization problem
 - The potential is convex
 - But it is not quadratic
 - Quid inelastic materials?

- Non-linear finite element resolution on Quantum Computers?
 - Inelastic materials
 - Existence of a Helmholtz free energy $\Psi(\varepsilon(x), \mathbf{q}(x))$ with $\varepsilon(x) = \nabla \otimes^s \mathbf{u}(x)$
 - Dissipation $\mathcal D$ and Clausius-Duhem inequality

•
$$\mathcal{D} = \boldsymbol{\sigma} : \dot{\boldsymbol{\varepsilon}} - \dot{\boldsymbol{\Psi}} \ge 0$$
 with $\dot{\boldsymbol{\Psi}} = \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} + \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\sigma}} \cdot \dot{\boldsymbol{q}}$

• Equality holds in case of a reversible transformation

$$\boldsymbol{\sigma} = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} \qquad \text{for an irreversible process:} \quad \mathcal{D} = \mathbf{Y} \cdot \dot{\mathbf{q}} \ge 0 \quad \text{with} \quad \mathbf{Y} = -\frac{\partial \Psi}{\partial \mathbf{q}}$$

Postulate the existence of a pseudo-potential $\Theta(\dot{\mathbf{q}})$ and its convex dual $\Theta^*(\mathbf{Y})$

•
$$\theta(\dot{\mathbf{q}}) = \max_{\mathbf{Y}} [\mathbf{Y} \cdot \dot{\mathbf{q}} - \theta^*(\mathbf{Y})]$$
 $\dot{\mathbf{q}} = \frac{\partial \theta^*(\mathbf{Y})}{\partial \mathbf{Y}}$ & $\mathbf{Y} = \frac{\partial \theta(\dot{\mathbf{q}})}{\partial \dot{\mathbf{q}}}$

- Power functional \mathcal{E}
 - New independent variables $(\dot{\varepsilon}, \dot{q})$

•
$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) = \dot{\boldsymbol{\Psi}} + \boldsymbol{\Theta}(\dot{\mathbf{q}}) = \frac{\partial \boldsymbol{\Psi}}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} - \mathbf{Y} \cdot \dot{\mathbf{q}} + \boldsymbol{\Theta}(\dot{\mathbf{q}})$$

$$\frac{\partial \mathcal{E}}{\partial \dot{\mathbf{q}}} = -\mathbf{Y} + \frac{\partial \Theta(\dot{\mathbf{q}})}{\partial \dot{\mathbf{q}}} = \mathbf{0}$$
 \(\mathcal{\mathcal{E}}\) has to be minimized with respect to internal state

- Effective power functional* $\mathcal{E}^{\mathrm{eff}}(\dot{\boldsymbol{\varepsilon}}) = \min_{\dot{\mathbf{q}}} \mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}})$ with $\boldsymbol{\sigma} = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} = \frac{\partial \mathcal{E}^{\mathrm{eff}}}{\partial \dot{\boldsymbol{\varepsilon}}}$
- The constitutive model is also a minimization problem

*Radovitzky, R. Ortiz M, CMAME 1999 Ortiz, M., Stainier, L., CMAME 1999



- Non-linear finite element resolution on Quantum Computers?
 - In elasticity we had

•
$$u(V) = \arg\min_{u'(V)} \Phi(u'(V))$$
 with $\Phi(u(V)) = \int_{V} \Psi(\nabla \otimes^{s} u(x)) dV - W^{\text{ext}}(u(x))$

- Double minimization problem in inelasticity
 - Power functional \mathcal{E}

$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) = \frac{\partial \Psi}{\partial \boldsymbol{\varepsilon}} : \dot{\boldsymbol{\varepsilon}} - \mathbf{Y} \cdot \dot{\mathbf{q}} + \Theta(\dot{\mathbf{q}}) \qquad & \mathcal{E}^{\text{eff}}(\dot{\boldsymbol{\varepsilon}}) = \min_{\dot{\mathbf{q}}} \mathcal{E}(\dot{\boldsymbol{\varepsilon}}, \dot{\mathbf{q}}) \qquad & \boldsymbol{\sigma} = \frac{\partial \mathcal{E}^{\text{eff}}}{\partial \dot{\boldsymbol{\varepsilon}}}$$

Volume power functional

$$\Phi(\dot{\boldsymbol{u}}(V), \dot{\mathbf{q}}(V)) = \int_{V} \mathcal{E}(\nabla \otimes^{S} \dot{\boldsymbol{u}}, \dot{\mathbf{q}}) - \dot{W}^{\text{ext}}(\dot{\boldsymbol{u}}(V))$$

• Incremental volume energy functional on time interval $[t_n \ t_{n+1}]^*$

$$\begin{split} \Delta \varPhi(\boldsymbol{u}_{n+1}, \boldsymbol{q}_{n+1}) &= \int_{V} \Delta \mathcal{E}(\boldsymbol{\nabla} \otimes^{s} \boldsymbol{u}_{n+1}, q_{n+1}) - \Delta W^{\text{ext}}(\boldsymbol{u}_{n+1}) \\ \text{with} \quad \Delta \mathcal{E}(\boldsymbol{\nabla} \otimes^{s} \boldsymbol{u}_{n+1}, \boldsymbol{q}_{n+1}) &= \int_{t_{n}}^{t_{n+1}} \mathcal{E}(\boldsymbol{\nabla} \otimes^{s} \dot{\boldsymbol{u}}, \dot{\boldsymbol{q}}) \quad \& \ \Delta \mathcal{E}^{\text{eff}}(\boldsymbol{\varepsilon}) = \min_{\boldsymbol{q}} \Delta \mathcal{E}(\boldsymbol{\varepsilon}, \boldsymbol{q}) \quad , \quad \boldsymbol{\sigma} = \frac{\partial \Delta \mathcal{E}^{\text{eff}}}{\partial \boldsymbol{\varepsilon}} \end{split}$$

The problem solution reads

$$\mathbf{q}_{n+1} = \arg\min_{\mathbf{q}'} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')$$

$$\Delta \Phi^{\text{eff}}(\mathbf{u}_{n+1}) = \min_{\mathbf{q}'} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}') = \int_{V} \Delta \mathcal{E}^{\text{eff}}(\nabla \otimes^{s} \mathbf{u}_{n+1}) - \Delta W^{\text{ext}}$$

$$\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')$$
*

*Ortiz, M., Stainier, L., CMAME 1999



Example: J2-elasto-plasticity

Helmholtz free energy

•
$$\Psi(\boldsymbol{\varepsilon}, \mathbf{q}) = \frac{1}{2} (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}^{\text{pl}}) : \mathbb{C}^{\text{el}} : (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}^{\text{pl}})$$
 with $\Delta \boldsymbol{\varepsilon}^{\text{pl}} = \Delta \gamma \mathbf{N}$



Internal variables $\mathbf{q} = \{\mathbf{N}, \Delta \gamma\}$ under constraints $\mathbf{N}: \mathbf{N} = \frac{3}{2}$, $\mathrm{tr}(\mathbf{N}) = 0$ & $\Delta \gamma \ge 0$

Dissipation pseudo-potential

$$\boldsymbol{\theta}(\dot{\mathbf{q}}) = \begin{cases} \left(\sigma_y^0 + R(\gamma)\right)\dot{\gamma} & \text{if } \dot{\gamma} \ge 0\\ \infty & \text{otherwise} \end{cases} \qquad \boldsymbol{\theta}^*(\mathbf{Y}) = \begin{cases} 0 & \text{if } \sigma_{\text{eq}} - \sigma_y^0 - R \le 0\\ \infty & \text{otherwise} \end{cases}$$



$$\Theta^*(\mathbf{Y}) = \begin{cases} 0 & \text{if } \sigma_{\text{eq}} - \sigma_y^0 - R \le 0\\ \infty & \text{otherwise} \end{cases}$$

Increment of the energy functional

•
$$\mathcal{E}(\dot{\boldsymbol{\varepsilon}},\dot{\mathbf{q}}) = \dot{\boldsymbol{\Psi}} + \boldsymbol{\Theta}(\dot{\mathbf{q}})$$

$$\Delta \mathcal{E}(\boldsymbol{\varepsilon}_{n+1}, \mathbf{q}) = \frac{1}{2} \left(\boldsymbol{\varepsilon}_{n+1} - \Delta \gamma \mathbf{N} - \boldsymbol{\varepsilon}_{n}^{\mathrm{pl}} \right) : \mathbb{C}^{\mathrm{el}} : \left(\boldsymbol{\varepsilon}_{n+1} - \Delta \gamma \mathbf{N} - \boldsymbol{\varepsilon}_{n}^{\mathrm{pl}} \right) + \int_{\gamma_{n}}^{\gamma_{n+1}} \left(\sigma_{y}^{0} + R(\gamma') \right) d\gamma'$$

$$- \frac{1}{2} \left(\boldsymbol{\varepsilon}_{n} - \boldsymbol{\varepsilon}_{n}^{\mathrm{pl}} \right) : \mathbb{C}^{\mathrm{el}} : \left(\boldsymbol{\varepsilon}_{n} - \boldsymbol{\varepsilon}_{n}^{\mathrm{pl}} \right)$$

$$\Delta \mathcal{E}^{\mathrm{eff}}(\boldsymbol{\varepsilon}) = \min_{\mathbf{q}} \Delta \mathcal{E}(\boldsymbol{\varepsilon}, \mathbf{q}) \qquad \text{with constraints} \qquad \mathbf{N} : \mathbf{N} = \frac{3}{2}, \quad \mathrm{tr}(\mathbf{N}) = 0 \quad \& \ \Delta \gamma \geq 0$$

$$\Delta \mathcal{E}^{\mathrm{eff}}(\boldsymbol{\varepsilon}) = \min_{\mathbf{q}} \Delta \mathcal{E}(\boldsymbol{\varepsilon}, \mathbf{q})$$

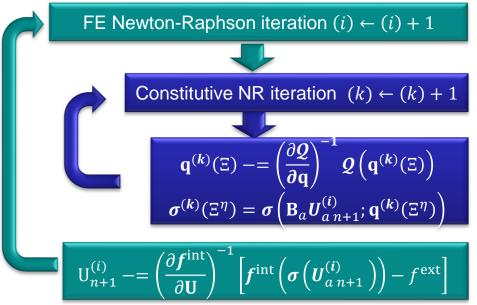
$$N: N = \frac{3}{2}, tr(N) = 0$$

$$\Delta \gamma \geq 0$$

The problem is stated as a double constrained minimization problem

$$\begin{bmatrix} \mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}') \\ \Delta \Phi^{\text{eff}}(\mathbf{u}_{n+1}) = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}') = \int_{V} \Delta \mathcal{E}^{\text{eff}}(\nabla \otimes^{s} \mathbf{u}_{n+1}) - \Delta W^{\text{ext}} \\ \mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}') \end{bmatrix}$$

Classical finite element resolution



Finite element as a double-minimization problem

```
Loop until convergence \mathbf{q}_{n+1} = rg \min_{\mathbf{q}' 	ext{constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');
\Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' 	ext{constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')
\mathbf{u}_{n+1} = rg \min_{\mathbf{u}' 	ext{admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')
```

- Quantum annealers: ground state of an Ising-Hamiltonian
 - No need for Jacobians
 - No problem of convergence
- But how to make the optimisation problem solvable by quantum annealing?



- Finite element as a double-minimization problem
 - Finite element problem

```
Loop until convergence

\mathbf{q}_{n+1} = \arg \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');

           \Delta \Phi^{\mathrm{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')
           u_{n+1} = \arg \min_{\mathbf{u}' \text{admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')
```

- Ising Hamiltonian for Quantum annealing
 - Goal: finding the ground state of a Hamiltonian H: $\mathbf{H} = \sum_{i \in V} h_i \mathbf{Z}_i + \sum_{(i,j) \in F} J_{ij} \mathbf{Z}_{ij}$ $|\phi_0\rangle = \arg\min_{|\phi\rangle} \langle \phi | \mathbf{H} | \phi \rangle$
 - Problem reformulated in terms of binary variables $\mathbf{b} = [b_i \ \forall i \in V]$ with $b_i \in \{0, 1\}$
 - QUBO optimisation problem $\mathcal{F}_{\text{QUBO}} = \sum_{(i,j) \in E \cup \{(i,i) \forall i \in V\}} A_{ij} b_i b_j = \mathbf{b}^T \mathbf{A} \mathbf{b}$ $\mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A}) \quad \text{User programmable parameters}$

$$\mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}';$$

- Steps to follow
 - Transform the constrained minimization problem into an unconstrained one
 - Transform the general unconstrained optimization problem into a series of quadratic ones
 - Transform each continuous quadratic optimization problem into a binarized one
 - Apply to the double-minimization framework



- Transform the constrained minimization problem into an unconstrained one
 - Constrained multivariate minimization problem
 - $\min_{\mathbf{w}} f(\mathbf{w})$ with $\mathbf{w}^{\min} \le \mathbf{w} \le \mathbf{w}^{\max}$
 - Under constraints $h(\mathbf{w}) = 0$ & $l(\mathbf{w}) \le 0$
 - Augmented minimization problem

•
$$f_{\text{aug}}(\mathbf{v}) = f_{\text{aug}}(\mathbf{w}, \lambda) = f(\mathbf{w}) + c^h(h(\mathbf{w}))^2 + c^l(l(\mathbf{w}) + \lambda)^2$$
 with $\mathbf{v} = \{\mathbf{w}, \lambda \ge 0\}$

- Unconstrained minimization problem
 - $\min_{\mathbf{v}} f_{\text{aug}}(\mathbf{v})$ with $\mathbf{v}^{\min} \leq \mathbf{v} \leq \mathbf{v}^{\max}$
 - Bounds will be enforced during the binarization process
- Definition of the double-unconstrained minimization problem

```
Loop until convergence \mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');
\Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')
\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')
```



```
Loop until convergence \mathbf{q}_{n+1}, \lambda = \arg\min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}', \lambda'); \Delta \Phi^{\mathrm{eff}} = \min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}', \lambda') \boldsymbol{u}_{n+1} = \arg\min_{\mathbf{u}' \mathrm{admissible}} \Delta \Phi^{\mathrm{eff}}(\mathbf{u}')
```

- Transform the constrained minimization problem into an unconstrained one
 - E.g. J2-plasticity

$$\Delta \mathcal{E} = \frac{1}{2} \left(\boldsymbol{\varepsilon}_{n+1} - \Delta \gamma \mathbf{N} - \boldsymbol{\varepsilon}_{n}^{\text{pl}} \right) : \mathbb{C}^{\text{el}} : \left(\boldsymbol{\varepsilon}_{n+1} - \Delta \gamma \mathbf{N} - \boldsymbol{\varepsilon}_{n}^{\text{pl}} \right) + \int_{\gamma_{n}}^{\gamma_{n+1}} \left(\sigma_{y}^{0} + R(\gamma') \right) d\gamma'$$

$$- \frac{1}{2} \left(\boldsymbol{\varepsilon}_{n} - \boldsymbol{\varepsilon}_{n}^{\text{pl}} \right) : \mathbb{C}^{\text{el}} : \left(\boldsymbol{\varepsilon}_{n} - \boldsymbol{\varepsilon}_{n}^{\text{pl}} \right)$$

- Under constraints N: $N = \frac{3}{2}$, $tr(N) = 0 & \Delta \gamma \ge 0$
- Change of variables

$$\begin{bmatrix} \mathbf{N} : \mathbf{N} = \boldsymbol{\alpha}^{T} \mathbf{M} \boldsymbol{\alpha} = \frac{3}{2} \\ \boldsymbol{\alpha} = [\alpha_{0} \dots \alpha_{4}]^{T}, -\sqrt{\frac{3}{2}} \le \alpha_{i} \le -\sqrt{\frac{3}{2}}, & \mathbf{N} = \begin{bmatrix} \alpha_{0} & \alpha_{2}/\sqrt{2} & \alpha_{2}/\sqrt{2} \\ & \alpha_{1} & \alpha_{4}/\sqrt{2} \\ \text{SYM} & -\alpha_{0} - \alpha_{1} \end{bmatrix} & \mathbf{\&} & \mathbf{M} = \mathbf{cst} \end{bmatrix}$$

Definition of the double unconstrained minimization problem

Loop until convergence $\mathbf{q}_{n+1} = \arg\min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}');$ $\Delta \Phi^{\text{eff}} = \min_{\mathbf{q}' \text{ constrained}} \Delta \Phi(\mathbf{u}_{n+1}, \mathbf{q}')$ $\mathbf{u}_{n+1} = \arg\min_{\mathbf{u}' \text{ admissible}} \Delta \Phi^{\text{eff}}(\mathbf{u}')$



Loop until convergence
$$\{\Delta\gamma, \boldsymbol{\alpha}\} = \arg\min_{\{\Delta\gamma', \boldsymbol{\alpha}'\}} \left[\int_{V} \Delta\mathcal{E}\left(\boldsymbol{u}_{n+1}, \Delta\gamma', \boldsymbol{\alpha}'\right) + c^{h} \left(\boldsymbol{\alpha}^{T} \mathbf{M}\boldsymbol{\alpha} - \frac{3}{2}\right)^{2} dV \right]$$

$$\Delta\Phi^{\mathrm{eff}} = \min_{\{\Delta\gamma', \boldsymbol{\alpha}'\}} \Delta\Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \Delta\gamma', \boldsymbol{\alpha}')$$

$$\boldsymbol{u}_{n+1} = \arg\min_{\boldsymbol{u}' \, \mathrm{admissible}} \Delta\Phi^{\mathrm{eff}}(\boldsymbol{u}')$$

- Transform the optimization problem into a series of quadratic ones
 - Unconstrained optimization problem
 - $\min_{\mathbf{v}} f_{\text{aug}}(\mathbf{v})$ with $\mathbf{v}^{\text{min}} \leq \mathbf{v} \leq \mathbf{v}^{\text{max}}$ Taylor's expansion
 $f_{\text{aug}}(\mathbf{v} + \mathbf{z}) \simeq f_{\text{aug}}(\mathbf{v})$ $f_{\text{aug}}(\mathbf{v} + \mathbf{z}) \simeq f_{\text{aug}}(\mathbf{v})$
 - New series of optimization problems
 - Iterate on **z** with: $\mathbf{z} = \arg\min_{\mathbf{z}'} QF(\mathbf{z}'; f_{\text{aug},\mathbf{v}}, f_{\text{aug},\mathbf{vv}})$
 - Application to the double minimisation problem

```
Loop until convergence \mathbf{q}_{n+1}, \lambda = \arg\min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}', \lambda'); \Delta \Phi^{\mathrm{eff}} = \min_{\{\mathbf{q}', \lambda'\}} \Delta \Phi_{\mathrm{aug}}(\boldsymbol{u}_{n+1}, \mathbf{q}', \lambda') \boldsymbol{u}_{n+1} = \arg\min_{\mathbf{u}' \mathrm{admissible}} \Delta \Phi^{\mathrm{eff}}(\mathbf{u}')
```



Loop until convergence

Loop on
$$u_{n+1} \leftarrow u_{n+1} + \Delta u$$

$$\Delta u = \arg \min_{\Delta u' \text{admissible}} \Delta u'^{\text{T}} \Delta \Phi_{,\mathbf{u}}^{\text{eff}} + \frac{1}{2} \Delta u'^{\text{T}} \Delta \Phi_{,\mathbf{u}\mathbf{u}}^{\text{eff}} \Delta u'$$
Loop on $q_{n+1} \leftarrow q_{n+1} + \Delta \mathbf{q}, \lambda \leftarrow \lambda + \Delta \lambda$

$$\Delta \mathbf{q}, \Delta \lambda = \arg \min_{\{\Delta \mathbf{q}', \Delta \lambda'\}} [\Delta \mathbf{q}'^{\text{T}} \Delta \lambda'] \Delta \Phi_{\text{aug}, \{\mathbf{q} \ \lambda\}} + \frac{1}{2} [\Delta \mathbf{q}'^{\text{T}} \Delta \lambda'] \Delta \Phi_{\text{aug}, \{\mathbf{q} \ \lambda\}} [\Delta \mathbf{q}'^{\text{T}} \Delta \lambda']^{\text{T}}$$

$$\Delta \Phi^{\text{eff}} = \Delta \Phi_{\text{aug}}(u_{n+1}, \mathbf{q}_{n+1}, \lambda)$$

- Transform the optimization problem into a series of quadratic ones
 - E.g. J2-plasticity
 - Minimization with respect to the internal variables (at constant displacement field)

$$- \Delta \Phi_{\text{aug}}(\boldsymbol{u}_{n+1}, \Delta \gamma, \boldsymbol{\alpha}) = \int_{V} \Delta \mathcal{E}(\boldsymbol{u}_{n+1}, \Delta \gamma', \boldsymbol{\alpha}) + c^{h} \left(\boldsymbol{\alpha}^{T} \mathbf{M} \boldsymbol{\alpha} - \frac{3}{2}\right)^{2} dV - \Delta W^{\text{ext}}(\boldsymbol{u}_{n+1})$$
with $\Delta \mathcal{E} = \frac{1}{2} \left(\boldsymbol{\varepsilon}_{n+1} - \Delta \gamma \mathbf{N} - \boldsymbol{\varepsilon}_{n}^{\text{pl}}\right) : \mathbb{C}^{\text{el}} : \left(\boldsymbol{\varepsilon}_{n+1} - \Delta \gamma \mathbf{N} - \boldsymbol{\varepsilon}_{n}^{\text{pl}}\right) + \int_{\gamma_{n}}^{\gamma_{n+1}} \left(\sigma_{y}^{0} + R(\gamma')\right) d\gamma'$

$$- \frac{1}{2} \left(\boldsymbol{\varepsilon}_{n} - \boldsymbol{\varepsilon}_{n}^{\text{pl}}\right) : \mathbb{C}^{\text{el}} : \left(\boldsymbol{\varepsilon}_{n} - \boldsymbol{\varepsilon}_{n}^{\text{pl}}\right)$$

$$\Delta \Phi_{\mathrm{aug},\alpha} = \sum_{\Xi} \left(\Delta \mathcal{E}_{,\mathbf{N}} : \frac{\partial \mathbf{N}}{\partial \alpha} + 2 c^h \mathbf{M} \alpha \left(\alpha^T \mathbf{M} \alpha - \frac{3}{2} \right) \right) \omega^{\Xi} \qquad \& \quad \Delta \Phi_{\mathrm{aug},\Delta\gamma} = \sum_{\Xi} \Delta \mathcal{E}_{,\Delta\gamma} \omega^{\Xi}$$

$$\Delta \Phi_{\mathrm{aug},\alpha\alpha}, \ \Delta \Phi_{\mathrm{aug},\alpha\Delta\gamma}, \ \Delta \Phi_{\mathrm{aug},\Delta\gamma\alpha}, \ \Delta \Phi_{\mathrm{aug},\Delta\gamma\alpha}, \ \Delta \Phi_{\mathrm{aug},\Delta\gamma\Delta\gamma}$$

Minimization with respect to u_{n+1} (at constant internal variables)

$$- \Delta \Phi^{\rm eff}(\boldsymbol{u}_{n+1}) = \int_{V} \Delta \mathcal{E}^{\rm eff}(\boldsymbol{u}_{n+1}) \, dV - \Delta W^{\rm ext}(\boldsymbol{u}_{n+1}) \qquad \text{with} \quad \boldsymbol{\sigma} = \frac{\partial \Delta \mathcal{E}^{\rm eff}}{\partial \boldsymbol{\varepsilon}}$$

$$\Delta \Phi_{\mathbf{,u}}^{\mathrm{eff}}(\boldsymbol{u}_{n+1}) = \sum_{\Xi} \mathbf{B}^{\mathrm{T}}(\Xi) \, \boldsymbol{\sigma}(\Xi) \omega^{\Xi} - \mathbf{f}^{\mathrm{ext}}$$
Constant material tensor
$$\Delta \Phi_{\mathbf{,uu}}^{\mathrm{eff}}(\boldsymbol{u}_{n+1}) = \sum_{\Xi} \mathbf{B}^{\mathrm{T}}(\Xi) \, \mathbb{C}^{\mathrm{el}}(\Xi) \mathbf{B}(\Xi) \omega^{\Xi} - \mathbf{f}^{\mathrm{ext}}$$

Only assembly operations required Performed on classical computers



- Transform each continuous quadratic optimization problem into a binarized one
 - Optimization problems to be solved

•
$$\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}', f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}})$$
 & $\mathrm{QF}(\mathbf{z}; f_{\mathrm{aug},\mathbf{v}}, f_{\mathrm{aug},\mathbf{vv}}) = \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{v}} + \frac{1}{2} \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug},\mathbf{vv}} \mathbf{z}$

- With bounds: $v_{min} \le v + z \le v_{max}$
- These are Ising Hamiltonians to be minimized, but not of the QUBO type
- QUBO
 - **b** = $[b_i \, \forall i \in V]$ with $b_i \in \{0, 1\}$
 - Eigen value $\mathcal{F}_{\text{QUBO}} = \mathbf{b}^T \mathbf{A} \mathbf{b}$
 - QUBO optimization $\mathbf{b} = \arg\min_{\mathbf{b}'} \mathcal{F}_{\text{QUBO}}(\mathbf{b}'; \mathbf{A})$ parameters

User programmable parameters

- Binary-decimal conversion of a scalar field
 - Definition of a *L*-bit string under the form $\mathbf{b_1} = [b_0 \dots b_{L-1}]^T$ with $b_i \in \{0, 1\}$

• Conversion
$$b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^T \mathbf{b_1}$$
 with $\boldsymbol{\beta} = [2^0 \ 2^1 \ \dots \ 2^{L-1}]^T$

• Introduce the bounds $z \in [z^{\min}, z^{\max}]$

$$z = z^{\min} + \epsilon_1 \boldsymbol{\beta}^T \mathbf{b_1}$$
 with the scaling $\epsilon_1 = \frac{z^{\max} - z^{\min}}{2^L - 1}$

- One scalar is represented (in a discrete way) by L qubits
- Binary-decimal conversion of a vector field
 - Vector of size N represented by $N \times L$ qubits

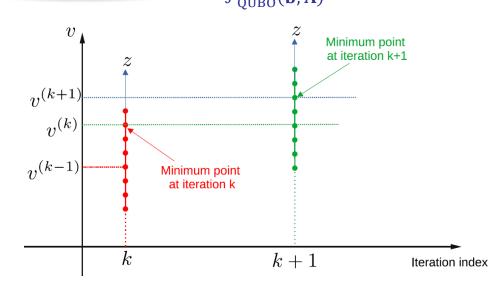
•
$$\mathbf{z} = \mathbf{z}^{\min} + [\epsilon_i \mathbf{\beta}^T \mathbf{b}_i \text{ for } i = 0..N - 1]$$
 $\mathbf{z} = \mathbf{a} + \mathbf{D}(\epsilon)\mathbf{b}$

- Transform each continuous quadratic optimization problem into a binarized one
 - Optimization problems to be solved
 - $\mathbf{z} = \arg\min_{\mathbf{z}'} \mathrm{QF}(\mathbf{z}', f_{\mathrm{aug,v}}, f_{\mathrm{aug,vv}})$ & $\mathrm{QF}(\mathbf{z}; f_{\mathrm{aug,v}}, f_{\mathrm{aug,vv}}) = \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug,v}} + \frac{1}{2} \mathbf{z}^{\mathrm{T}} f_{\mathrm{aug,vv}} \mathbf{z}$
 - With bounds: $v_{min} \le v + z \le v_{max}$
 - Binarization of $z \in \mathbb{R}^N$ into $N \times L$ qubits
 - $\mathbf{z} = \mathbf{a} + \mathbf{D}(\epsilon)\mathbf{b}$ with the bounds defining $\mathbf{a} = \mathbf{z}^{\min}$ & the scales $\epsilon = \frac{\mathbf{z}^{\max} \mathbf{z}^{\min}}{2^L 1}$

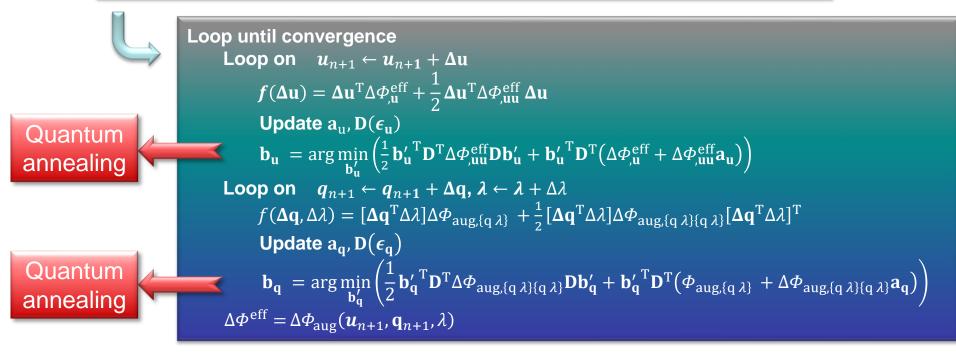
$$QF(\mathbf{z}; f_{\text{aug,}\mathbf{v}}, f_{\text{aug,}\mathbf{v}}) = \frac{1}{2} \mathbf{b}^{\text{T}} \mathbf{D}^{\text{T}} f_{\text{aug,}\mathbf{v}} \mathbf{D} \mathbf{b} + \mathbf{b}^{\text{T}} \mathbf{D}^{\text{T}} (f_{\text{aug,}\mathbf{v}} + f_{\text{aug,}\mathbf{v}} \mathbf{a}) + \frac{1}{2} \mathbf{a}^{\text{T}} (f_{\text{aug,}\mathbf{v}} \mathbf{a} + f_{\text{aug,}\mathbf{v}})$$

$$\mathcal{F}_{\text{OUBO}}(\mathbf{b}; \mathbf{A})$$

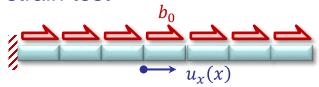
- Minimization
 - Bound $\mathbf{a} = \mathbf{z}^{\min}$ and
 - Scale $\epsilon = \frac{\mathbf{z}^{\max} \mathbf{z}^{\min}}{2^L 1}$
 - · Updated when building the QUBO



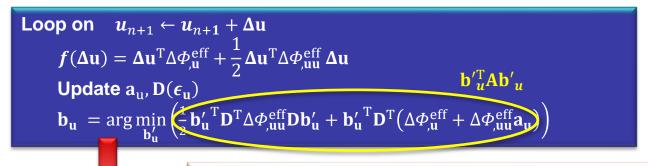
Application to the double-minimization problem



Uniaxial-strain test



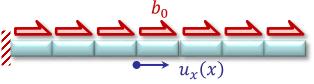
- Elastic case
 - Simple minimization conducted on the displacement field
 - Consider different numbers *N* of elements
 - Consider different binarizations L of each nodal displacement: $b_{L-1} \dots b_0 \equiv \sum_{i=0}^{j} b_i \ 2^j = \boldsymbol{\beta}^T \mathbf{b_i}$
 - Resolution by quantum annealing on DWave Advantage QPU



Quantum annealing

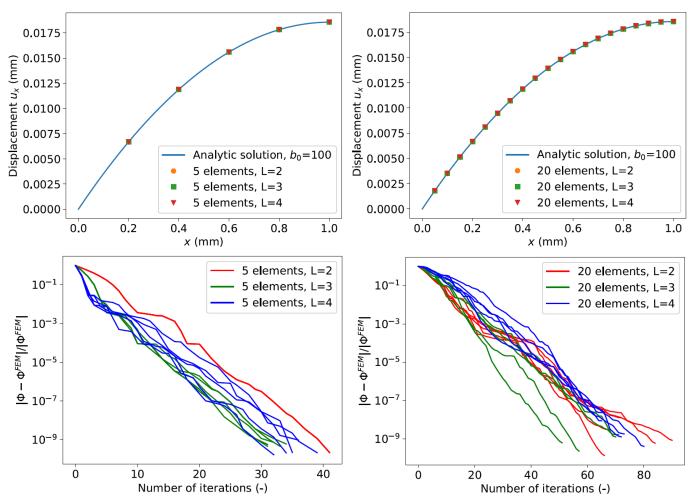
from dwave.system import DWaveSampler, EmbeddingComposite sampler = EmbeddingComposite(DWaveSampler()) sampleset = sampler.sample_qubo(A, num_reads=100, annealing_time=20) b = sampleset.first.sample

- Uniaxial-strain test
- Elastic case



$$b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^{\mathrm{T}} \mathbf{b}_i$$

Error analysis for 5 realizations for different total numbers of qubits

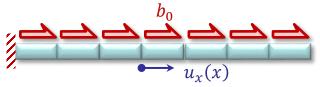


With increasing total number $N \times L$ of qubits

- Discrepancy between realizations increases
- Required number of iterations increases

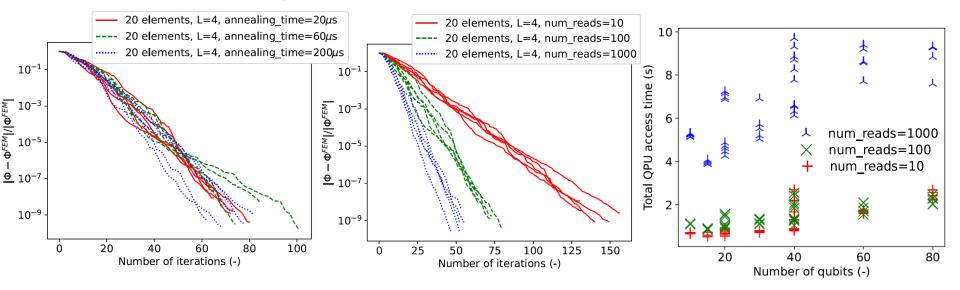


- Uniaxial-strain test
- Elastic case



 $b_{L-1} \dots b_0 \equiv \sum_{j=0}^{L-1} b_j \ 2^j = \boldsymbol{\beta}^{\mathrm{T}} \mathbf{b}_i$

Effect of annealing time and number of reads

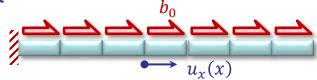


With increasing number of reads

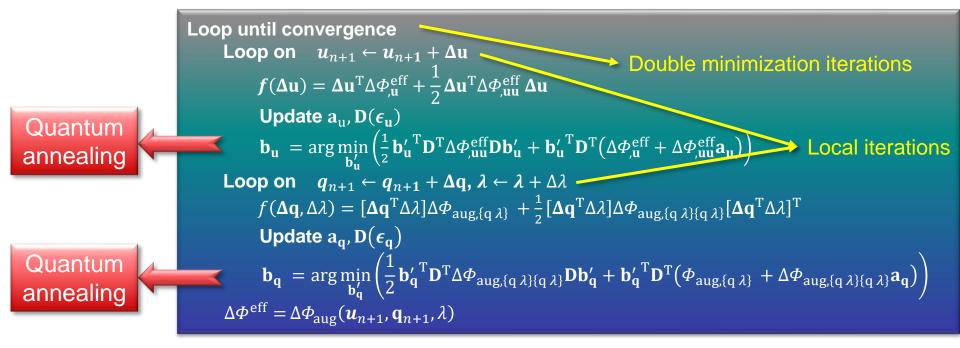
- Required number of iterations decreases
- But not necessarily the quantum processing unit (QPU) access time



Uniaxial-strain test

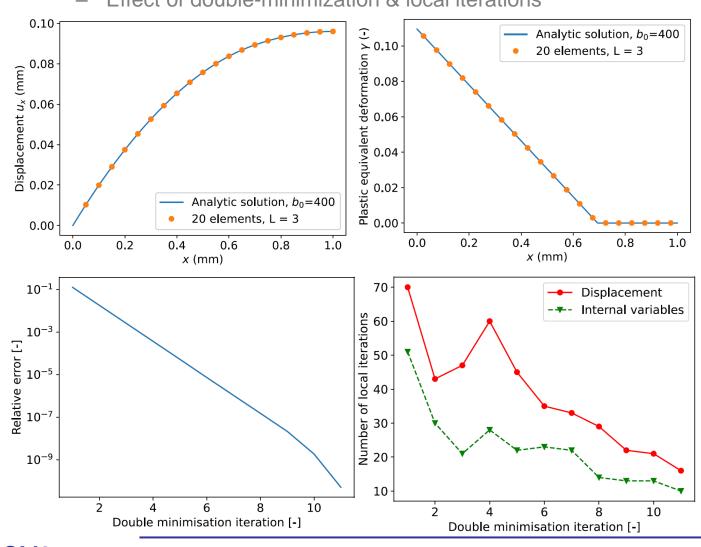


- Elasto-plastic case
 - Double minimization
 - Binarizations L of each nodal displacement and internal variable: $b_{L-1} \dots b_0 \equiv \sum_{i=0}^{J} b_i \ 2^j = \boldsymbol{\beta}^T \mathbf{b}_i$
 - Resolution by quantum annealing on DWave Advantage QPU



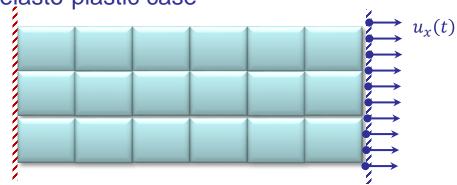
- Uniaxial-strain test
- Elasto-plastic case

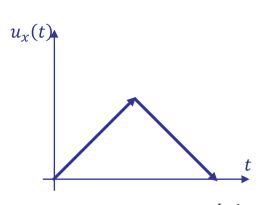




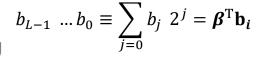
The number of local iterations decreases as the double minimisation iterations proceed

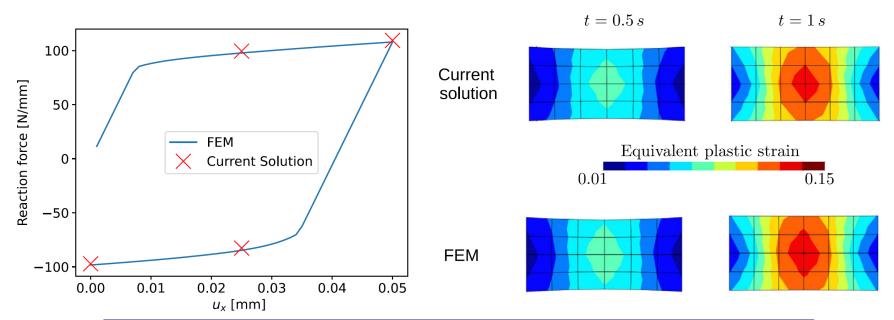
2D-elasto-plastic case



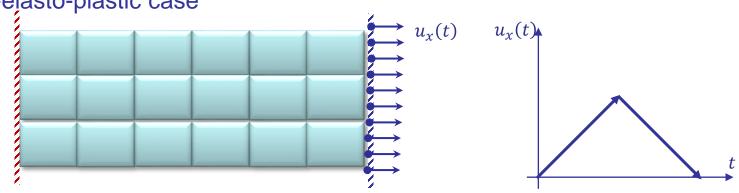


- Double minimization
 - Binarizations L of each nodal displacement and internal variable: $b_{L-1} \dots b_0 \equiv \sum_{i=1}^{J-1} b_i \ 2^j = \beta^T \mathbf{b}_i$
- Resolution by quantum annealing on DWave Advantage QPU

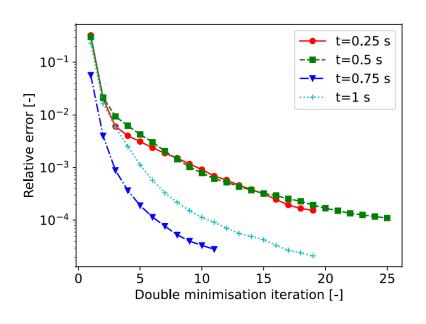


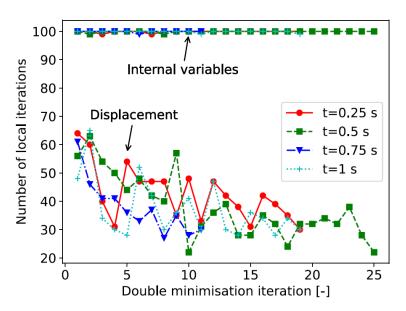


2D-elasto-plastic case



Effect of double-minimization & local iterations





Conclusions

Application of QC to FEM

- FE resolution needs to be rethought
- It will probably stay advantageous to solve part of the problem on classical computers

Quantum annealing

- Real annealers can now be used
- Efficient to solve optimization problem.... FEM is actually a minimization problem.
- Main current limitation is the number of connected qubits

Publication

V. D. Nguyen, F. Remacle, L. Noels. A quantum annealing-sequential quadratic programming assisted finite element simulation for non-linear and history-dependent mechanical problems. *European Journal of Mechanics – A/solids* 105, 105254 10.1016/j.euromechsol.2024.105254

Data and code on

Doi: <u>10.5281/zenodo.10451584</u>

