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Steady and Unsteady Numerical Characterisation of a Highly-Loaded Low-Pressure Compressor Stage

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Context and PhD objectives

Solutions for emission reduction:





Motivations of the project: Lack of information on

- Identify phenomena linked with performance and stability loss
- Characterise critical flow features and their evolution
- Identify flow mechanisms leading to stall
- Understand the role of geometrical features
- Improve design guidelines

[1] https://aerospaceamerica.aiaa.org/features/high-gear/

[2] Peters A. et al. "Ultrashort Nacelles for Low Fan Pressure Ratio Propulsors" Journal of Turbomachinery 2014 [3] Leiffson L.T. "Multidisciplinary Design Optimization of Low-Noise Transport Aircraft" PhD thesis, Virginia P&S University, 2005 2/19 [4] Gunn et al. "Aerodynamics of Boundary Layer Ingesting Fans" ASME Turbo Expo 2014





Research project overview



- Distortion effects in transonic compressors
- Literature survey to continue all over the PhD project

In this presentation

- Characterisation of the distorted machine

Characterisation of the clean machine:

- Define a robust numerical setup Ο
- Reach high level of accuracy 0
- Support existing experimental data 0
- Support design of experiments 0
- Generate a clean reference case 0



Experimental environment



Characteristics of the test section

- Representative of a modern GTF LPC
- 4 measurement planes available
- Characterised in clean conditions (EU FP7 DREAM project) Independent variation of Re and Ma
- Nominal speed considered for the present activity

VKI R4 high-speed compressor test rig:



Characteristics of the facility

- Controlled temperature and pressure
- Precision throttling
- - Different engine operating conditions (cruise, take-off)



Numerical model and setup

Numerical setup and domain:



<u>Solver:</u> Numeca Fine/Turbo <u>Grid generator:</u> AutoGrid5 (multi-block structured)

Numerical setup:

- Simulation: RANS & URANS
- R/S int. RANS: Mixing plane + NRBC
- R/S int. URANS: Domain scaling
- Tu model: k-epsilon Chien
- Inlet Tu BC: TI = 0.35%, Tu viscosity ratio
- Inlet BC: Pt & Tt (from experiments)
- Outlet BC: Mass-flow (from experiments)
- Solid wall BC: Adiabatic
- Wall resolved simulation (y + = 1.2)

<u>Geometrical setup:</u>

- Fillets and tip gaps
- Hot geometries
- Closed cavities (not included)

Chosen after assessment of real geometrical features impact



Presentation overview

Sections of the presentation:

- Turbulence model assessment for secondary-flow characterisation (ASME Turbo Expo 2022) 0
- Characterisation of the machine in clean conditions 0
- Current activities 0
- Conclusions and next steps

Grid refinement study:



Impact on global performance and secondary structures:



<u>Rotor suction side - Skin friction lines</u>

Massflow reduction



Overall driving mechanisms and secondary flow field evolution:

Rotor inlet/outlet conditions: eddy viscosity



Rotor hub wall - skin friction lines



- 1. The larger K-eps eddy viscosity into the BL decreases the crossflow and the size of the hub corner separation
- 2. The smaller K-eps eddy viscosity at mid-span increases the size of the shock-BL separation

Overestimation of hub corner separation for SST is linked to the computed eddy viscosity and BL height



Validation against experimental results:







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Critical flow regions and phenomena

- (unsteadiness already filtered by RANS)







Critical flow regions and phenomena

IGV-rotor wake propagation: experimental evidence



Experimental observation

- 5, 27Hz components appear prior to flow breakdown
- IGV wakes through rotor generate a Pt "hole" at stator outlet
- Pt reduction moves toward stator SS at reduced mass-flow
- Stator midspan separation induced by increased incidence
- Such separation is thought to be at the origin of the instability

[5] Dell'Era G. et al. "Experimental Characterisation of the Unstable Range of a High Speed Booster" Draft version

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 Role of IGV-rotor wake interaction? • Improve stability modifying IGV-stator clocking?



Considerations about the loss of stability

CLOCKING 1

Effect of the clocking on the stator outlet field:

Schematic



- Correspondence 1:1 IGV-stator clocking on DREAM
- Modification of Pt "hole" position with different clocking
- Machine stability possibly improved at reduced speed with modified clocking
- In the test section the clocking can not be modified







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- Conclusions and next steps 0

Current activities

Full-annulus simulations in clean conditions:

<u>Motivations behind the use of a full annulus domain:</u>

- To avoid impact on secondary flow structures
- To capture low-frequency modes and instabilities

Numerical setup and mesh:

- Same setup and mesh of previous URANS (domain scaling)
- Analysis at DE and NS operating points
- Computational cost: 0.75M CPU hours/simul on 350M cells

Infrastructure:

• Access to Tier-1 Zenobe cluster (Consortium CÉCI)



Current activities

Experimental campaign in clean conditions:

Tasks:

- Steady and unsteady characterisation of the machine in stable operating range
- Characterisation of the unstable operating range (critical features for stability)

Lessons learned from CFD:

- Need of high instrumentation resolution at rotor and stator outlet
- Analyse axial correlation for IGV wakes propagation and clocking effects

<u>Realised so far:</u>

- Definition of experimental setup and instrumentation to employ
- Calibration of 3 hole virtual fast-response pressure probe: static, dynamic, aerodynamic

The complementary interpretation of numerical and experimental results will allow a full-characterisation of the DREAM test section in clean conditions

Conclusions and next steps

Outcome of the presented activity:

- Geometrical features included into the domain (fillets, tip gaps and hot geometries)
- No general Tu-model better than others (K-eps better at NS, while SST at DE)
- Two critical flow structures detected in clean conditions:
 - Rotor hub corner separation: structure most affected by OP variation 1.
 - Propagation of IGV-rotor wakes: phenomena impacting on the stability

Next steps:



- <u>Full-annulus simulations in distorted conditions</u> (*Tier-1 Zenobe cluster*):
 - Understand distortion effects on compressor performance and stability
 - Characterise pre-existing and new critical phenomena
 - **Distortion pattern considered**: *Under definition* targeting as realistic as possible pattern
 - Modification of the test section for installation of distortion screen on target pattern • Steady and unsteady data in both stable and unstable operating range
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- Consortium CÉCI Access to Tier-1 Zenobe cluster

Numerical domain - geometrical features

List of geometrical features of interest:







Domain and mesh for cavity and no-cavity case:

Solid wall boundary conditions

Mesh topology Cavity Matching connections Added block Cavities Connection

Interfaces substituted with non-rotating solid walls in the no-cavity configuration

Same topology for the 2 configurations





Numerical domain - geometrical features

Impact of cavities on the main channel flow:









Experimental instrumentation





Total pressure (Kiel probe)

Total temperature (Shielded thermocouple)

Inlet and outlet rakes



Static pressure (Pressure taps)

Flow direction (3-hole probes)



Hot-wire anemometer (Hub and tip turbulence intensity)

Total and static pressure, total temperature (AP1-C25 probe)



Static pressure (Fast response pressure taps)



Total pressure (FP2, FP3, 3-hole virtual probe)



Experimental instrumentation

Quantities to measure:

<u>Steady measurements:</u>

- Compressor map:
 - Total to total pressure ratio
 - Static to total pressure ratio
 - Efficiency
 - Massflow
- Spanwise distributions:
 - Total pressure in planes 1,2,3,4
 - Total temperature in planes 1,2,3,4
 - Ma in planes 1,2,3,4
 - Flow angle in planes 1,2,3,4
- Maps:
 - Total pressure in plane 4
 - Total temperature in plane 4
 - Ma in plane 4
 - Flow angle in plane 4

<u>Unsteady measurements:</u>

- Spanwise distributions:
 - Total pressure in planes 3,4
- Maps:

 - Total pressure in planes 3,4 - Flow angles in planes 3,4
 - Static pressure at casing
- <u>Unstable operating range:</u>
- Stall inception and post-stall:
 - Hub, midspan and casing velocity in planes 1,2
 - Pressure signals at casing inlet, midchord and outlet
 - Pressure signal at rotor outlet hub, midspan and tip
 - Pressure signal at stator outlet hub



(Circumferential locations where it is possible to perform radial traversing)

Experimental setup

Plane by plane and meridional experimental setup:



Backup slide

Nomenclature:

- HW: Hot-wires

