



Ultrafast time-of-flight imaging with SPAD and picosecond laser for validation of the stray light rejection in an optical calibration facility

L. Clermont¹, P. Blain¹, E. Mazy¹, W. Khaddour², W. Uhring², M. Georges¹

¹ Centre Spatial de Liège, STAR Institute, Liège Université, Belgium

² Université de Strasbourg, ICube Research Institute, Strasbourg, France







• What is Stray Light (SL) ?

- Unwanted/parasitic light reaching the detector of an optical imaging system
- It comes from the field observed (in-field SL) or out of the field (out-of-field SL)
- Stray light degrades the images







- Innovative way to characterize SL L. Clermont, W. Uhring, M. Georges, Sci. Rep. 11:10081 (2021)

 $dt = 2 ps \iff OPL = 0.6 mm$

- Discrimination of SL components in function of their Optical Path Length (OPL)
- SL components reach the detector at specific time

 $dt = N [ps] \iff OPL = 0.3N [mm]$

- Time-of-Flight imaging of SL components of an optical system
 - Femtosecond laser (Ti:Sapph)
 - Streak camera







Space optical instruments

- Earth Observation instruments need to be characterized in term of SL
- The usual facilities are collimators illuminating the space optical instrument



FOCAL3 facility at CSL











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• Facilities for SL characterization





Characterize SL generated by the facility



• Characterization of facility-linked SL by Time-of-Flight method





Characterize SL generated by the facility



Characterization of facility-linked SL by Time-of-Flight method





Experimental set-up



Test collimator









Single ToF acquisition

At the focal plane of the detection system, the SPAD measures a ToF spectrum from light coming within the iFOV (β =±0,0141°) of the imaging lens

OPL=f(time)



Angular scan

We rotate the detection system around its pupil and acquire a ToF spectrum at each angle. We measure the SL in the facility decomposed in the spatio-temporal dimensions







• Full 2D reconstruction of SL components

- Angular scan along 2 directions $\theta_x \theta_y$
- A movie of $I_{SL}(\theta_x, \theta_y, OPL)$ is obtained
- Coarse angular scan: large FOV

(OPL = -1.1m)

SL from the optical fiber

SL from the first vane (OPL = 3.5m)





SL around the collimator and on the back wall (OPL = 4.33 m)



 θ_{x}

 θ_y



Experimental Results



• Refined angular scan (small FOV –field near the nominal peak)







• Measurement at small angles (near-field)

We observe that the SPAD "sees itself" ! As the detection system is scanned angularly, light illuminates the surrounding of the SPAD and create a ghost → A diaphragm will be used to hide the surrounding of the SPAD







• Measurement at small angles (near-field)

A measurement at a single angle in the near field allows to decompose the different contributors:









Measurement at small angles (near-field)



Already in our preliminary measurements, we have achieved a dynamic range of 10⁻¹¹



We characterize the facility signature by acquiring ToF spectra in the near-field. We isolate:

- SL contribution from the facility alone (time t₀)
- SL induced by the ToF detector assembly





Straylight can be characterized by ToF imaging

- Every straylight contribution is characterized by its OPL
- ToF imaging allows separating them in time
- Picosecond resolution were obtained in the past based on
 - Femtosecond laser
 - Streak camera
- Application : SL in optical instruments (ghosts, scattering,...)

• In this study

- Lower temporal resolution is shown based on
 - SPAD detector with 40 ps resolution
 - Picosecond laser 40 MHz repetition rate
- Longer OPL
 - Measurement range : a few meters
 - Resolution : centimeters
- Application :
 - European Space Agency requests now a verification of usual SL calibration facilities (not ToF based)
 - ToF based method is recommended (one day mandatory ?)
 - Low resolution presented here is the key
 - SL inherent to facility could be separated to the one of the instrument