

Simulation-based inference and its applications in neuroscience

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Gilles Louppe
g.louppe@uliege.be



Kyle Cranmer



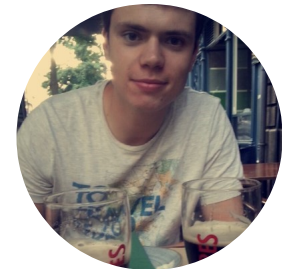
Johann
Brehmer



Joeri
Hermans



Antoine
Wehenkel



Norman Marlier



Siddharth
Mishra-
Sharma



Christoph
Weniger



Arnaud
Delaunoy



Malavika
Vasist



Francois Rozet

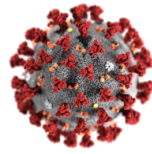
xxx update with new faces: pedro, alex



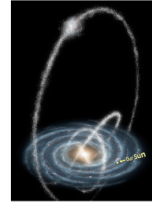
Chemical reactions



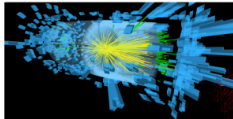
Flames



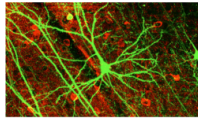
Epidemics



Stellar streams



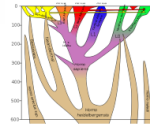
Collider experiments



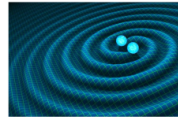
Neurons



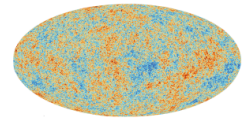
Robotics



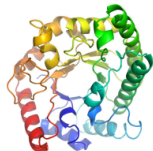
Evolution



Gravitational waves



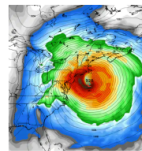
Evolution of the Universe



Protein networks



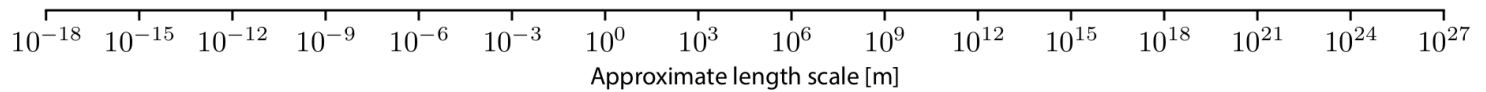
Ecological systems

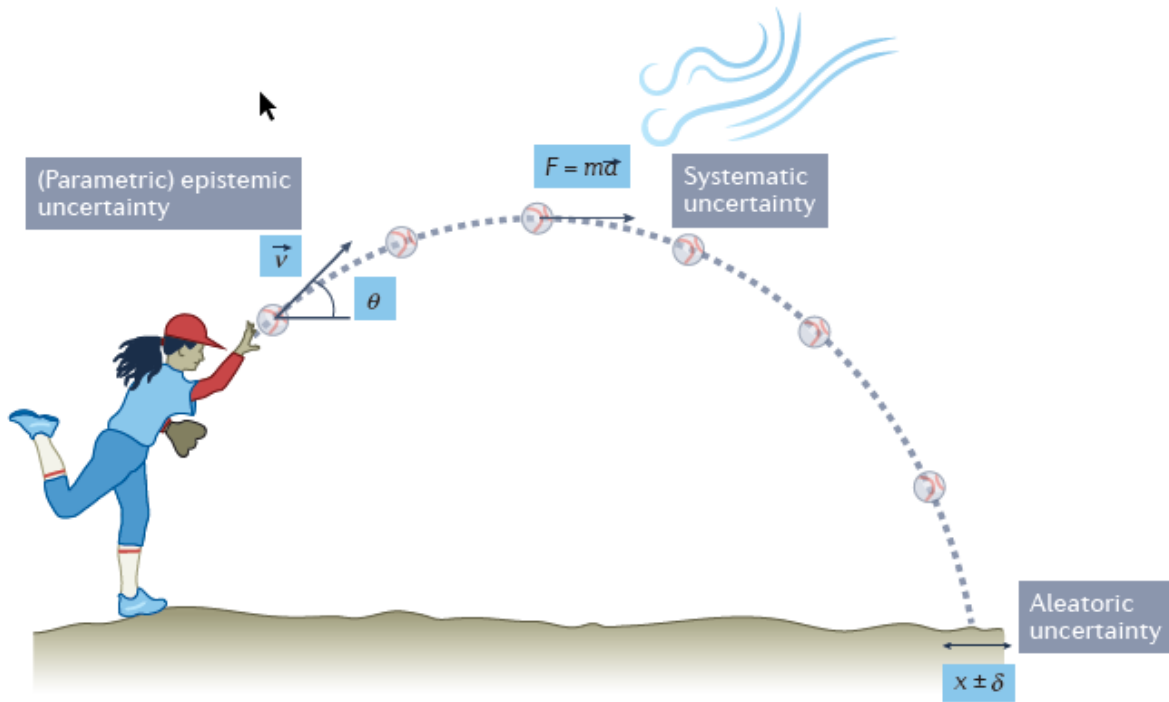


Weather and climate



Gravitational lensing







$$v_x = v \cos(\alpha), \quad v_y = v \sin(\alpha),$$

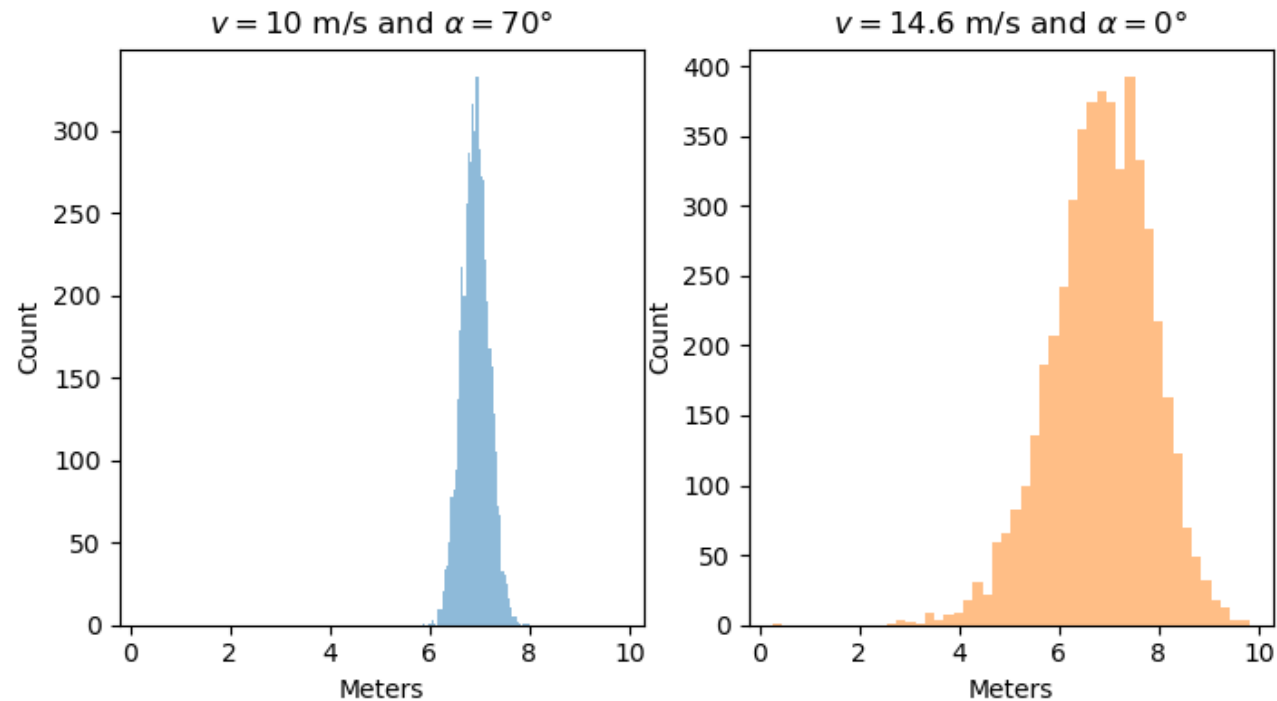
$$\frac{dx}{dt} = v_x, \quad \frac{dy}{dt} = v_y, \quad \frac{dv_y}{dt} = -G.$$



```
def simulate(v, alpha, dt=0.001):  
    v_x = v * np.cos(alpha) # x velocity m/s  
    v_y = v * np.sin(alpha) # y velocity m/s  
    y = 1.1 + 0.3 * random.normal()  
    x = 0.0  
  
    while y > 0: # simulate until ball hits floor  
        v_y += dt * -G # acceleration due to gravity  
        x += dt * v_x  
        y += dt * v_y  
  
    return x + 0.25 * random.normal()
```

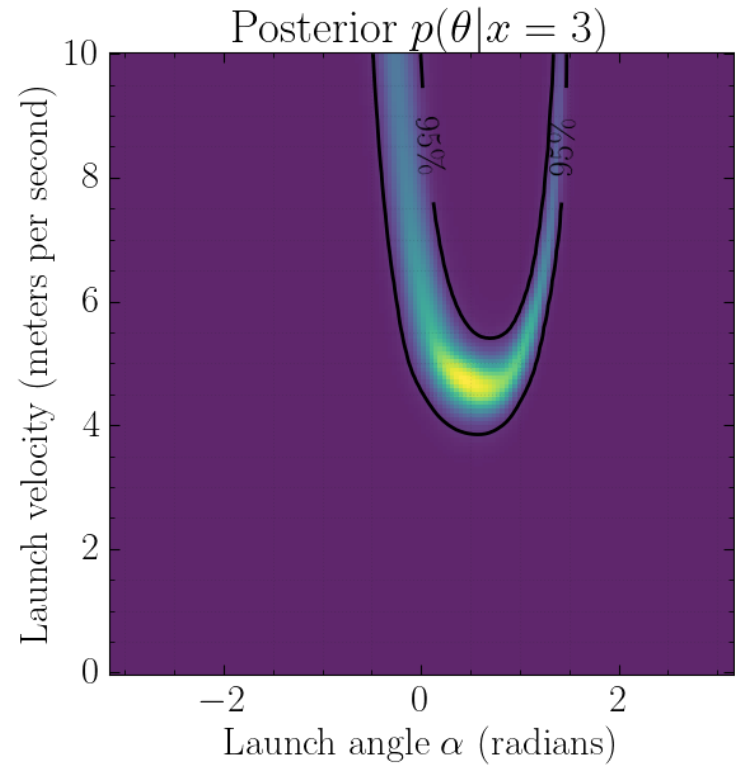
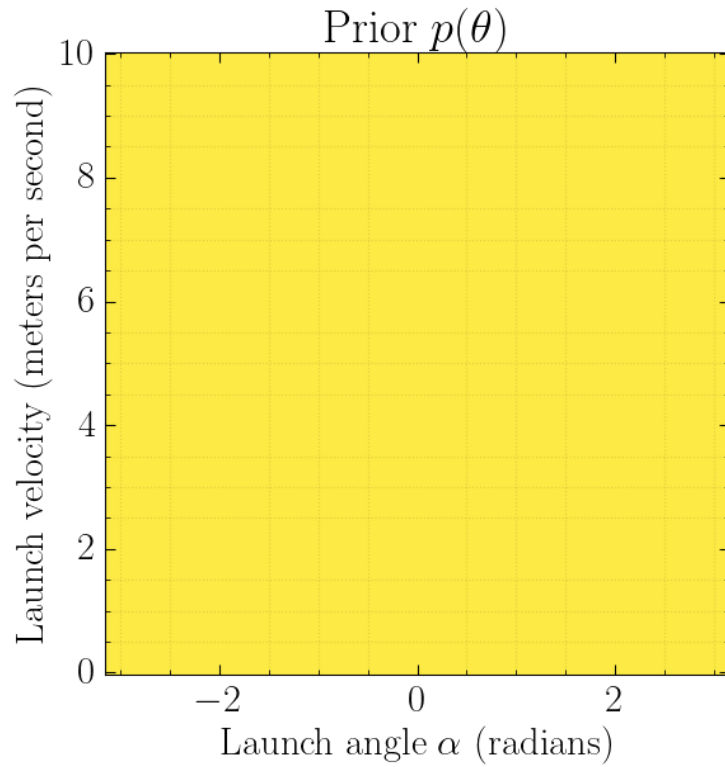


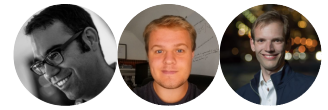
The computer simulator defines the likelihood function $p(x|\theta)$ implicitly.



What parameter values θ are the most plausible?

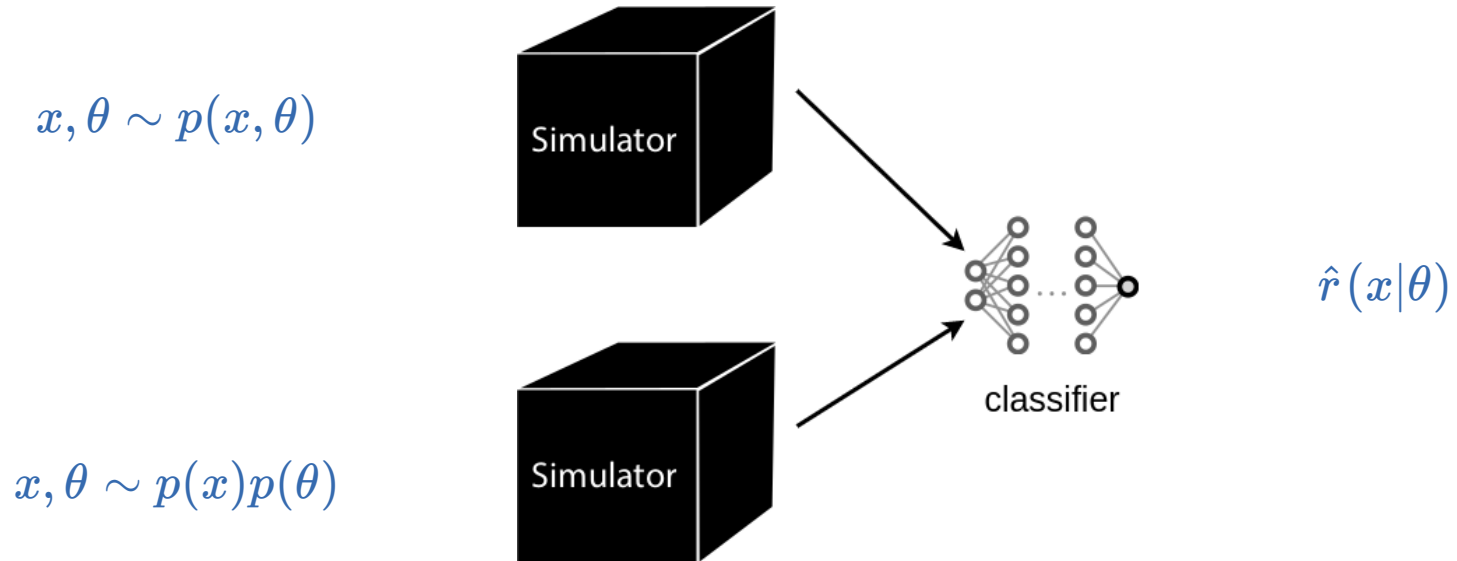
$$p(\theta | x_{\text{obs}}) = \frac{p(x_{\text{obs}} | \theta) p(\theta)}{p(x_{\text{obs}})}$$

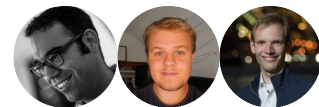




Neural ratio estimation (NRE)

The likelihood-to-evidence $r(x|\theta) = \frac{p(x|\theta)}{p(x)} = \frac{p(x,\theta)}{p(x)p(\theta)}$ ratio can be learned, even if neither the likelihood nor the evidence can be evaluated:



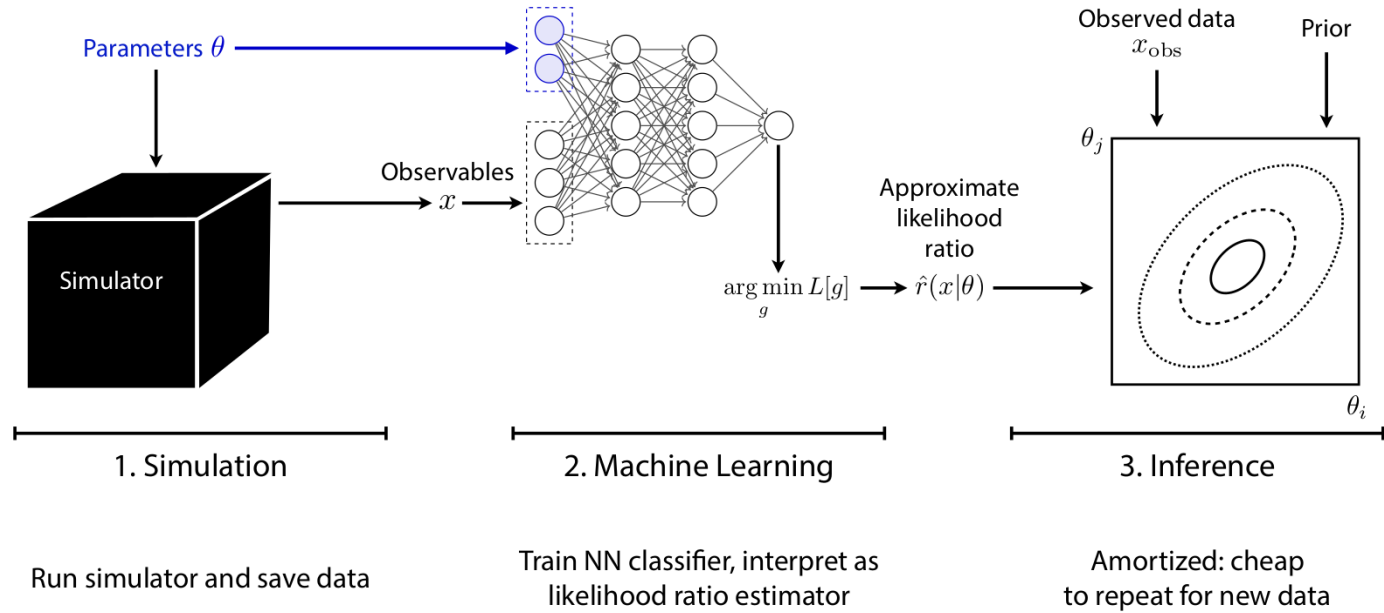
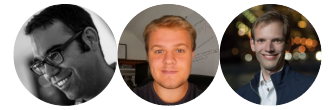


The solution d found after training approximates the optimal classifier

$$d(x, \theta) \approx d^*(x, \theta) = \frac{p(x, \theta)}{p(x, \theta) + p(x)p(\theta)}.$$

Therefore,

$$r(x|\theta) = \frac{p(x|\theta)}{p(x)} = \frac{p(x, \theta)}{p(x)p(\theta)} \approx \frac{d(x, \theta)}{1 - d(x, \theta)} = \hat{r}(x|\theta).$$



$$p(\theta|x) \approx r(x|\theta)p(\theta)$$

Constraining dark matter with stellar streams (Bayesian)



Palomar 5 (Pal5) stream
Pal5 was discovered in 2001 as the first thin stream formed from a globular cluster. Its current orbit takes it far over the galactic center.

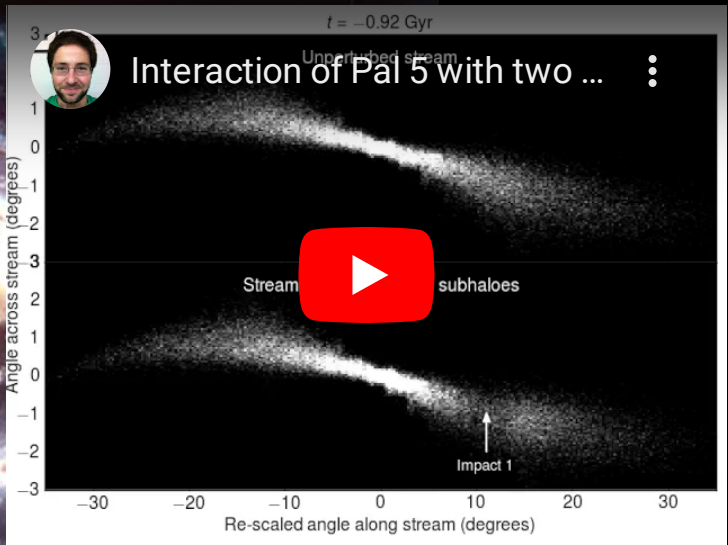
Globular clusters
These hives typically hold 100,000 stars or fewer and give rise to long, thin streams.

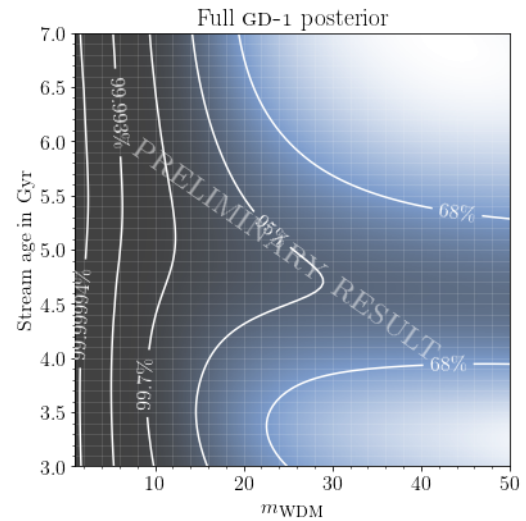
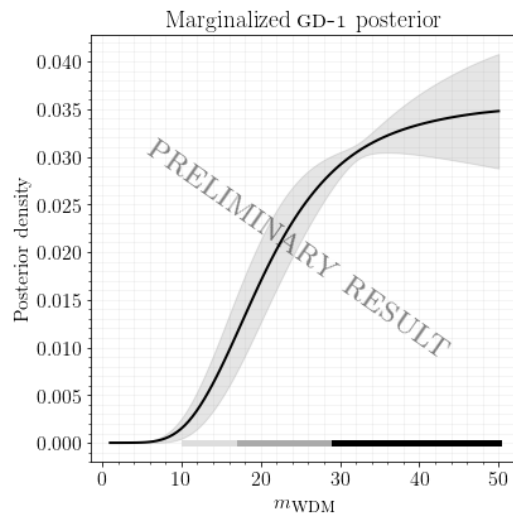
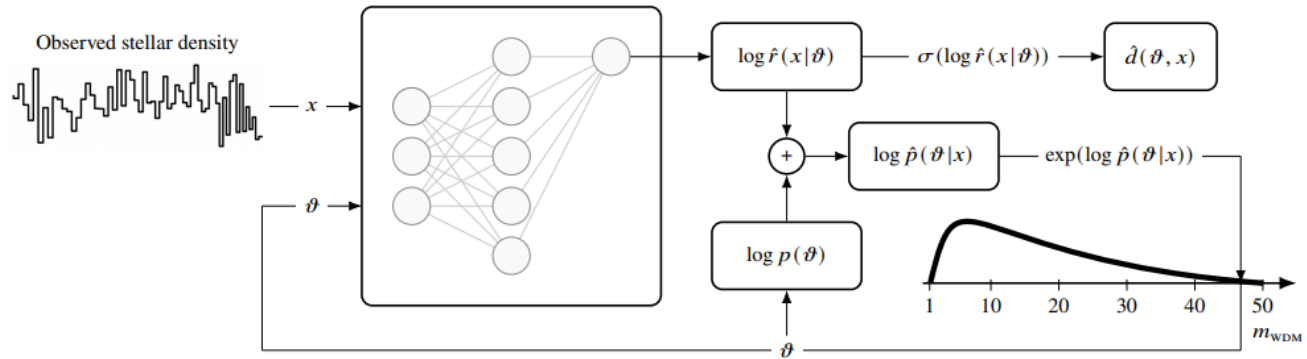
← Gap

Sun

Milky Way

GD1 stream
Discovered in 2006, GD1 is the longest known thin stream, stretching across more than half the northern sky. It contains a gap that could be the scar of a dark matter collision 500 million years ago.

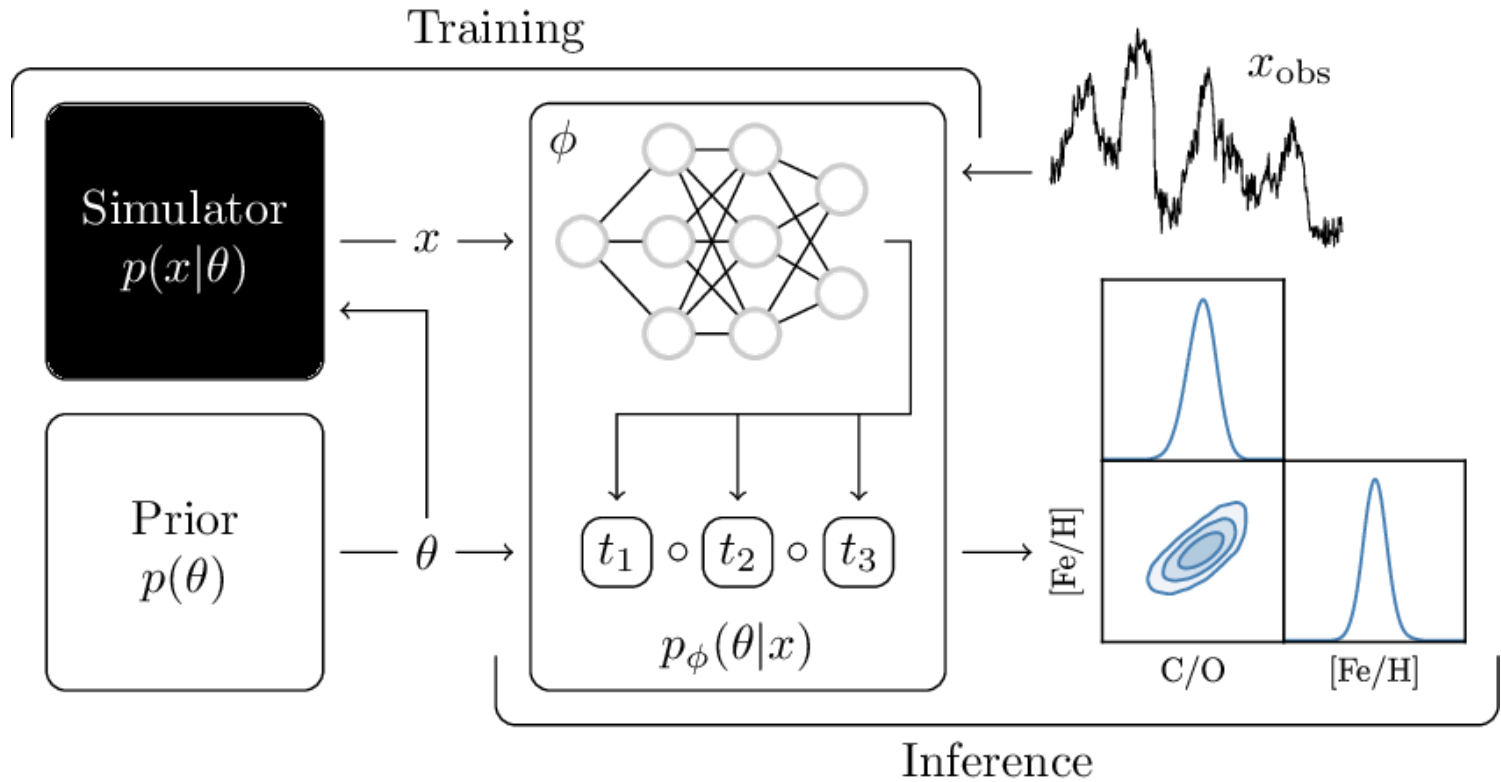






Preliminary results for GD-1 suggest a **preference for CDM over WDM.**

Neural Posterior Estimation (NPE)

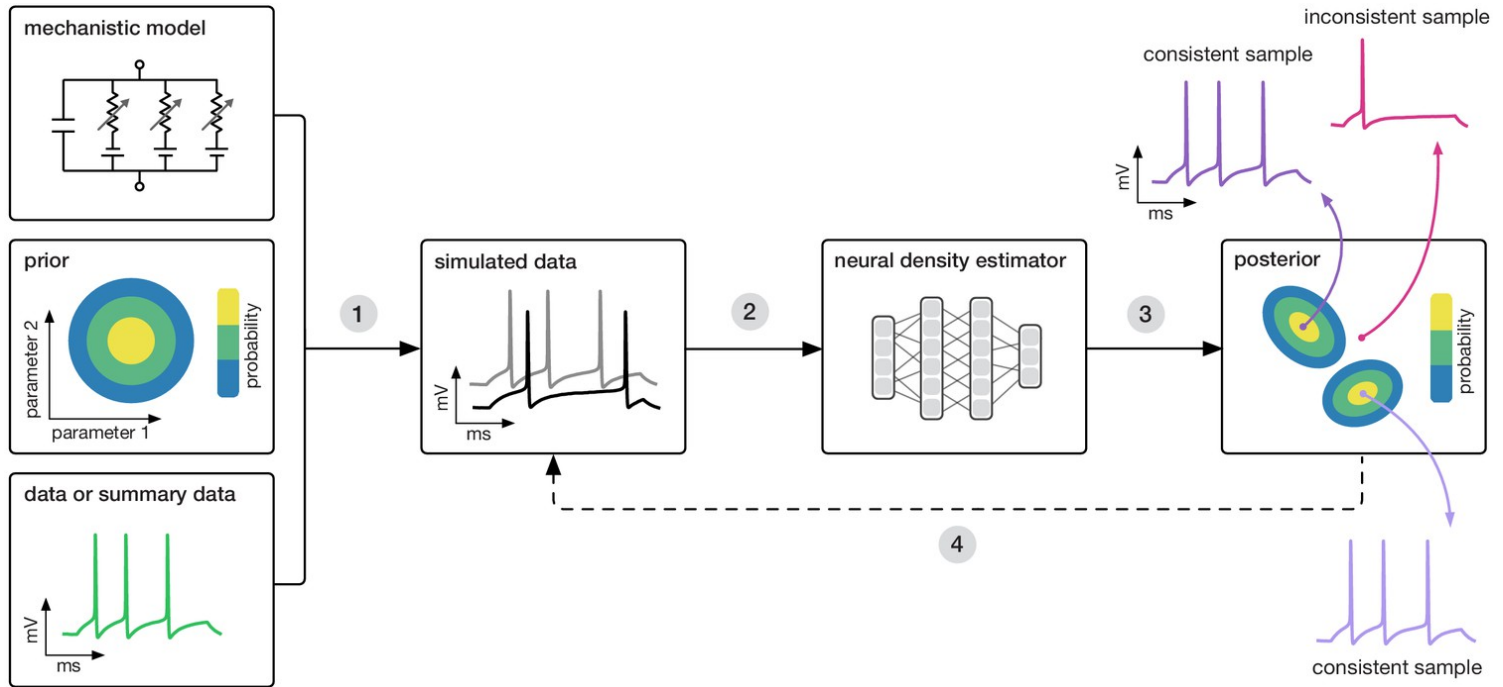


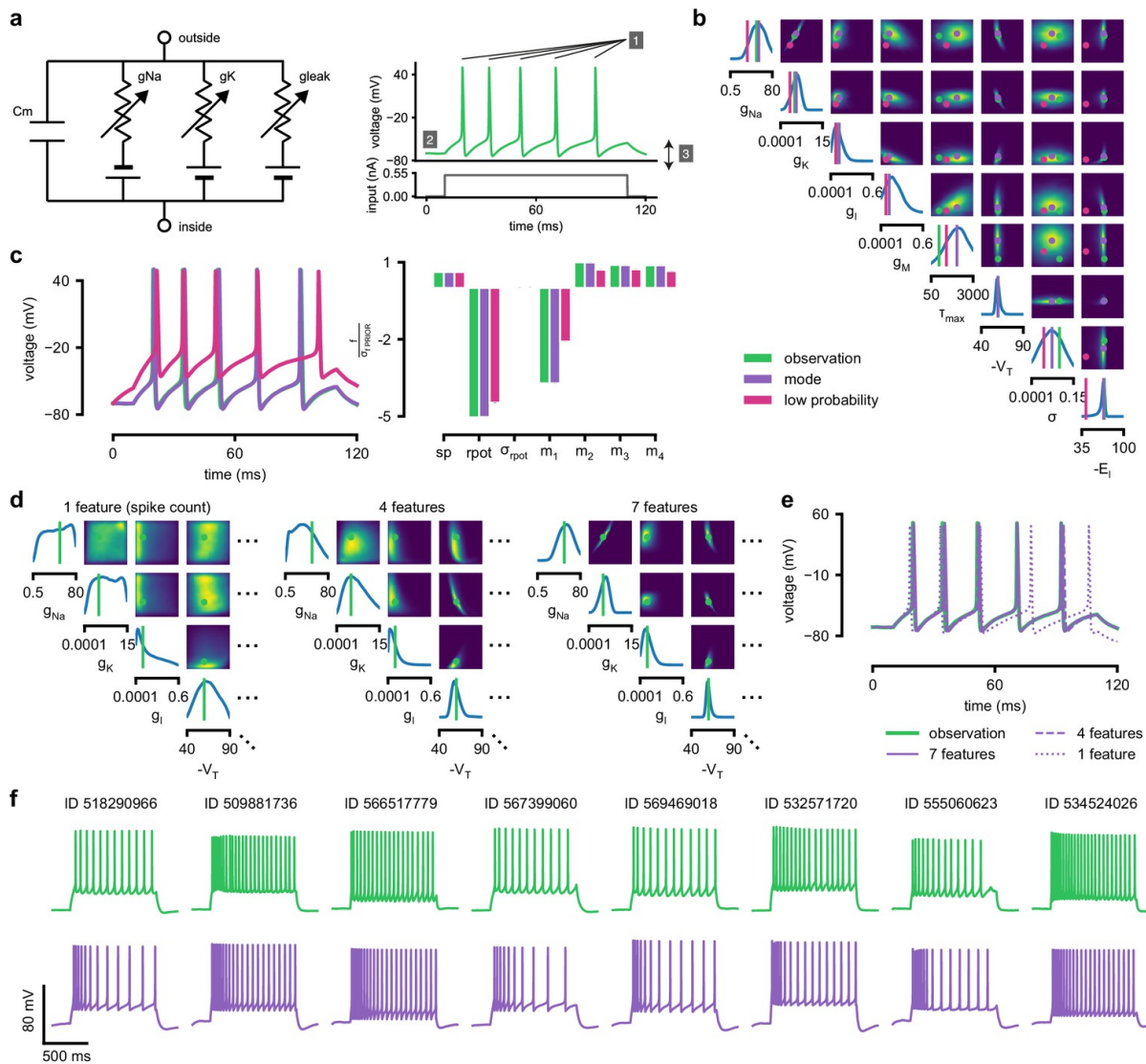
Use variational inference to directly estimate the posterior, by solving

$$\begin{aligned} & \min_{q_\phi} \mathbb{E}_{p(x)} [\text{KL}(p(\theta|x) || q_\phi(\theta|x))] \\ &= \min_{q_\phi} \mathbb{E}_{p(x)} \mathbb{E}_{p(\theta|x)} \left[\log \frac{p(\theta|x)}{q_\phi(\theta|x)} \right] \\ &= \max_{q_\phi} \mathbb{E}_{p(x,\theta)} [\log q_\phi(\theta|x)] \end{aligned}$$

where q_ϕ is a neural density estimator, such as a normalizing flow.

Mechanistic models of neural dynamics (Gonçalves et al, 2022)



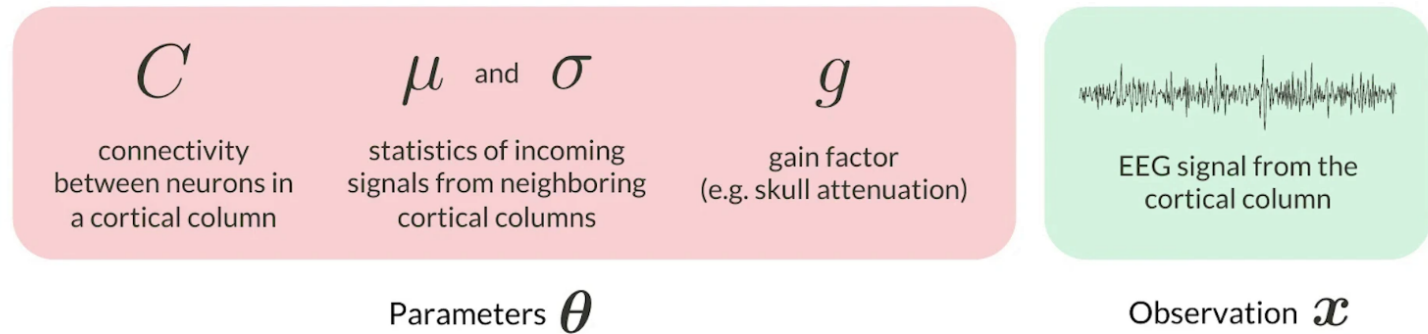


HNPE: Leveraging global parameters for NPE (Rodrigues et al, 2021)

An example on computational neuroscience...

[Jansen & Rit (1995)]

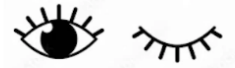
The Jansen-Rit Neural Mass Model



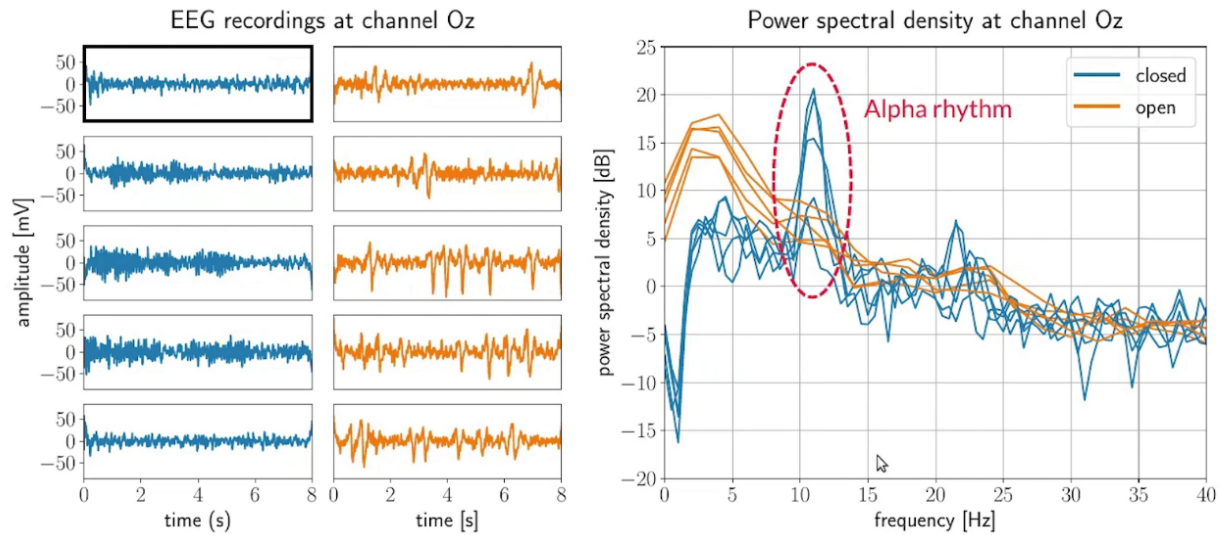
Question: can we infer physiological parameters from EEG recordings?

⌘

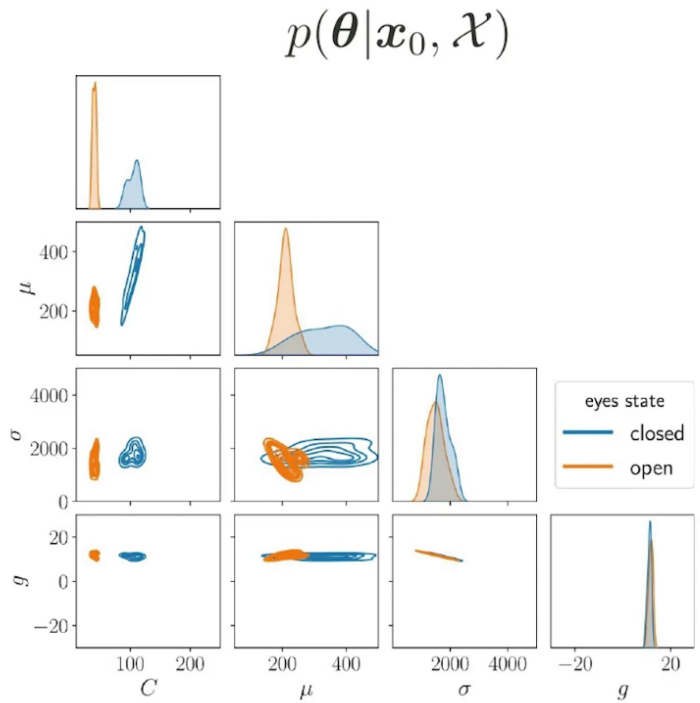
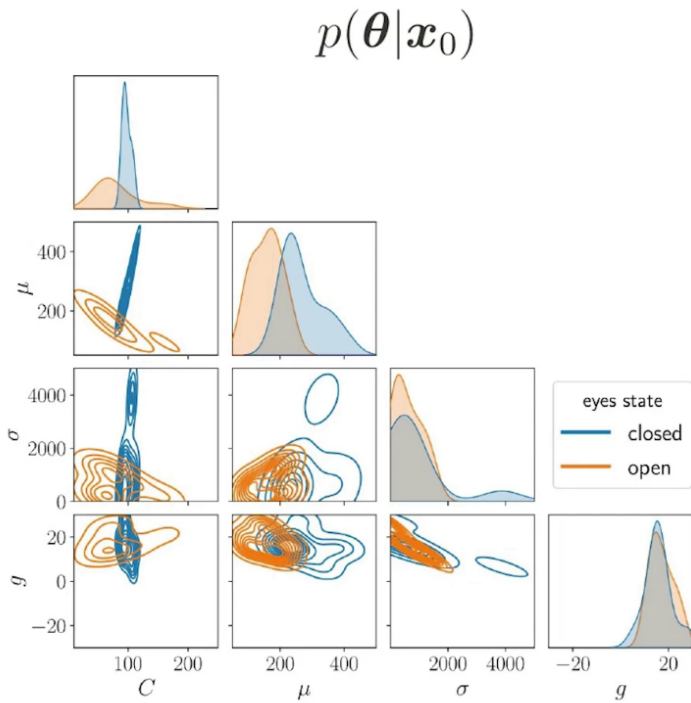
An example on computational neuroscience...



We consider a database of EEG recordings from subjects with eyes open or closed



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Amortized Inference for Causal Structure Learning

Lars Lorch¹, Scott Sussex¹, Jonas Rothfuss¹, Andreas Krause^{1*}, Bernhard Schölkopf^{2,1,*}

¹ETH Zürich, Zürich, Switzerland; ²Max Planck Institute for Intelligent Systems, Tübingen, Germany

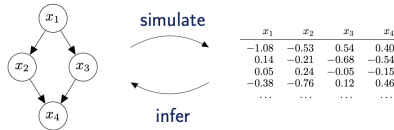
Correspondence to: lars.lorch@inf.ethz.ch *Equal supervision

Summary

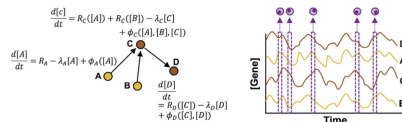
- We *amortize* causal structure learning by training a neural net to predict causal structure from data
- Training on simulated data allows learning realistic inductive biases from prior knowledge that is hard to cast as score functions or independence tests
- Our models are robust to distribution shift, scale to unseen problem sizes, predict calibrated uncertainty, and often significantly outperform existing work

Forward Model as Inductive Bias

- Causal structure learning as inverse problem

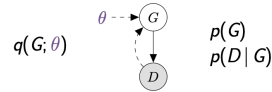


- Forward models are often-well studied and more general, but may not have a tractable likelihood e.g., for single-cell gene expression data [1]



AVICI: Amortized VI for Causal Discovery

- Domain as data-generating distribution



- Amortized variational inference:** train model f_ϕ to predict variational parameters θ from data $D \sim p(D)$

$$\arg \min_{\phi} \mathbb{E}_{p(D)} [\text{KL}(p(G|D) \| q(G; f_\phi(D)))]$$

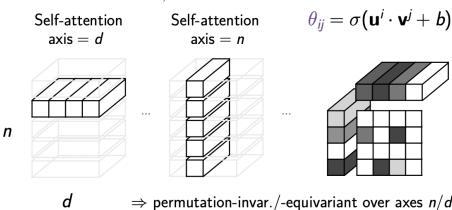
$$= \arg \max_{\phi} \mathbb{E}_{p(G,D)} [\log q(G; f_\phi(D))]$$

Inference Model f_ϕ

- Variational family

$$q(G; \theta) = \prod_{i,j} q(g_{ij}; \theta_{ij}) \quad \text{where } g_{ij} \sim \text{Bern}(\theta_{ij})$$

- Inference Model $f_\phi : D \rightarrow \theta$



Example: Gene Regulatory Networks

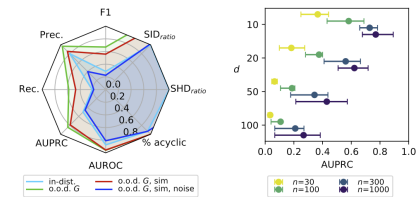


Figure 1. AVICI is robust to distribution shift of $p(G)$ and $p(D|G)$

Figure 2. AVICI generalizes to larger problems than trained on ($d \leq 50$, $n = 200$)

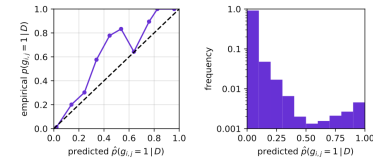


Figure 3. AVICI predicts calibrated edge probabilities, reflecting the observed empirical frequencies, while exhibiting high confidence

Paper:



arXiv: 2205.12934

Code:



github.com/larslorch/avici

References:

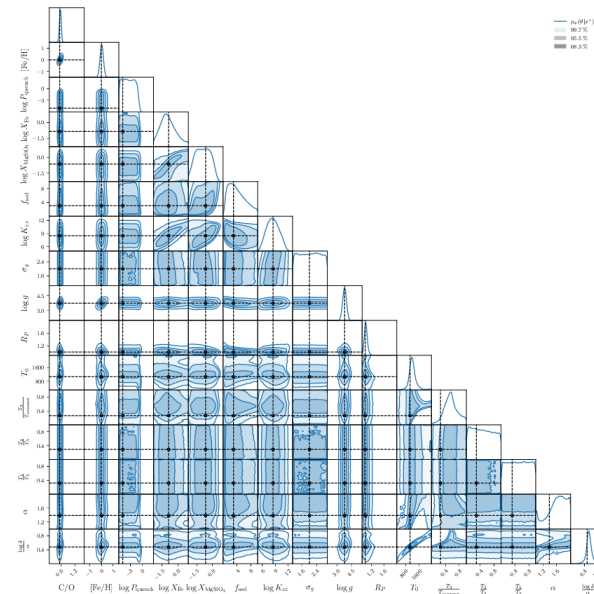
- [1] Payam Dibaenia and Saurabh Sinha. SERGIO: A Single-Cell Expression Simulator Guided by Gene Regulatory Networks. *Cell Systems*, 11(3):252–271, 2020.

36th Conference on Neural Information Processing Systems, Dec. 2022

Computational faithfulness

$$\hat{p}(\theta|x) = \text{sbi}(p(x|\theta), p(\theta), x)$$

We must make sure our approximate simulation-based inference algorithms can (at least) actually realize faithful inferences on the (expected) observations.



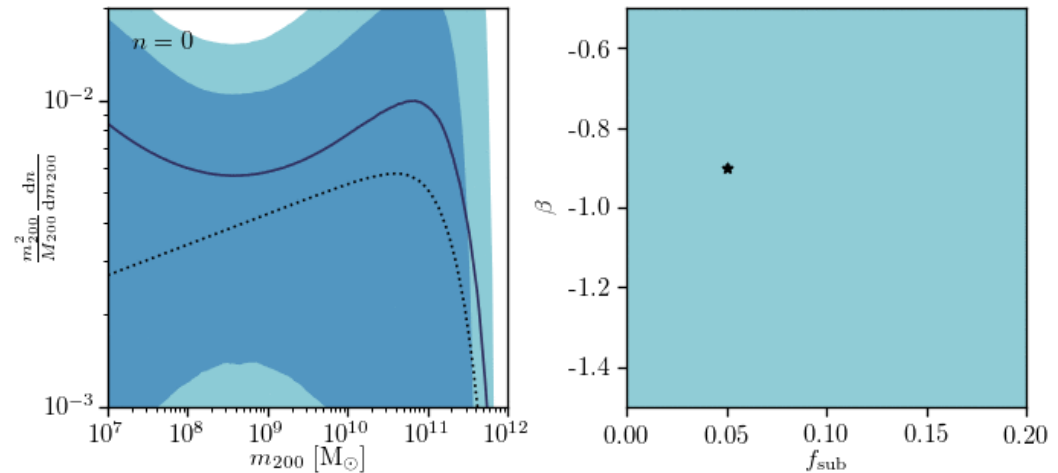
How do we know this is good enough?



Mode convergence:

The maximum a posteriori estimate converges towards the nominal value θ^* for an increasing number of independent and identically distributed observables $x_i \sim p(x|\theta^*)$:

$$\begin{aligned} & \lim_{N \rightarrow \infty} \arg \max_{\theta} p(\theta | \{x_i\}_{i=1}^N) \\ &= \lim_{N \rightarrow \infty} \arg \max_{\theta} p(\theta) \prod_{x_i} r(x_i | \theta) = \theta^* \end{aligned}$$



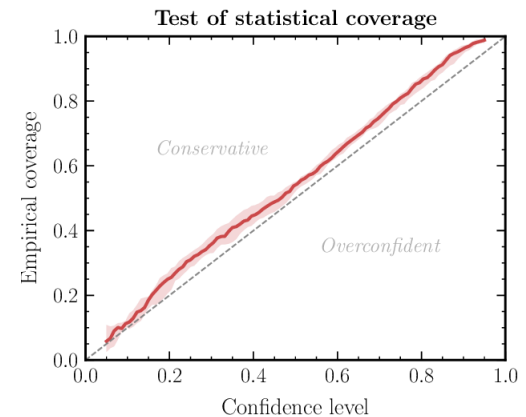


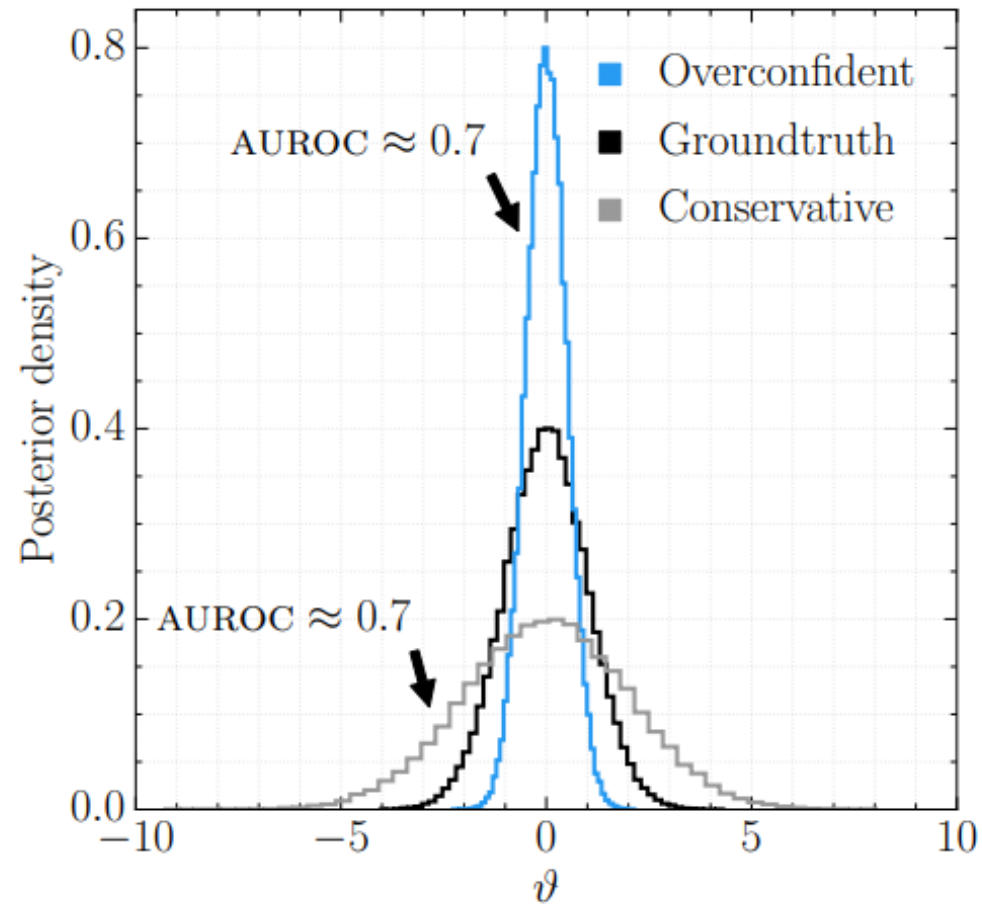
A common observation at the root of several other diagnostics is to check for the **self-consistency** of the Bayesian joint distribution,

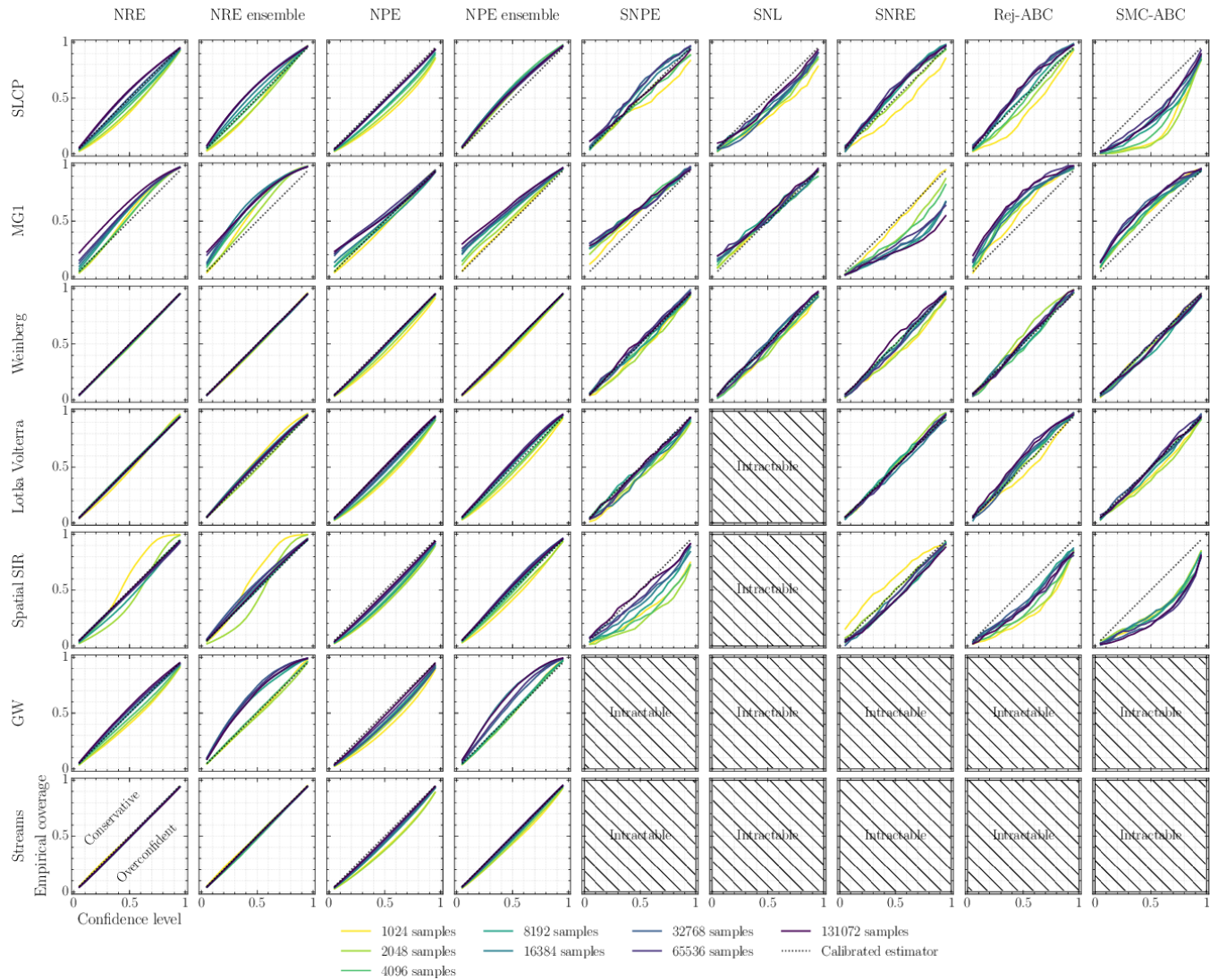
$$p(\theta) = \int p(\theta')p(x|\theta')p(\theta|x)d\theta' dx.$$

Coverage diagnostic:

- For $x, \theta \sim p(x, \theta)$, compute the $1 - \alpha$ credible interval based on $\hat{p}(\theta|x)$.
- If the fraction of samples for which θ is contained within the interval is larger than the nominal coverage probability $1 - \alpha$, then the approximate posterior $\hat{p}(\theta|x)$ has coverage.







What if diagnostics fail?

Summary

Simulation-based inference is a major evolution in the statistical capabilities for science, enabled by advances in machine learning.

Need to reliably and efficiently evaluate the quality of the posterior approximations.

The end.