Computational & Multiscale Mechanics of Materials

 $\overline{\mathcal{E}}$

 $\overline{\sigma}$



Multiscale Modeling of Composites – Piecewise-Uniform Model Order Reduction







The research has been funded by the Walloon Region under the agreement no.7911-VISCOS in the context of the 21st SKYWIN call

LIÈGE université

ICCS24, Porto, 14 – 16 June 2021

Homogenization of the mechanics of composite materials

- Strategy: finding a representative volume element (RVE)
- RVE represents a macroscopic point *X*, contains the micro-structure
- Aim: achieving macroscopic/effective RVE response $\overline{\epsilon} \rightarrow \overline{\sigma}$ (BVP)
- Use of bounds, mean-field homogenization → only need for phase properties and volume fractions
- Two-scale modeling: Linking microscopic and macroscopic scales: $x \leftrightarrow X$



Taking into account micro-structure and microscopic effects

macro-response by averaging over the RVE \rightarrow computational effort is immense







Two-scale reduced order modeling: Uniform fields









$$\Delta \overline{\boldsymbol{\varepsilon}} = \sum_{r=1}^{\kappa} v_r \Delta \boldsymbol{\varepsilon}_r$$

→ Determination of \mathbb{A}_r^{el} for each subdomain and \mathbb{D}_{rs} between all subdomains in the offline stage





Microscopic elastic strain concentration tensors

 $\varepsilon(x) = \mathbb{A}^{\mathrm{el}}(x): \overline{\varepsilon}$

apply boundary conditions $\overline{\boldsymbol{\varepsilon}}$ compute local strains $\varepsilon(x)$ determine entries of $\mathbb{A}^{\mathrm{el}}(\mathbf{x})$



Spatial decomposition based on $\mathbb{A}^{\mathrm{el}}(\mathbf{x})$ $\rightarrow \mathbb{A}_r^{\mathrm{el}}$

Eigenstrain – strain interaction tensors

With $\overline{\boldsymbol{\varepsilon}} = \boldsymbol{0}$ and eigenstrain in one subdomain _

$$\boldsymbol{\varepsilon}_r = \mathbb{D}_{rs} : \boldsymbol{\varepsilon}_s^*$$

apply eigenstrain \mathcal{E}_{S}^{*} compute $\boldsymbol{\varepsilon}_r$ determine entries of \mathbb{D}_{rs}





- TFA issue: not well-captured inelastic fields using elasticity-based subdomains
- - \rightarrow Incorrect strain distributions over the subvolumes
 - \rightarrow Especially: overestimated strain accumulation in stiff material phase

→ Over-stiff composite overall response

Particularly in cases of highly-localized plasticity or highly heterogeneous plastic fields





TFA: Integration of inelasticity



- → Change of plan: cluster decomposition based on inelastic micro-fields to respect inelastic micromechanical patterns
- → include more information of the real physics into the two-scale modeling approach





- Evident: well-chosen boundary conditions in order to capture different possible shear bands which can occur in the online stage
- Selection based on low-fidelity FE simulations: compare plastic fields under various complex loading conditions and under several proportional loadings
- Chosen four monotonic strain boundary conditions

(1)
$$\bar{\varepsilon} = \frac{1}{2}E(e_1 \otimes e_1 - e_2 \otimes e_2)$$
 bi-axial isochoric
(2) $\bar{\varepsilon} = \frac{1}{2}E(e_1 \otimes e_2 + e_2 \otimes e_1)$ pure shear
(3) $\bar{\varepsilon} = (1) + \frac{1}{2}(2)$ mixed isochoric
(4) $\bar{\varepsilon} = \frac{1}{2}(1) + (2)$ mixed isochoric

 \rightarrow Ability to detect different kinds of evolving shear bands





- Material system: elastic inclusions in a J2-plastic matrix
 - $\sigma^{Y} = \sigma^{Y0} + R$ yield stress
 - $R = Hp^m$ hardening stress

Perfect plasticity

	G (GPa)	K (GPa)	v (-)	H (MPa)	m (-)
Matrix	3	10	0.36	~ 0	1
Inclusions	6	20	0.36	-	-

• 2D periodic RVE micro-structure: random distribution of circular inclusions

• Inclusion volume fraction: 21 %







• perfectly-plastic matrix behavior

(1)
$$\bar{\varepsilon} = \frac{1}{2}E(e_1 \otimes e_1 - e_2 \otimes e_2)$$

(2) $\bar{\varepsilon} = \frac{1}{2}E(e_1 \otimes e_2 + e_2 \otimes e_1)$
(3) $\bar{\varepsilon} = (1) + \frac{1}{2}(2)$
(4) $\bar{\varepsilon} = \frac{1}{2}(1) + (2)$

bi- axial isochoricpure shearmixed isochoricmixed isochoric











- Weighting factors: $w^{(1)} = 10, w^{(2)} = 10, w^{(3)} = 1, w^{(4)} = 1$
- Normalized, weighted plastic fields

$$q^{(l)}(x) = w^{(l)} \frac{p^{(l)}(x)}{\bar{p}^{(l)}} \quad l \in 1, ..., 4$$

$$\rightarrow \boldsymbol{q}(x) = (q^{(1)}(x), q^{(2)}(x), q^{(3)}(x), q^{(4)}(x))^T$$



• K-means clustering based on similarity of local field q(x)



resulting subdomains



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Offline stage: Application











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Results: Uniaxial tension





Results

• Plasticity-based clustering allows more accurate modeling than elasticity-based clustering



- Clearly faster convergence to full-field result
- Drawbacks:
 - Inelastic simulations with fine mesh required in offline stage
 - Integration of many more loading cases in offline stage \rightarrow interferencing patterns















• Transformation Field Analysis:

George J. Dvorak (1992), Transformation Field Analysis of Inelastic Composite Materials, *Proceedings: Mathematical and Physical Sciences*, 437: 311-327

Pierre Suquet (1997), Continuum Micromechanics, Springer





