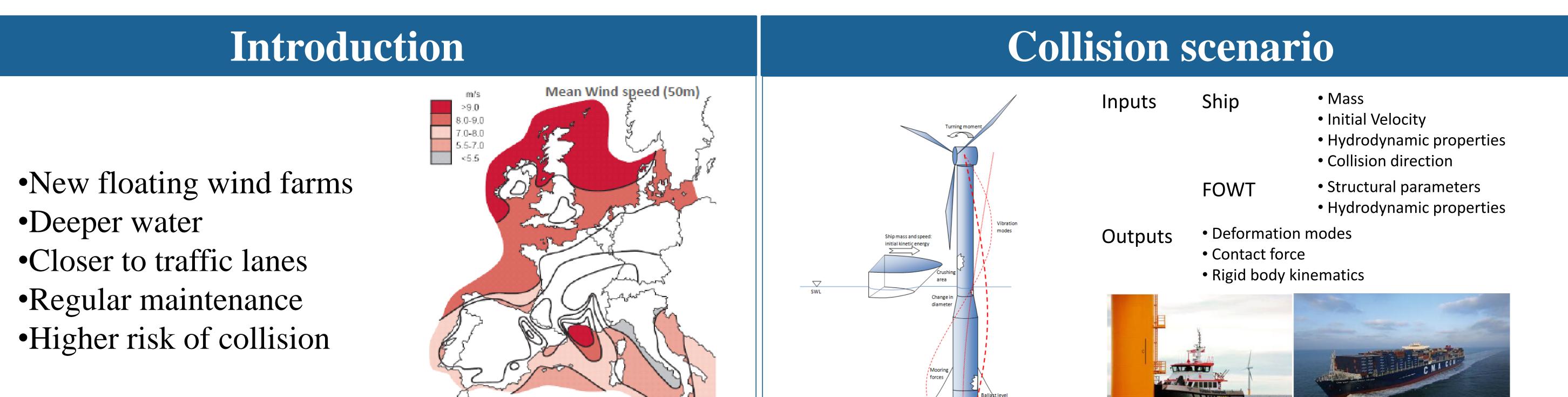
Numerical Crashworthiness Analysis of a Spar Floating Offshore Wind Turbine Impacted by a Ship (influencing parameters) Sara ECHEVERRY¹, Lucas MARQUEZ¹, Philippe RIGO¹, Hervé LE SOURNE² ¹ANAST– University of Liege, Belgium ²GeM Institute UMR 6183 CNRS – ICAM Nantes, France





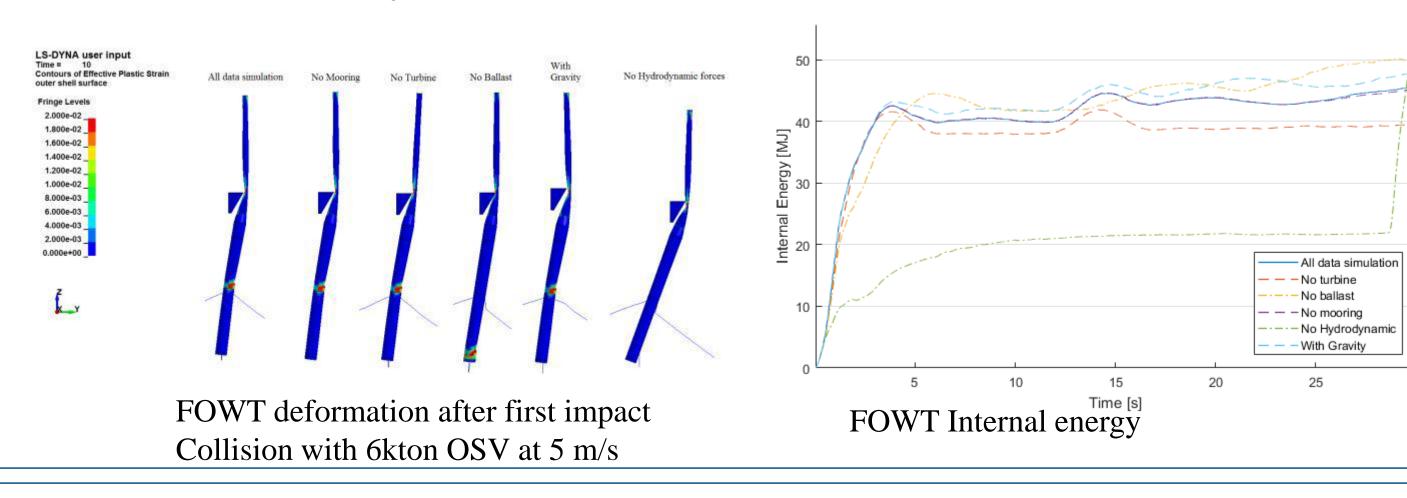


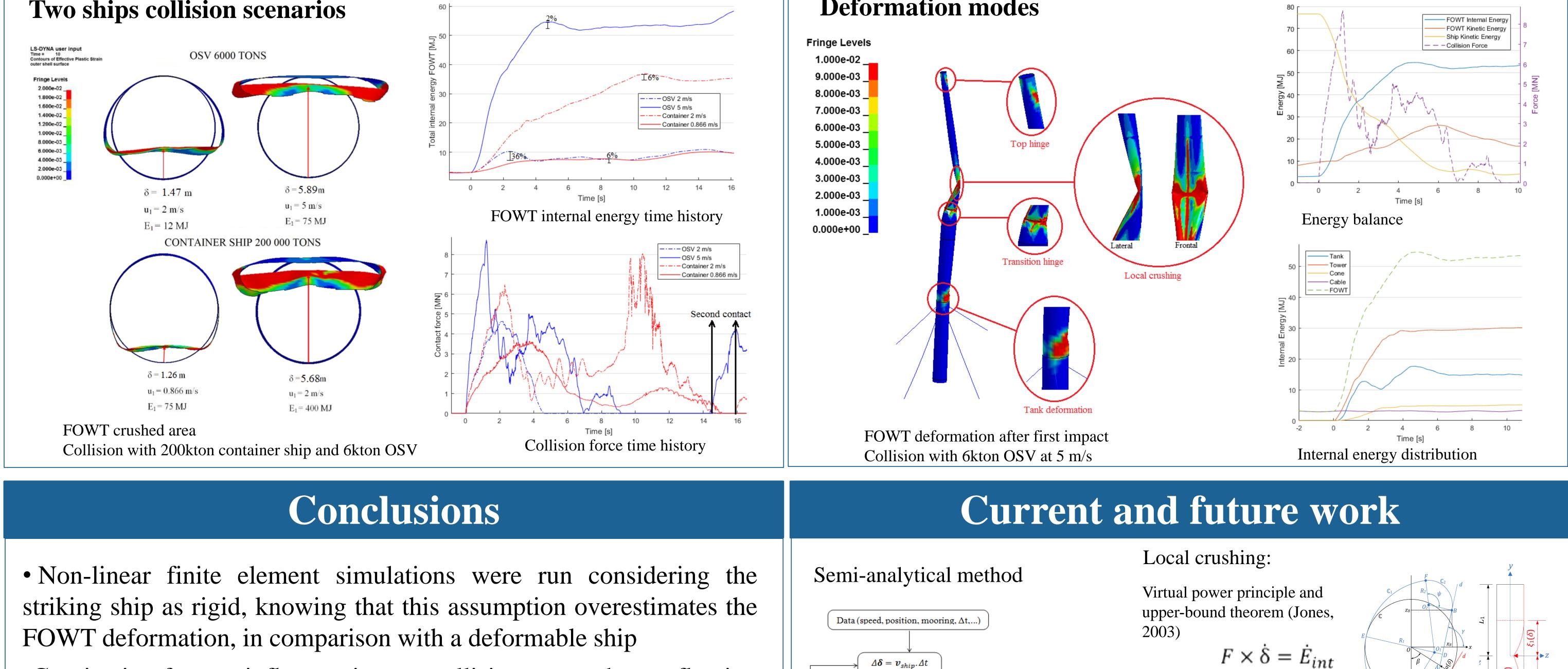
CMA CGM Maersk-Safmarine

Example of ships considered in the collision scenario

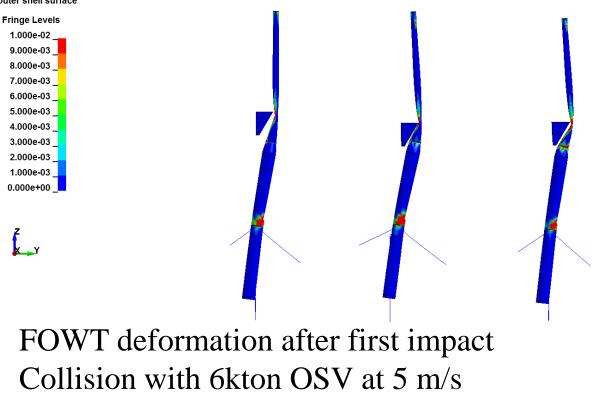
Main results

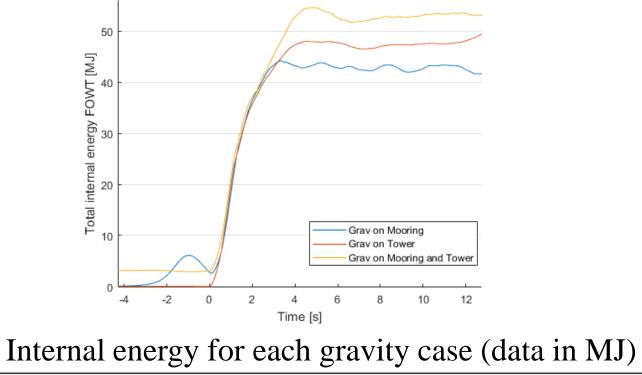
Parametric analysis





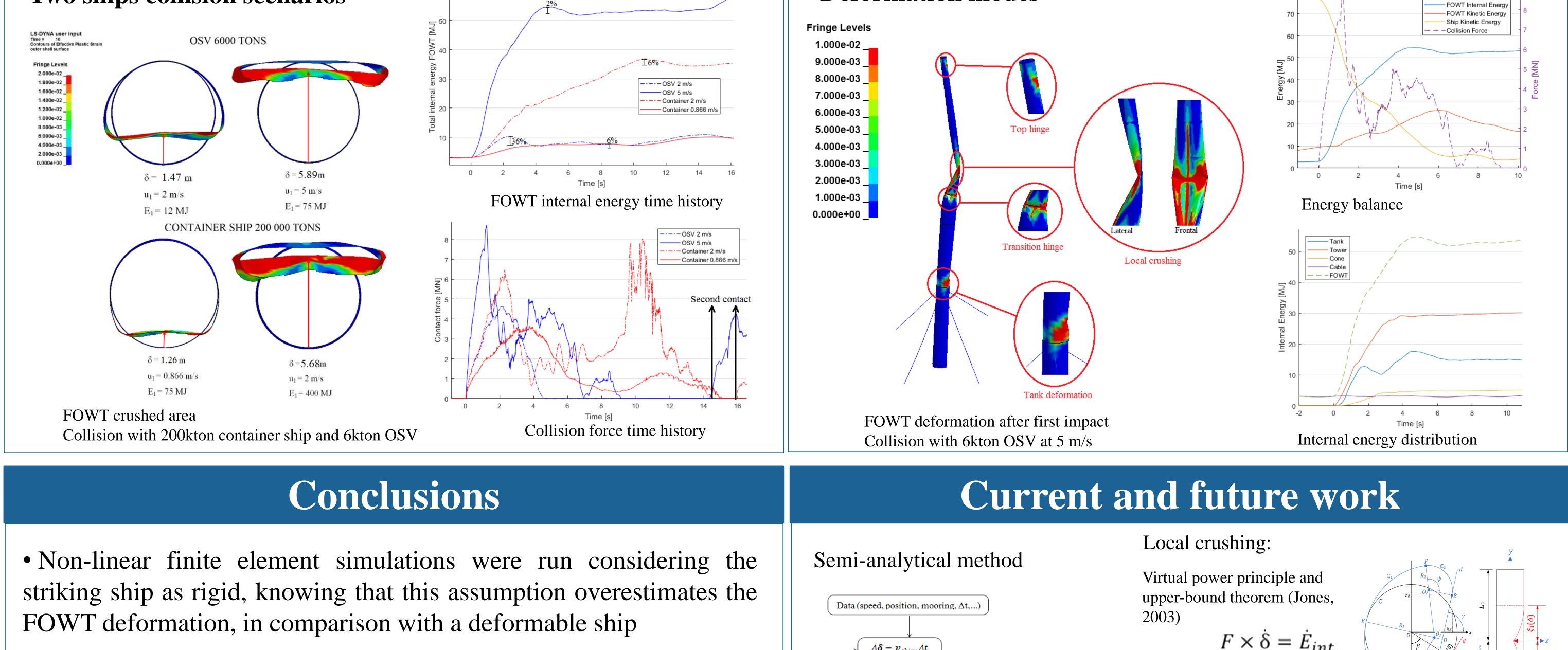






Part	No Gravity	G on Mooring	G on Tower	G on Mooring and Tower
Tower	17.4	18.2	20	30
Tank	21.9	20	26	15
Cone	0.84	0.8	1.2	5
Mooring	0.003	3	0.0012	3

Deformation modes

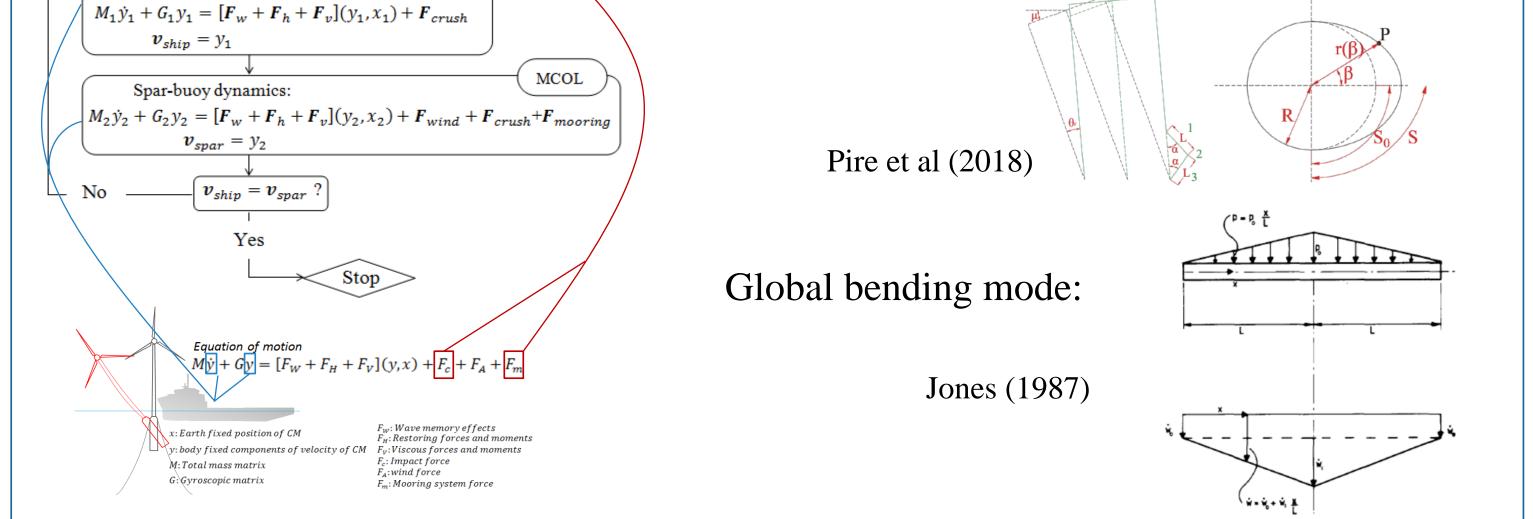


•Gravity is of great influence in any collision case when a floating structure is involved. Moreover, when a catenary mooring system is used

$F \times \dot{\delta} = \dot{E}_{int}$ Buldgen et al (2014) Tank deformation:

• The main deformation modes of a spar buoy FOWT collided by a ship are: plastic indentation in the collided area (local mode), beamlike response of the overall FOWT (global mode), plastic deformation near the ballast level (elephant foot), and seakeeping response governed by mooring stabilization

•The hinge in the transition piece due to punching of the tower, will be accounted as part of the global mode in the semi-analytical method.



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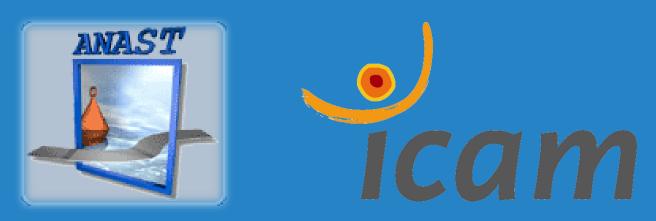
Super-element method

MCOL

Rigid ship, deformable spar-buoy

 $F_{mooring}(\delta)$ and $F_{crush}(\delta)$

Ship dynamics:



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