

Contributions to spatial data analysis and Stein's method

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Introduction

Part I : Spatial dependence

- 1 Outliers in spatial multivariate data
- 2 Robustness of tests for spatial autocorrelation

Part II: Stein's method

- 3 Stein differentiation
- 4 First order covariance identities and inequalities
- 5 Infinite covariance expansions
- 6 Stein factors and distances between distributions
- 7 General conclusions and perspectives

Part 1: spatial dependence

Two research questions

Part 1: spatial dependence

Question 1



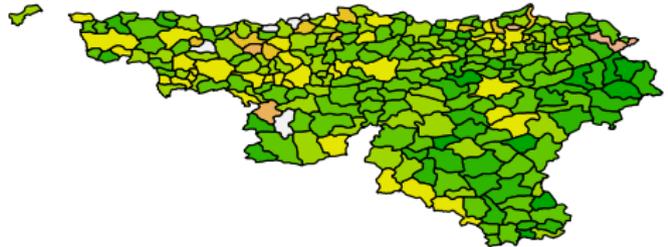
Spatial data

Spatial data:

- geographical positions
- non spatial attributes

Example

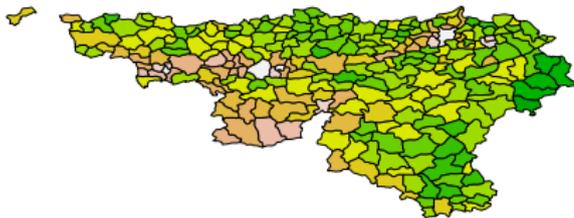
Waste per capita (kg) in the Walloon region in Belgium



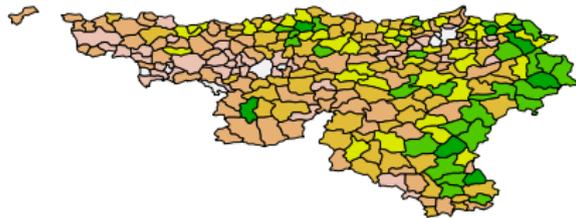
Multivariate spatial data

Example 2D

Unemployment rate



Old buildings (≥ 30 years)



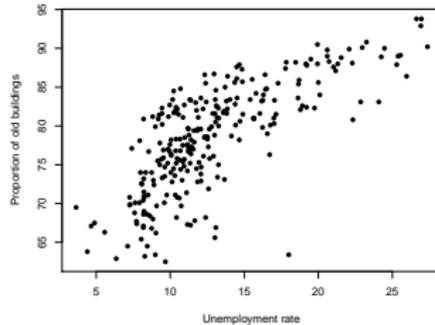
Multivariate spatial data

Example 2D

Spatial locations



Attribute representation



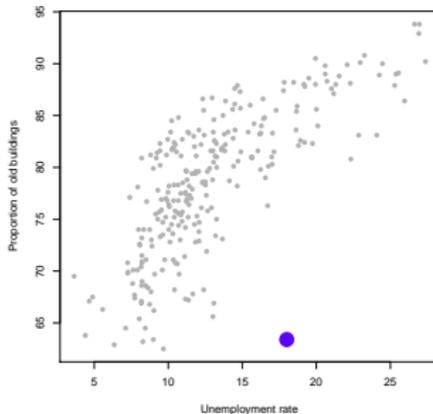
Multivariate spatial outliers

Two types of outliers (Haslett *et al.* (1991)):

- **global outlier**: extreme behaviour wrt all observations

Example 2D

Froidchapelle: global outlier



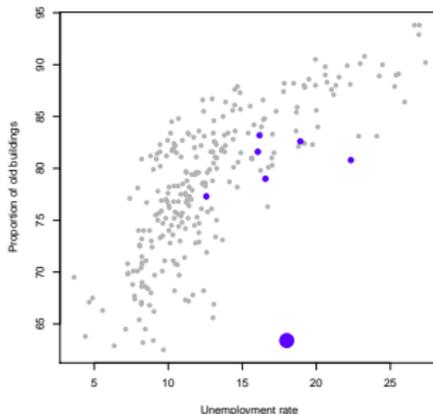
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Example 2D

Froidchapelle: global and local outlier



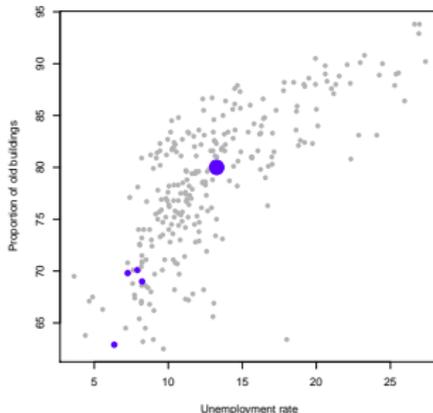
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Example 2D

Martelange: local outlier



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Global outliers detection

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- Usual outlier detection techniques can be used
⇒ not considered here

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Local outliers detection

- Review of some existing techniques
- Suggestion of an adaptation
- Comparison with examples and simulations

Considered Techniques

- ① Chen *et al.* (2008)
- ② Harris *et al.* (2014)
- ③ Filzmoser *et al.* (2014)

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- ① Chen *et al.* (2008): **Componentwise median** and robust Mahalanobis distance
- ② Harris *et al.* (2014): **Geographically Weighted PCA** with robust estimator
- ③ Filzmoser *et al.* (2014): Robust “**Mahalanobis-type**” detection
- ④ Regularized spatial detection technique: **Adaptation** of Filzmoser *et al.* (2014) (E. and Haesbroeck, 2017)

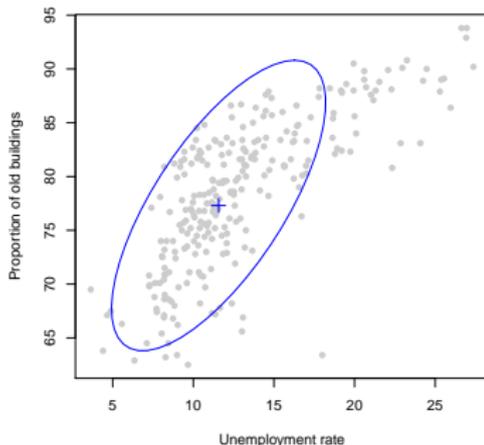
Filzmoser, Ruiz-Gazen and Thomas-Agnan (2014)

Approach

Robust “Mahalanobis-type” detection

- 1 Preliminary global step:
Robust estimation of the general structure: $(\hat{\mu}, \hat{\Sigma})$

Example 2D



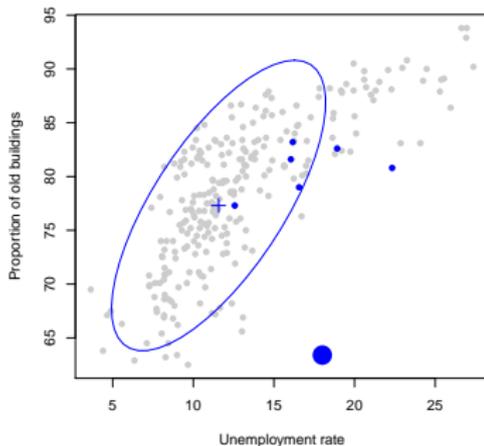
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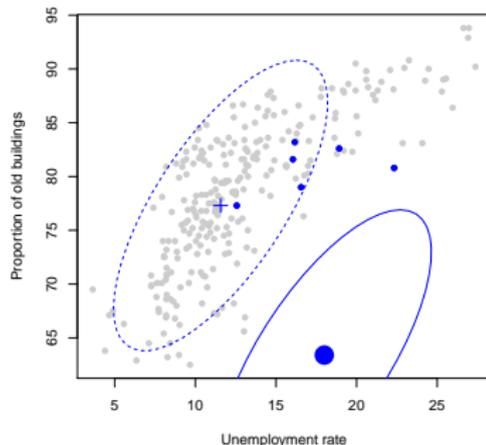
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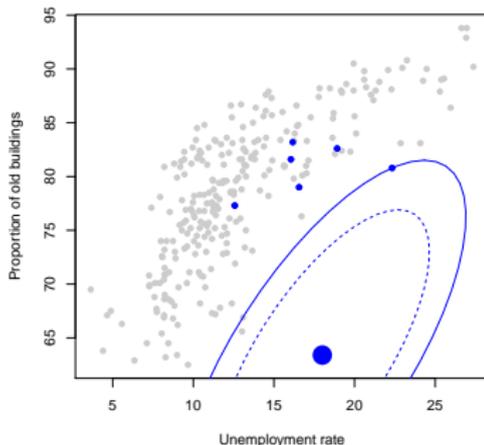
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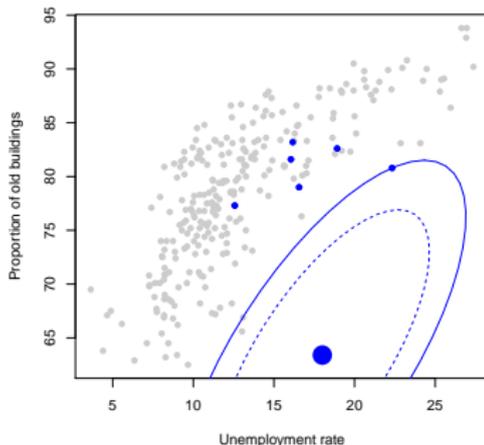
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 - If its tolerance level is larger than a theoretical quantile
⇒ **local outlier**

Example 2D



Regularized spatial detection technique

(E. and Haesbroeck, 2017)

Approach: adaptation of Filzmoser *et al.* (2014)

Work with **local structure** and only on the most **homogeneous neighbourhoods**

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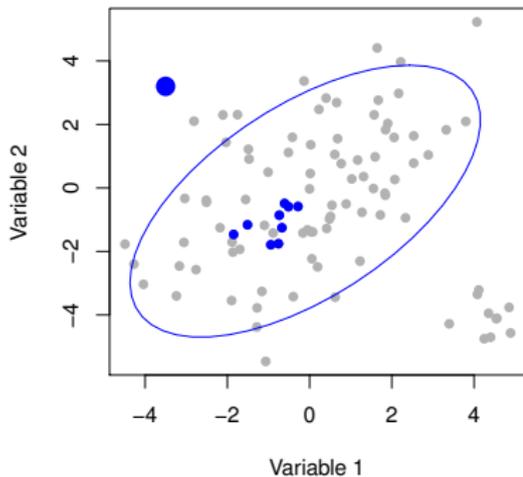
② Global step: Selection of 10%, 20%, ... of smallest values

③ Local step: work only on *selected* neighbourhoods

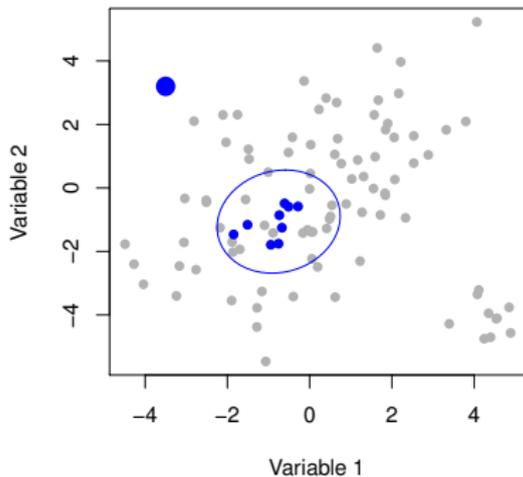
- Centring the *local* structure on the observation
- Determination of the ellipsoid containing the next neighbour
- If its tolerance level is larger than an empirical quantile \Rightarrow
local outlier

Illustration

Outliers for Filzmoser et al.

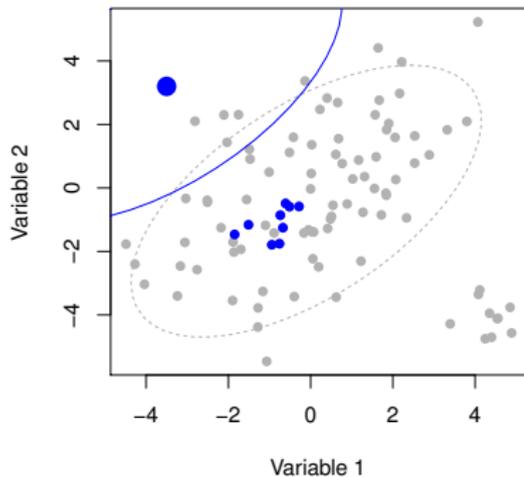


Outliers for regularization
Test on 10% of neighbourhoods

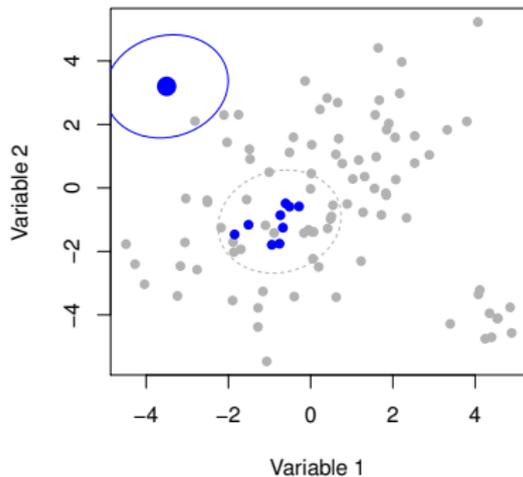


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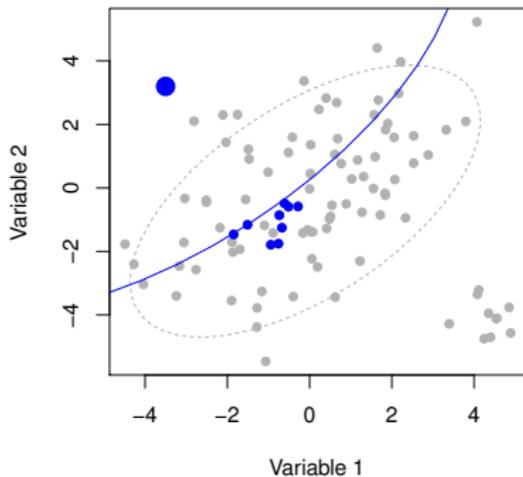


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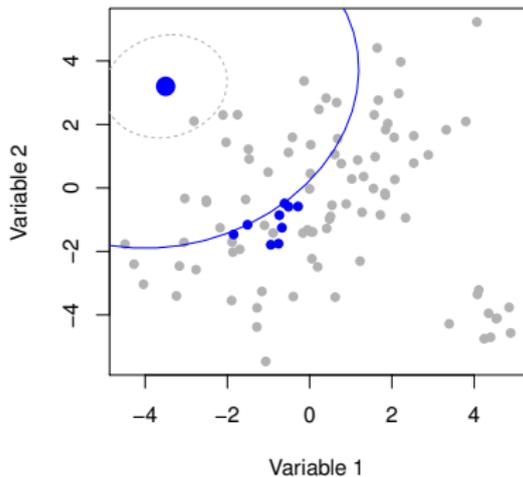


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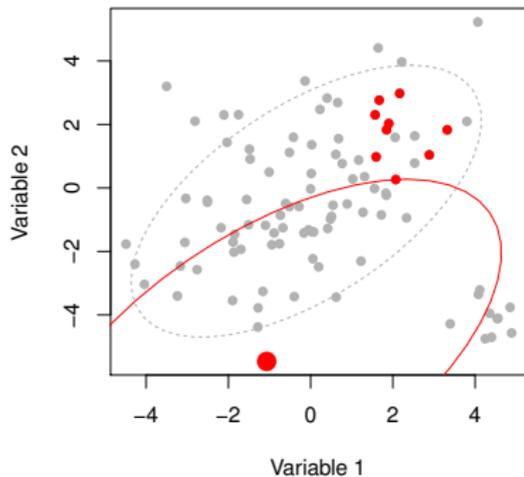


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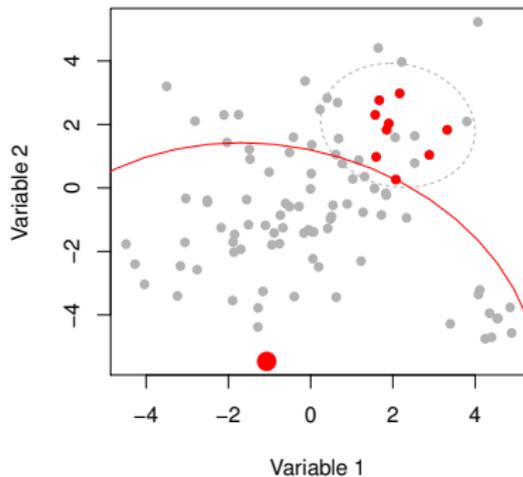


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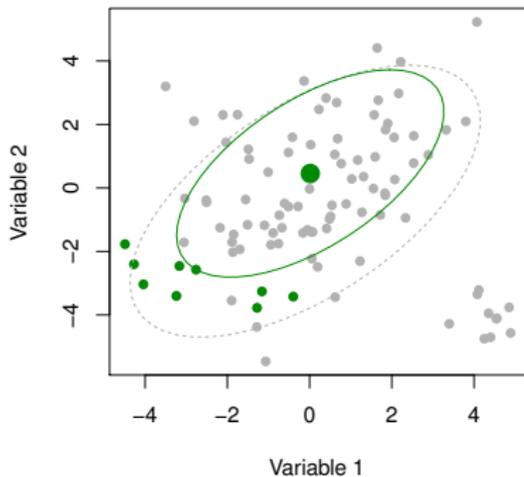


Outliers for regularization
Test on 20% of neighbourhoods

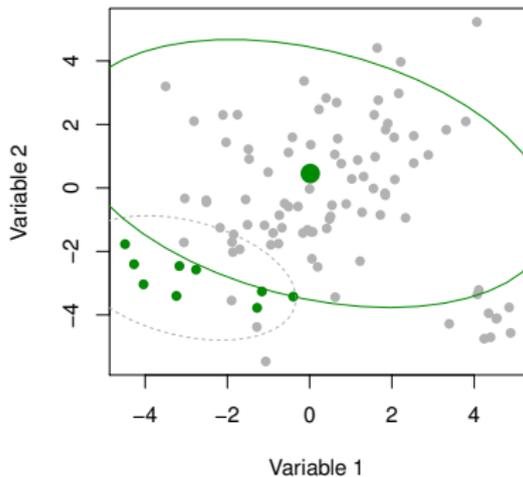


Illustration

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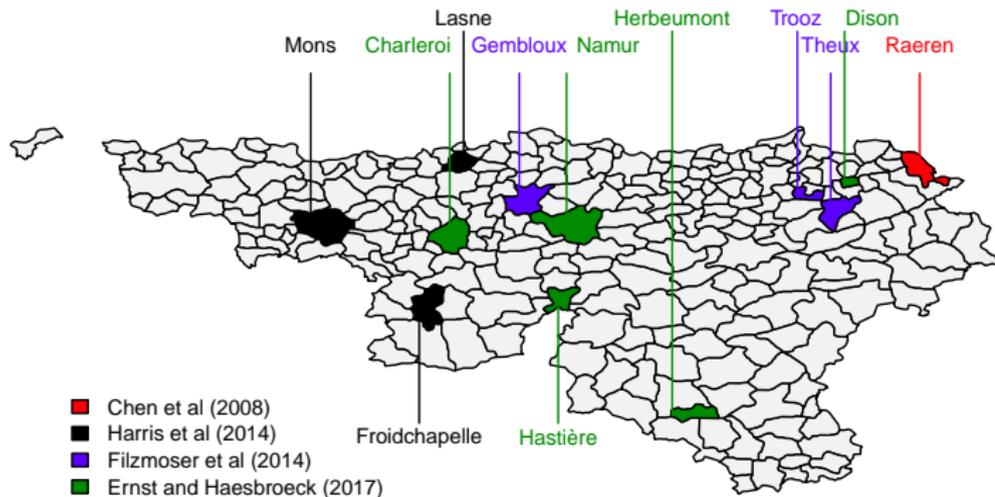


Outliers for regularization
Test on 30% of neighbourhoods



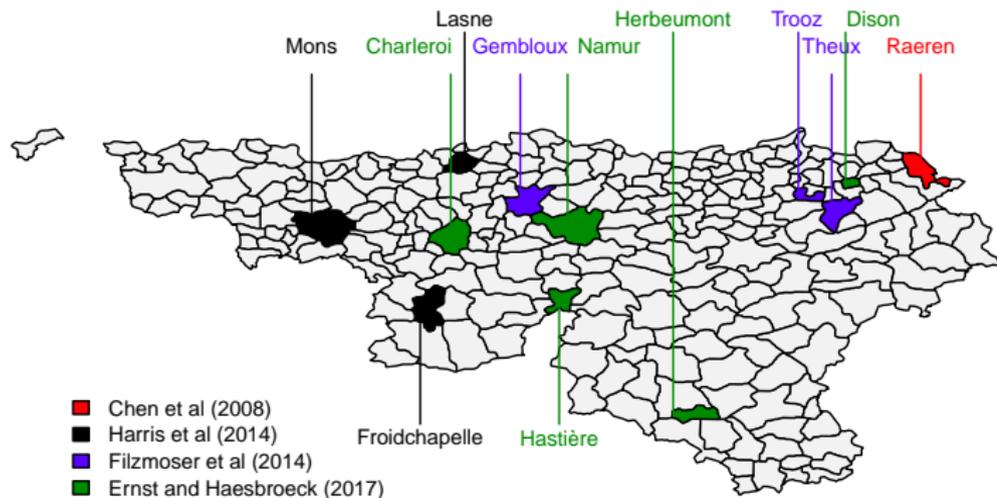
Illustrations

Wallonia: 14 socio-economic variables for the 262 municipalities



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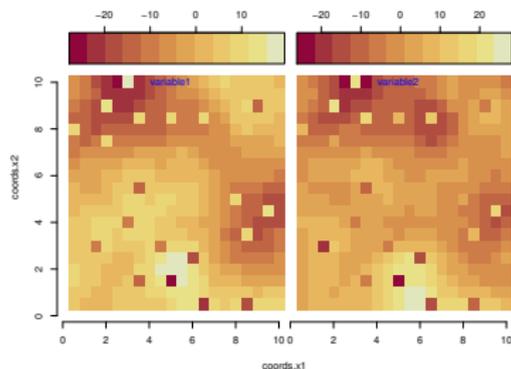
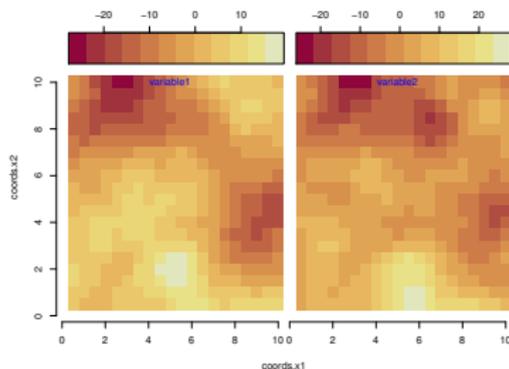
↪ Simulations for the comparison

Simulations

Generate spatial data of p variables for n locations (grid or Walloon municipalities)

Simulation set-up

- Matérn model to generate spatial data varying the overall smoothness
- Contamination by swapping observations with high/small PCA scores¹



¹Harris *et al.* (2014)

Results

- Harris et al. (2014) wrongly flags too many good observations as local outliers.
- Chen et al. (2008) handles well the regular domain with the less smooth design.
- Filzmoser et al (2014) outperforms the two previous techniques in most configurations (smoother variable and/or irregular domain).
- The adaptation has similar results as the initial technique; these results being dependent on the homogeneity constraint that we set.

Spatial autocorrelation

Question 2: When do we have to consider spatial techniques?

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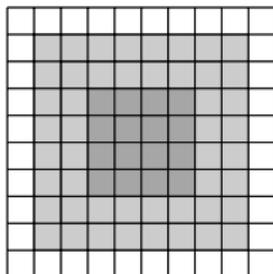
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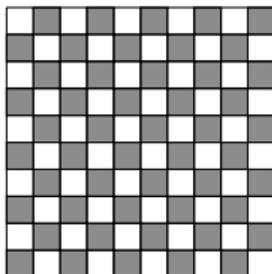
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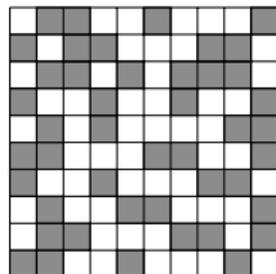
↪ check spatial autocorrelation



Positive spatial
autocorrelation



Negative spatial
autocorrelation



No spatial
autocorrelation

Neighbours

Weighting matrix W

Locations s_i and s_j are neighbours if and only if $w_{ij} > 0$.
Otherwise, $w_{ij} = 0$.

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Different choices:

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Different choices:

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Convention: zero diagonal and $S_0 = \sum_i \sum_j w_{ij}$.

Measures of spatial autocorrelation

Sample data points $\mathbf{z} = \{z_1, \dots, z_n\}$ observed at spatial locations $\{s_1, \dots, s_n\}$

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Moran's Index (1950)

$$I(\mathbf{z}) = \frac{n}{S_0} \frac{\sum_{i=1}^n \sum_{j=1}^n w_{ij} (z_i - \bar{z})(z_j - \bar{z})}{\sum_{i=1}^n (z_i - \bar{z})^2}$$

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Geary's ratio (1954)

$$c(\mathbf{z}) = \frac{n-1}{2S_0} \frac{\sum_{i=1}^n \sum_{j=1}^n w_{ij} (z_i - z_j)^2}{\sum_{i=1}^n (z_i - \bar{z})^2}$$

Getis and Ord's statistics (1992)

$$G(\mathbf{z}) = \frac{\sum_{i=1}^n \sum_{j=1}^n w_{ij} z_i z_j}{\sum_{i=1}^n \sum_{j=1, j \neq i}^n z_i z_j}$$

Inference

Tests based on asymptotic normality

Without spatial autocorrelation, I , c and G are **asymptotically Gaussian** under normality (N) and/or randomisation (R) assumption.

Inference

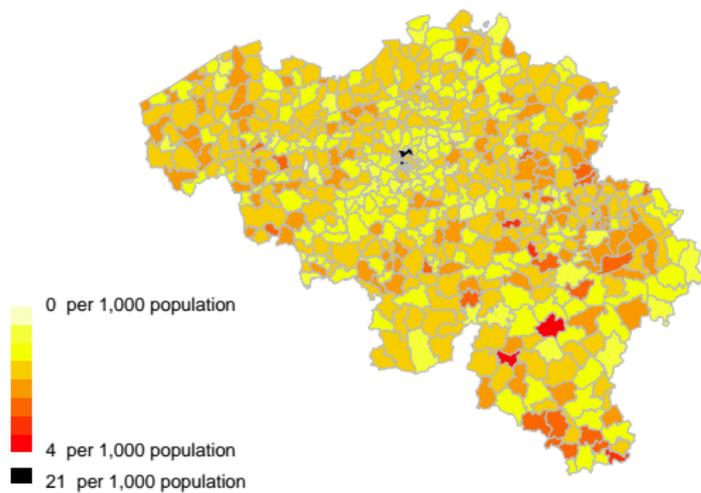
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Moran's I	Geary's c	Getis and Ord's G
Test under R	Test under R	Test under R
Test under N	Test under N	
Permutation test	Permutation test	Permutation test
Dray's test		

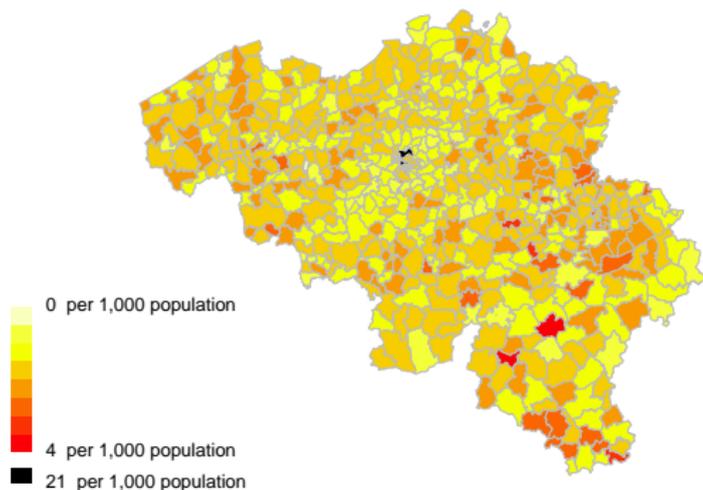
Robustness: example

Crude divorce rate in Belgium



Robustness: example

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- Moran's $I = 0.01$
- $E_{H_0}[I] = -0.0017$
- Range values:
 $-0.67 \leq I \leq 1.16$
- $p\text{-value} = 0.25$ (0.32)
under R (under N)

Robustness of the tests

Robustness (Huber, 1981)

Insensitivity to small deviations from assumptions and more precisely, outlier resistance

Classic robustness tools

- Breakdown point (Hampel 1971)
- Influence function (Hampel et al. 1986)

Characteristic

Based on functionals ($n \rightarrow \infty$)

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Characteristic

Based on functionals ($n \rightarrow \infty$) \rightsquigarrow favour empirical tools (finite n)

Empirical influence function of the p -value

(Lambert 1981)

Definition

$$EIF(\xi, i) = \frac{\text{p-value}(\mathbf{z} + \xi \mathbf{e}_i) - \text{p-value}(\mathbf{z})}{1/n}$$

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Proposition (Chapter 2, Prop. 2.4.1)

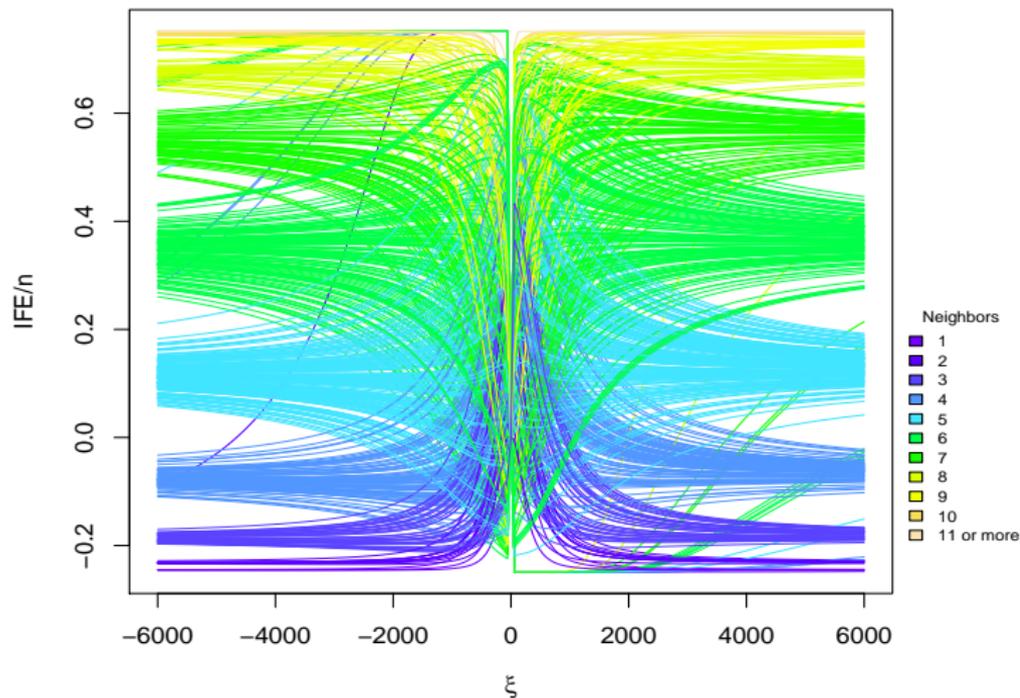
The EIF of the p -value of unilateral tests based on asymptotic normality for Moran's index is explicitly given by

$$\begin{aligned} EIF(\xi, i; I) &= n \left[\Phi \left(-\frac{I(\mathbf{z} + \xi \mathbf{e}_i) - \mathbb{E}[I]}{\sigma[I(\mathbf{z} + \xi \mathbf{e}_i)]} \right) - \Phi \left(-\frac{I(\mathbf{z}) - \mathbb{E}[I]}{\sigma[I(\mathbf{z})]} \right) \right] \\ &\rightarrow n \left[\Phi \left(\frac{2(nw_{i\bullet} - S_0)}{(n-1)S_0\sigma[I]} \right) - \Phi \left(-\frac{I(\mathbf{z}) - \mathbb{E}[I]}{\sigma[I]} \right) \right] \end{aligned}$$

as ξ tends to infinity.

Robustness: example

Crude divorce rate: hair-plot (Genton and Ruiz-Gazen, 2010)



Resistance of a test

(Ylvisaker 1977)

Definition

Resistance to acceptance (resp. rejection): smallest proportion of the data that must be corrupted to guarantee the acceptance (rejection) of H_0 .

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Proposition (Chapter 2, Prop. 2.4.2 - 2.4.3)

- Resistance to acceptance is $1/n$ for both asymptotic tests
- The resistance to rejection is m/n where m is the size of the smallest subset $A \subseteq \{1, \dots, n\}$ which satisfies

$$\begin{cases} \frac{n^2 w_A - 2nm(w_A + w_B) + m^2 S_0}{S_0 m(n-m)} > \frac{-1}{n-1} + \sigma_N[I] z_{1-\alpha} & \text{under N} \\ \frac{n^2 w_A - 2mn(w_A + w_B) + m^2 S_0}{S_0 m(n-m)} > \frac{-1}{n-1} + \sqrt{a_1 - a_2 \frac{n^2 - 3nm + 3m}{(n-m)m}} z_{1-\alpha} & \text{under R} \end{cases}$$

Robustness: example

Example: Belgium

- *Resistance to acceptance*: for divorces, the contaminated rate of Brussels modified the result into an acceptance of H_0 . If the “true” value is associated with Brussels², Moran's I is 0.14 (p -value < 0.0001) instead of 0.01 (p -value ≥ 0.25).

²Brussels: 24 local divorces vs 3698 divorces

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Other tests

The lack of robustness of the other tests is similarly proved.

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Robust alternative 1

Rank Moran index I_r

Idea: replace observations by their rank

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Proposition (Chapter 2, Prop 2.5.2)

$$EIF(\xi, i; I_r) = n \left[\Phi \left(\frac{I_r(\mathbf{z}) - E[I_r]}{\sigma[I_r]} \right) - \Phi \left(\frac{I_r(\mathbf{z}) - E[I_r]}{\sigma[I_r]} + \frac{e}{\sigma[I_r]} \right) \right]$$

where $e = I_r(\mathbf{z} + \xi \mathbf{e}_i) - I_r(\mathbf{z})$ is explicit.

The impact of contamination on the p -value is limited.

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Rank Moran index I_r

Idea: replace observations by their rank

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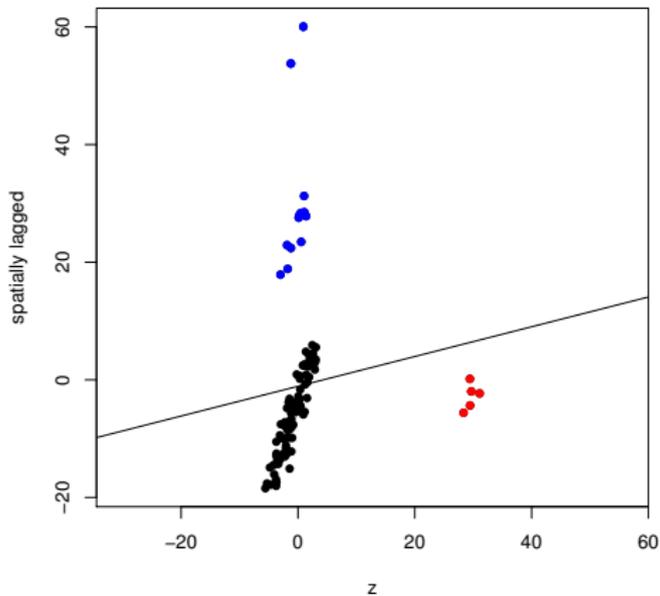
Estimated resistances (Belgium)

- Resistance to rejection: at most 14/589
- Resistance to acceptance: 6/589

Robust alternative 2

Moran scatterplot

Moran can be interpreted as the slope in a OLS regression of spatially lagged observations over z .

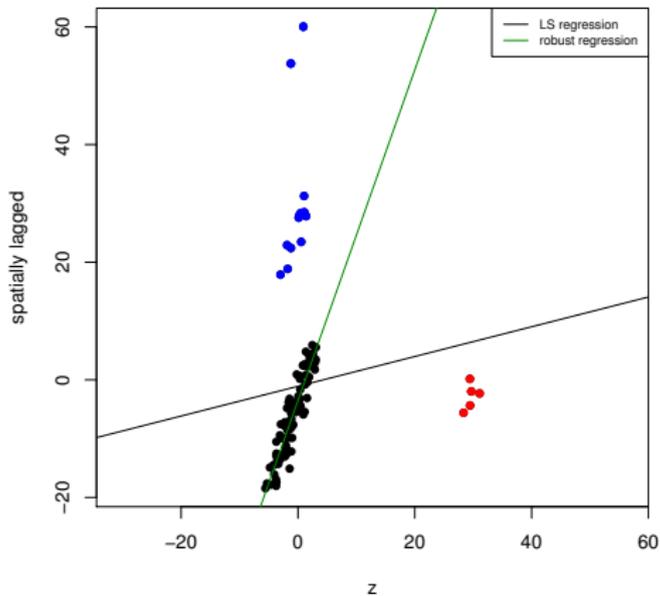


Robust alternative 2

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Moran can be interpreted as the slope in a OLS regression of spatially lagged observations over \mathbf{z} .

↪ **Idea:** use robust regression



Robust and efficient regression estimation

Different methods

- S-estimator (Rousseeuw and Yohai, 1984)
- Least Trimmed Squares (LTS - Rousseeuw, 1985)
- MM-estimator (Yohai, 1987)
- Robust and Efficient Weighted Least Squares Estimator (REWLSE - Gervini and Yohai, 2002)

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Robustness of adapted Moran index

Due to robust properties of regression estimators,

- the impact on the p -value is zero almost everywhere;
- the resistance is m/n where m is the minimal number of observations for which the joint neighbourhoods contains at most 50% of the points in Moran scatterplot.

Simulation study

Efficiency of robust tests

Comparison of level and power of robust and classic tests.

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Spatial autoregressive model

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Results

- Comparable power and level for all tests
- Power increases with n
- Power increases with ρ

Gaussian case

Stein's identity

If $X \sim \mathcal{N}(0, 1)$, then

$$\mathbb{E}[Xg(X)] = \mathbb{E}[g'(X)] \quad \forall g \text{ s.t. } \mathbb{E}[|g'(X)|] < \infty$$

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Stein operator

The associated *Stein operator* is defined by

$$\mathcal{T}g(x) = xg(x) - g'(x)$$

and $\mathbb{E}[\mathcal{T}g(X)] = 0$ for any appropriate g .

Let $X \sim p$. The derivative-type operators are

$$\Delta^{\ell} f(x) = \begin{cases} f'(x) & \text{if } \ell = 0; \\ f(x+1) - f(x) & \text{if } \ell = +1; \\ f(x) - f(x-1) & \text{if } \ell = -1. \end{cases}$$

Formalism

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Canonical Stein operator

For any $f : \mathbb{R} \rightarrow \mathbb{R}$, the *canonical Stein operator* is defined as

$$\mathcal{T}_p^\ell : f(x) \mapsto \mathcal{T}_p^\ell f(x) := \frac{\Delta^\ell(f(x)p(x))}{p(x)}.$$

For any f from the *canonical Stein class*, $\mathbb{E}[\mathcal{T}_p f(X)] = 0$.

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Particular case: the score function

$$\rho_p^\ell(x) = \mathcal{T}_p^\ell \mathbf{1}(x) = \frac{\Delta^\ell p(x)}{p(x)}$$

Example: Poisson density

$$p(x) = e^{-\lambda} \lambda^x / x! \text{ for } x \in \mathbb{N} \text{ and } \ell = \pm 1$$

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- $\mathcal{T}_p^+ f(x) = \frac{\Delta^+(f(x)p(x))}{p(x)} = f(x+1) \frac{\lambda}{x+1} - f(x)$
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The score functions

- $\rho_p^+(x) = \mathcal{T}_p^+ 1(x) = \frac{\lambda}{x+1} - 1$
- $\rho_p^-(x) = \mathcal{T}_p^- 1(x) = 1 - \frac{x}{\lambda}$

Pseudo inverse Stein operator

The *canonical pseudo inverse Stein operator* for the operator \mathcal{T}_p^ℓ is

$$\mathcal{L}_p^\ell : h(x) \mapsto \mathcal{L}_p^\ell h(x) := \frac{1}{p(x)} \int_a^{x-a_\ell} (h(u) - \mathbb{E}[h(X)]) p(u) \mu(du)$$

where $a_\ell = \mathbb{I}[\ell = 1]$.

Properties

- $\mathcal{L}_p^\ell \mathcal{T}_p^\ell f(x) = f(x)$
- $\mathcal{T}_p^\ell \mathcal{L}_p^\ell h(x) = h(x) - \mathbb{E}[h(X)]$

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Stein equation

Standardized Stein operator

$$\mathcal{A}g(x) = \mathcal{T}_p^\ell (f(\cdot)g(\cdot - \ell))(x) = \mathcal{T}_p^\ell f(x)g(x) + f(x)\Delta^{-\ell}g(x)$$

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Stein covariance identity (IBP 1)

For all “appropriate” f and g ,

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Stein covariance identity (IBP 2)

For all “appropriate” f and g ,

$$\text{Cov} [f(X), g(X)] = \mathbb{E} \left[- \left(\mathcal{L}_\rho^\ell f(X) \right) \Delta^{-\ell} g(X) \right]$$

Representations of the inverse operator

E., Reinert and Swan (2019)

- $\mathcal{L}_p^\ell f(x) = \mathbb{E} \left[(f(\mathbf{X}) - \mathbb{E}[f(\mathbf{X})]) \frac{\mathbb{I}[\mathbf{X} \leq x - \mathbf{a}_\ell]}{p(x)} \right] \quad (\text{Definition})$

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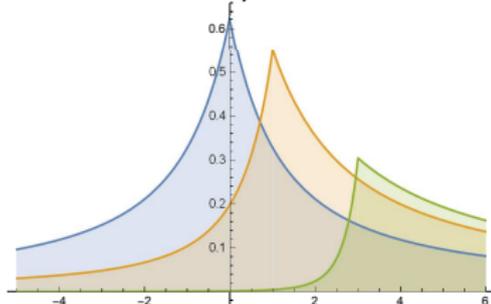
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References for $\ell = 0$:

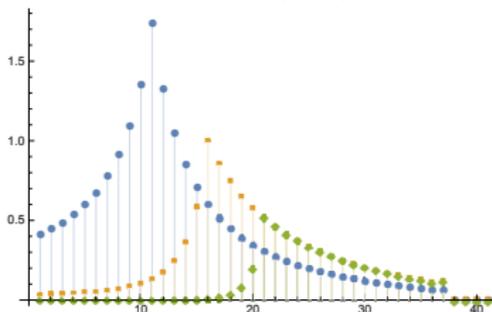
- Rep. I is non-explicitly given in Chatterjee and Shao (2011)
- Rep. II is available in Saumard (2019)
- Symmetric kernel K_p^0 : first appearance attributed to Höfding (1940)

Examples

$$x \mapsto K_p^\ell(x, x')/p(x)$$

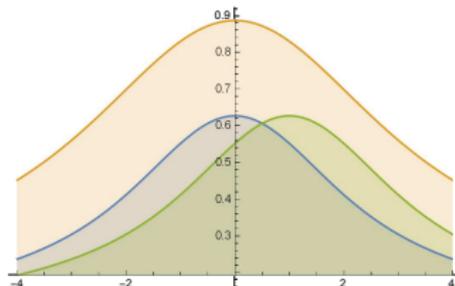


$\mathcal{N}(0, 1)$

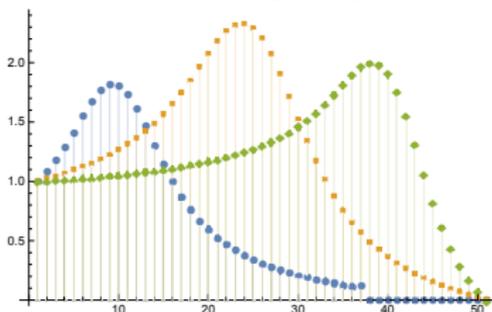


$\text{Bin}(50, 0.2)$

$$x \mapsto K_p^\ell(x, x)/p(x)$$



$\mathcal{N}(\mu, \sigma^2)$



$\text{Bin}(50, \theta)$

Applications

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Application 1: First order variance bounds

Family of first order lower and upper covariance bounds for functionals of arbitrary univariate distributions.

↪ E., Reinert and Swan (2019a), Bernoulli.

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Application 3: Stein factor and distances

Estimates of distances between univariate probability distributions.

↪ E. and Swan (2019), arXiv:1909.11518

Application 1: first order variance bounds

Theorem (Cramer-Rao and weighted Poincaré inequality)

$$\frac{\mathbb{E} \left[-\mathcal{L}_p^\ell h(X) (\Delta^{-\ell} g(X)) \right]^2}{\text{Var}(h(X))} \leq \text{Var}[g(X)] \leq \mathbb{E} \left[(\Delta^{-\ell} g(X))^2 \frac{-\mathcal{L}_p^\ell h(X)}{\Delta^{-\ell} h(X)} \right]$$

for decreasing h with equality if and only if $g \propto h$.

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Examples

- (Chernoff, 1980) If $X \sim \mathcal{N}(0, 1)$ then

$$\mathbb{E}[g'(X)]^2 \leq \text{Var}[g(X)] \leq \mathbb{E}[(g'(X))^2]$$

- (Brascamp-Lieb, 1976) For appropriate density and g ,

$$\frac{\mathbb{E} \left[(\Delta^{-\ell} g(X))^2 \right]}{\mathbb{E} \left[(\rho_p^\ell(X))^2 \right]} \leq \text{Var}[g(X)] \leq \mathbb{E} \left[\frac{(\Delta^{-\ell} g(X))^2}{-\Delta^{-\ell} \rho_p^\ell(X)} \right]$$

Application 2: infinite expansion

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Papathanasiou-type expansion

$$\text{Cov} [\mathbf{f}(X)] = \sum_{k=1}^n (-1)^{k-1} \mathbb{E} \left[\Delta^{-\ell_k} \mathbf{f}_{k-1}(X) \Delta^{-\ell_k} \mathbf{f}'_{k-1}(X) \frac{\Gamma_k^\ell \mathbf{h}(X)}{\Delta^{-\ell_k} h_k(X)} \right] \\ + (-1)^n R_n^\ell(\mathbf{h})$$

for weight sequences $\Gamma_k^\ell \mathbf{h}(x)$ and remainder term $R_n^\ell(\mathbf{h})$.

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References:

- $h_k(x) = x$: Papathanasiou (1988, $\ell_k = 0$)
- $h_k(x) = x$: Afendras et al. (2007, $\ell_k = -1$)
- $n = 1$ and $h_1 = -(\log p)'$ for log-concave p : Brascamp-Lieb inequality

Examples

Normal expansion

if $X \sim \mathcal{N}(0, 1)$ then $\Gamma_k^0(x) = \frac{1}{k!}$ for all k and

$$\text{Cov}[f(X), g(X)] = \sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k!} \mathbb{E} \left[f^{(k)}(X) g^{(k)}(X) \right].$$

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Beta expansion

If $X \sim \text{Beta}(a, b)$ then $\Gamma_k^0(x) = \frac{(x(1-x))^k}{k!(a+b)^{[k]}}$ for all k and

$$\text{Cov}[f(X), g(X)] = \sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k!(a+b)^{[k]}} \mathbb{E} \left[f^{(k)}(X) g^{(k)}(X) X^k (1-X)^k \right].$$

Examples (2)

Poisson expansion

If $X \sim \text{Poi}(\lambda)$, the order 1 expansions are

$$\begin{aligned}\text{Var}[g(X)] &= \mathbb{E} [X(\Delta^- g(X))^2] - R_1^+ \\ &= \lambda \mathbb{E} [(\Delta^+ g(X))^2] - R_1^-;\end{aligned}$$

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and the order 2 expansions are

$$\begin{aligned}\text{Var}[g(X)] &= \mathbb{E} [X(\Delta^- g(X))^2] - \frac{1}{2} \mathbb{E} [X(X-1)(\Delta^{--} g(X))^2] - R_2^{++} \\ &= \mathbb{E} [X(\Delta^- g(X))^2] - \frac{1}{2} \lambda \mathbb{E} [X(\Delta^{-+} g(X))^2] - R_2^{+-} \\ &= \lambda \mathbb{E} [(\Delta^+ g(X))^2] - \frac{1}{2} \lambda \mathbb{E} [X(\Delta^{+-} g(X))^2] - R_2^{-+} \\ &= \lambda \mathbb{E} [(\Delta^+ g(X))^2] - \frac{1}{2} \lambda^2 \mathbb{E} [(\Delta^{++} g(X))^2] - R_2^{--}\end{aligned}$$

Application 3: Stein factors and distances

Let X_n and X_∞ be random variables.

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Stein identity (IBP 1)

Two linear operators \mathcal{T}_∞^ℓ and \mathcal{L}_∞^ℓ are associated with X_∞ such that

$$\mathbb{E} \left[(\mathcal{T}_\infty^\ell c(X_\infty)) g(X_\infty) \right] = -\mathbb{E} \left[c(X_\infty) \Delta^{-\ell} g(X_\infty) \right]$$

are valid for all sufficiently regular functions c, g .

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Stein discrepancy

Quantify the “distance” between the laws of X_n and X_∞ :

$$\mathcal{S}(X_n, X_\infty, \mathcal{G}) := \sup_{g \in \mathcal{G}} \left| \mathbb{E} \left[(\mathcal{T}_\infty^\ell c(X_n)) g(X_n) + c(X_n) \Delta^{-\ell} g(X_n) \right] \right|$$

IPM and Stein discrepancy

Integral Probability Metric (IPM)

$$\mathcal{D}_{\mathcal{H}}(X_n, X_{\infty}) = \sup_{h \in \mathcal{H}} |\mathbb{E}h(X_n) - \mathbb{E}h(X_{\infty})|$$

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- **Kolmogorov distance:** $\sup_{z \in \mathbb{R}} |\mathbb{P}(X_n \leq z) - \mathbb{P}(X_{\infty} \leq z)|$
is associated with $\mathcal{H}_{\text{Kol}} = \{h(x) = \mathbb{I}[x \in (-\infty, z]] : z \in \mathbb{R}\}$.

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- **Wasserstein distance:** $\int_{-\infty}^{\infty} |\mathbb{P}(X_n \leq z) - \mathbb{P}(X_{\infty} \leq z)| dz$
is associated with $\mathcal{H}_{\text{Wass}} = \{h : |h(x) - h(y)| \leq |x - y|\}$.

IPM and Stein discrepancy

Integral Probability Metric (IPM)

$$\mathcal{D}_{\mathcal{H}}(X_n, X_{\infty}) = \sup_{h \in \mathcal{H}} |\mathbb{E}h(X_n) - \mathbb{E}h(X_{\infty})|$$

Theorem

$$\mathcal{D}_{\mathcal{H}}(X_n, X_{\infty}) = \mathcal{S}(X_n, X_{\infty}, \mathcal{G}_{\mathcal{H}})$$

where

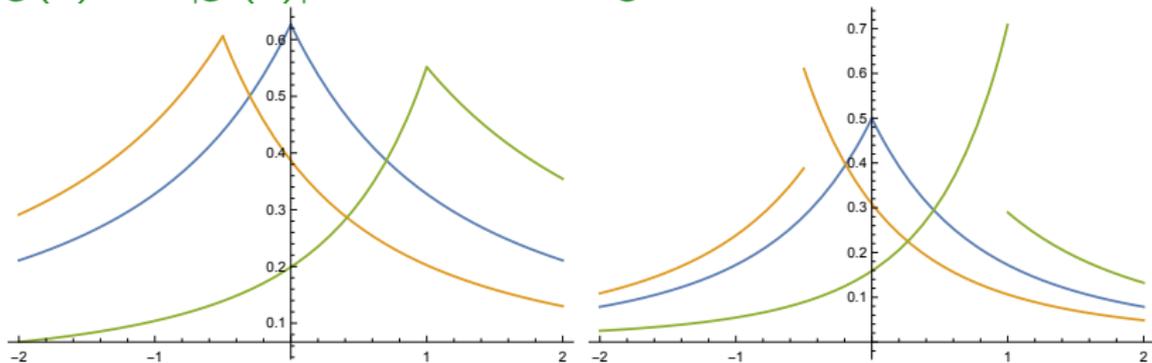
$$\mathcal{G}_{\mathcal{H}} = \left\{ g_h(x) = \frac{\mathcal{L}_p^{\ell} h(x + \ell)}{c(x + \ell)} : h \in \mathcal{H} \right\}.$$

Examples

Lower half-line indicator: $h(x) = \mathbb{I}[x \leq \xi]$ ($\ell = 0$)

- $g(x) = \frac{1}{c(x)} \frac{P(\xi \wedge x) \bar{P}(\xi \vee x)}{\rho(x)}$
- $g'(x) = \frac{\mathbb{I}[x \leq \xi] - P(\xi)}{c(x)} - \frac{T_p^0 c(x)}{c^2(x)} \frac{P(\xi \wedge x) \bar{P}(\xi \vee x)}{\rho(x)}$.

$g(x)$ and $|g'(x)|$ for Gaussian target



Examples

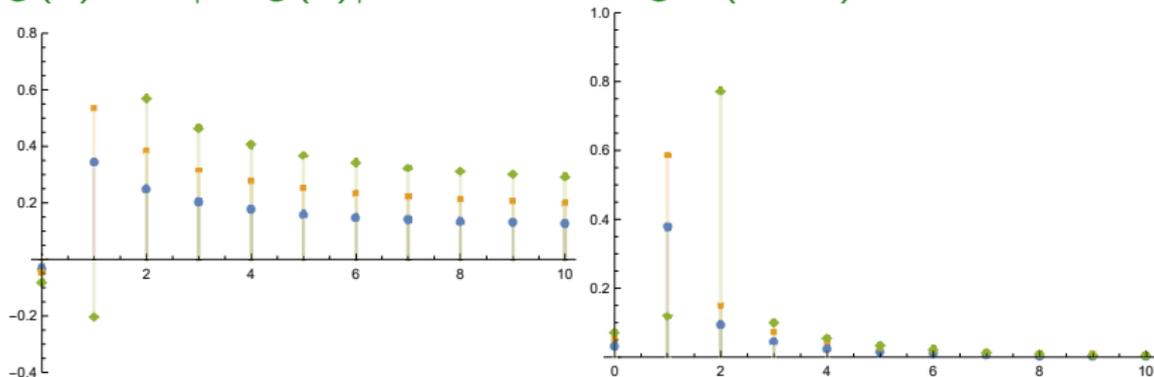
Point mass: $h(x) = \mathbb{I}[x = \xi]$ ($\ell = \pm 1$)

- $g(x) = \frac{p(\xi)}{c(x+\ell)p(x+\ell)} (\mathbb{I}[x \geq \xi + b_\ell] - P(x - b_\ell))$

- If $c = \tau_p^\ell$,

$$\Delta^{-\ell} g_\xi^\ell(x) = \frac{\mathbb{I}[x=\xi]-p(\xi)}{\tau_p^+(x)} + \frac{p(\xi)(\mathbb{I}[x \geq \xi]-P(x))}{p(x)} \left(\frac{1}{\tau_p^-(x)} - \frac{1}{\tau_p^+(x)} \right)$$

$g(x)$ and $|\Delta^- g(x)|$ for Poisson target ($\ell = 1$)



Stein factor for general h

Proposition

Let $\kappa_1 = \sup_{y \in \mathcal{S}(p)} h(y) - \inf_{y \in \mathcal{S}(p)} h(y)$ and $\kappa_2 = \sup_{y \in \mathcal{S}(p)} |\Delta^{-\ell} h(y)|$.

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① If h is bounded then

- $|g(x)| \leq \kappa_1 \frac{P(x-b_\ell)\bar{P}(x-b_\ell)}{\rho(x+\ell)} \frac{1}{c(x+\ell)}$
- $|\Delta^{-\ell} g(x)| \leq \kappa_1 \frac{1}{c(x)} \left(1 + \frac{|\mathcal{T}_\rho^\ell c(x)|}{c(x+\ell)} \frac{P(x-b_\ell)\bar{P}(x-b_\ell)}{\rho(x+\ell)} \right).$

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② If $\Delta^{-\ell} h$ exists and is bounded then

- $|g(x)| \leq \kappa_2 \frac{\tau_\rho^\ell(x+\ell)}{c(x+\ell)}$
- $|\Delta^{-\ell} g(x)| \leq \kappa_2 \left(\frac{|x - \mathbb{E}[X]|}{c(x)} + \frac{|\mathcal{T}_\rho^\ell c(x)|}{c(x)} \frac{\tau_\rho^\ell(x+\ell)}{c(x+\ell)} \right).$

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If, moreover, $c = -\mathcal{L}_\rho^\ell \eta$, three other bounds are provided.

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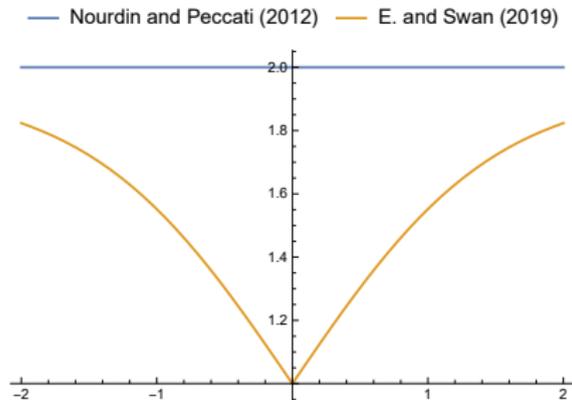
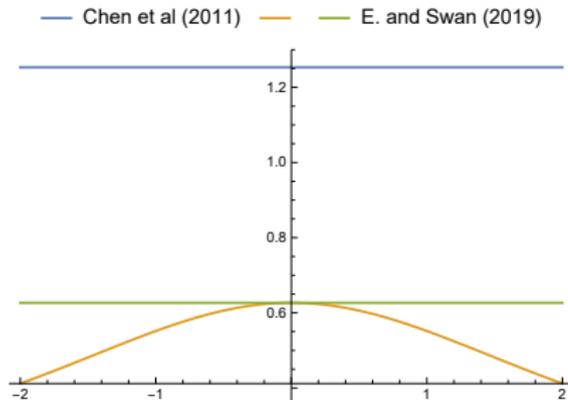
Some references for $\ell = 0$: Döbler (2012, 2015)

Application to specific distributions

Gaussian distribution

$$\begin{aligned} |g(x)| &\leq \kappa_1 \frac{\Phi(x)(1 - \Phi(x))}{\varphi(x)} \\ &\leq \kappa_1 \frac{1}{2} \sqrt{\frac{\pi}{2}} \end{aligned}$$

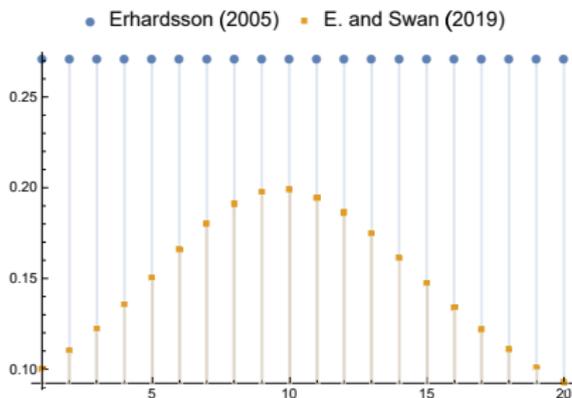
$$\begin{aligned} |g'(x)| &\leq \kappa_1 \left(1 + |x| \frac{\Phi(x)(1 - \Phi(x))}{\varphi(x)} \right) \\ &\leq 2\kappa_1 \end{aligned}$$



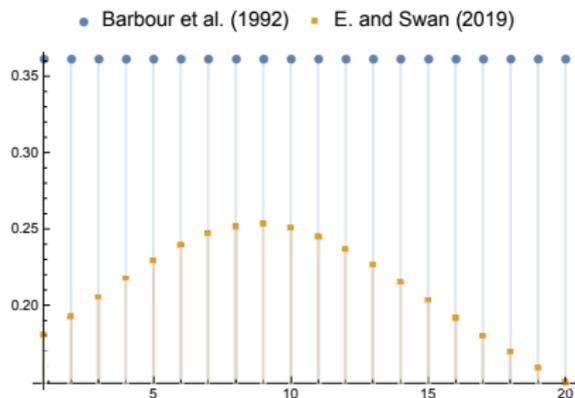
Application to specific distributions

Poisson distribution with parameter 10

Bounds on $|g^-(x)|$



Bounds on $|\Delta^+ g^-(x)|$



Bounds on IPM's

Theorem: Stein discrepancies

Let $X_n \sim p_n$ be some random variable and let X_∞ have canonical Stein operators $\mathcal{T}_\infty^{\ell_\infty}$ and $\mathcal{L}_\infty^{\ell_\infty}$. Then,

$$\begin{aligned}\mathbb{E}h(X_n) - \mathbb{E}h(X_\infty) &= \mathbb{E} \left[(\eta_1(X_n) - \mathbb{E}[\eta_1(X_\infty)]) \frac{\mathcal{L}_\infty^{\ell_\infty} h(X_n + \ell_\infty)}{\mathcal{L}_\infty^{\ell_\infty} \eta(X_n + \ell_\infty)} \right] \\ &\quad + \mathbb{E} \left[\mathcal{L}_\infty^{\ell_\infty} \eta(X_n) \Delta^{-\ell_\infty} \left(\frac{\mathcal{L}_\infty^{\ell_\infty} h(\cdot + \ell_\infty)}{\mathcal{L}_\infty^{\ell_\infty} \eta(\cdot + \ell_\infty)} \right) (X_n) \right] \\ &= \mathbb{E} \left[(\mathcal{T}_\infty^{\ell_\infty} c_1(X_n)) \frac{\mathcal{L}_\infty^{\ell_\infty} h(X_n + \ell_\infty)}{c_1(X_n + \ell_\infty)} \right] \\ &\quad + \mathbb{E} \left[c_1(X_n) \Delta^{-\ell_\infty} \left(\frac{\mathcal{L}_\infty^{\ell_\infty} h(\cdot + \ell_\infty)}{c_1(\cdot + \ell_\infty)} \right) (X_n) \right].\end{aligned}$$

In particular, IPM can be written as suprema of either of the above.

Example: Gaussian target

$$X_\infty \sim \mathcal{N}(0, 1)$$

Total variation distance

$$\text{TV}(X_n, X_\infty) \leq \frac{1}{2} \sqrt{\frac{\pi}{2}} \mathbb{E} [|X_n + \rho_n(X_n)|] + \sup_z \kappa_1^*(z)$$

Example: Gaussian target

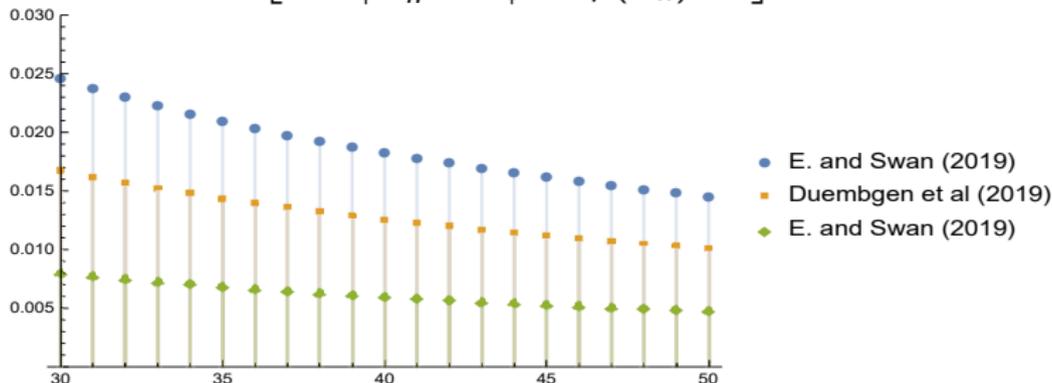
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Normal vs Student ($X_n \sim t_n$)

$$\text{TV}(X_n, X_\infty) \leq \mathbb{E} \left[|X_n| \left| \frac{X_n^2 - 1}{X_n^2 + n} \right| \frac{\Phi(X_n) \bar{\Phi}(X_n)}{\varphi(X_n)} \right] \leq \frac{2/\sqrt{e} - 1/2}{n - 1}$$



Example: Gaussian target

$$X_\infty \sim \mathcal{N}(0, 1)$$

Wasserstein distance

$$\text{Wass}(X_n, X_\infty) \leq \mathbb{E}[|\rho_n(X_n) + X_n|] + \sup_{h \in \text{Lip}(1)} |\kappa_1^*(h)|$$

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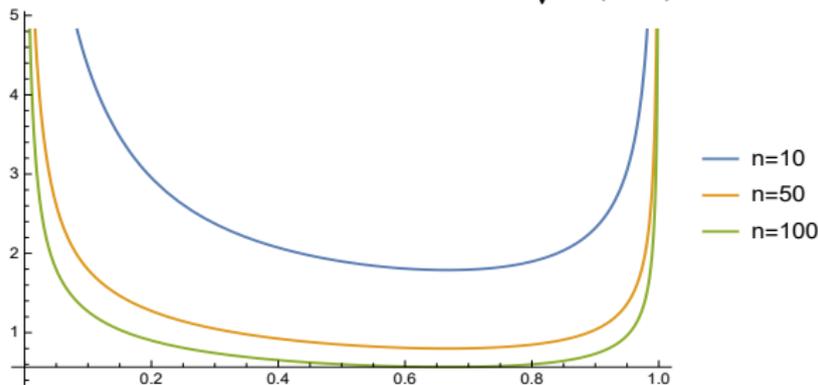
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Normal vs Binomial

If X_n is standardized binomial with parameters (n, θ) ,

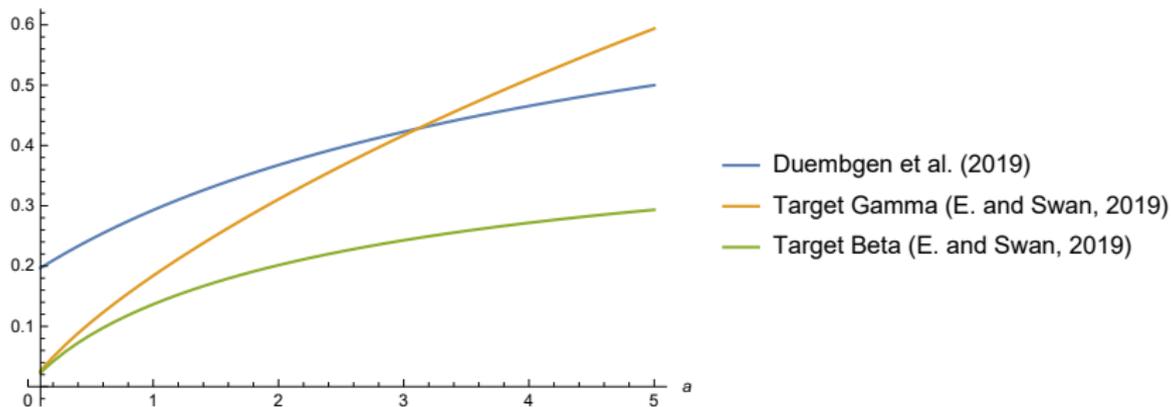
$$\text{Wass}(X_n, X_\infty) \leq 2\sqrt{\frac{1}{\theta} - 1} \frac{1}{\sqrt{n}} + \frac{2}{\sqrt{n\theta(1-\theta)}} + (1-\theta)^n$$



Example: Beta vs Gamma

TV between $\text{Beta}(a, 3)$ and $\text{Gamma}(a, a + 3)$

We can choose $X_\infty \sim \text{Beta}(a, 3)$ and $X_n \sim \text{Gamma}(a, a + 3)$ or the opposite.



Conclusion

Part 1: spatial data

- Ernst, M. and G. Haesbroeck (2017). Comparison of local outlier detection techniques in spatial multivariate data. *Data Mining and Knowledge Discovery* 31(2), 371–399.
- Ernst, M. and G. Haesbroeck. Robustness of tests for spatial autocorrelation.

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- Ernst, M. and G. Haesbroeck. Robustness of tests for spatial autocorrelation.

Part 2: Stein's method

- Ernst, M., G. Reinert, and Y. Swan (2019). First order covariance inequalities via Stein's method. *Bernoulli*. In press.
- Ernst, M., G. Reinert, and Y. Swan (2019). On infinite covariance expansions. arXiv:1906.08376.
- Ernst, M. and Y. Swan (2019). Distances between distributions via Stein's method. arXiv:1909.11518.

