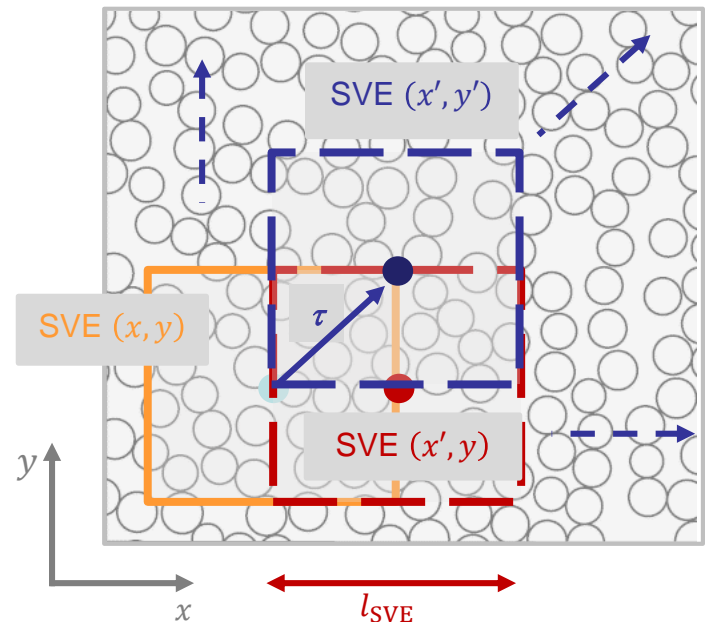
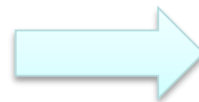
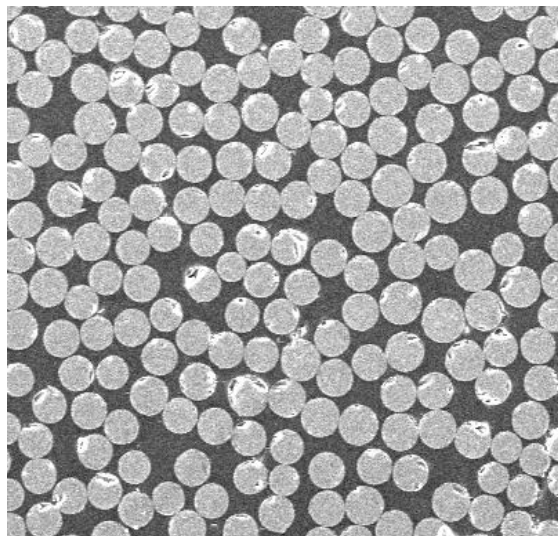


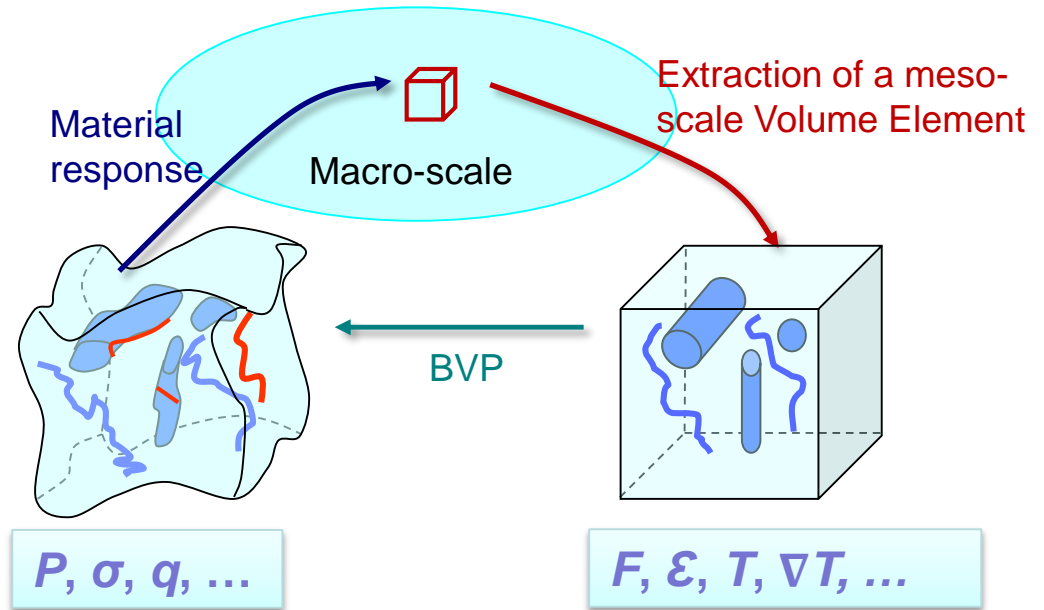
An inverse Mean-Field-Homogenization-based micro-mechanical model for stochastic multiscale simulations of unidirectional composites

L. Wu, J. M. Calleja, V.-D. Nguyen, L. Noels



Objectives

- Multi-scale modelling
 - 2 problems are solved concurrently
 - The macro-scale problem
 - The meso-scale problem (on a meso-scale Volume Element)
- Length-scales separation



$$L_{\text{macro}} \gg L_{\text{VE}} \gg L_{\text{micro}}$$

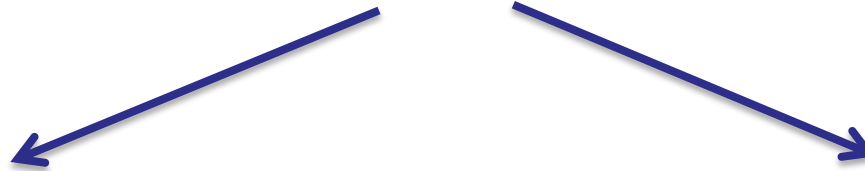
For accuracy: Size of the meso-scale volume element smaller than the characteristic length of the macro-scale loading

To be statistically representative: Size of the meso-scale volume element larger than the characteristic length of the micro-structure

Objectives

- Non-linear responses of composites
 - RVE size is too large
 - Structural response suffers from scatter
 - Requires the use of smaller VEs

$$L_{\text{macro}} \gg L_{\text{VE}} \sim L_{\text{micro}}$$



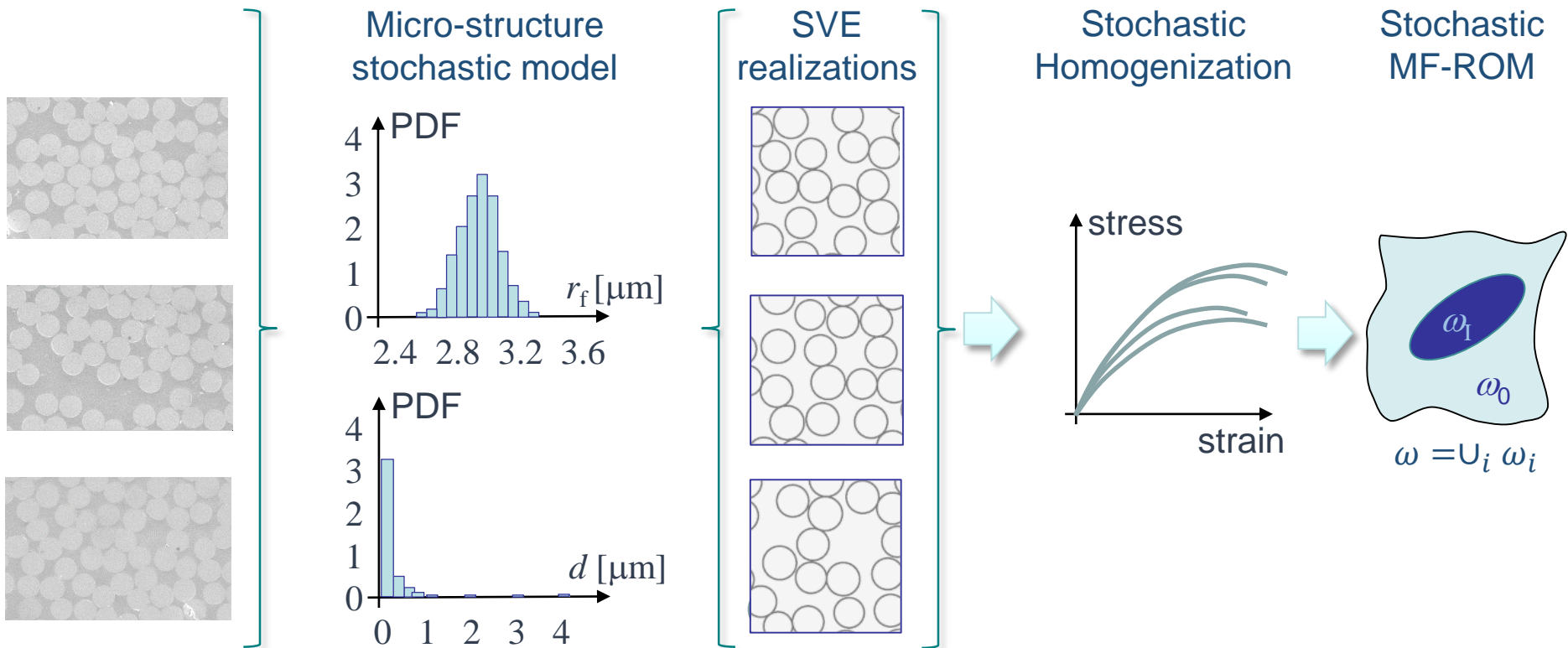
For accuracy: Size of the meso-scale volume element smaller than the characteristic length of the macro-scale loading

Meso-scale volume element no longer statistically representative: Stochastic Volume Elements

- Main objective
 - To develop an integrated stochastic multiscale approach to predict failure of composites

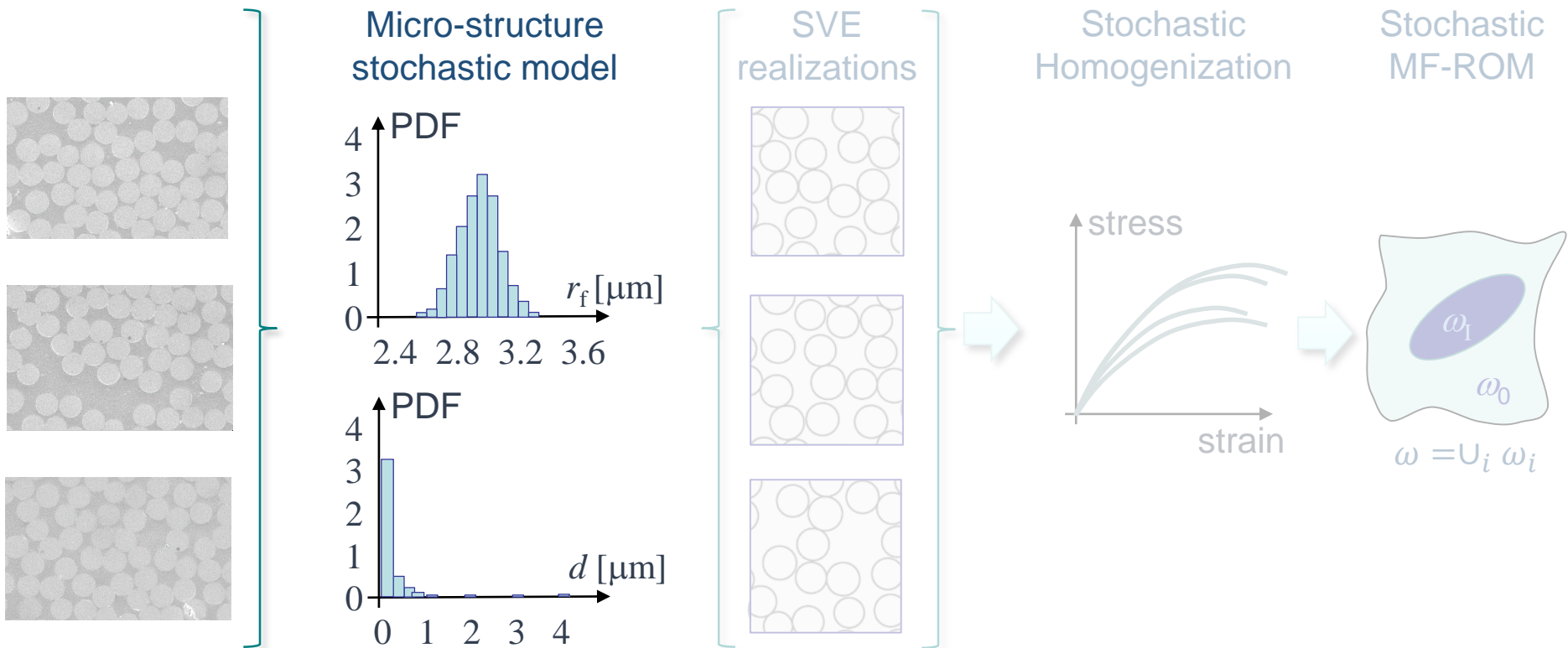
- Proposed methodology

- To develop a stochastic Mean Field Homogenization method able to predict the probabilistic distribution of material response at an intermediate scale from micro-structural constituents characterization



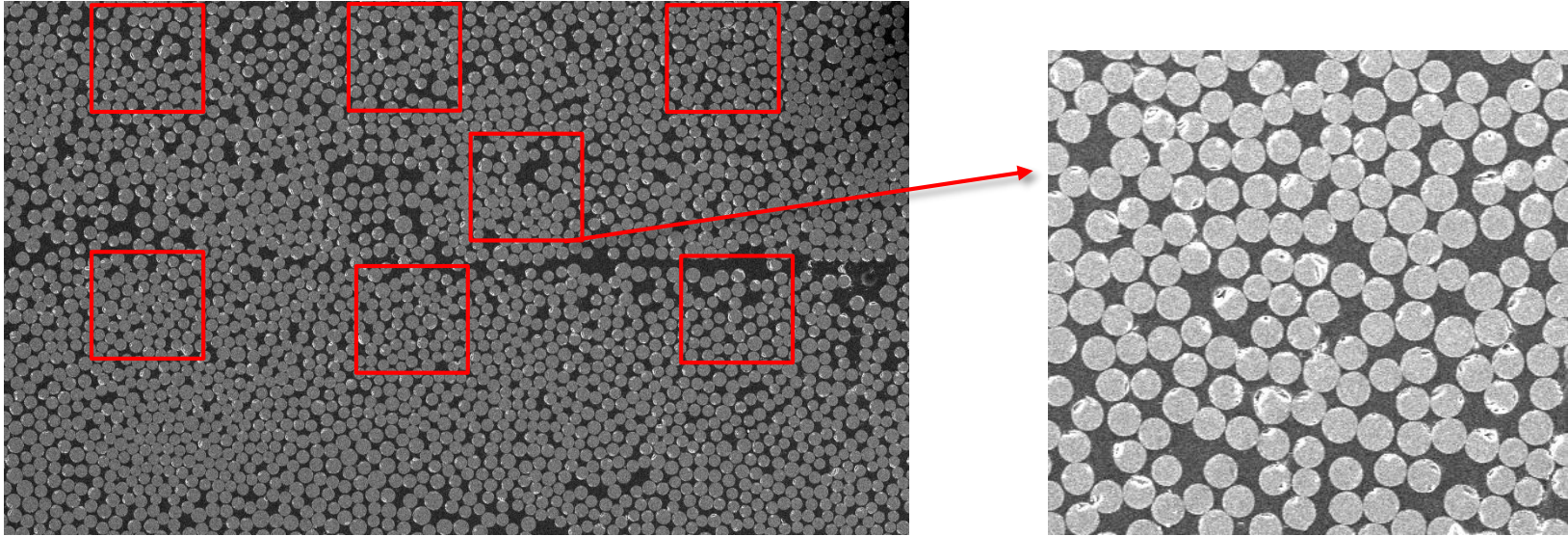
Methodology

- Uncertainty quantification of micro-structure & micro-structure generator

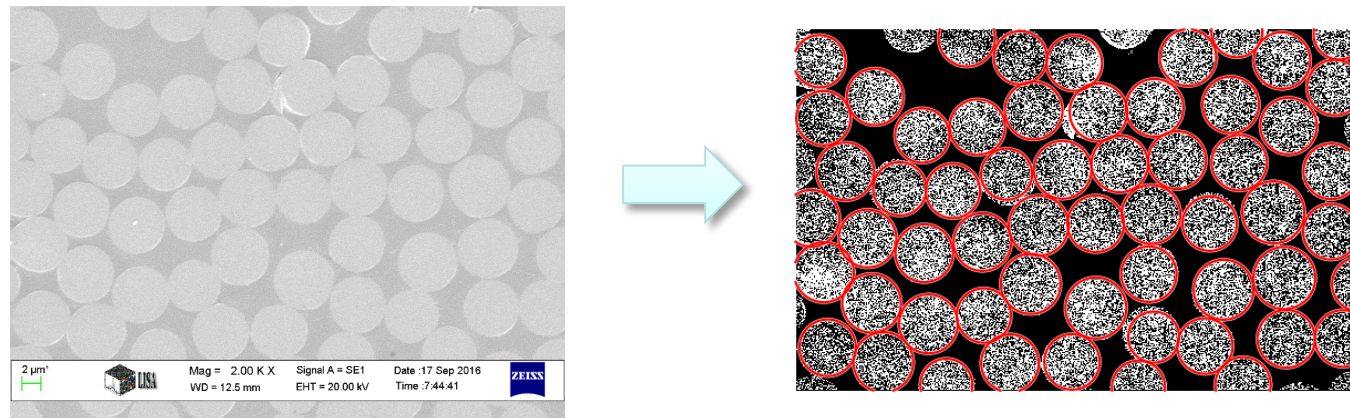


Experimental measurements

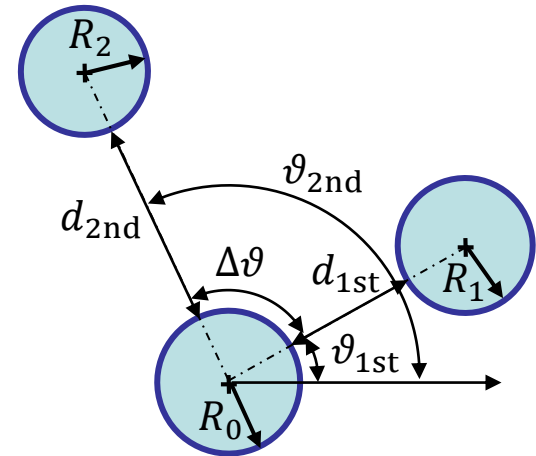
- 2000x and 3000x SEM images



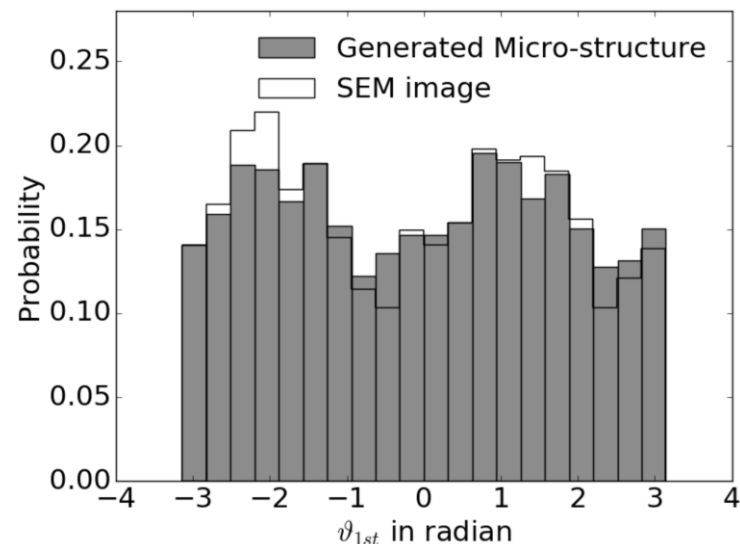
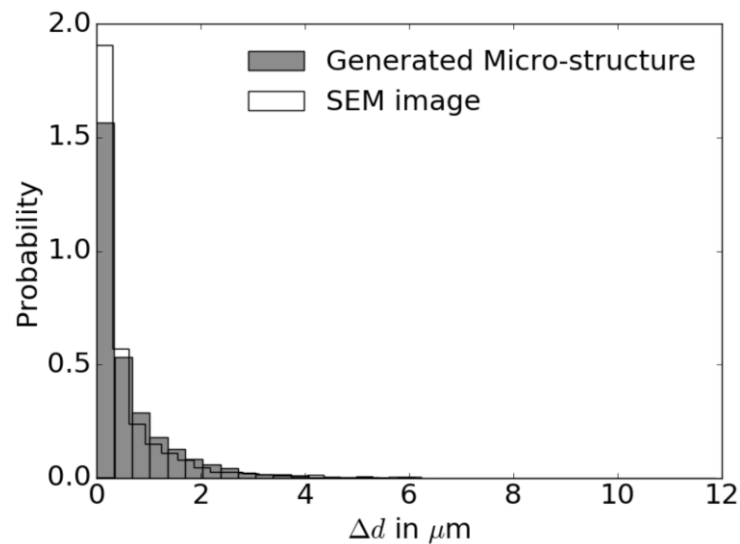
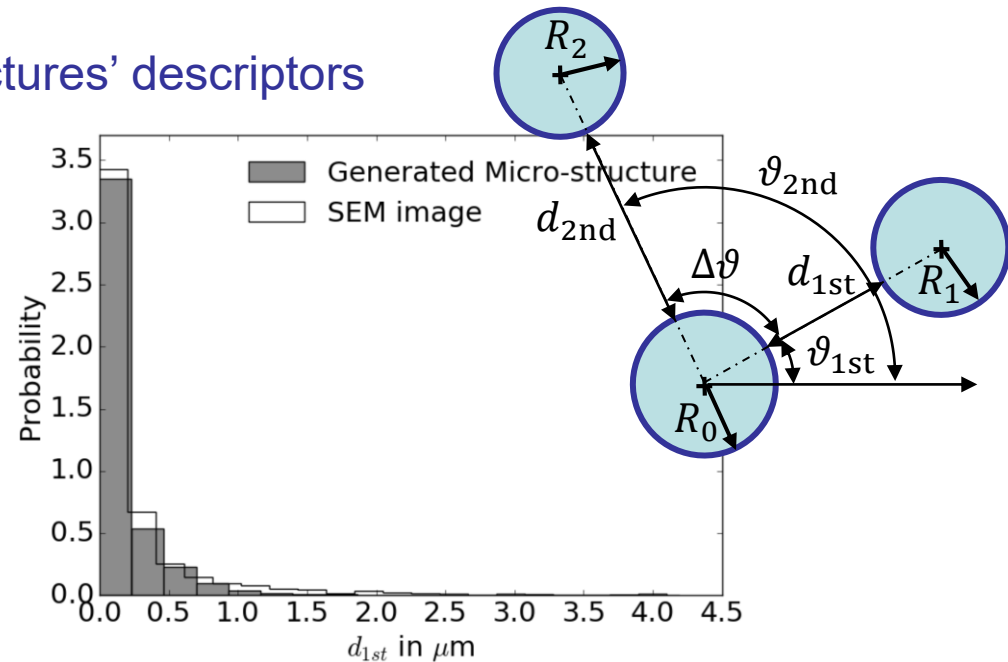
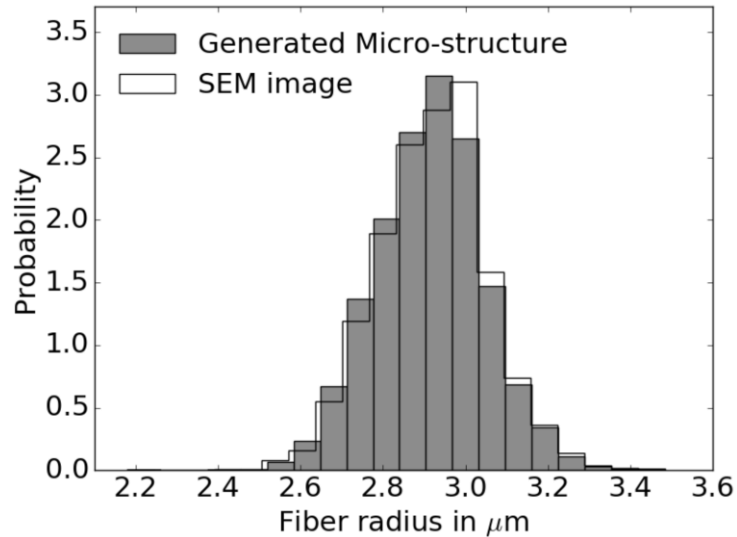
- Fibers detection



- Basic geometric information of fibers' cross sections
 - Fiber radius distribution $p_R(r)$
- Basic spatial information of fibers
 - The distribution of the nearest-neighbor net distance function $p_{d_{1st}}(d)$
 - The distribution of the orientation of the undirected line connecting the center points of a fiber to its nearest neighbor $p_{\vartheta_{1st}}(\theta)$
 - The distribution of the difference between the net distance to the second and the first nearest-neighbor $p_{\Delta d}(d)$ with $\Delta d = d_{2nd} - d_{1st}$
 - The distribution of the second nearest-neighbor's location referring to the first nearest-neighbor $p_{\Delta\vartheta}(\theta)$ with $\Delta\vartheta = \vartheta_{2nd} - \vartheta_{1st}$

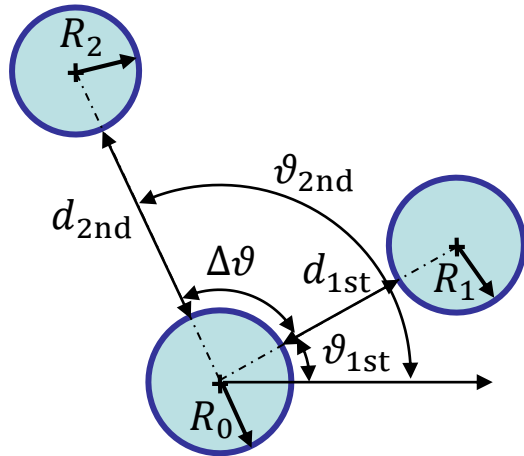


- Histograms of random micro-structures' descriptors



Micro-structure stochastic model

- Dependency of the four random variables $d_{1st}, \Delta d, \vartheta_{1st}, \Delta\vartheta$
- Correlation matrix



	d_{1st}	Δd	ϑ_{1st}	$\Delta\vartheta$
d_{1st}	1.0	0.21	0.01	0.02
Δd		1.0	0.002	-0.005
ϑ_{1st}			1.0	0.02
$\Delta\vartheta$				1.0

- Distances correlation matrix

d_{1st} and Δd are dependent
 → they will have to be generated from their empirical copula

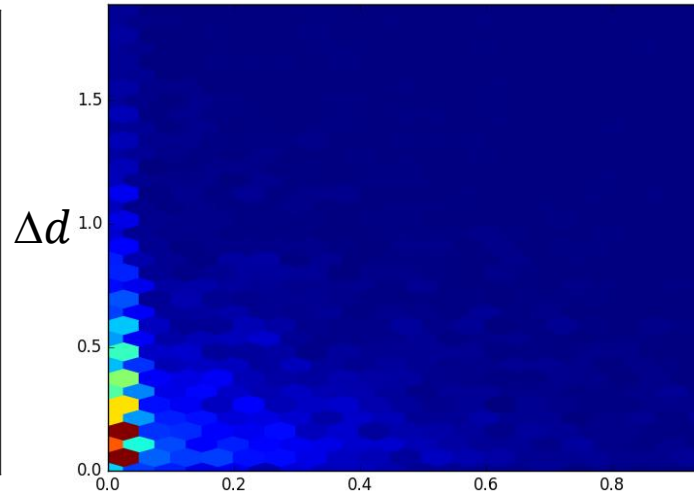
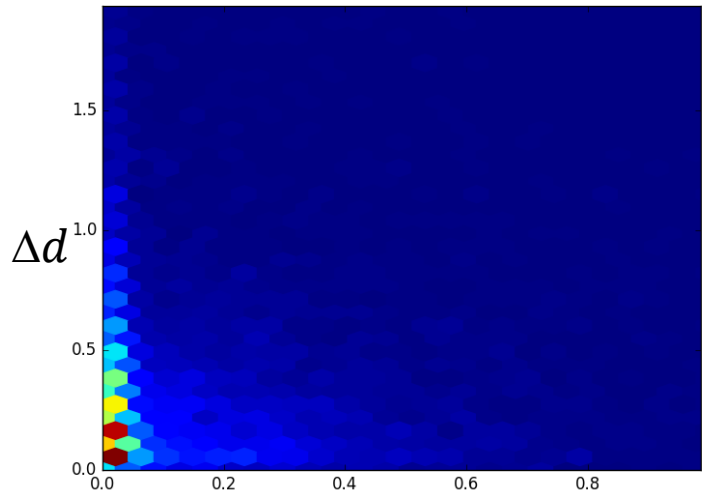
	d_{1st}	Δd	ϑ_{1st}	$\Delta\vartheta$
d_{1st}	1.0	0.27	0.04	0.08
Δd		1.0	0.05	0.06
ϑ_{1st}			1.0	0.05
$\Delta\vartheta$				1.0

Micro-structure stochastic model

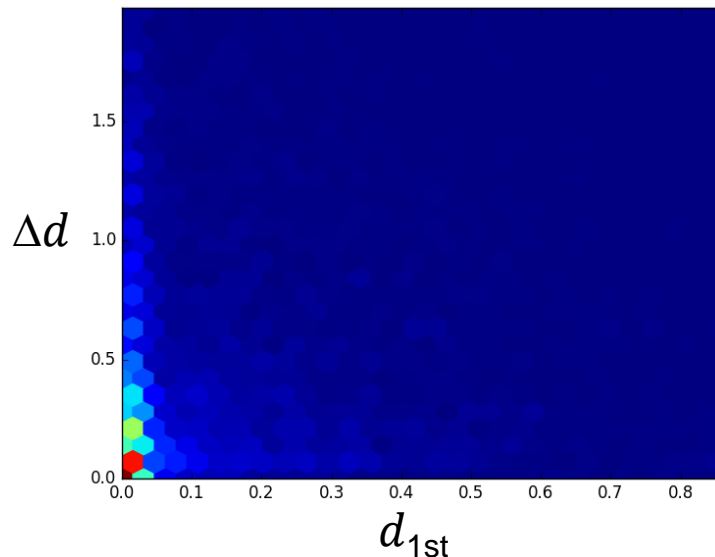
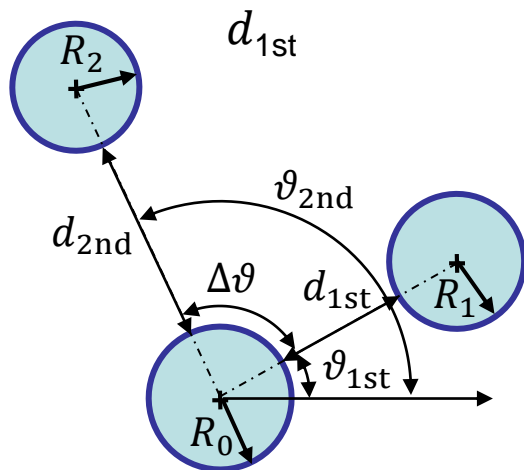
- d_{1st} and Δd should be generated using their empirical copula

SEM sample

Generated sample



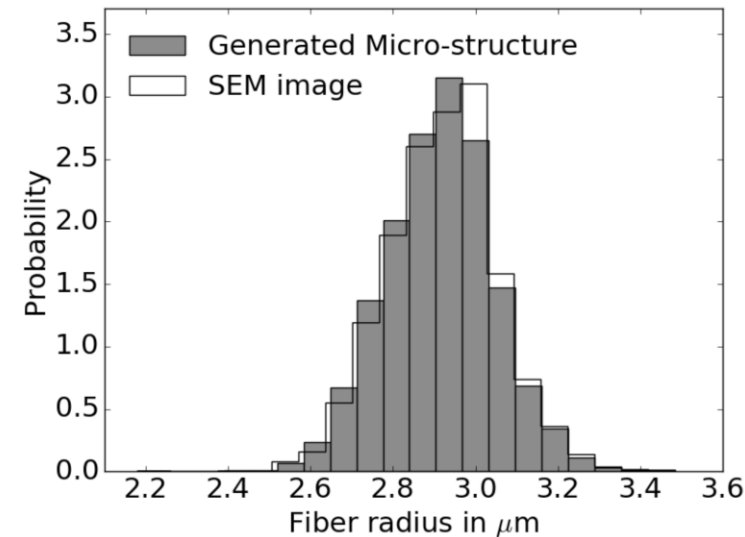
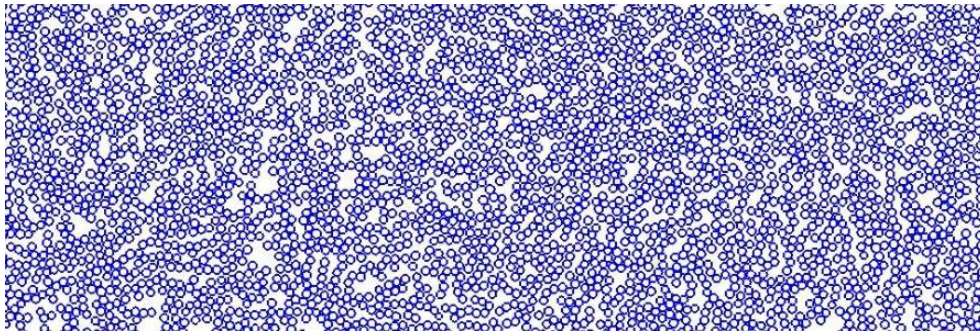
Directly from
copula generator



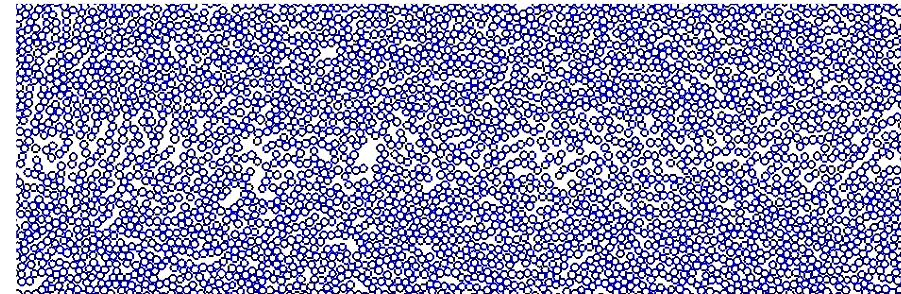
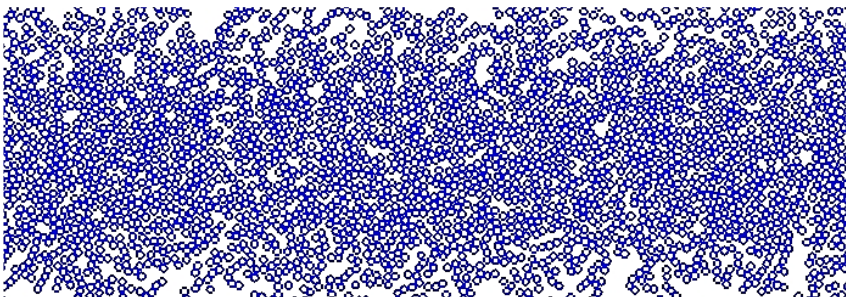
Statistic result from
generated SVE

Micro-structure stochastic model

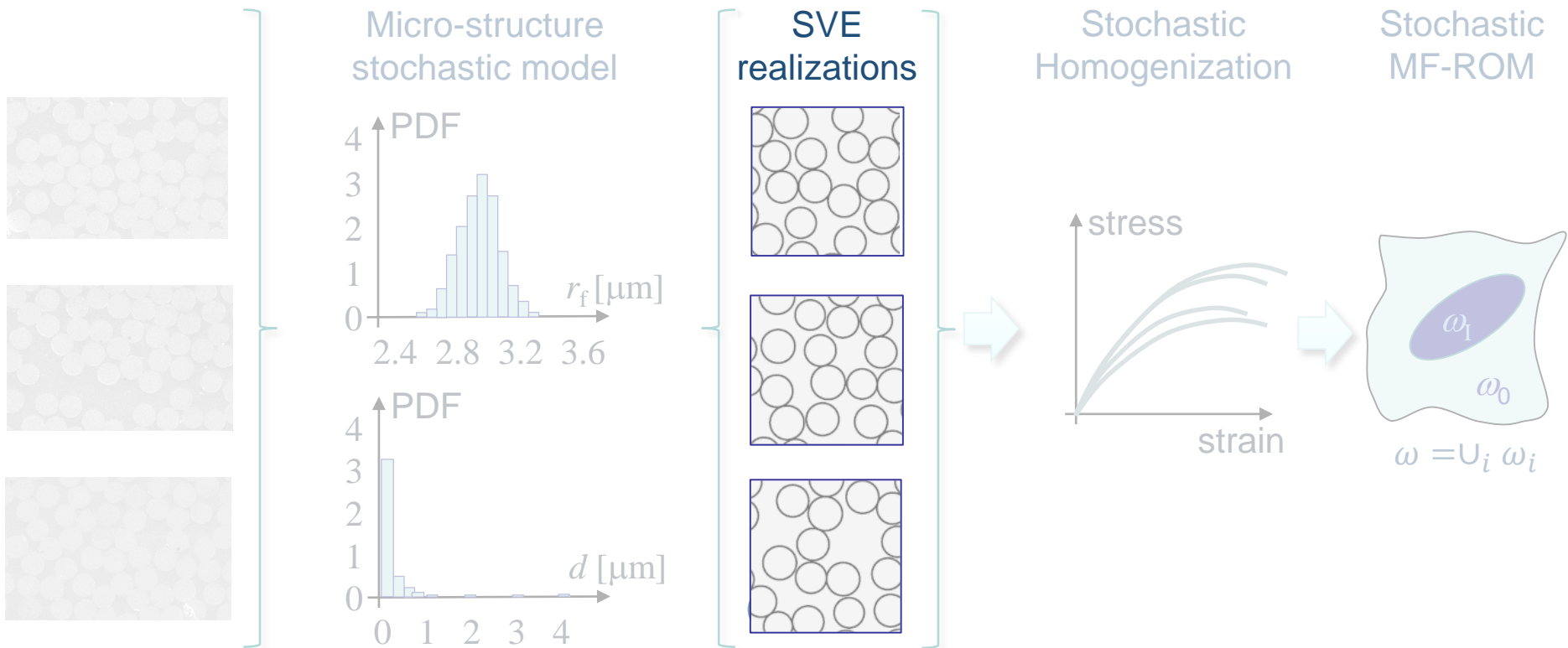
- Numerical micro-structures are generated by a fiber additive process
 - Arbitrary size
 - Arbitrary number



- Possibility to generate non-homogenous distributions



- SVEs definition



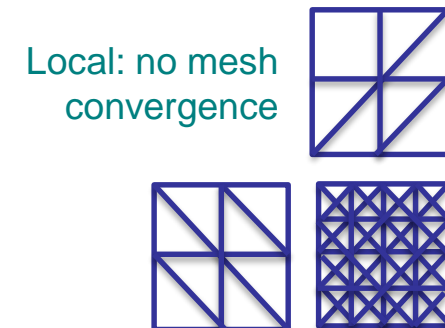
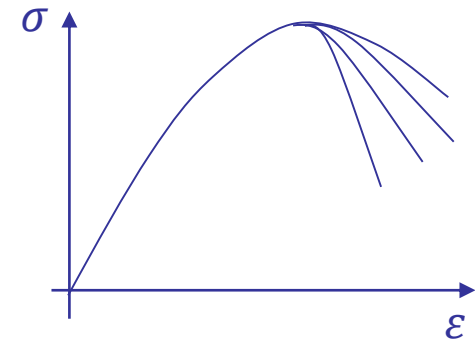
Micro-structural model of fiber-reinforced highly crosslinked epoxy

- UD Composites with RTM6 epoxy matrix

- Identified matrix material behaviour
 - Hyperelastic viscoelastic-viscoplastic constitutive model enhanced by a multi-mechanism nonlocal damage model
- To be used in micro-structural analysis
 - Behaviour in composite is different
 - Introduce a length-scale effect

- Resin model implementation:

- Requires non-local form [Bažant 1988]
 - Introduction of characteristic length l_c
 - Weighted average: $\tilde{Z}(\mathbf{x}) = \int_{V_c} W(\mathbf{y}; \mathbf{x}, l_c) Z(\mathbf{y}) d\mathbf{y}$
- Implicit form [Peerlings et al. 1998]
 - New degrees of freedom: \tilde{Z}
 - New Helmholtz-type equations: $\tilde{Z} - l_c^2 \Delta \tilde{Z} = Z$
- Has a length scale effect



Micro-structural model of fiber-reinforced highly crosslinked epoxy

- Resin model

- Material changes represented via internal variables

- Constitutive law $\mathbf{P}(\mathbf{F}; \mathbf{Z}(t'))$

- Internal variables $\mathbf{Z}(t')$

- Multi-damage strategy

$$\mathbf{P} = (\mathbf{1} - D_s)(\mathbf{1} - D_f)\hat{\mathbf{P}}$$

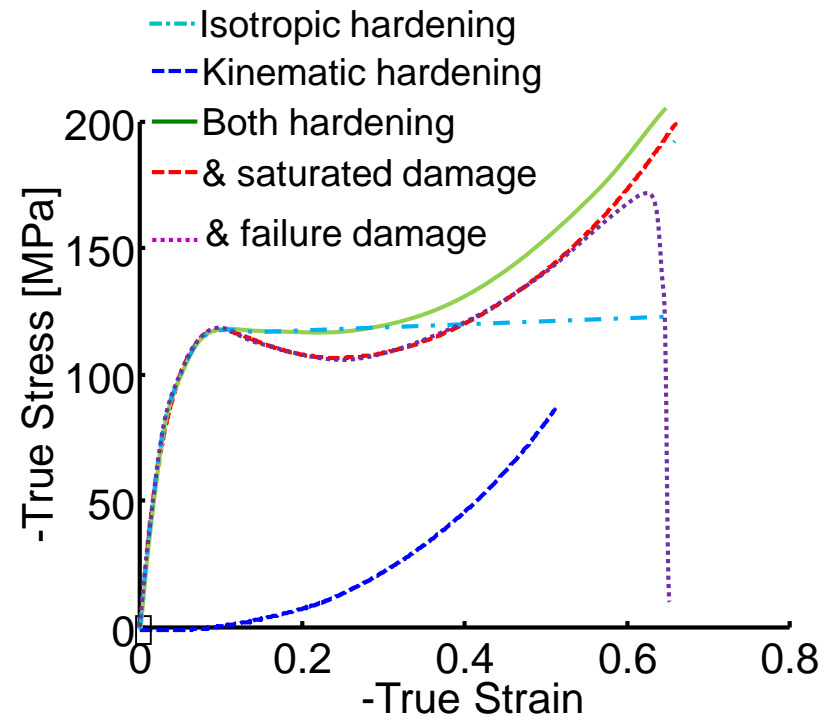
- Non-local damage evolution laws

- Saturation law

$$\left\{ \begin{array}{l} \dot{D}_s = D_s(D_s, \mathbf{F}(t), \chi_s(t); \mathbf{Z}(\tau), \tau \in [0 t]) \dot{\chi}_s \\ \chi_s(t) = \max_{\tau} (\tilde{\gamma}_s(\tau)) \\ \tilde{\gamma}_s - l_s^2 \Delta \tilde{\gamma}_s = \gamma_s \end{array} \right.$$

- Failure law

$$\left\{ \begin{array}{l} \dot{D}_f = D_f(D_f, \mathbf{F}(t), \chi_f(t); \mathbf{Z}(\tau), \tau \in [0 t]) \dot{\chi}_f \\ \chi_f(t) = \max_{\tau} (\tilde{\gamma}_f(\tau)) \\ \tilde{\gamma}_f - l_f^2 \Delta \tilde{\gamma}_f = \gamma_f \end{array} \right.$$



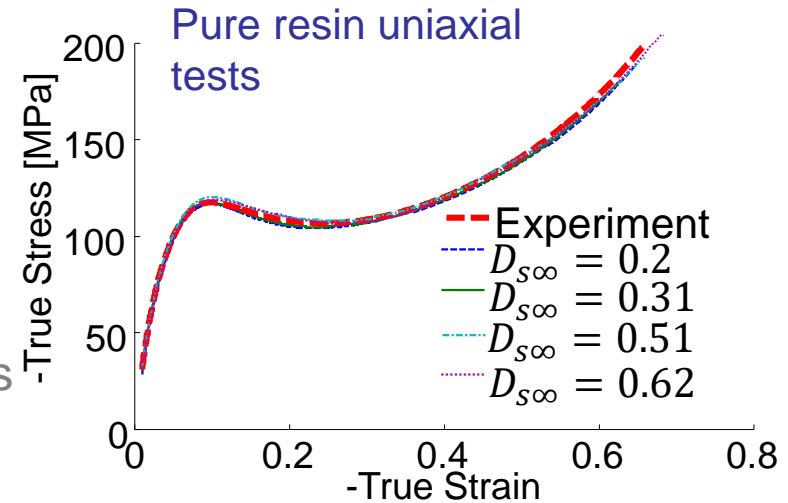
Micro-structural model of fiber-reinforced highly crosslinked epoxy

- Resin model: saturated softening

- Saturated damage evolution

$$\left\{ \begin{array}{l} \dot{D}_s = H_s (\chi_s - \chi_{s0})^{\zeta_s} (D_{s\infty} - D_s) \dot{\chi}_s \\ \chi_s = \max_{\tau} (\chi_{s0}, \tilde{\gamma}_s(\tau)) \\ \tilde{\gamma}_s - l_s^2 \Delta \tilde{\gamma}_s = \gamma \end{array} \right.$$

- Several hardening/softening combinations
 - Requires composite material tests



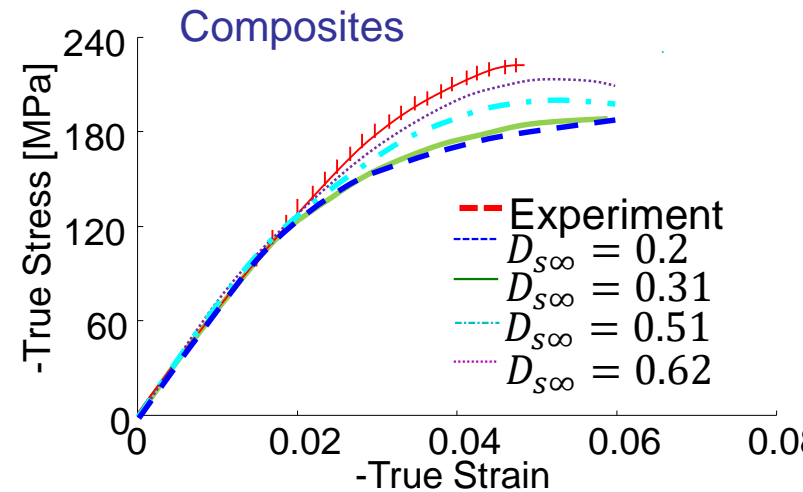
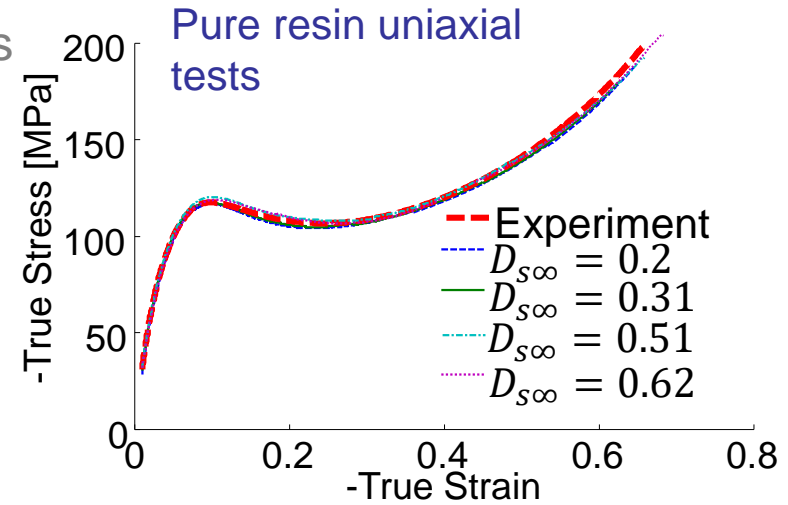
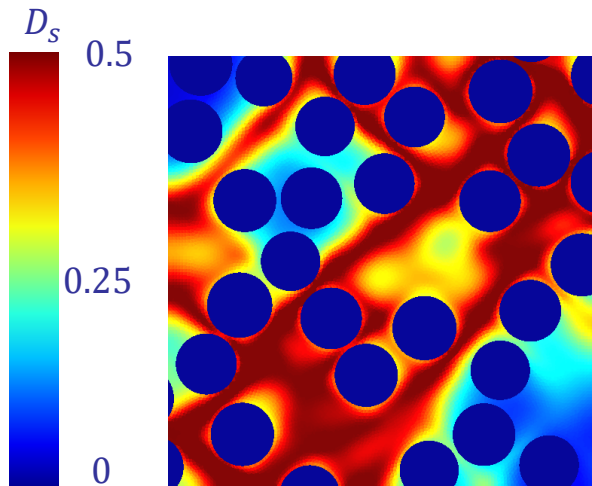
Micro-structural model of fiber-reinforced highly crosslinked epoxy

- Resin model: saturated softening
 - Several hardening/softening combinations
 - Requires composite material tests
 - Length scale effect

$$l_s = 3\mu\text{m} \left(1 - \frac{D_s}{D_{s\infty}} \right)$$

- Non-local BC at fibre interface

$$[[\dot{\gamma}_s]] = 0$$



Micro-structural model of fiber-reinforced highly crosslinked epoxy

- Resin model: failure softening

- Failure surface

$$\left\{ \begin{array}{l} \phi_f = \gamma - a \exp\left(-b \frac{\text{tr}(\hat{\tau})}{3\hat{\tau}^{eq}}\right) - c \\ \phi_f - r \leq 0; \dot{r} \geq 0; \text{ and } \dot{r}(\phi_f - r) = 0 \\ \dot{\gamma}_f = \dot{r} \end{array} \right.$$

- Damage evolution

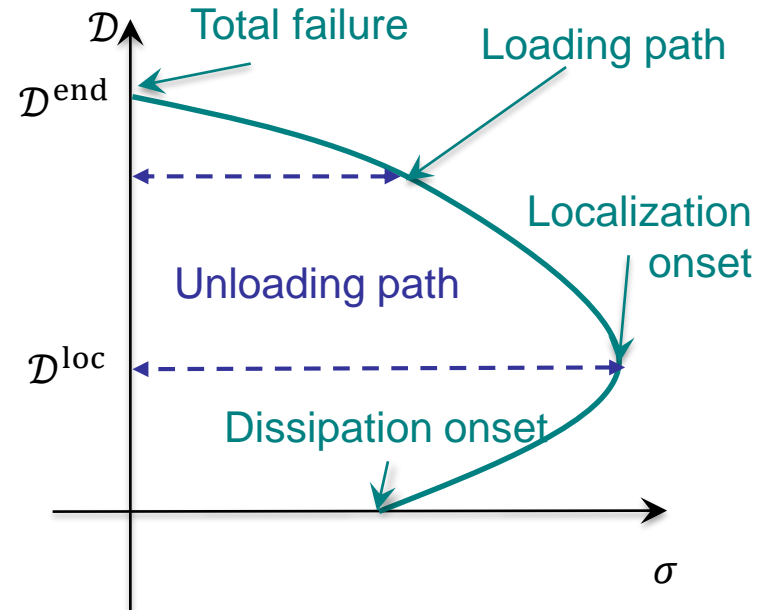
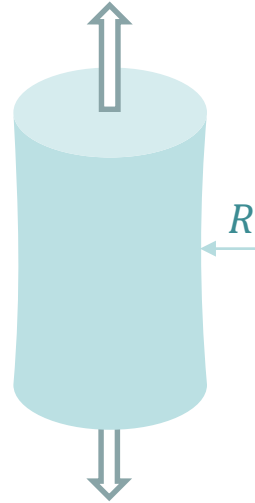
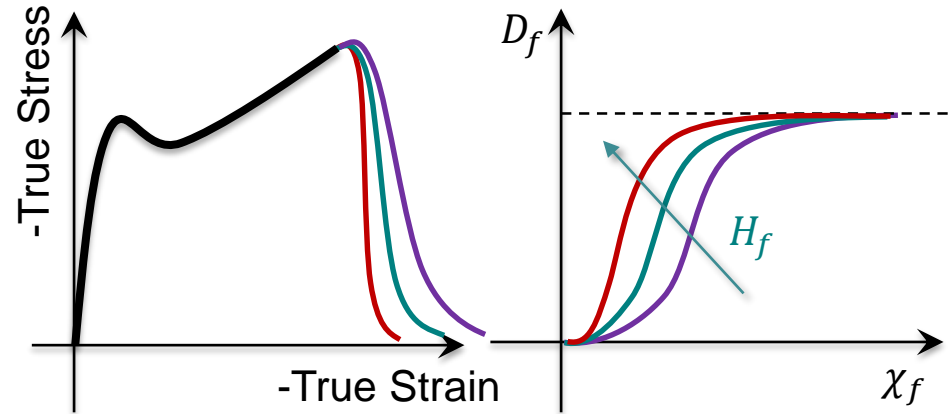
$$\left\{ \begin{array}{l} \dot{D}_f = H_f(\chi_f)^{\zeta_f} (1 - D_f)^{-\zeta_a} \dot{\chi}_f \\ \chi_f = \max_{\tau} (\tilde{\gamma}_f(\tau)) \\ \tilde{\gamma}_f - l_f^2 \Delta \tilde{\gamma}_f = \gamma_f \\ l_f = 3 \mu\text{m} \quad \nabla_0 \tilde{\gamma}_f \cdot \mathbf{N} = 0 \end{array} \right.$$

- Affect ductility

- Calibration

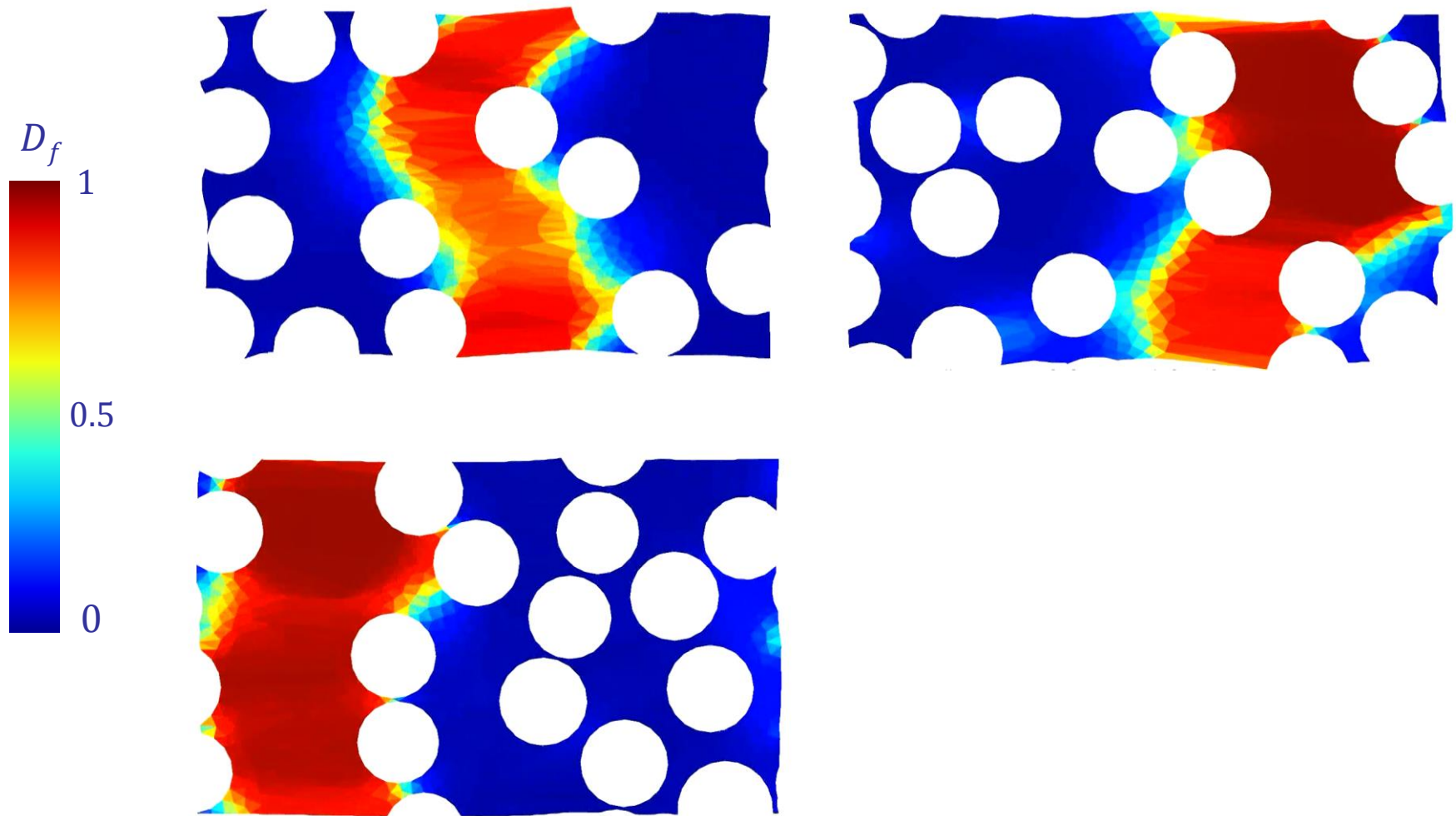
- From localization simulation
 - Recover the epoxy G_c

$$G_c = \frac{\mathcal{D}^{\text{end}} - \mathcal{D}^{\text{loc}}}{A_0}$$

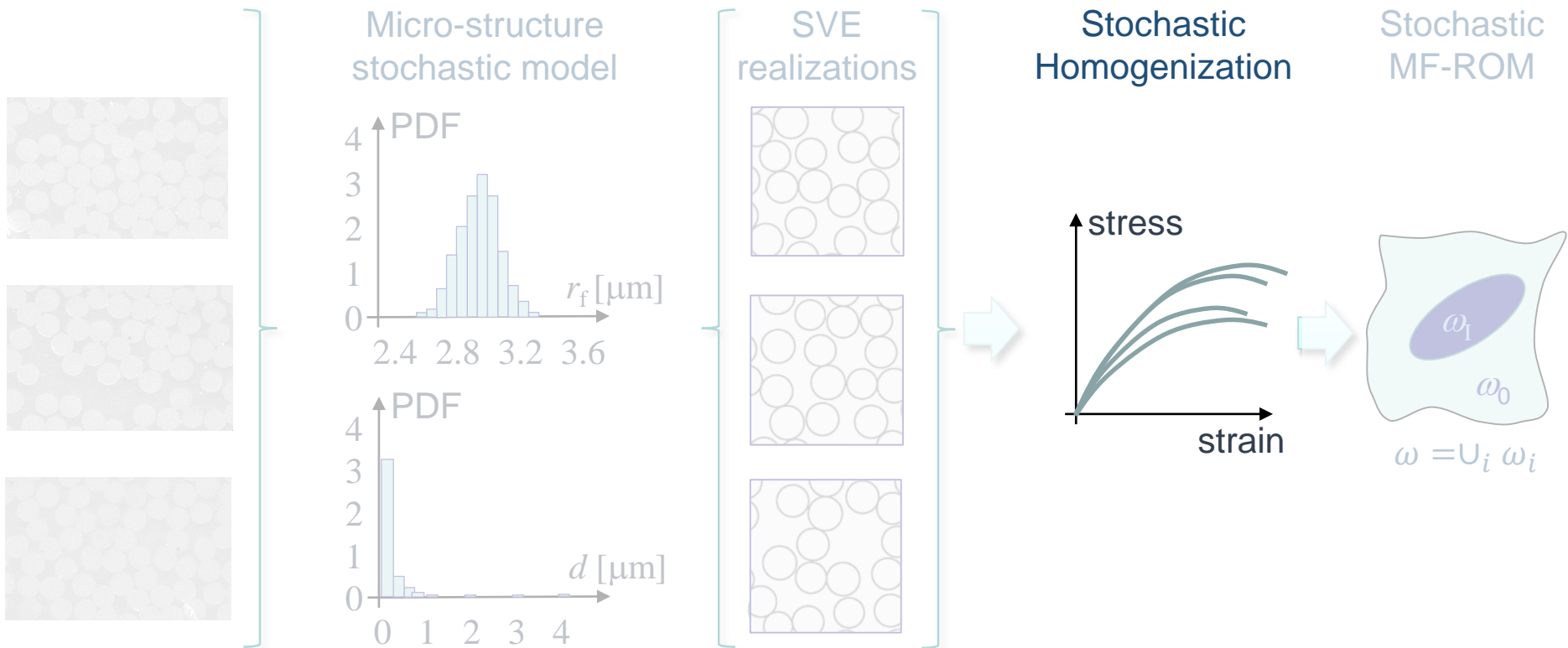


Micro-structural model of fiber-reinforced highly crosslinked epoxy

- UD Composites with RTM6 epoxy matrix
 - 2D simulations of 25 x 25 μm 40% volume fraction composite SVEs



- Extraction of apparent responses



- Window technique

- Extraction of Stochastic Volume Elements

- $l_{SVE} = 25 \mu m$
- Correlation

$$R_{rs}(\tau) = \frac{\mathbb{E}[(r(\mathbf{x}) - \mathbb{E}(r))(s(\mathbf{x} + \boldsymbol{\tau}) - \mathbb{E}(s))]}{\sqrt{\mathbb{E}[(r - \mathbb{E}(r))^2]} \sqrt{\mathbb{E}[(s - \mathbb{E}(s))^2]}}$$

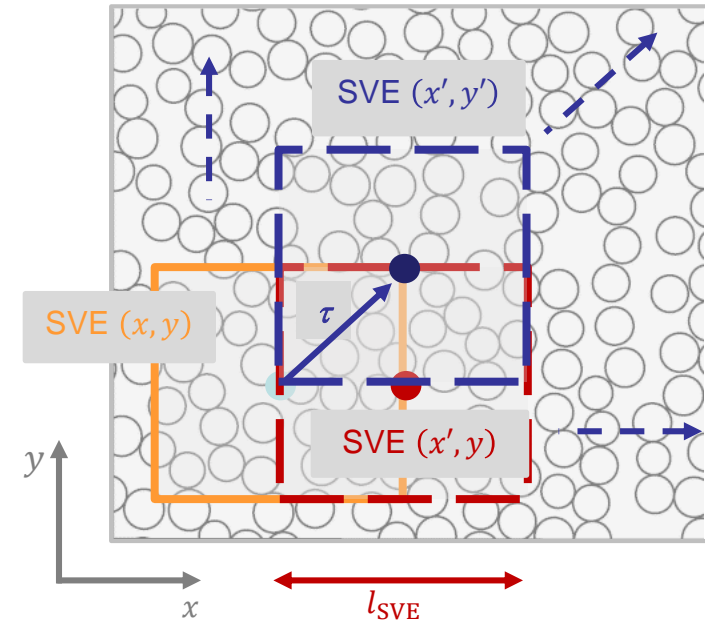
- For each SVE

- Extract apparent homogenized material tensor \mathbb{C}_M

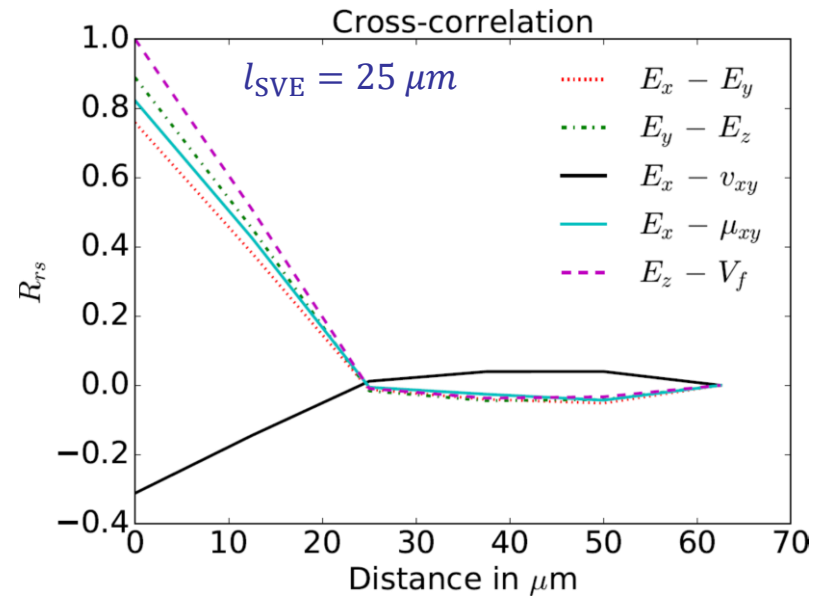
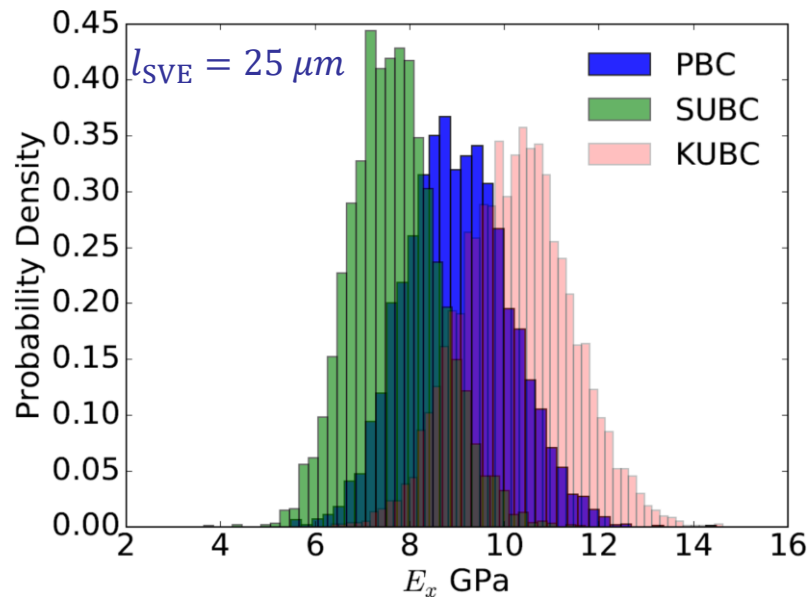
$$\begin{cases} \boldsymbol{\varepsilon}_M = \frac{1}{V(\omega)} \int_{\omega} \boldsymbol{\varepsilon}_m d\omega \\ \boldsymbol{\sigma}_M = \frac{1}{V(\omega)} \int_{\omega} \boldsymbol{\sigma}_m d\omega \\ \mathbb{C}_M = \frac{\partial \boldsymbol{\sigma}_M}{\partial \mathbf{u}_M \otimes \nabla_M} \end{cases}$$

- Consistent boundary conditions:

- Periodic (PBC)
- Minimum kinematics (SUBC)
- Kinematic (KUBC)



- Apparent elastic properties: distribution & Correlation



- For large enough RVE ($l_{SVE} > 10 \mu m$)

Auto/cross correlation vanishes at $\tau = l_{SVE}$

Distributions get closer to normal



Apparent properties of different SVEs are independent

However the distributions depend on

- l_{SVE}
- The boundary conditions

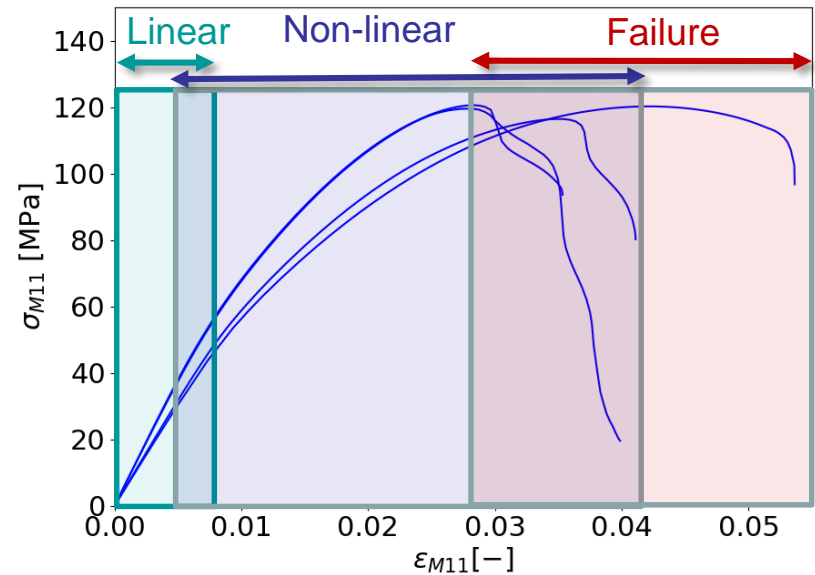
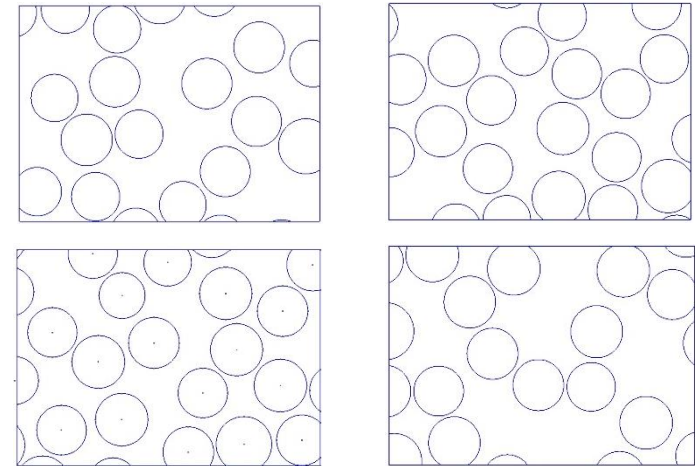
Stochastic homogenization on the SVEs

- Apparent response
 - Independent Stochastic Volume Elements
 - $l_{SVE} = 25 \mu m$
 - Stochastic homogenization
 - Extract apparent responses

$$\left\{ \begin{array}{l} \boldsymbol{\varepsilon}_M = \frac{1}{V(\omega)} \int_{\omega} \boldsymbol{\varepsilon}_m d\omega \\ \boldsymbol{\sigma}_M = \frac{1}{V(\omega)} \int_{\omega} \boldsymbol{\sigma}_m d\omega \\ \mathbb{C}_M = \frac{\partial \boldsymbol{\sigma}_M}{\partial \mathbf{u}_M \otimes \nabla_M} \end{array} \right.$$

- 3 stages
 - Linear response
 - (Damage-enhanced) elasto-plasticity
 - Failure (loss of size objectivity)

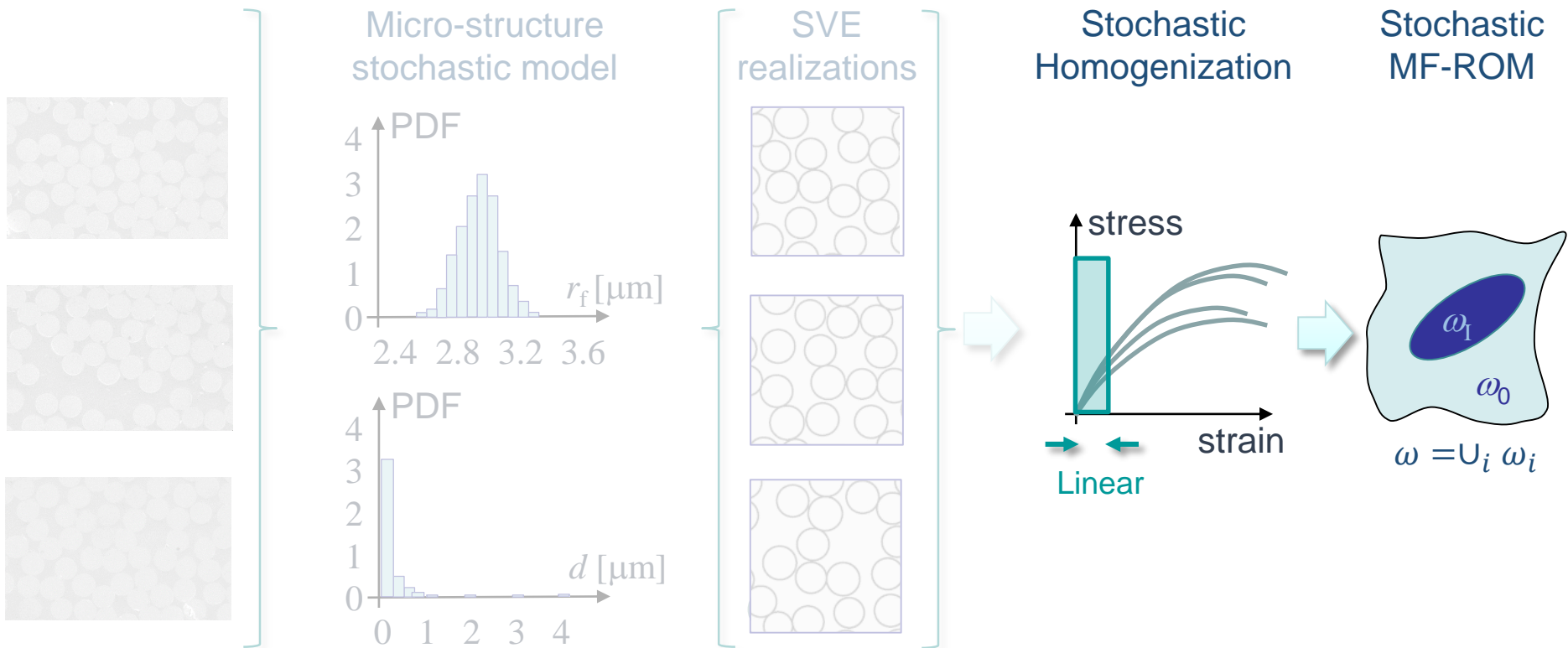
SVE realizations



Stochastic Homogenization

Methodology

- Stochastic Mean-Field Homogenization-based model
 - First stage: linear elasticity



Stochastic Mean-Field Homogenization

- Mean-Field-Homogenization (MFH)

- Linear composites

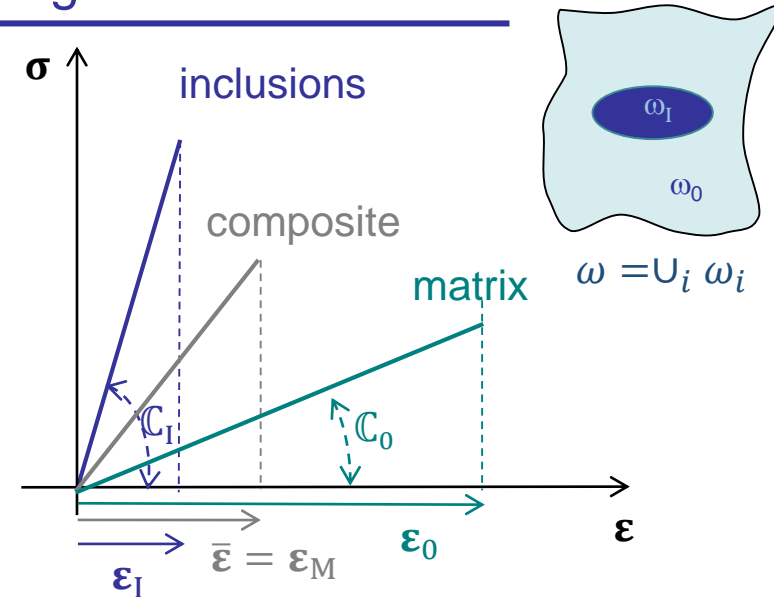
$$\left\{ \begin{array}{l} \sigma_M = \bar{\sigma} = \nu_0 \sigma_0 + \nu_1 \sigma_1 \\ \epsilon_M = \bar{\epsilon} = \nu_0 \epsilon_0 + \nu_1 \epsilon_1 \\ \epsilon_1 = \mathbb{B}^\epsilon(I, C_0, C_1) : \epsilon_0 \end{array} \right.$$

→ $C_M = C_M(I, C_0, C_1, \nu_1)$

- We use Mori-Tanaka assumption for $\mathbb{B}^\epsilon(I, C_0, C_1)$

- Stochastic MFH

- How to define randomness?



Stochastic Mean-Field Homogenization

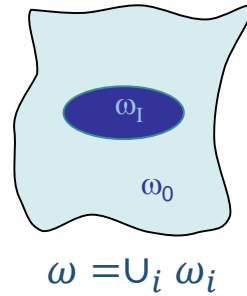
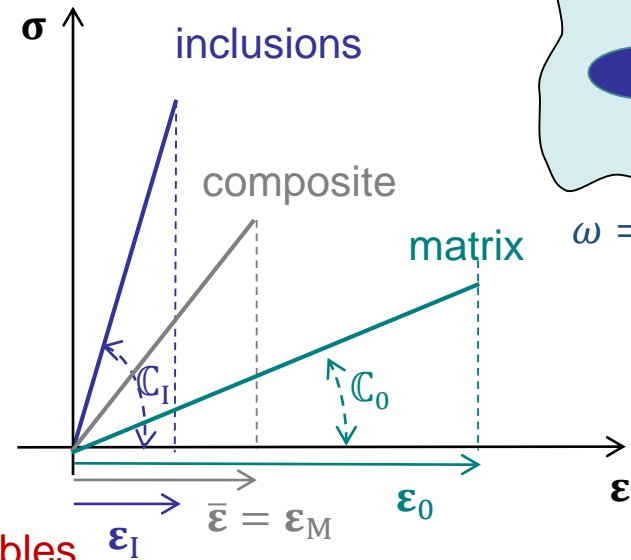
- Mean-Field-Homogenization (MFH)

- Linear composites

$$\left\{ \begin{array}{l} \sigma_M = \bar{\sigma} = v_0 \sigma_0 + v_1 \sigma_1 \\ \varepsilon_M = \bar{\varepsilon} = v_0 \varepsilon_0 + v_1 \varepsilon_1 \\ \varepsilon_1 = \mathbb{B}^\varepsilon(I, C_0, C_I) : \varepsilon_0 \end{array} \right.$$

→ $\hat{C}_M = \hat{C}_M(I, C_0, C_I, v_I)$

Defined as random variables



- Consider an equivalent system

- For each SVE realization i :

→ C_M and v_I known

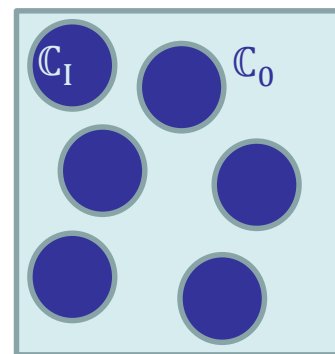
- Anisotropy from C_M^i

→ θ is evaluated

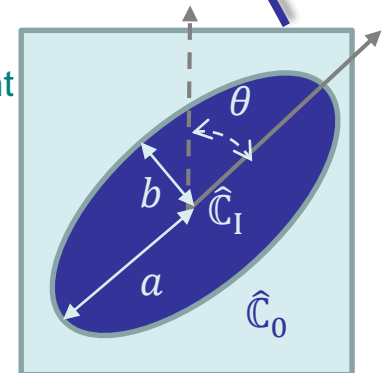
- Fiber behavior uniform

→ \hat{C}_I for one SVE

$$C_M \approx \hat{C}_M(\hat{I}, \hat{C}_0, \hat{C}_I, v_I, \theta)$$



Equivalent inclusion

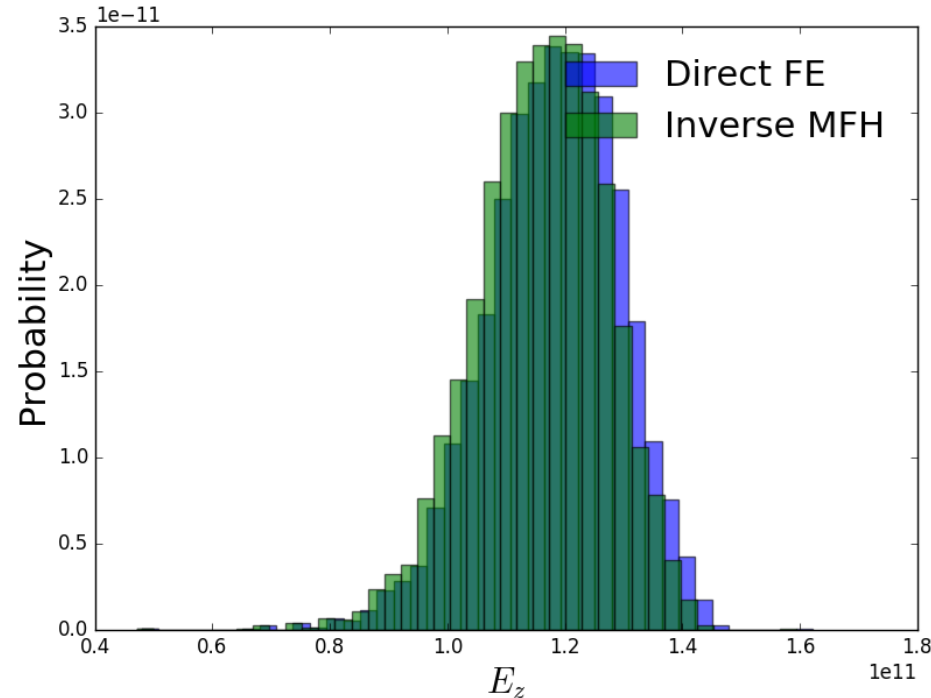
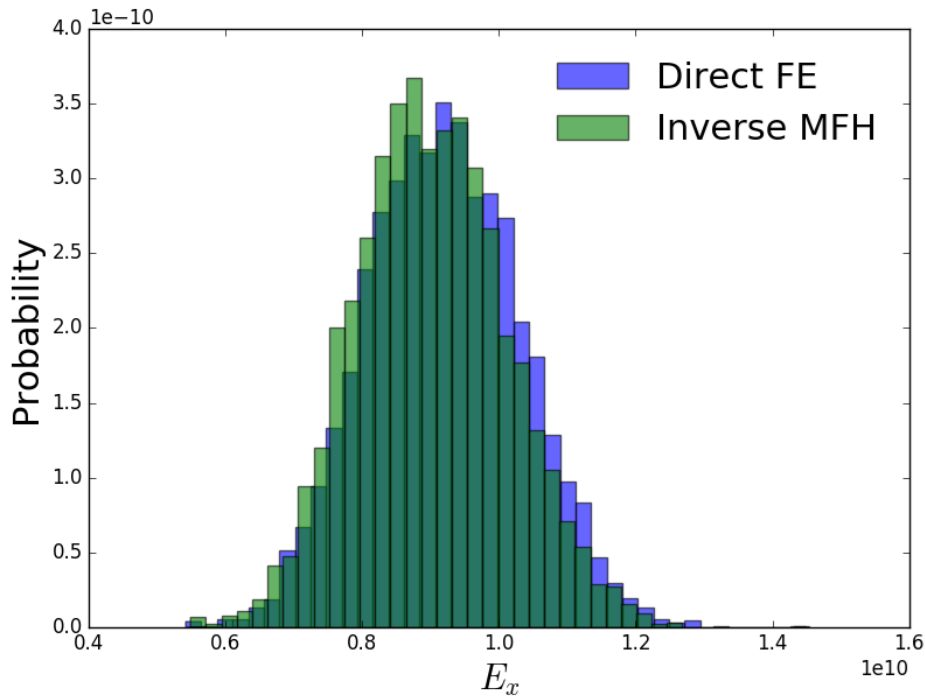
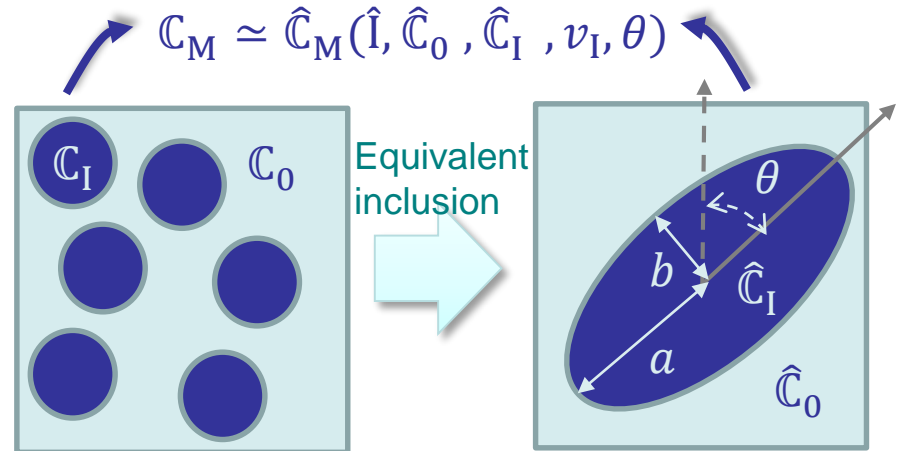


- Remaining optimization problem: $\min_{\frac{a}{b}, \hat{E}_0, \hat{\nu}_0} \left\| C_M - \hat{C}_M\left(\frac{a}{b}, \hat{E}_0, \hat{\nu}_0; v_I, \theta, \hat{C}_I\right) \right\|$

Stochastic Mean-Field Homogenization

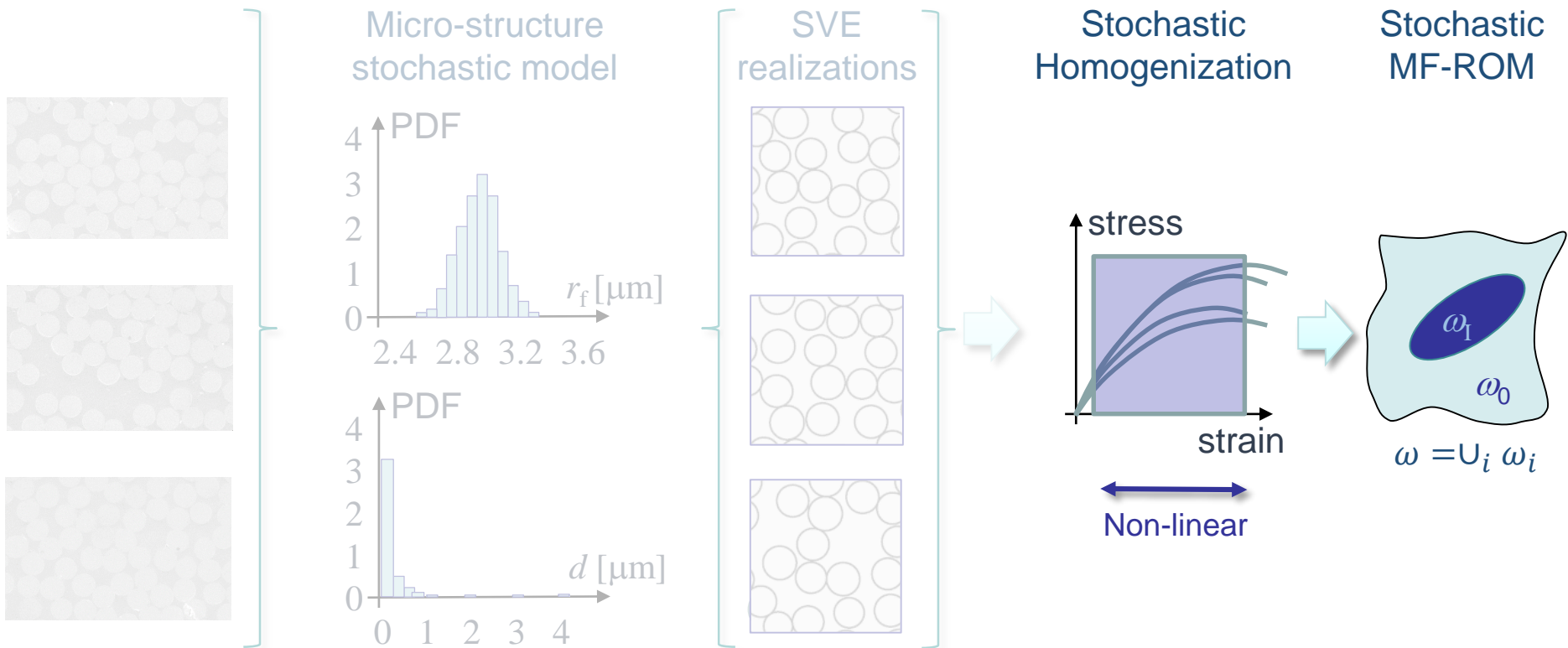
- Inverse stochastic identification

- Comparison of homogenized properties from SVE realizations and stochastic MFH



Methodology

- Stochastic Mean-Field Homogenization-based model
 - Second stage: damage-enhanced elasto-plasticity



Non-linear stochastic Mean-Field Homogenization

- Non-linear Mean-Field-homogenization

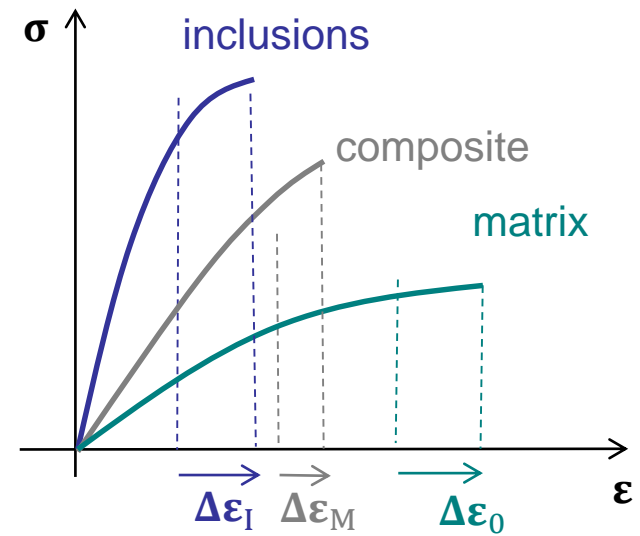
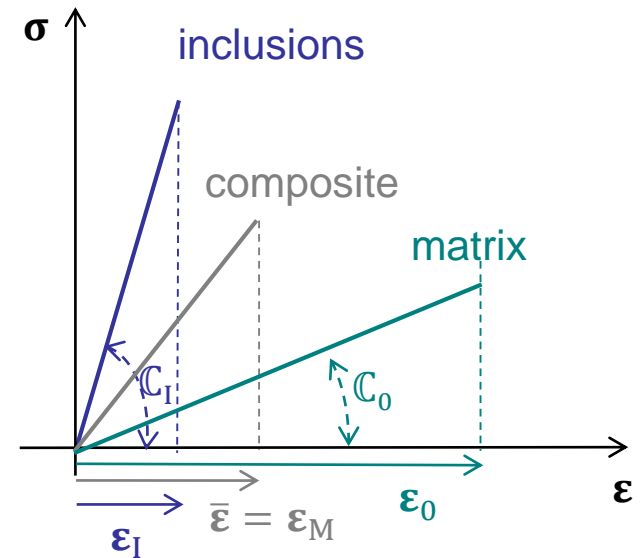
- Linear composites

$$\left\{ \begin{array}{l} \sigma_M = \bar{\sigma} = v_0 \sigma_0 + v_I \sigma_I \\ \varepsilon_M = \bar{\varepsilon} = v_0 \varepsilon_0 + v_I \varepsilon_I \\ \varepsilon_I = \mathbb{B}^\varepsilon(I, C_0, C_I) : \varepsilon_0 \end{array} \right.$$

- Non-linear composites

$$\left\{ \begin{array}{l} \sigma_M = \bar{\sigma} = v_0 \sigma_0 + v_I \sigma_I \\ \Delta \varepsilon_M = \bar{\Delta \varepsilon} = v_0 \Delta \varepsilon_0 + v_I \Delta \varepsilon_I \\ \Delta \varepsilon_I = \mathbb{B}^\varepsilon(I, C_0^{LCC}, C_I^{LCC}) : \Delta \varepsilon_0 \end{array} \right.$$

Define a linear comparison composite material



Non-linear stochastic Mean-Field Homogenization

- View to damage Mean-Field-homogenization

- Incremental forms

- Strain increments in the same direction

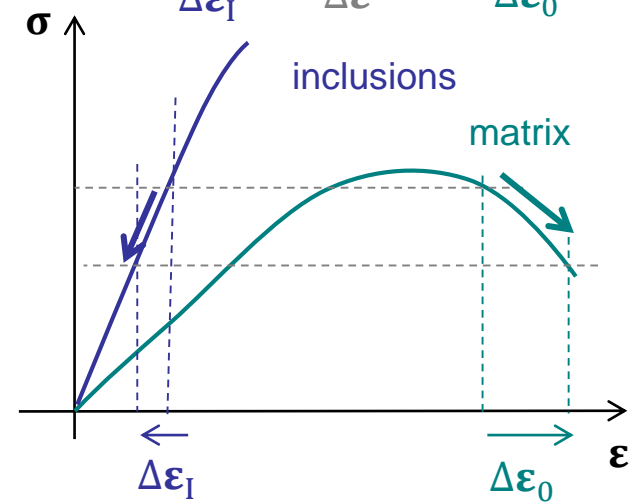
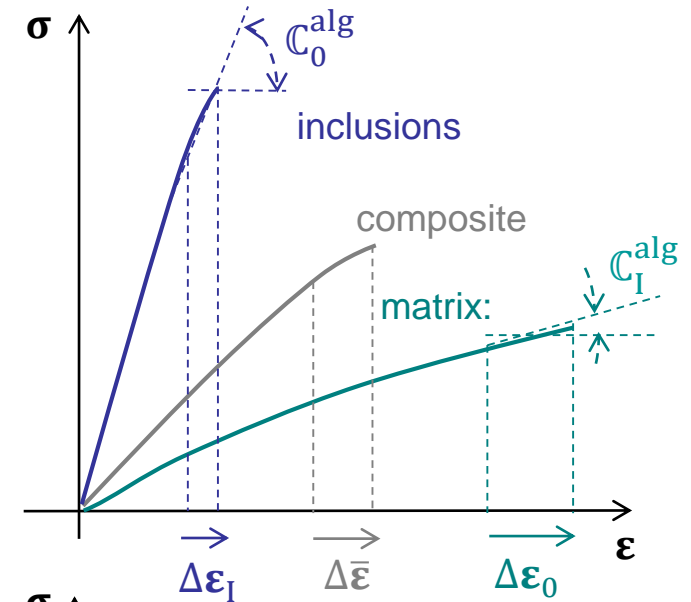
$$\Delta \boldsymbol{\varepsilon}_I = \mathbb{B}^\varepsilon \left(I, \mathbb{C}_0^{\text{alg}}, \mathbb{C}_I^{\text{alg}} \right) : \Delta \boldsymbol{\varepsilon}_0$$

- Because of the damaging process, the fiber phase is elastically unloaded during matrix softening



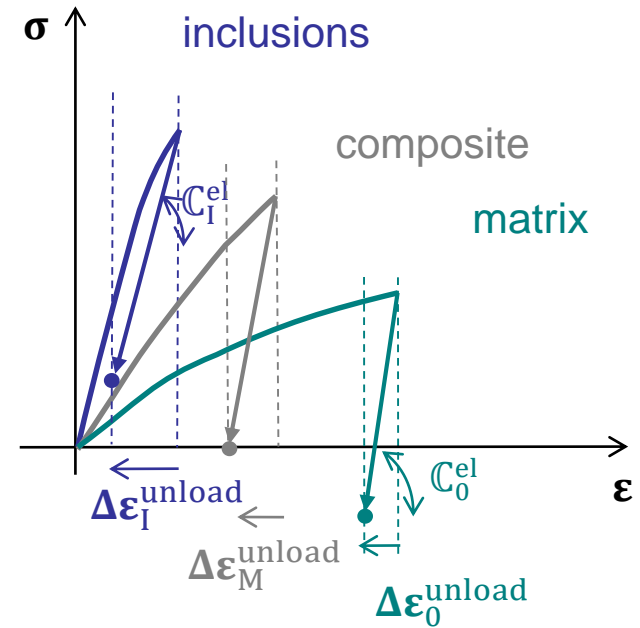
- Solution

- We need to define the LCC from another state



Non-linear stochastic Mean-Field Homogenization

- Incremental-secant Mean-Field-homogenization
 - Virtual elastic unloading from previous state
 - Composite material unloaded to reach the stress-free state
 - Residual stress in components



Non-linear stochastic Mean-Field Homogenization

- Incremental-secant Mean-Field-homogenization

- Virtual elastic unloading from previous state
 - Composite material unloaded to reach the stress-free state
 - Residual stress in components

- Define Linear Comparison Composite

- From unloaded state

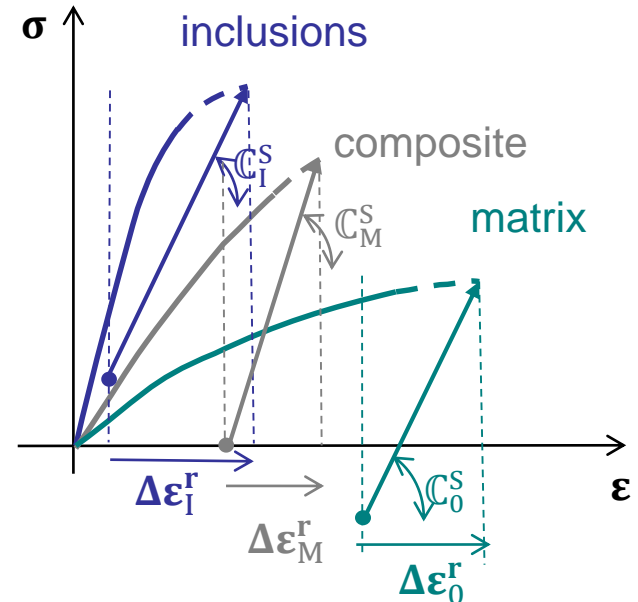
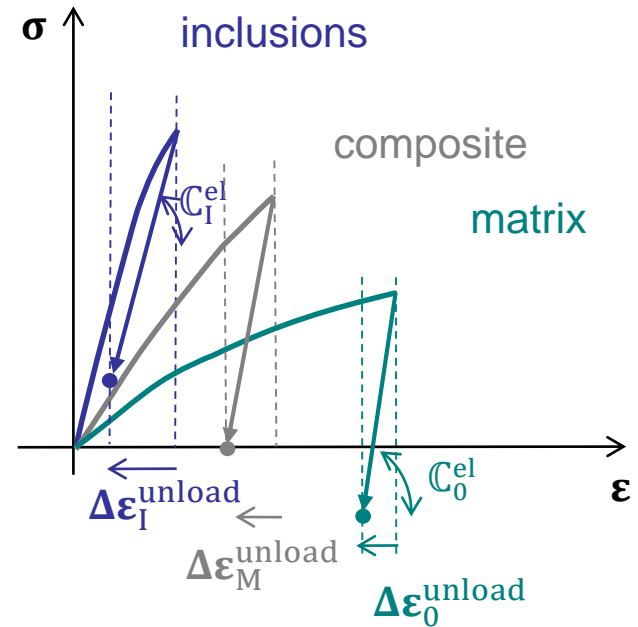
$$\Delta \boldsymbol{\varepsilon}_{I/0}^r = \Delta \boldsymbol{\varepsilon}_{I/0} + \Delta \boldsymbol{\varepsilon}_{I/0}^{\text{unload}}$$

- Incremental-secant loading

$$\left\{ \begin{array}{l} \boldsymbol{\sigma}_M = \bar{\boldsymbol{\sigma}} = \nu_0 \boldsymbol{\sigma}_0 + \nu_1 \boldsymbol{\sigma}_I \\ \Delta \boldsymbol{\varepsilon}_M^r = \bar{\Delta \boldsymbol{\varepsilon}} = \nu_0 \Delta \boldsymbol{\varepsilon}_0^r + \nu_1 \Delta \boldsymbol{\varepsilon}_I^r \\ \Delta \boldsymbol{\varepsilon}_I^r = \mathbb{B}^\varepsilon(I, \mathbb{C}_0^S, \mathbb{C}_I^S) : \Delta \boldsymbol{\varepsilon}_0^r \end{array} \right.$$

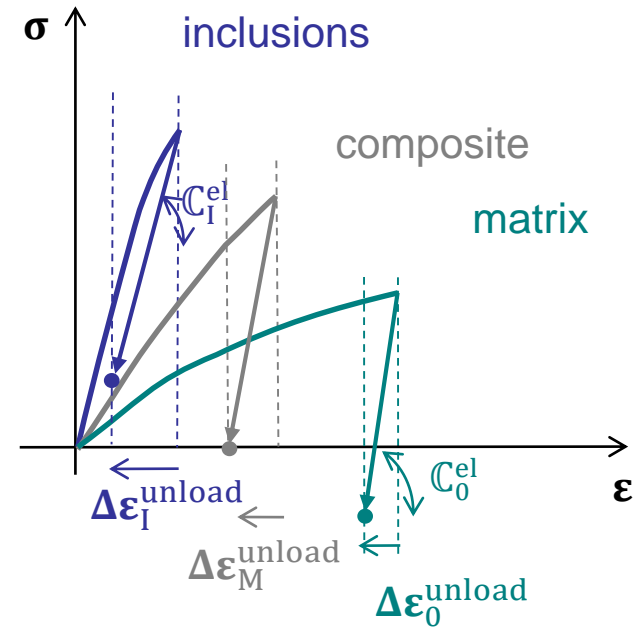
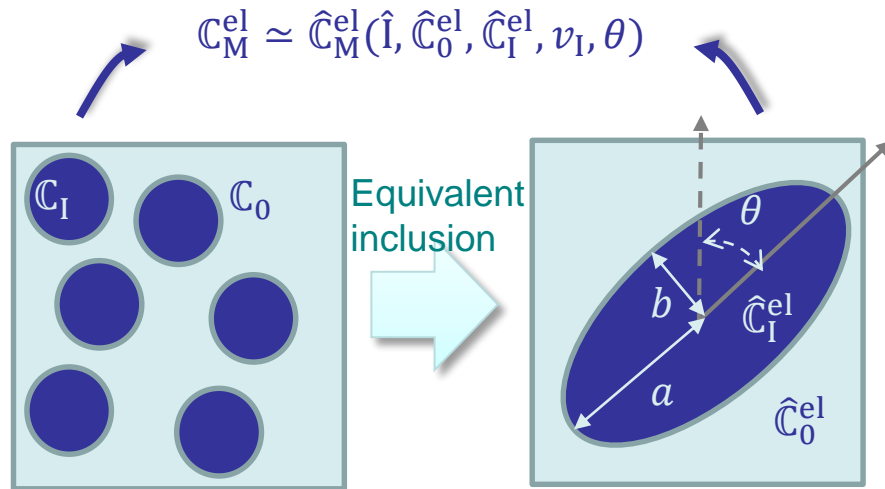
- Incremental secant operator

$$\Rightarrow \Delta \boldsymbol{\sigma}_M = \mathbb{C}_M^S(I, \mathbb{C}_0^S, \mathbb{C}_I^S, \nu_1) : \Delta \boldsymbol{\varepsilon}_M^r$$



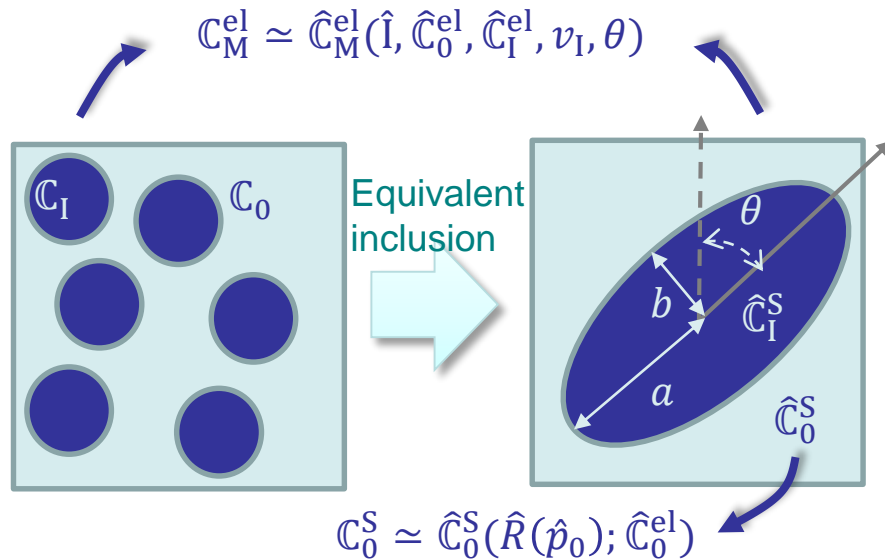
Non-linear stochastic Mean-Field Homogenization

- Non-linear inverse identification
 - First step from elastic response



Non-linear stochastic Mean-Field Homogenization

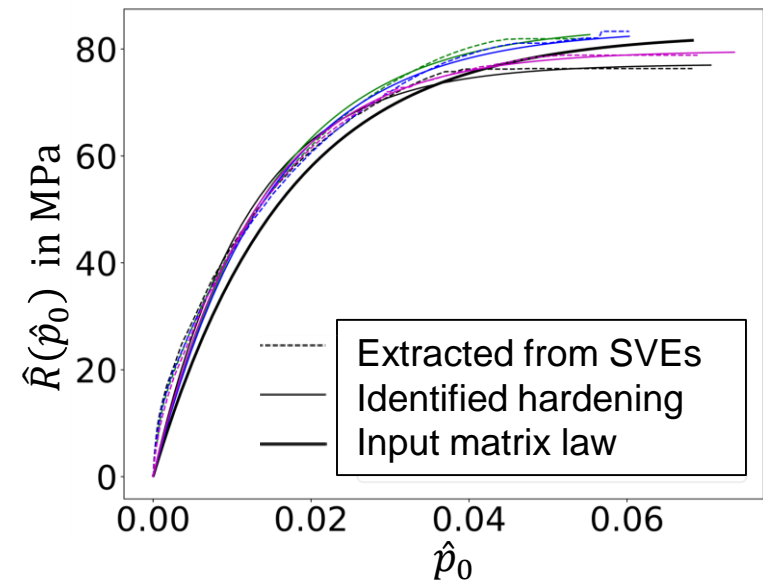
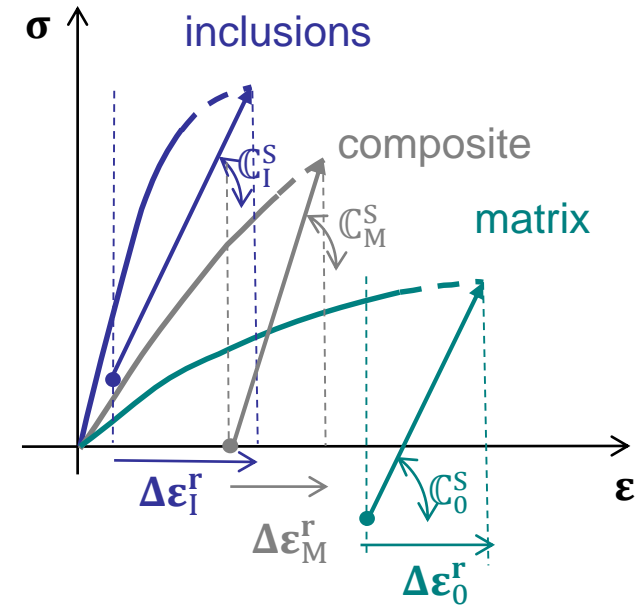
- Non-linear inverse identification
 - First step from elastic response



- Second step from the LCC
 - New optimization problem

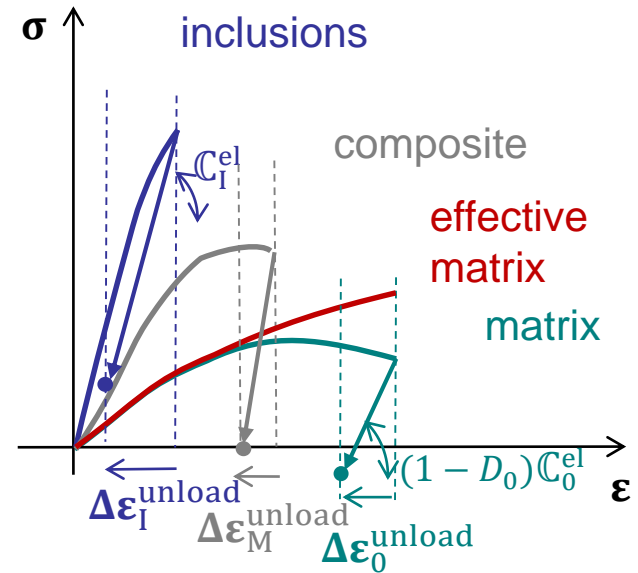
$$\Delta \sigma_M \approx \hat{\mathbb{C}}_M^S(\hat{\mathbf{I}}, \hat{\mathbb{C}}_0^S, \mathbb{C}_I^S, \nu_I, \theta): \Delta \epsilon_M^r$$
 - Extract the equivalent hardening $\hat{R}(\hat{p}_0)$ from the incremental secant tensor

$$\mathbb{C}_0^S \approx \hat{\mathbb{C}}_0^S(\hat{R}(\hat{p}_0); \hat{\mathbb{C}}_0^{el})$$



Non-linear stochastic Mean-Field Homogenization

- Damage-enhanced Mean-Field-homogenization
 - Virtual elastic unloading from previous state
 - Composite material unloaded to reach the stress-free state
 - Residual stress in components



Non-linear stochastic Mean-Field Homogenization

- Damage-enhanced Mean-Field-homogenization

- Virtual elastic unloading from previous state
 - Composite material unloaded to reach the stress-free state
 - Residual stress in components

- Define Linear Comparison Composite

- From elastic state

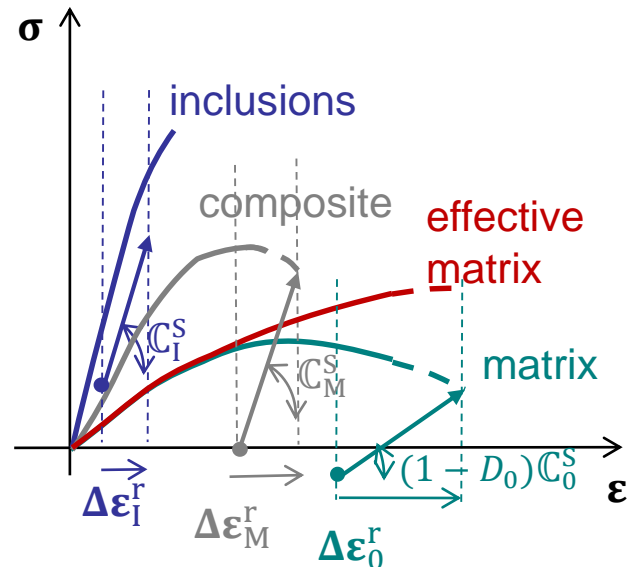
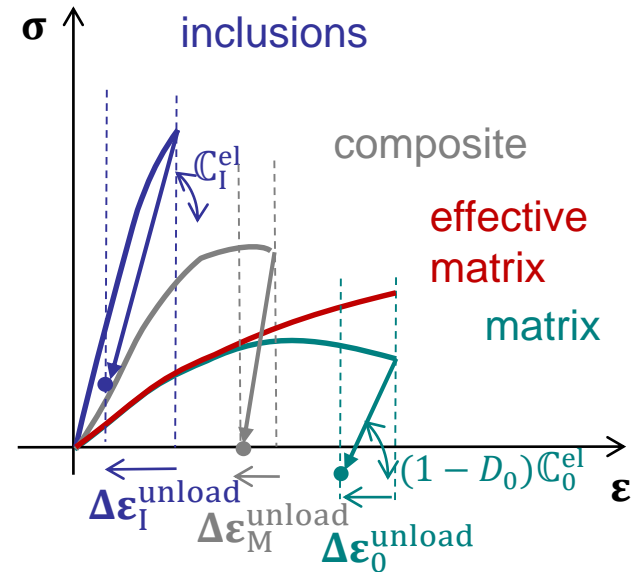
$$\Delta \boldsymbol{\varepsilon}_{I/0}^r = \Delta \boldsymbol{\varepsilon}_{I/0} + \Delta \boldsymbol{\varepsilon}_{I/0}^{\text{unload}}$$

- Incremental-secant loading

$$\left\{ \begin{array}{l} \boldsymbol{\sigma}_M = \bar{\boldsymbol{\sigma}} = v_0 \boldsymbol{\sigma}_0 + v_I \boldsymbol{\sigma}_I \\ \Delta \boldsymbol{\varepsilon}_M^r = \bar{\Delta \boldsymbol{\varepsilon}} = v_0 \Delta \boldsymbol{\varepsilon}_0^r + v_I \Delta \boldsymbol{\varepsilon}_I^r \\ \Delta \boldsymbol{\varepsilon}_I^r = \mathbb{B}^\varepsilon(I, (1 - D_0) \mathbb{C}_0^S, \mathbb{C}_I^S) : \Delta \boldsymbol{\varepsilon}_0^r \end{array} \right.$$

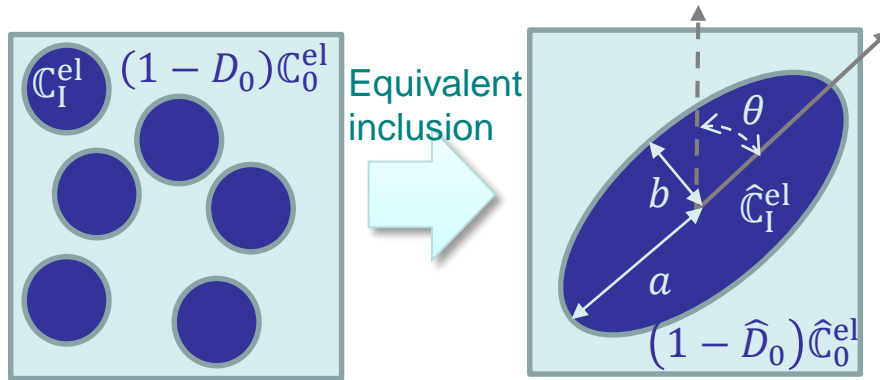
- Incremental secant operator

$$\Rightarrow \Delta \boldsymbol{\sigma}_M = \mathbb{C}_M^S(I, (1 - D_0) \mathbb{C}_0^S, \mathbb{C}_I^S, v_I) : \Delta \boldsymbol{\varepsilon}_M^r$$



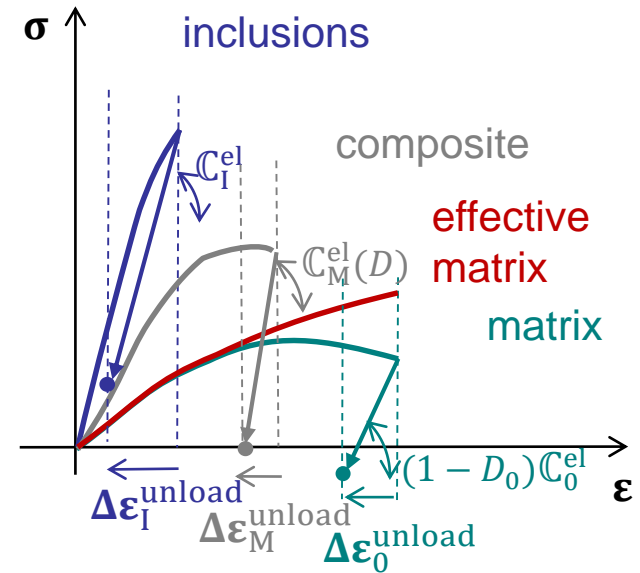
Non-linear stochastic Mean-Field Homogenization

- Damage-enhanced inverse identification
 - Second step: elastic unloading



- Identify damage evolution \hat{D}_0

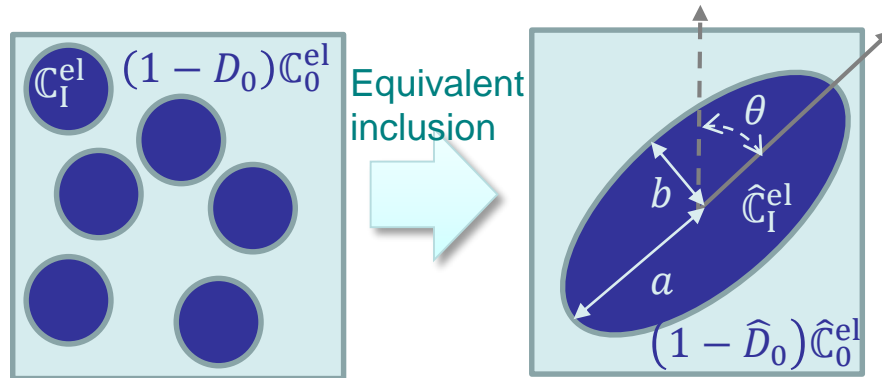
$$\mathbb{C}_M^{el}(D) \simeq \hat{\mathbb{C}}_M^{el}(\hat{I}, (1 - \hat{D}_0)\hat{\mathbb{C}}_0^{el}, \hat{\mathbb{C}}_I^{el}, \nu_I, \theta)$$



Non-linear stochastic Mean-Field Homogenization

- Damage-enhanced inverse identification

- Second step: elastic unloading



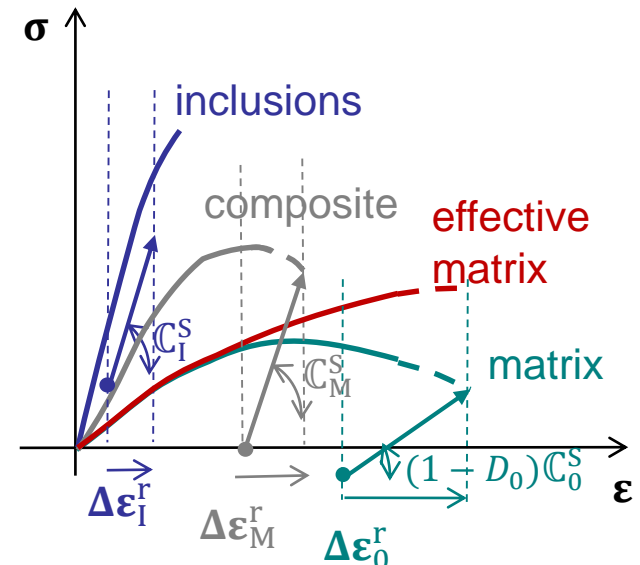
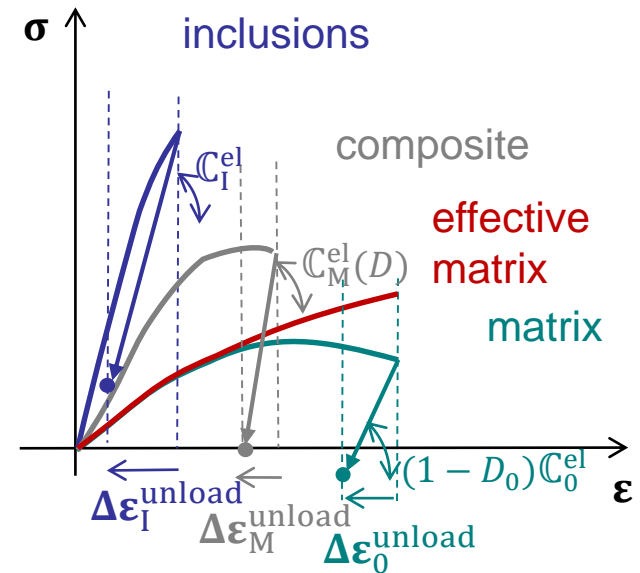
- Identify damage evolution \hat{D}_0

$$\mathbb{C}_M^{el}(D) \simeq \hat{\mathbb{C}}_M^{el}(\hat{I}, (1 - \hat{D}_0)\hat{\mathbb{C}}_0^{el}, \hat{\mathbb{C}}_I^{el}, \nu_I, \theta)$$

- Third step from the LCC

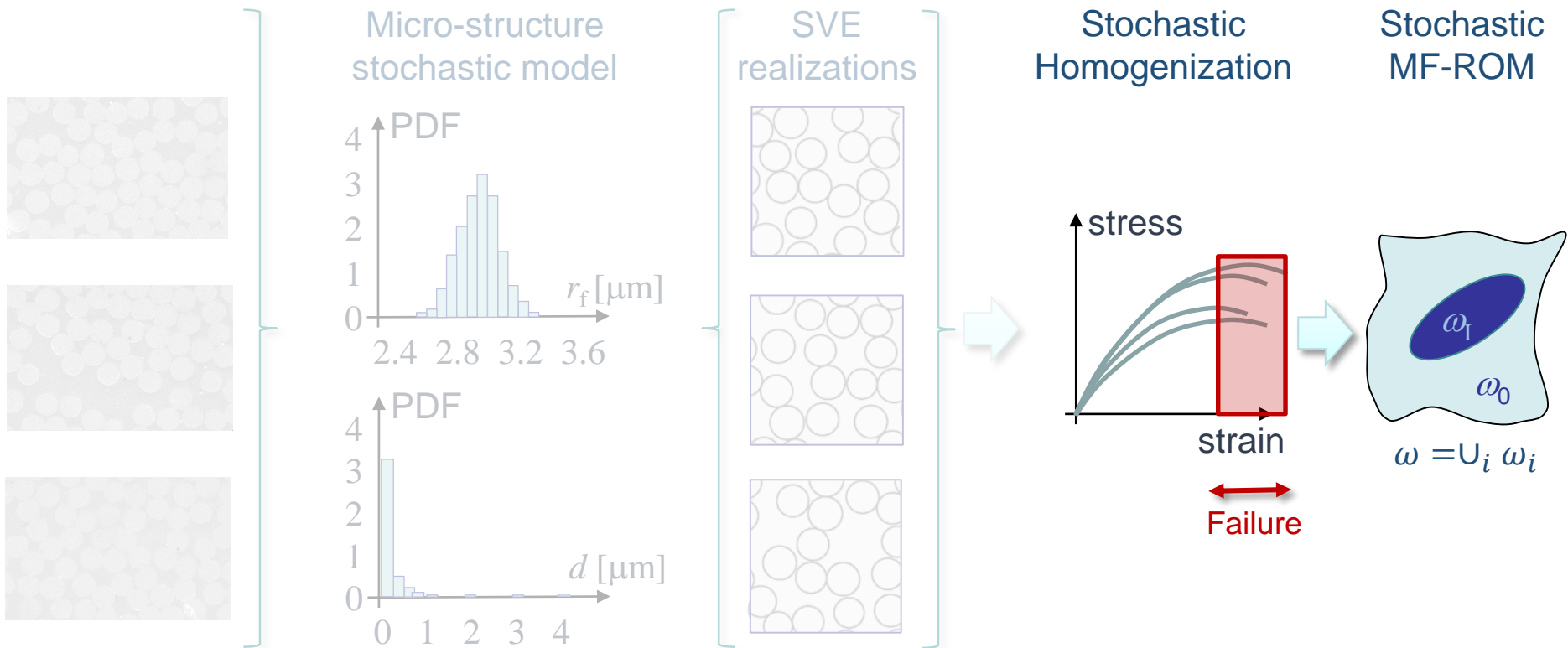
- $\Delta\sigma_M = \mathbb{C}_M^S(I, (1 - D_0)\mathbb{C}_0^S, \mathbb{C}_I^S, \nu_I): \Delta\varepsilon_M^r$
- Extract the equivalent hardening $\hat{R}(\hat{p}_0)$ & damage evolution $\hat{D}_0(\hat{p}_0)$ from incremental secant tensor:

$$(1 - D_0)\mathbb{C}_0^S \simeq (1 - \hat{D}_0(\hat{p}_0))\hat{\mathbb{C}}_0^S(\hat{R}(\hat{p}_0); \hat{\mathbb{C}}_0^{el})$$



Methodology

- Stochastic Mean-Field Homogenization-based model
 - Third stage: Failure

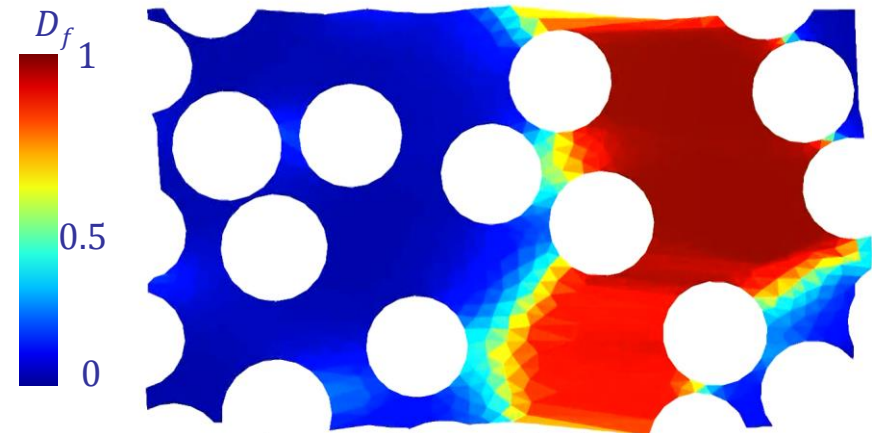
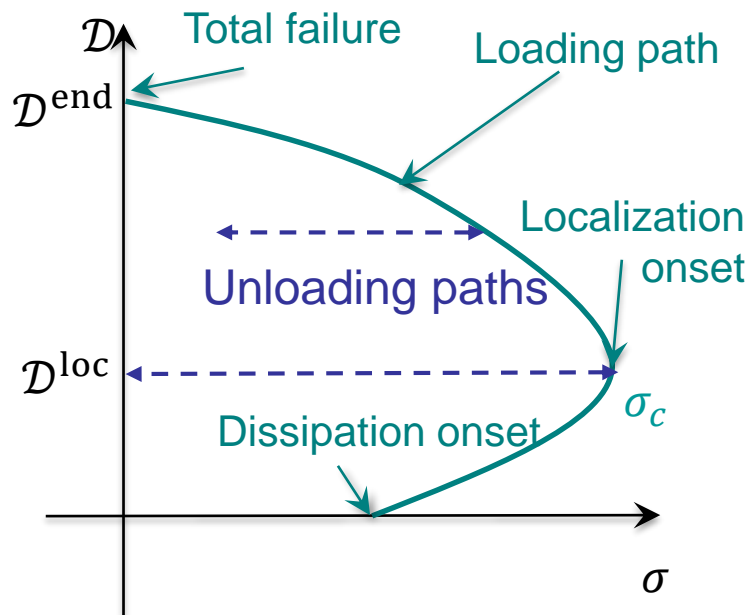


Mean-Field Homogenization with failure

- Need to recover size objectivity

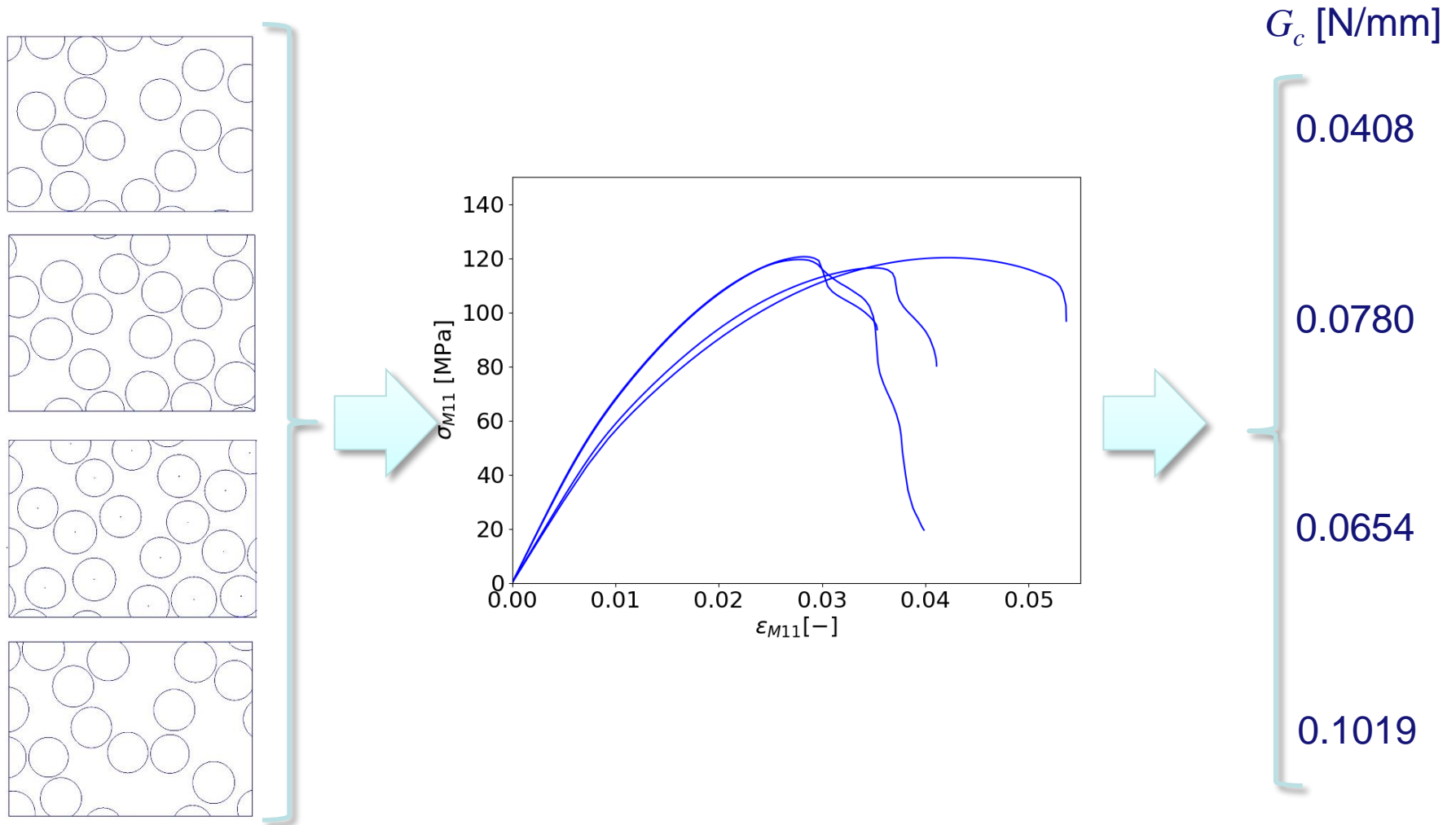
- Strength is objective σ_c

- Critical energy release rate is objective $G_c = \frac{\mathcal{D}^{\text{end}} - \mathcal{D}^{\text{loc}}}{A_0}$



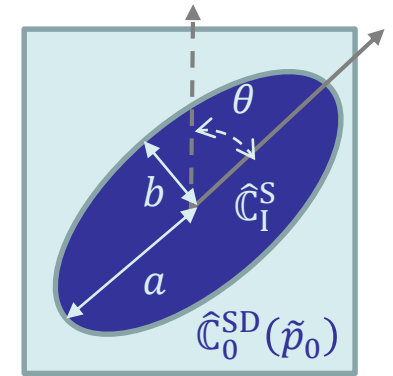
Mean-Field Homogenization with failure

- Non-linear SVE simulations



Mean-Field Homogenization with failure

- Damage-enhanced mean-field homogenization
 - Requires non-local form for the matrix part of homogenized behavior
 - Following implicit form [Peerlings et al. 1998]
 - Apparent matrix plastic strain p_0
 - Non-local apparent matrix plastic strain \tilde{p}_0
 - Matrix damage evolution
$$\Delta D_0 = F_D(\Delta \boldsymbol{\varepsilon}_0, \Delta p_0) \quad \Rightarrow \quad \Delta D_0 = F_D(\Delta \boldsymbol{\varepsilon}_0, \Delta \tilde{p}_0)$$
 - New Helmholtz-type equations:
 - $\tilde{p}_0 - l_c^2 \nabla \cdot (\nabla \tilde{p}_0) = p_0$
 - Definition of non-local length l_c



Mean-Field Homogenization with failure

- Damage-enhanced mean-field homogenization

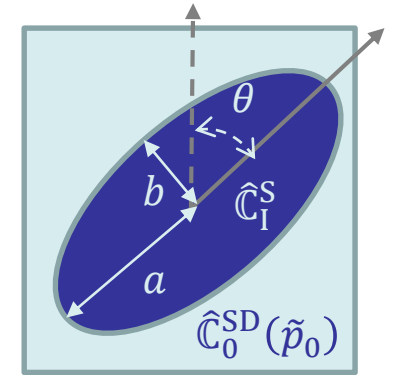
- Requires non-local form for the matrix homogenized behavior

- Matrix damage evolution $\Delta D_0 = F_D(\Delta \boldsymbol{\varepsilon}_0, \Delta \tilde{p}_0)$

- New Helmholtz-type equations:

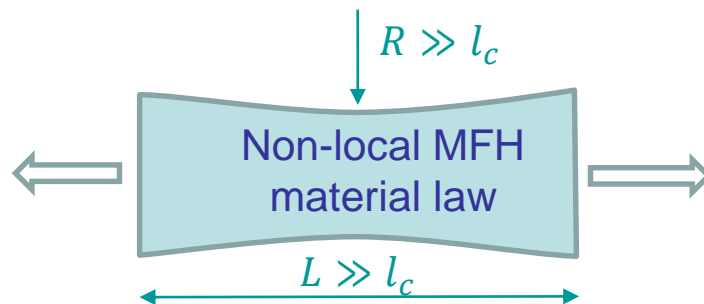
- $\tilde{p}_0 - l_c^2 \nabla \cdot (\nabla \tilde{p}_0) = p_0$

- Definition of non-local length l_c

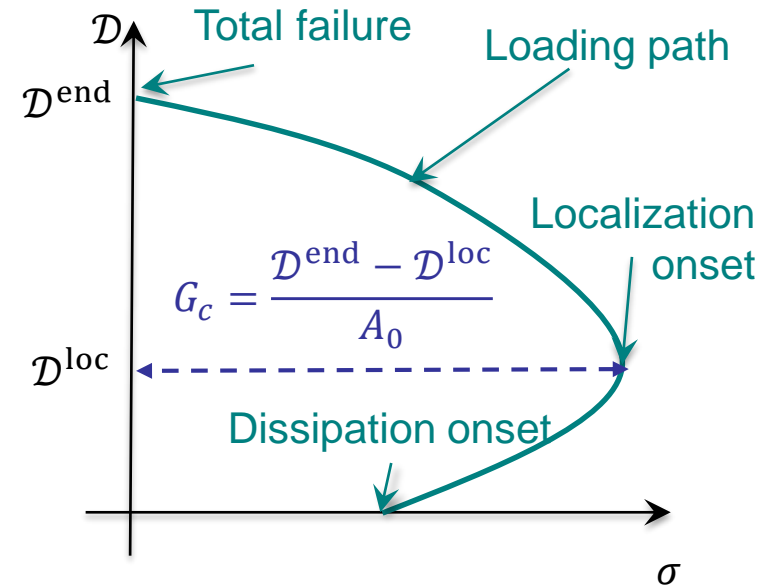


- Evaluation of non-local length

- To recover the energy release rate of SVEs



l_c (μm)	MFH G_c [N mm^{-1}]	SVE G_c [N mm^{-1}]
20	1.008	0.1035
5	0.363	
2	0.0922	



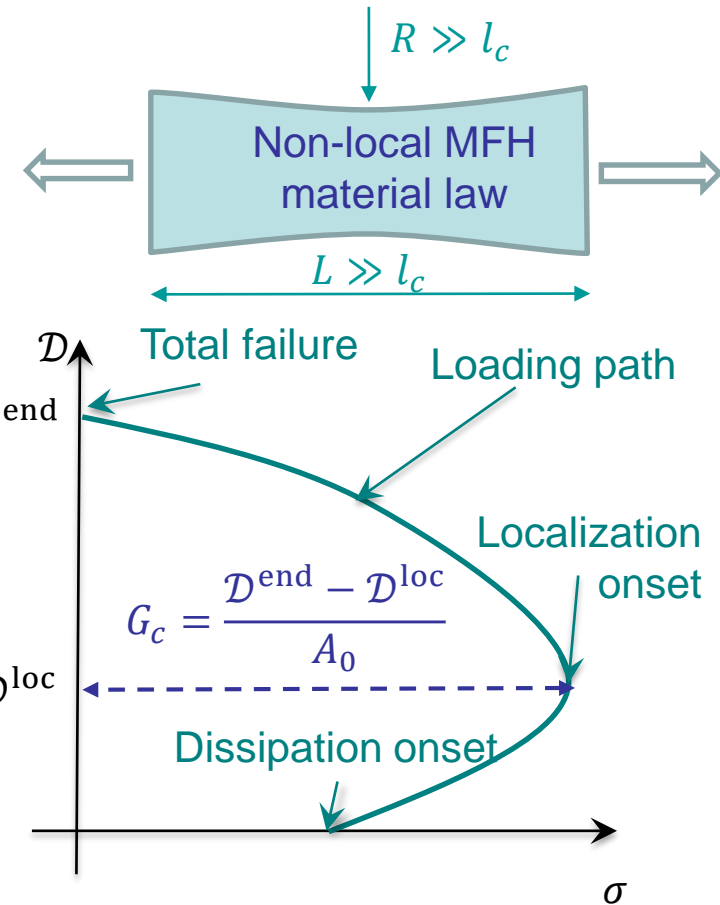
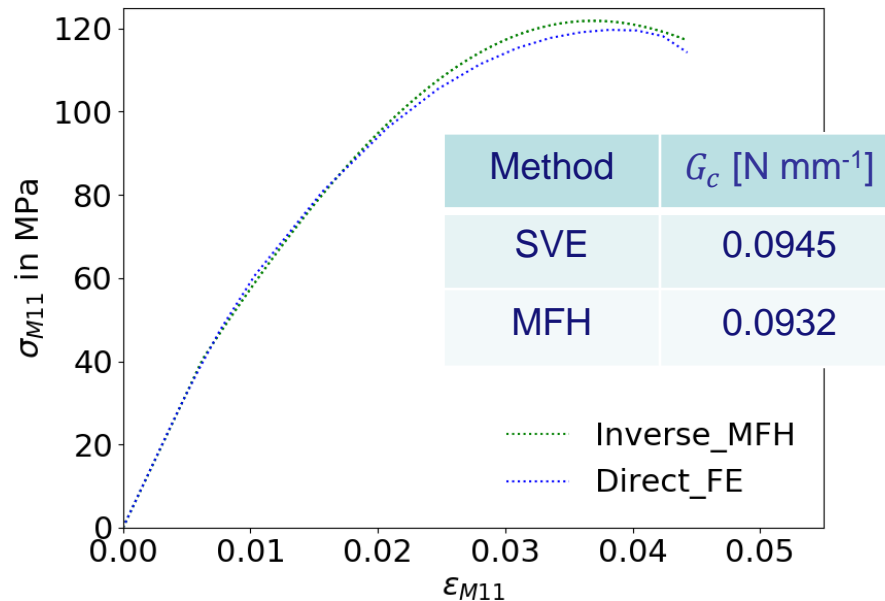
Mean-Field Homogenization with failure

- More convenient to fix non-local length
 - For macro-scale Stochastic FEM
 - To increase its length
- Modify the damage evolution to recover G_c
 - Before localization onset: identified evolution

$$\Delta D_0 = F_D(\Delta \boldsymbol{\varepsilon}_0, \Delta \tilde{p}_0)$$

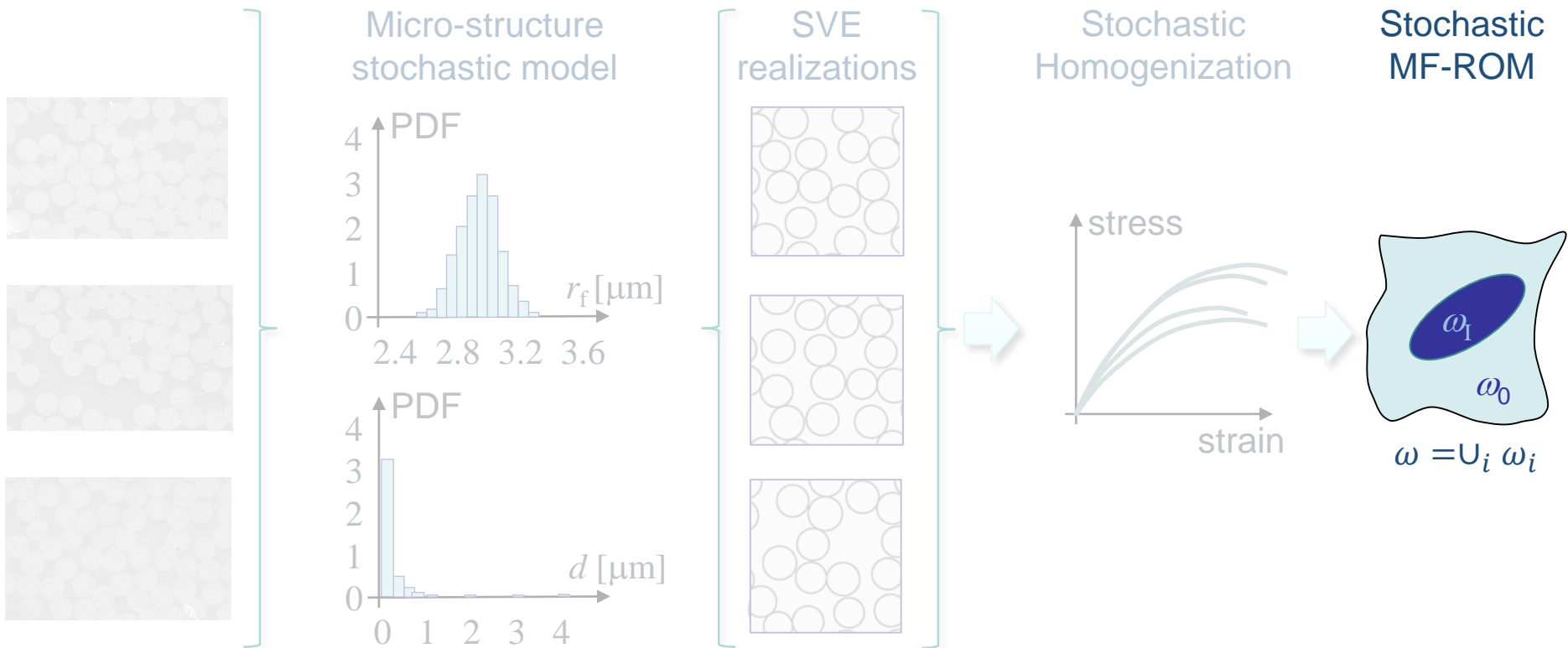
- After localization onset:

- $\Delta D_0 = \alpha(\tilde{p}_0 + \Delta \tilde{p}_0 - \tilde{p}_{0_{\text{onset}}})^\beta \Delta \tilde{p}_0$
- Iterate on α and β



Methodology

- Use Stochastic Mean-Field Homogenization as constitutive law

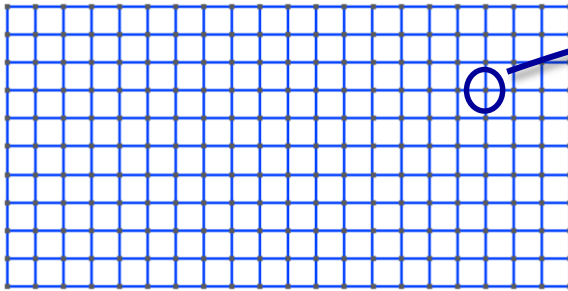


Use of stochastic Mean-Field Homogenization

- Stochastic simulations require two discretizations

- Random vector field discretization

- Of MFH-model parameters



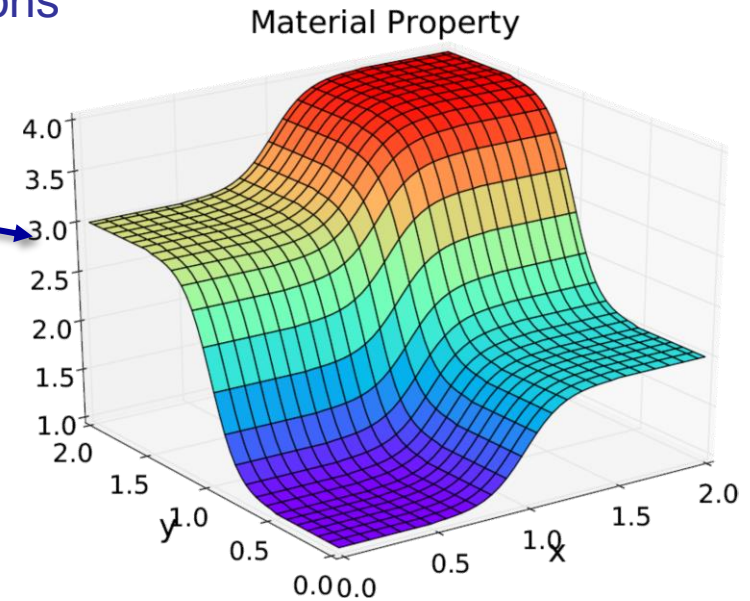
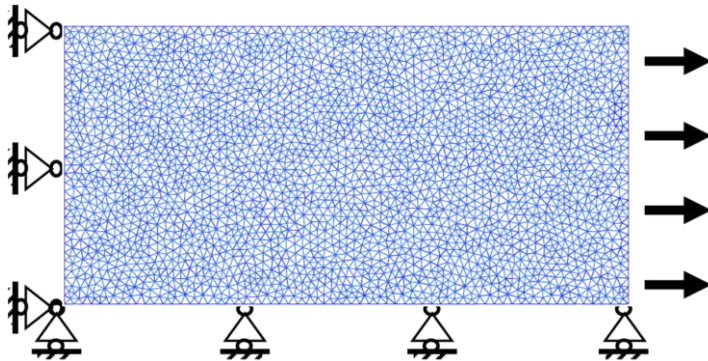
- Stochastic MFH-model parameters identified
- Potentially more cells than SVE realizations



parameters need to be generated

- Finite element discretization

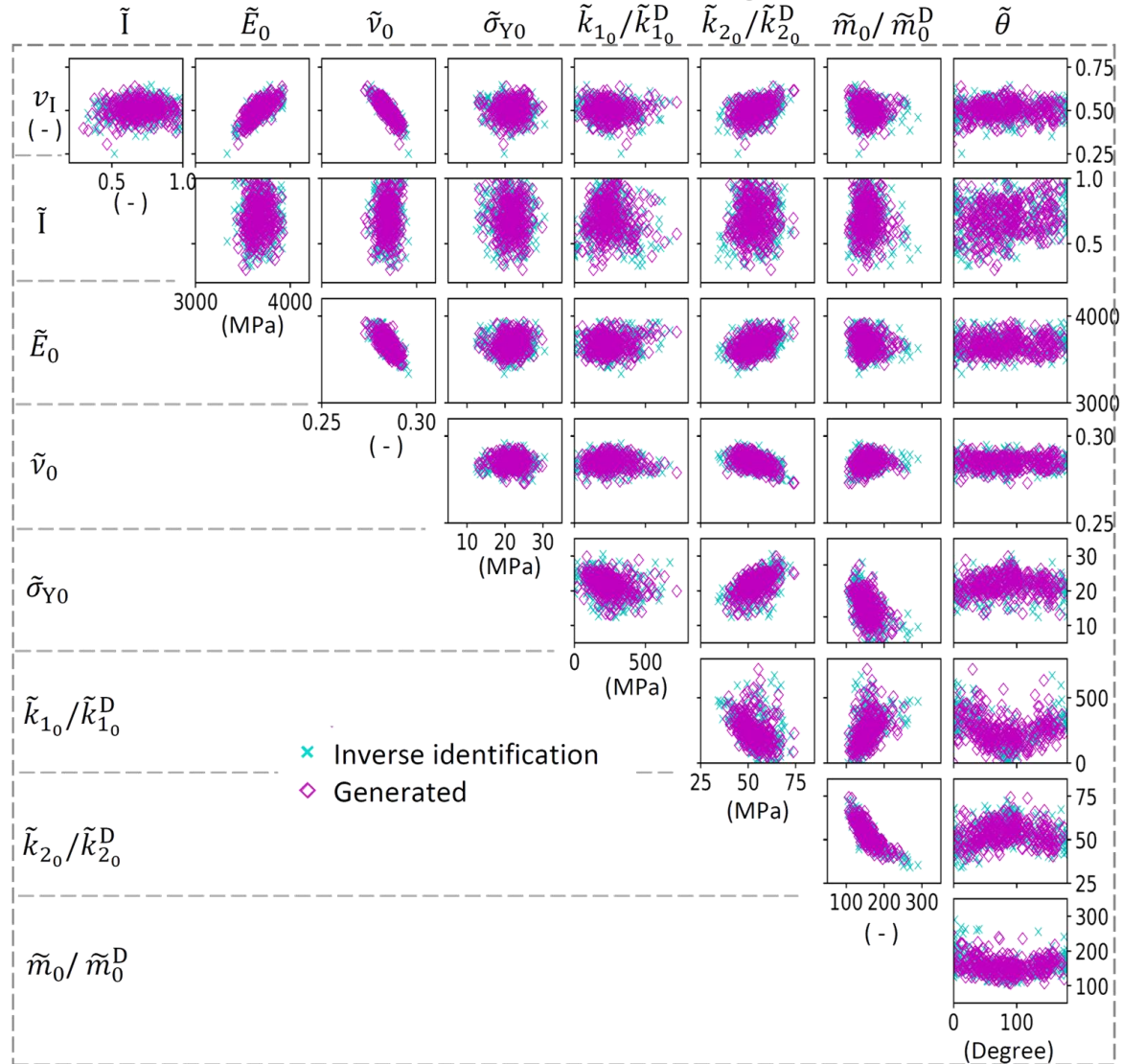
- Finer than random field grid



Use of stochastic Mean-Field Homogenization

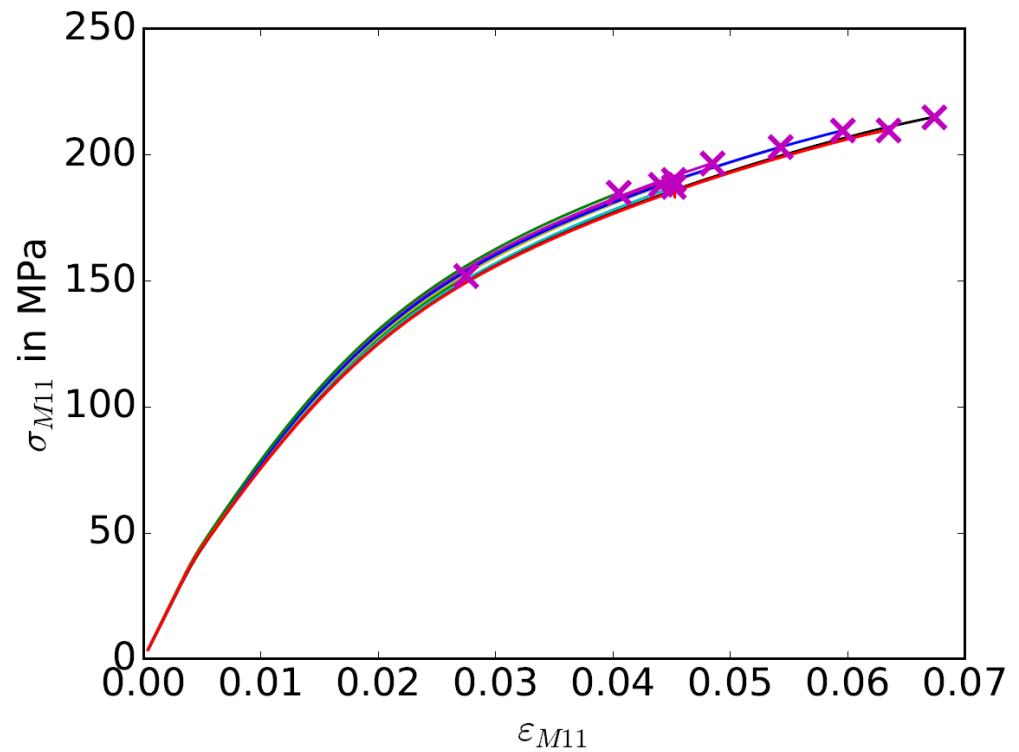
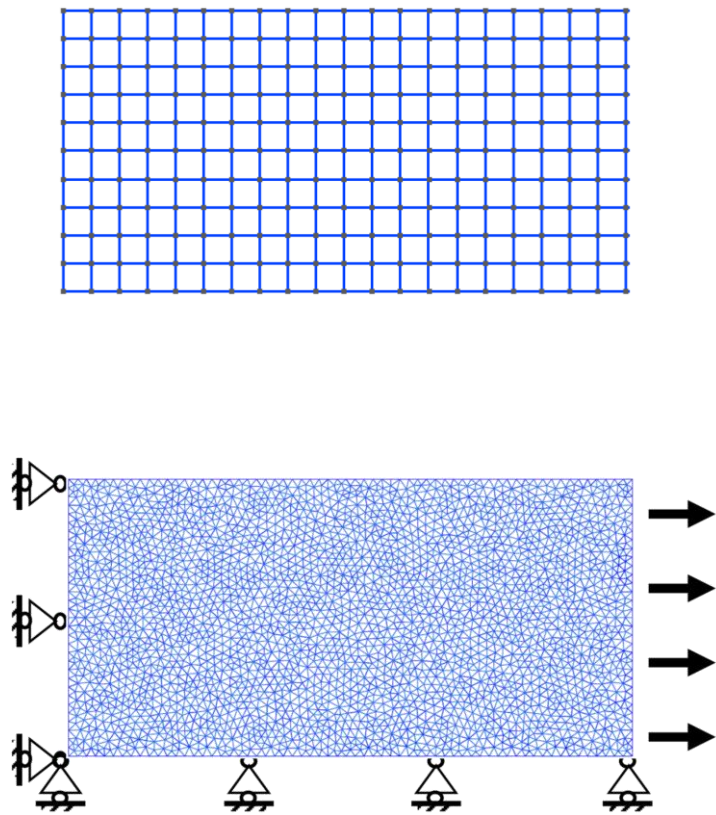
- Generation of random field

- Inverse identification vs. diffusion map –based generator [Soize, Ghanem 2016]



Use of stochastic Mean-Field Homogenization

- Ply loading realizations
 - Preliminary results (softening part not implemented)



- **Stochastic micro-structures**
 - Geometrical features from statistical measurements
 - Micro-structure geometry generator
 - Experimentally calibrated/validated epoxy model with length scale effect
- **Inverse MFH identification**
 - MFH is used as a micro-mechanics based model
 - Parameters identified from SVE simulations
 - Localization behaviour identified using objective fields
- **Stochastic Finite elements**
 - Stochastic MFH is used as material law
 - Random fields (MFH parameters) generated using data-driven approach
 - First ply simulations

Thank you for your attention!

Special thanks to:



Wallonie
STOMMMAC project

fnrs
LA LIBERTÉ DE CHERCHER

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