

Approximating likelihood ratios with calibrated classifiers

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Joint work with



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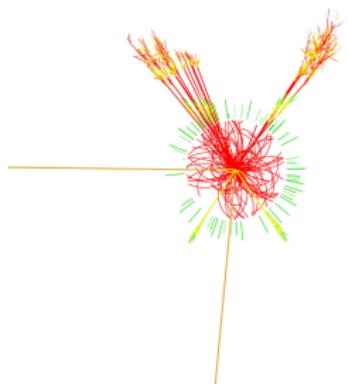


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See paper ([Cranmer et al., 2015](#)) for full details.

Likelihood-free setup

- Complex simulator p parameterized by θ ;
- Samples $\mathbf{x} \sim p$ can be generated on-demand;
- ... but the likelihood $p(\mathbf{x}|\theta)$ **cannot be evaluated!**



Simple hypothesis testing

- Assume some observed data $\mathcal{D} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$;
- Test a null $\theta = \theta_0$ against an alternative $\theta = \theta_1$;
- The Neyman-Pearson lemma states that the most powerful test statistic is

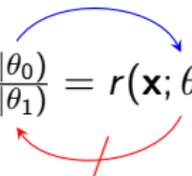
$$\lambda(\mathcal{D}; \theta_0, \theta_1) = \prod_{\mathbf{x} \in \mathcal{D}} \frac{p_{\mathbf{X}}(\mathbf{x}|\theta_0)}{p_{\mathbf{X}}(\mathbf{x}|\theta_1)}.$$

- ... but neither $p_{\mathbf{X}}(\mathbf{x}|\theta_0)$ nor $p_{\mathbf{X}}(\mathbf{x}|\theta_1)$ can be evaluated!

Straight approximation

1. Approximate $p_{\mathbf{X}}(\mathbf{x}|\theta_0)$ and $p_{\mathbf{X}}(\mathbf{x}|\theta_1)$ individually, using density estimation algorithms;
2. Evaluate their ratio $r(\mathbf{x}; \theta_0, \theta_1)$.

Works fine for low-dimensional data, but because of the curse of dimensionality, this is in general a difficult problem! Moreover, **it is not even necessary!**

$$\frac{p_{\mathbf{X}}(\mathbf{x}|\theta_0)}{p_{\mathbf{X}}(\mathbf{x}|\theta_1)} = r(\mathbf{x}; \theta_0, \theta_1)$$


When solving a problem of interest, do not solve a more general problem as an intermediate step. – Vladimir Vapnik

Approximating likelihood ratios with classifiers

- Theorem: The likelihood ratio is invariant under the change of variable $\mathbf{U} = s(\mathbf{X})$, provided $s(\mathbf{x})$ is monotonic with $r(\mathbf{x})$.

$$r(\mathbf{x}) = \frac{p_{\mathbf{X}}(\mathbf{x}|\theta_0)}{p_{\mathbf{X}}(\mathbf{x}|\theta_1)} = \frac{p_{\mathbf{U}}(s(\mathbf{x})|\theta_0)}{p_{\mathbf{U}}(s(\mathbf{x})|\theta_1)}$$

- Well, a classifier trained to distinguish $\mathbf{x} \sim p_0$ from $\mathbf{x} \sim p_1$ approximates

$$s^*(\mathbf{x}) = \frac{p_{\mathbf{X}}(\mathbf{x}|\theta_1)}{p_{\mathbf{X}}(\mathbf{x}|\theta_0) + p_{\mathbf{X}}(\mathbf{x}|\theta_1)},$$

which is monotonic with $r(\mathbf{x})$.

- Estimating $p(s(\mathbf{x})|\theta)$ is now easy, since the change of variable $s(\mathbf{x})$ projects \mathbf{x} in a 1D space, where only the informative content of the ratio is preserved.
- Disentangle training from calibration.

Inference and composite hypothesis testing

Approximated likelihood ratios can be used for inference, since

$$\begin{aligned}\hat{\theta} &= \arg \max_{\theta} p(\mathcal{D}|\theta) \\ &= \arg \max_{\theta} \prod_{\mathbf{x} \in \mathcal{D}} \frac{p(\mathbf{x}|\theta)}{p(\mathbf{x}|\theta_1)} \\ &= \arg \max_{\theta} \prod_{\mathbf{x} \in \mathcal{D}} \frac{p(s(\mathbf{x}; \theta, \theta_1)|\theta)}{p(s(\mathbf{x}; \theta, \theta_1)|\theta_1)}\end{aligned}\tag{1}$$

where θ_1 is fixed and $s(\mathbf{x}; \theta, \theta_1)$ is a family of classifiers parameterized by (θ, θ_1) .

Accordingly, generalized (or profile) likelihood ratio tests can be evaluated in the same way.

Parameterized learning

For inference, we need to build a family $s(\mathbf{x}; \theta, \theta_1)$ of classifiers.

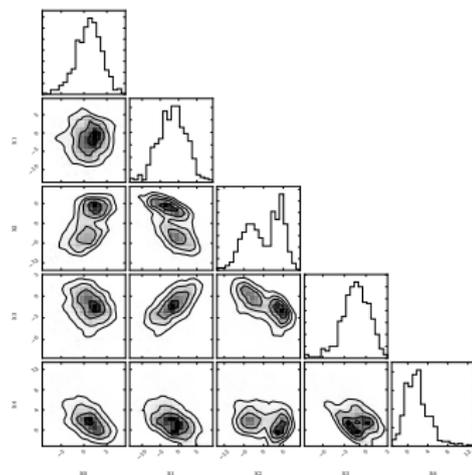
- One could build a classifier s independently for all θ, θ_1 . But this is computationally expensive and would not guarantee a smooth evolution of $s(\mathbf{x}; \theta, \theta_1)$ as θ varies.
- Solution: build a single parameterized classifier instead, where parameters are additional input features ([Cranmer et al., 2015](#); [Baldi et al., 2016](#)).

```
 $\mathcal{T} := \{\};$   
while  $\text{size}(\mathcal{T}) < N$  do  
  Draw  $\theta_0 \sim \pi_{\Theta_0}$ ;  
  Draw  $\mathbf{x} \sim p(\mathbf{x}|\theta_0)$ ;  
   $\mathcal{T} := \mathcal{T} \cup \{(\mathbf{x}, \theta_0, \theta_1), y = 0\}$ ;  
  Draw  $\theta_1 \sim \pi_{\Theta_1}$ ;  
  Draw  $\mathbf{x} \sim p(\mathbf{x}|\theta_1)$ ;  
   $\mathcal{T} := \mathcal{T} \cup \{(\mathbf{x}, \theta_0, \theta_1), y = 1\}$ ;  
end while  
Learn a single classifier  $s(\mathbf{x}; \theta_0, \theta_1)$  from  $\mathcal{T}$ .
```

Example: Inference from multidimensional data

Let assume 5D data \mathbf{x} generated from the following process p_0 :

- $\mathbf{z} := (z_0, z_1, z_2, z_3, z_4)$, such that
 - $z_0 \sim \mathcal{N}(\mu = \alpha, \sigma = 1)$,
 - $z_1 \sim \mathcal{N}(\mu = \beta, \sigma = 3)$,
 - $z_2 \sim \text{Mixture}(\frac{1}{2} \mathcal{N}(\mu = -2, \sigma = 1), \frac{1}{2} \mathcal{N}(\mu = 2, \sigma = 0.5))$,
 - $z_3 \sim \text{Exponential}(\lambda = 3)$, and
 - $z_4 \sim \text{Exponential}(\lambda = 0.5)$;
- $\mathbf{x} := R\mathbf{z}$, where R is a fixed semi-positive definite 5×5 matrix defining a fixed projection of \mathbf{z} into the observed space.



Observed data \mathcal{D}

Our goal is to infer the values α and β based on \mathcal{D} .

🕒 Check out [\(Louppe et al., 2016\)](#) to reproduce this example.

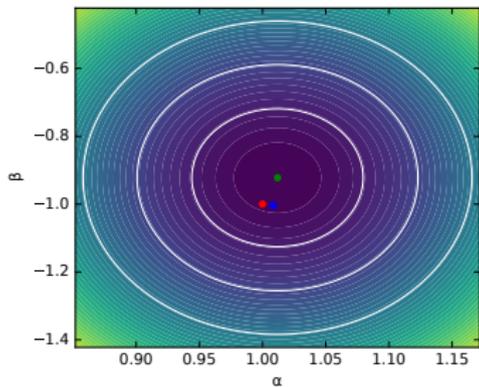
Example: Inference from multidimensional data

Recipe:

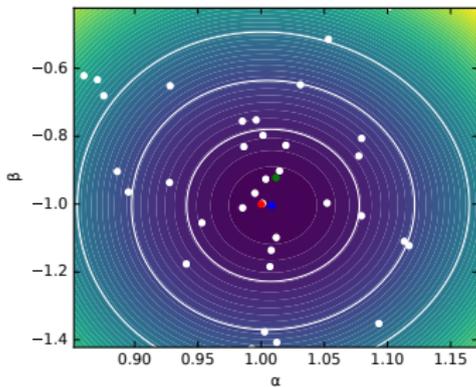
1. Build a single parameterized classifier $s(\mathbf{x}; \theta_0, \theta_1)$, in this case a 2-layer NN trained on 5+2 features, with the alternative fixed to $\theta_1 = (\alpha = 0, \beta = 0)$.
2. Find the approximated MLE $\hat{\alpha}, \hat{\beta}$ by solving Eqn. 1.
 - Solve Eqn. 1 using likelihood scans or through optimization.
 - Since the generator is inexpensive, $p(s(\mathbf{x}; \theta_0, \theta_1) | \theta)$ can be calibrated on-the-fly, for every candidate (α, β) , e.g. using histograms.
3. Construct the log-likelihood ratio (LLR) statistic

$$-2 \log \Lambda(\alpha, \beta) = -2 \log \frac{p(\mathcal{D} | \alpha, \beta)}{p(\mathcal{D} | \hat{\alpha}, \hat{\beta})}$$

Exact $-2 \log \Lambda(\alpha, \beta)$



Approx. LLR (smoothed by a Gaussian Process)

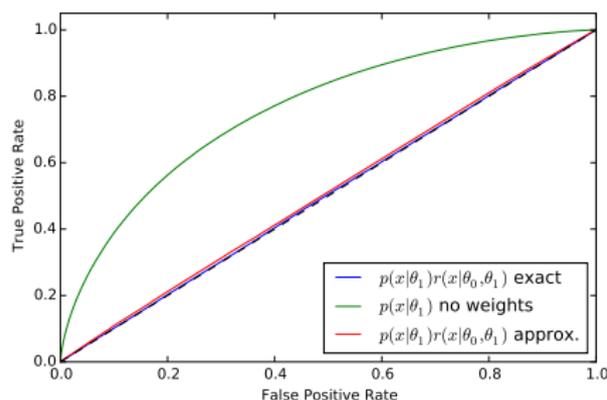
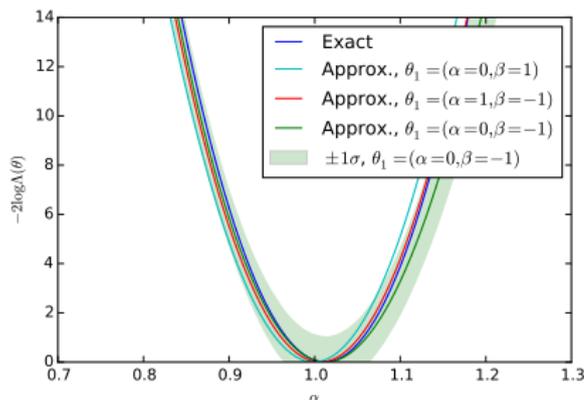


• $\alpha = 1, \beta = -1$ • Exact MLE • Approx. MLE

Diagnostics

In practice $\hat{r}(\hat{s}(\mathbf{x}; \theta_0, \theta_1))$ will not be exact. Diagnostic procedures are needed to assess the quality of this approximation.

1. For inference, the value of the MLE $\hat{\theta}$ should be independent of the value of θ_1 used in the denominator of the ratio.
2. Train a classifier to distinguish between unweighted samples from $p(\mathbf{x}|\theta_0)$ and samples from $p(\mathbf{x}|\theta_1)$ weighted by $\hat{r}(\hat{s}(\mathbf{x}; \theta_0, \theta_1))$.



Likelihood ratio of mixtures

For models defined as known mixtures of several components, the target LR can be formulated in terms of pairwise approximations of sub-LRs. Specifically, we can write

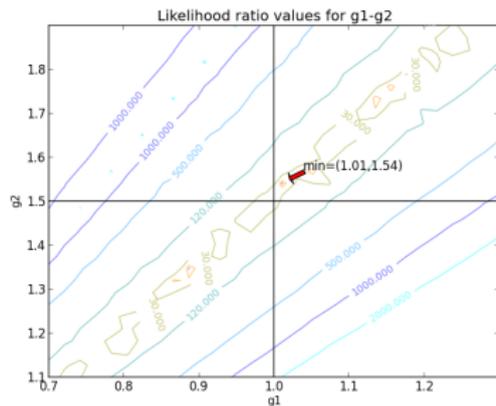
$$\begin{aligned}\frac{p(\mathbf{x}|\theta_0)}{p(\mathbf{x}|\theta_1)} &= \frac{\sum_c w_c(\theta_0) p_c(\mathbf{x}|\theta_0)}{\sum_{c'} w_{c'}(\theta_1) p_{c'}(\mathbf{x}|\theta_1)} \\ &= \sum_c \left[\sum_{c'} \frac{w_{c'}(\theta_1)}{w_c(\theta_0)} \frac{p_{c'}(\mathbf{x}|\theta_1)}{p_c(\mathbf{x}|\theta_0)} \right]^{-1} \\ &= \sum_c \left[\sum_{c'} \frac{w_{c'}(\theta_1)}{w_c(\theta_0)} \frac{p_{c'}(s_{c,c'}(\mathbf{x}; \theta_0, \theta_1)|\theta_1)}{p_c(s_{c,c'}(\mathbf{x}; \theta_0, \theta_1)|\theta_0)} \right]^{-1}.\end{aligned}$$

This allows to focus the capacity of the classifiers on simpler problems, resulting in better approximations.

In the common case where free parameters only concern the component weights, sub-LRs can all be precomputed before fitting!

Application to Higgs EFT

- Ongoing effort using the outlined method for estimating coupling parameters for Higgs EFT.
- In case of mixtures (as for Higgs EFT), the LR estimation problem can be rewritten as pairwise LR estimation problems.



Preliminary results

Summary

- We proposed an approach for approximating LR in the likelihood-free setup.
- Evaluating likelihood ratios reduces to supervised learning. Both problems are deeply connected.
- Alternative to Approximate Bayesian Computation, without the need to define a prior over parameters.

References

- Baldi, P., Cranmer, K., Faucett, T., Sadowski, P., and Whiteson, D. (2016). Parameterized Machine Learning for High-Energy Physics. *arXiv preprint arXiv:1601.07913*.
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- Louppe, G., Cranmer, K., and Pavez, J. (2016). carl: a likelihood-free inference toolbox. <http://dx.doi.org/10.5281/zenodo.47798>, <https://github.com/diana-hep/carl>.