

Damage Detection in Structures Based on Principal Component Analysis of Forced Harmonic Responses

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- **Principal Component Analysis**
 - Definition and mathematical formulation
 - Computation of the POMs
 - Interpretation of the POMs
 - Detection of damage
 - Localization of damage
 - **Example of a truss structure**
 - **Conclusion**

Principal component analysis is a multi-variate statistical method.

Aim: to obtain a compact representation of the data.

Principal Component Analysis = Proper Orthogonal Decomposition

PCA has been successfully applied for operational modal analysis (OMA) of civil engineering structures including temperature effects [1-2].

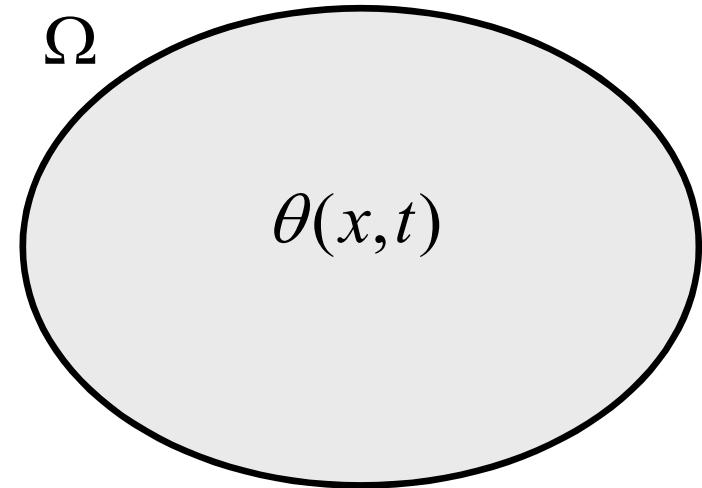
1. A-M Yan, G. Kerschen, P. De Boe, J.-C. Golinval, Structural damage diagnosis under varying environmental conditions - Part I: A linear analysis, *Mechanical Systems & Signal Processing*, Academic Press Ltd Elsevier Science Ltd, (2005) 19(4), 847—864.
2. V.H. Nguyen, J. Mahowald, J.-C. Golinval, S. Maas, Damage Detection in Civil Engineering Structure Considering Temperature Effect, *International Modal Analysis Conference (IMAC) XXXII*, Society of Experimental Mechanics, Orlando (FL), 3-6 February 2014.

Mathematical formulation

Let $\theta(x,t)$ be a random field on a domain Ω

$$\theta(x,t) = \mu(x) + \mathcal{G}(x,t)$$

↑ mean
↓ time varying part



At time t_k , the system displays a snapshot $\mathcal{G}^k(x) = \mathcal{G}(x, t_k)$

The POD aims at obtaining the most characteristic structure $\phi(x)$ of an ensemble of snapshots i.e.

$$\text{Maximize } \left\langle \left| (\mathcal{G}^k, \phi) \right|^2 \right\rangle \quad \text{with} \quad \|\phi\|^2 = 1$$

where $(f, g) = \int_{\Omega} f(x) g(x) d\Omega$

$\langle \cdot \rangle$ denotes the averaging operation

$\|\cdot\|$ denotes the norm

It can be shown that the problem reduces to the following integral eigenvalue problem

$$\int_{\Omega} \left\langle \mathcal{G}^k(x) \mathcal{G}^k(x') \right\rangle \phi(x') dx' = \lambda \phi(x)$$

averaged auto-correlation function

Thus the solution of the optimization problem

$$\text{Maximize } \left\langle \left| (\mathcal{G}^k, \phi) \right|^2 \right\rangle \quad \text{with } \|\phi\|^2 = 1$$

is given by the orthogonal eigenfunctions $\phi_i(x)$ of the integral equation

$$\int_{\Omega} \left\langle \mathcal{G}^k(x) \mathcal{G}^k(x') \right\rangle \phi(x') dx' = \lambda \phi(x)$$

$\phi_i(x)$ are called the proper orthogonal modes (POM)

λ_i are called the proper orthogonal values (POV)

and we have

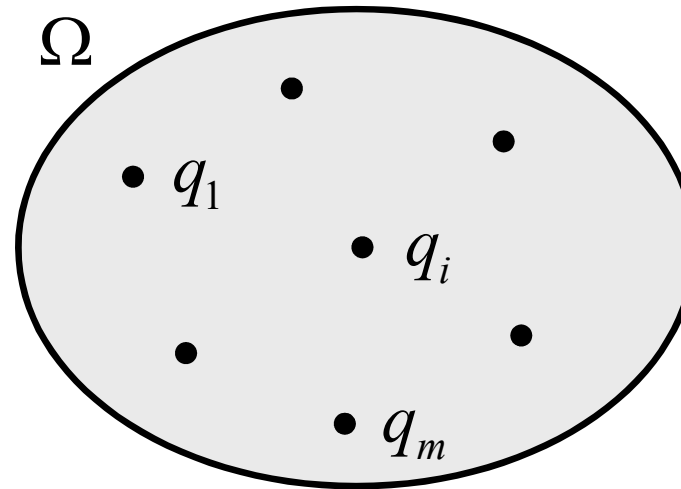
$$\mathcal{G}(x, t) = \sum_{i=1}^{\infty} a_i(t) \phi_i(x)$$

$$\text{where } a_i(t) = (\mathcal{G}(x, t), \phi_i(x))$$

→ uncorrelated coefficients

In practice, the data are discretized in space and time.

Instrumented structure



n snapshots

Observation matrix:

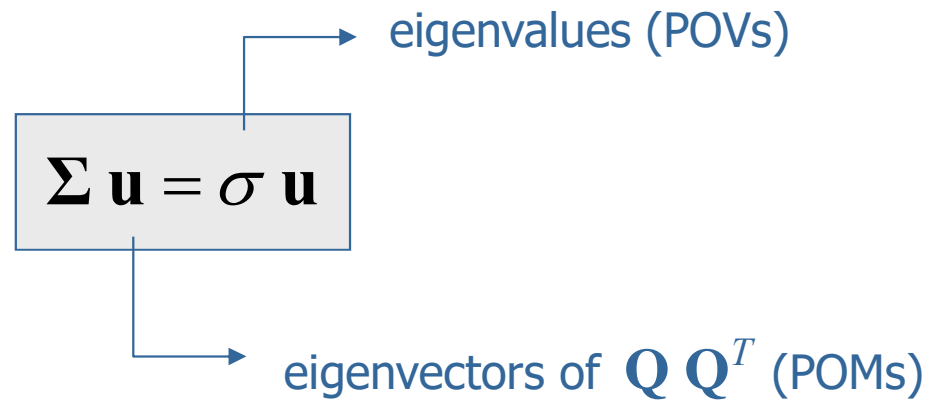
$$\mathbf{Q}_{m \times n} = \begin{bmatrix} q_1(t_1) & \dots & q_1(t_n) \\ \vdots & \ddots & \vdots \\ q_m(t_1) & \dots & q_m(t_n) \end{bmatrix}$$

m
 measurement coordinates

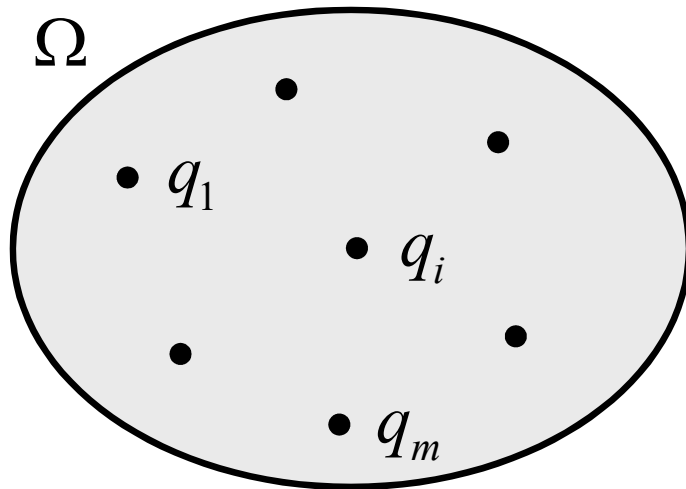
The $m \times m$ covariance matrix Σ is built

$$\Sigma = \frac{1}{m} \mathbf{Q} \mathbf{Q}^T$$

The eigenvalue problem is solved



Computation of the POMs using SVD



m measurement co-ordinates

n time samples

$$\mathbf{Q}_{m \times n} = \begin{bmatrix} q_1(t_1) & \dots & q_1(t_n) \\ \vdots & \ddots & \vdots \\ q_m(t_1) & \dots & q_m(t_n) \end{bmatrix}$$

Using SVD

$$\text{diag}(\sqrt{\sigma_i}) \quad (\sigma_i \equiv \text{POV})$$

$$\mathbf{Q}_{m \times n} = \mathbf{U}_{m \times m} \mathbf{S}_{m \times n} \mathbf{V}_{n \times n}^T$$

eigenvectors of $\mathbf{Q} \mathbf{Q}^T$ (POM)

$$\mathbf{M} \ddot{\mathbf{q}} + \mathbf{C} \dot{\mathbf{q}} + \mathbf{K} \mathbf{q} = \mathbf{F} \sin(\omega t)$$

Forced response:

$$\mathbf{q}(t) = \Im(\mathbf{H}(i\omega) \mathbf{F} e^{i\omega t})$$

where

$$\mathbf{H}(i\omega) = (\mathbf{K} - \omega^2 \mathbf{M} + i\omega \mathbf{C})^{-1} \quad \text{is the FRF matrix}$$

The ($m \times n$) response matrix writes

$$\mathbf{Q} = [\mathbf{q}(t_1) \quad \dots \quad \dots \quad \mathbf{q}(t_n)]$$

$$\mathbf{Q} = \Re(\mathbf{H}) \mathbf{F} \begin{bmatrix} \sin(\omega t_1) \\ \vdots \\ \sin(\omega t_n) \end{bmatrix}^T + \Im(\mathbf{H}) \mathbf{F} \begin{bmatrix} \cos(\omega t_1) \\ \vdots \\ \cos(\omega t_n) \end{bmatrix}^T$$

$$\mathbf{Q} = \Re(\mathbf{H}) \mathbf{F} \mathbf{e}_s^T + \Im(\mathbf{H}) \mathbf{F} \mathbf{e}_c^T$$

$$\mathbf{Q} = \underbrace{\begin{bmatrix} \Re(\mathbf{H}) \mathbf{F} & \Im(\mathbf{H}) \mathbf{F} \\ \|\Re(\mathbf{H}) \mathbf{F}\| & \|\Im(\mathbf{H}) \mathbf{F}\| \end{bmatrix}}_{\mathbf{U}} \underbrace{\mathbf{A} \begin{bmatrix} \|\Re(\mathbf{H}) \mathbf{F}\| \|\mathbf{e}_s\| & 0 & 0 & \dots & 0 \\ 0 & \|\Im(\mathbf{H}) \mathbf{F}\| \|\mathbf{e}_c\| & 0 & \dots & 0 \\ 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 0 \end{bmatrix}}_{\mathbf{S}} \underbrace{\begin{bmatrix} \mathbf{e}_s / \|\mathbf{e}_s\| \\ \mathbf{e}_c / \|\mathbf{e}_c\| \\ \mathbf{B} \end{bmatrix}}_{\mathbf{V}^T}$$

It follows that there are only two non-zero singular values
 → the forced harmonic response is captured by two POMs
 which reflect the real and imaginary parts of the ODS.

Concept of subspace angle

Key idea

- Use PCA to extract the structural response subspace
- Use the concept of subspace angles to compare the hyperplanes associated with the **reference (undamaged)** state and with the **current (possibly damaged?)** state of the structure.

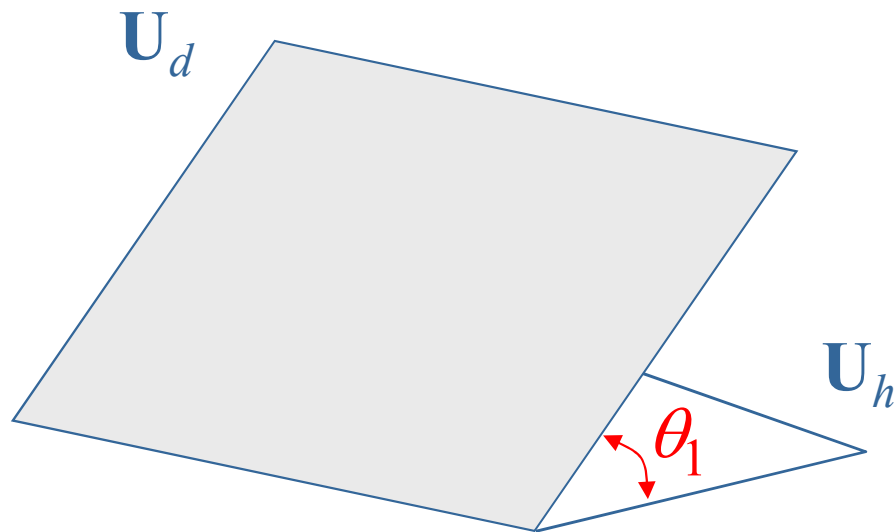
Concept of subspace angle

Given two subspaces $\mathbf{U}_h \in \mathbb{R}^{m \times n}$ and $\mathbf{U}_d \in \mathbb{R}^{m \times n}$

Carry out the QR-factorizations

$$\mathbf{U}_h = \mathbf{Q}_h \mathbf{R}_h \quad \text{and} \quad \mathbf{U}_d = \mathbf{Q}_d \mathbf{R}_d$$

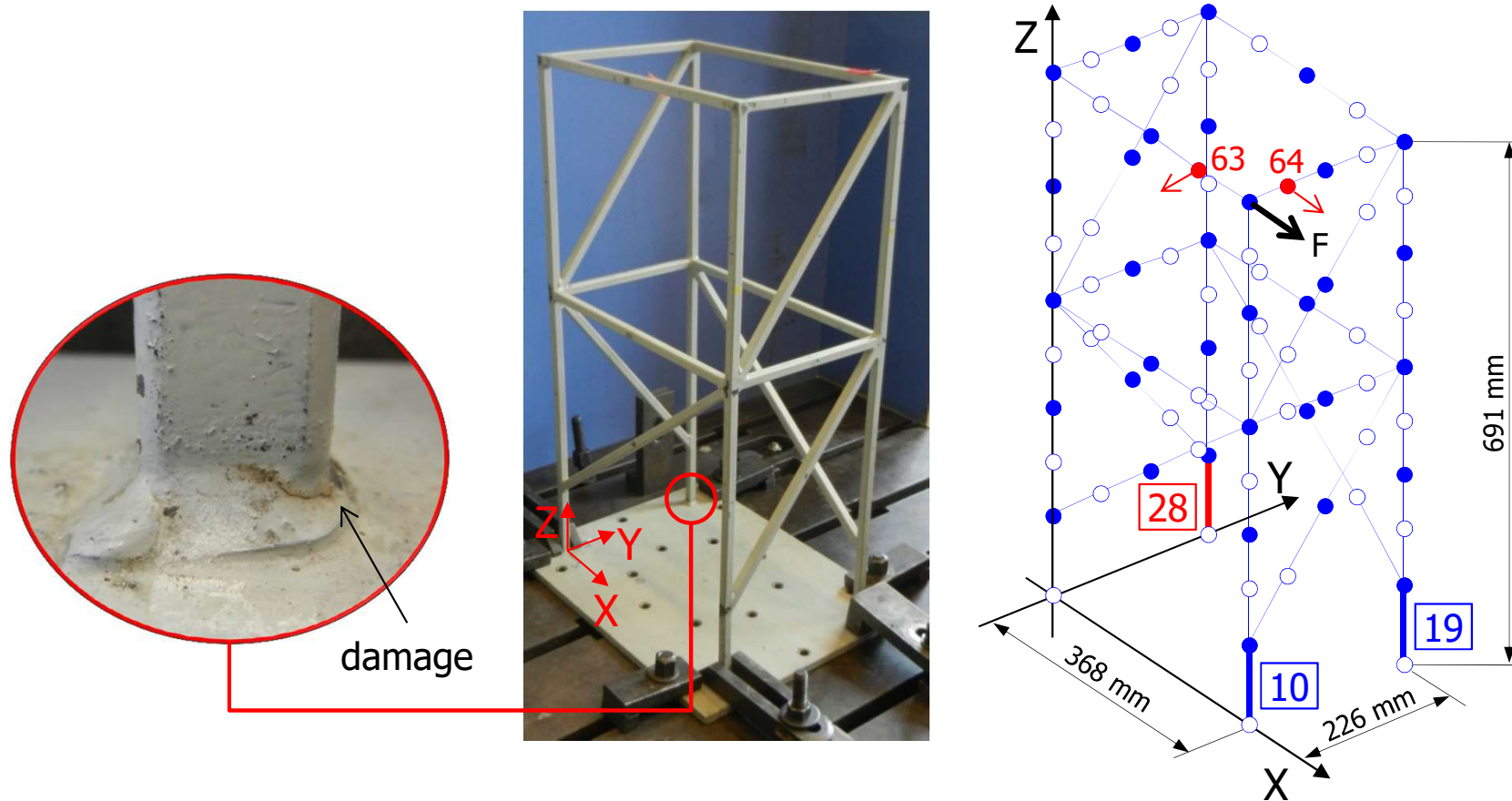
↓
define orthonormal bases



The angles θ_i between subspaces \mathbf{U}_h and \mathbf{U}_d are defined through the singular values associated to

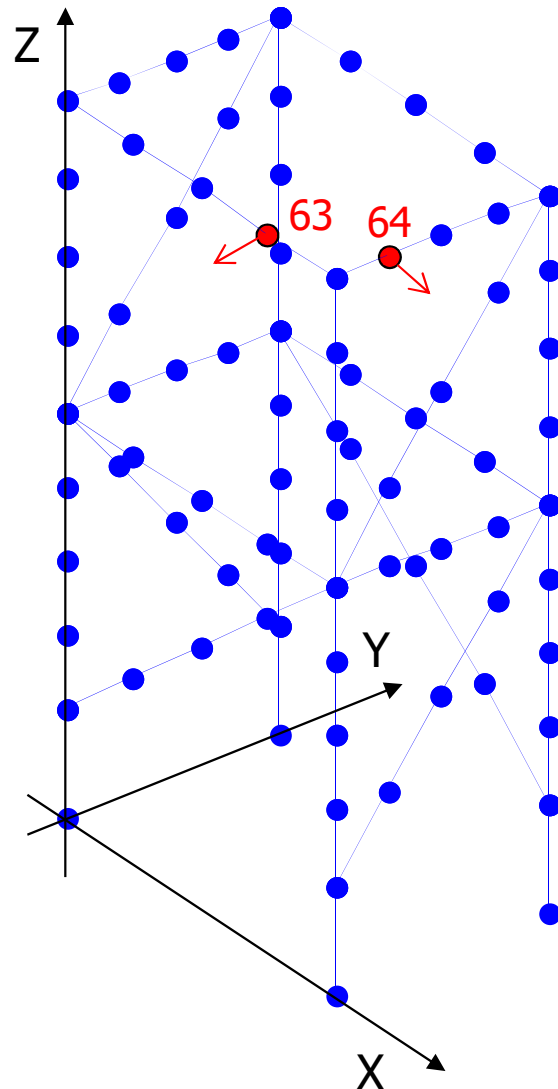
$$\mathbf{Q}_h^T \mathbf{Q}_d = \mathbf{U}_{hd} \boldsymbol{\Sigma}_{hd} \mathbf{V}_{hd}^T$$

$$\boldsymbol{\Sigma}_{hd} = \text{diag}(\cos \theta_i) \quad (i = 1, \dots, 2)$$



Presence of rust \rightarrow reduction of stiffness of 40 % of element 28

Measurement set-up

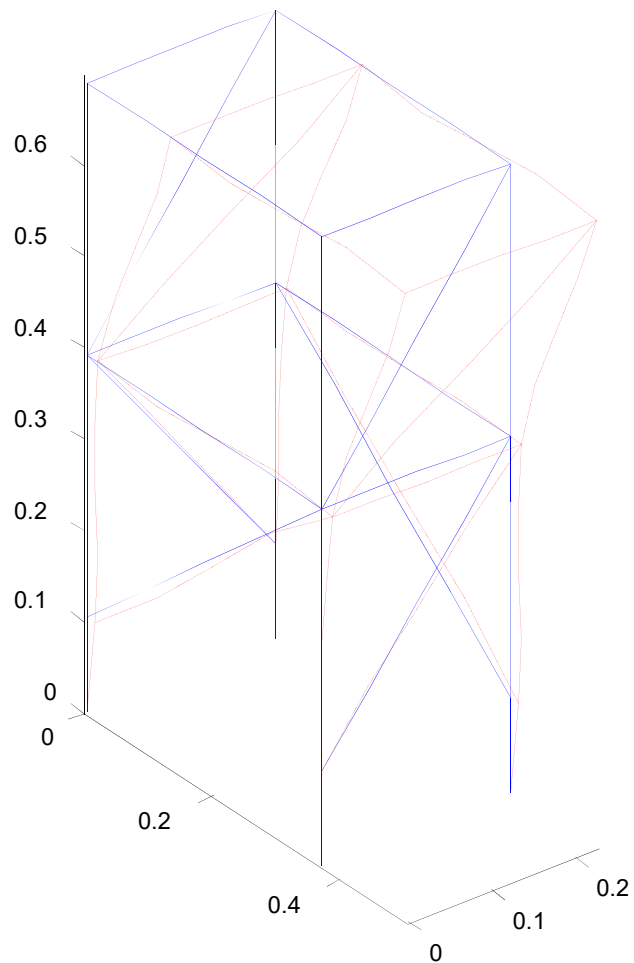


Impact excitation (roving hammer technique)

- Accelerometer at node 63 (Y) and at node 64 (X)
- Impact at 36 nodes in directions X and Y
- Frequency range: [0 - 400] Hz
- Resolution: 4096 lines \rightarrow 0.1 Hz
- Identification using the PolyMAX method

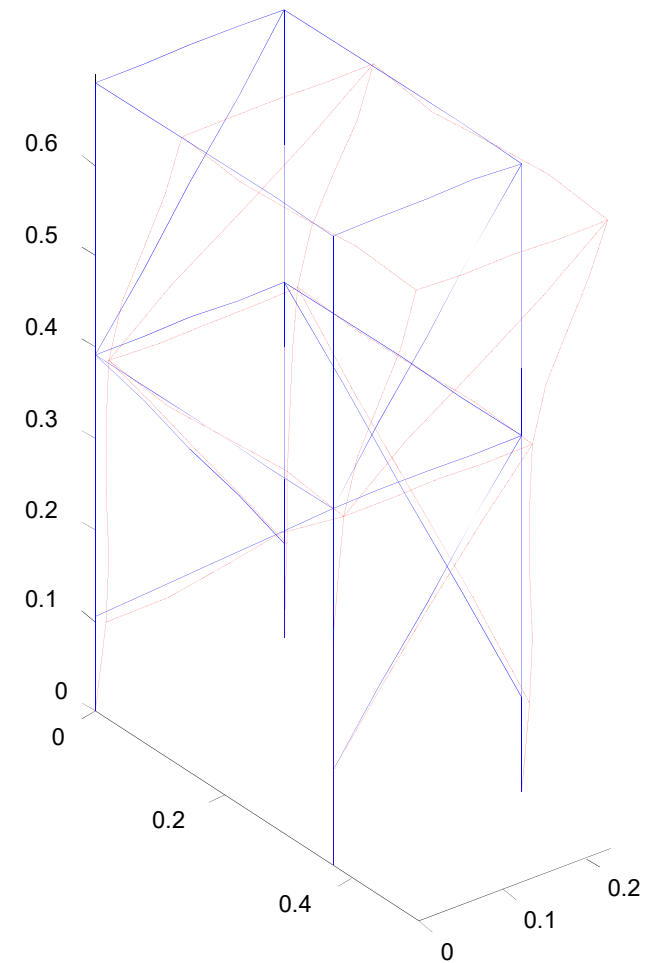
Healthy structure

FE Mode n° 1 (78.21 Hz)



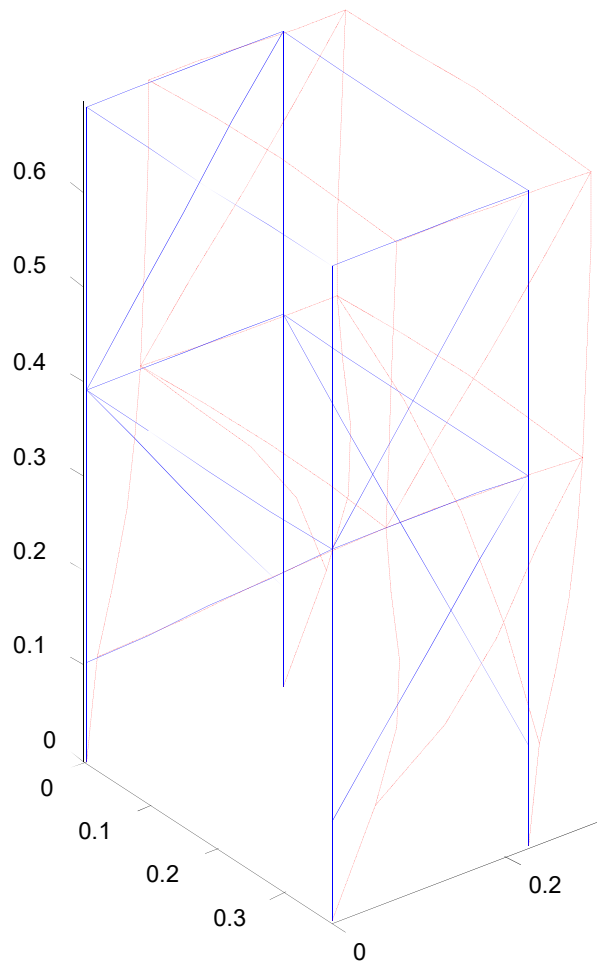
Damaged structure

Experimental mode n° 1 (77.50 Hz)



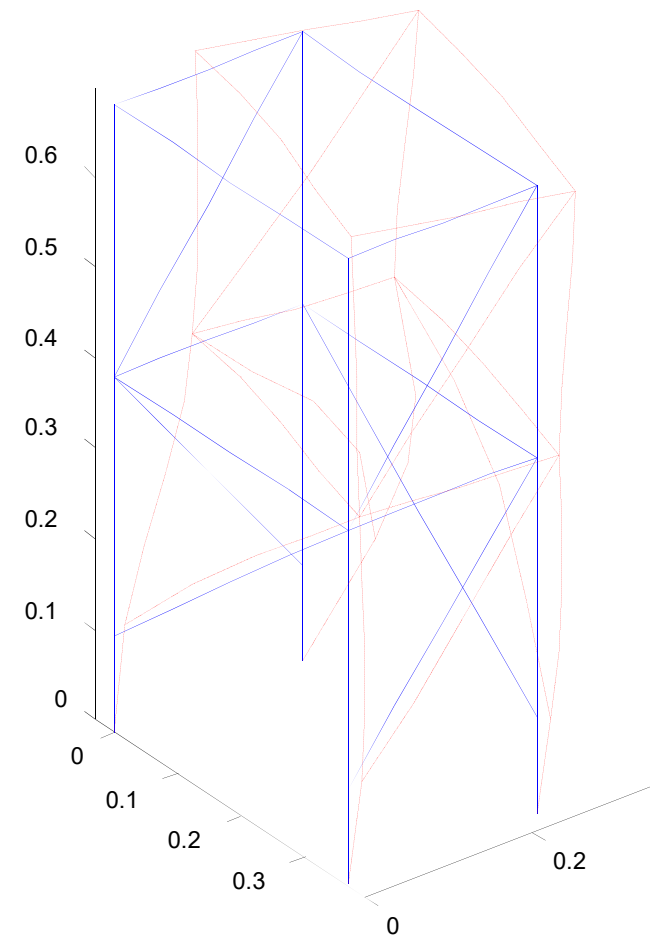
Healthy structure

FE mode n° 2 (124.59 Hz)



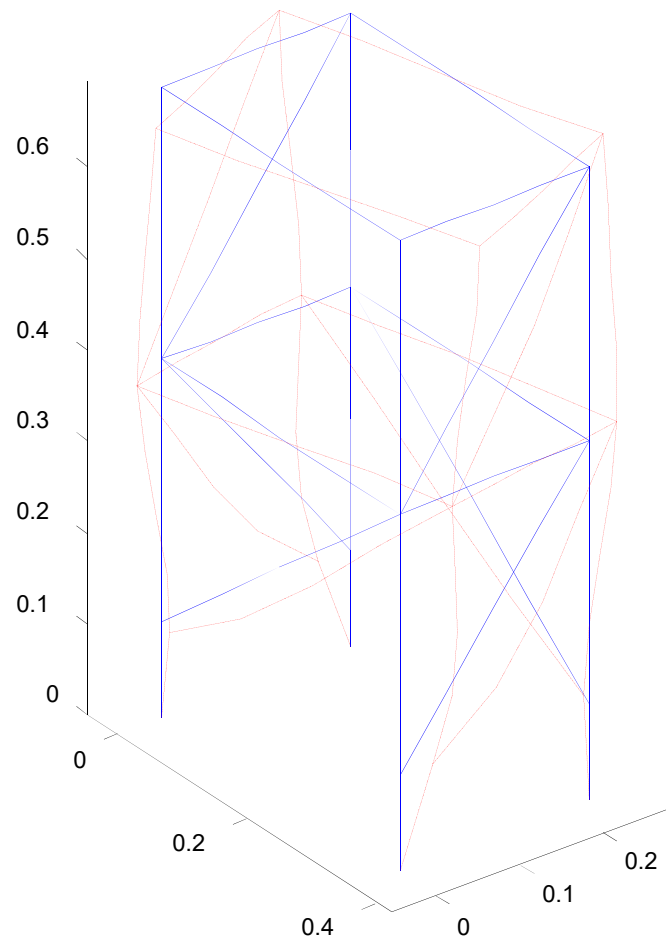
Damaged structure

Experimental mode n° 2 (113.95 Hz)



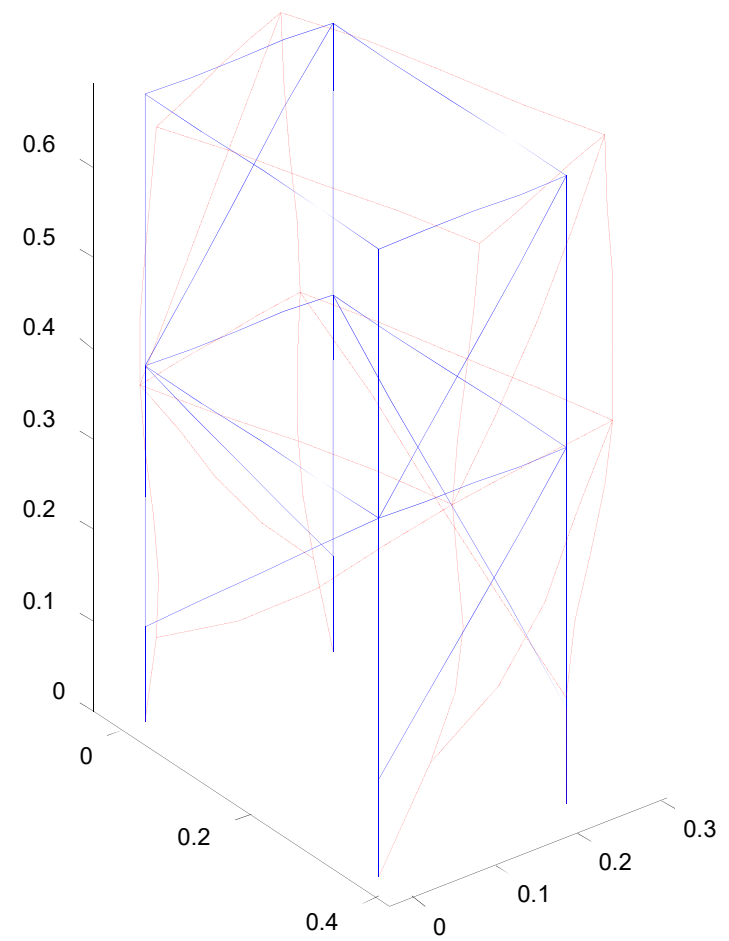
Healthy structure

FE mode n° 3 (137.66 Hz)



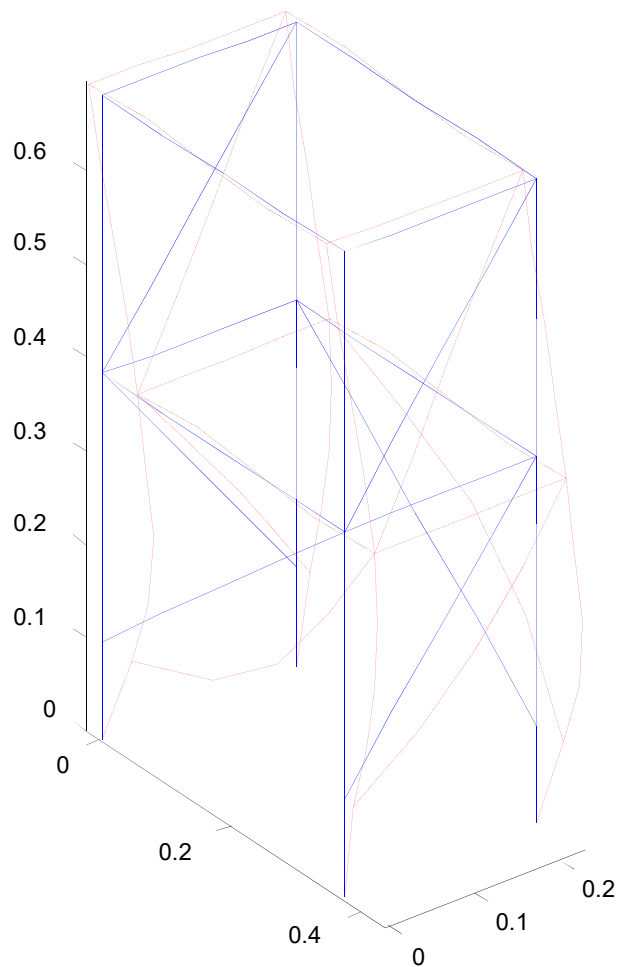
Damaged structure

Experimental mode n° 3 (136.10 Hz)



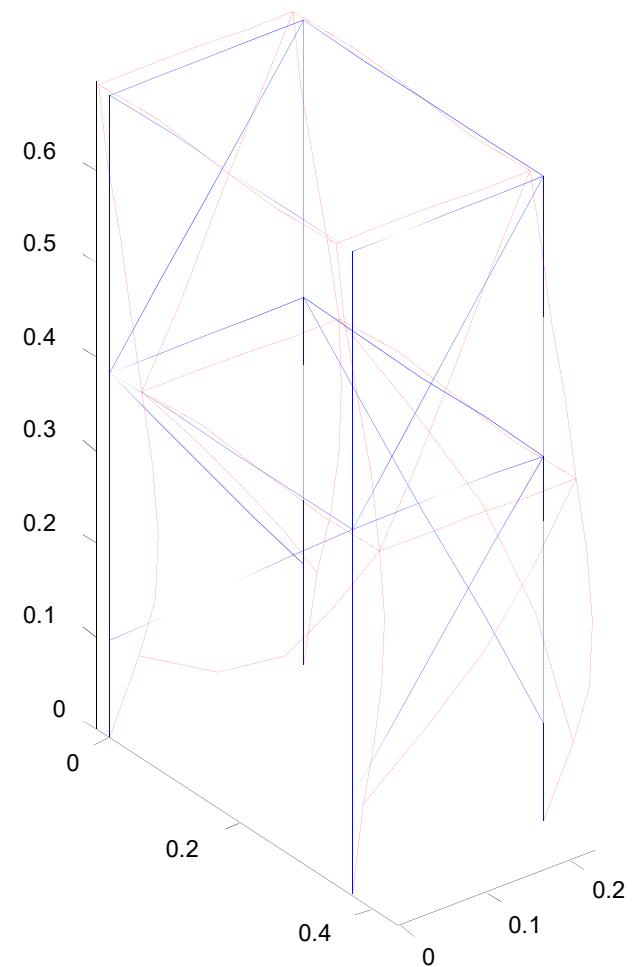
Healthy structure

FE mode n° 4 (160.19 Hz)

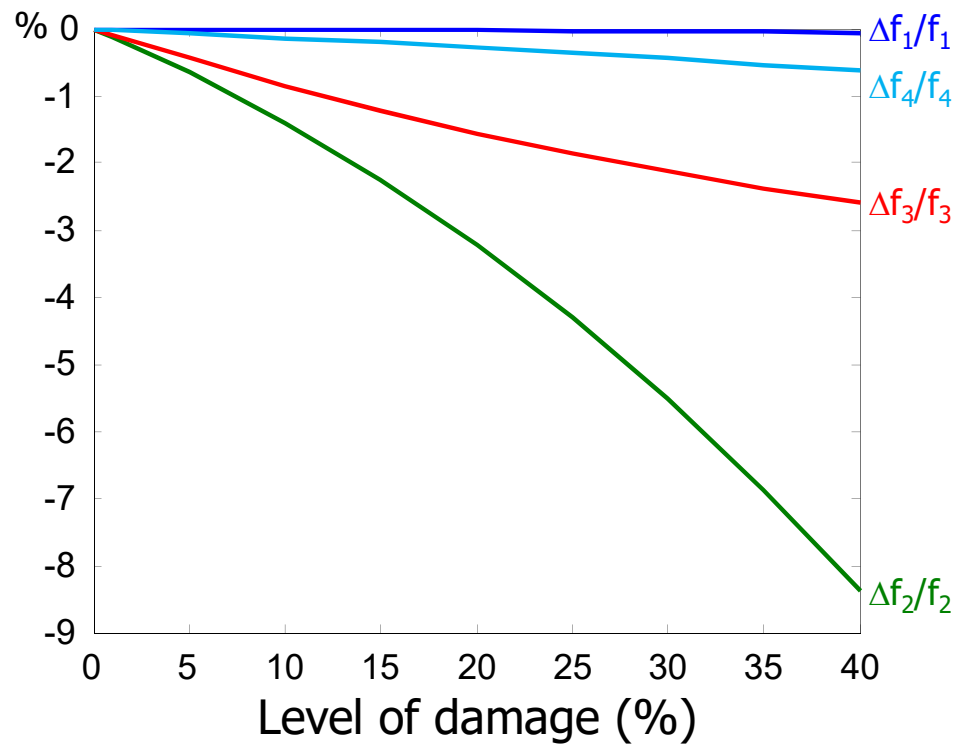


Damaged structure

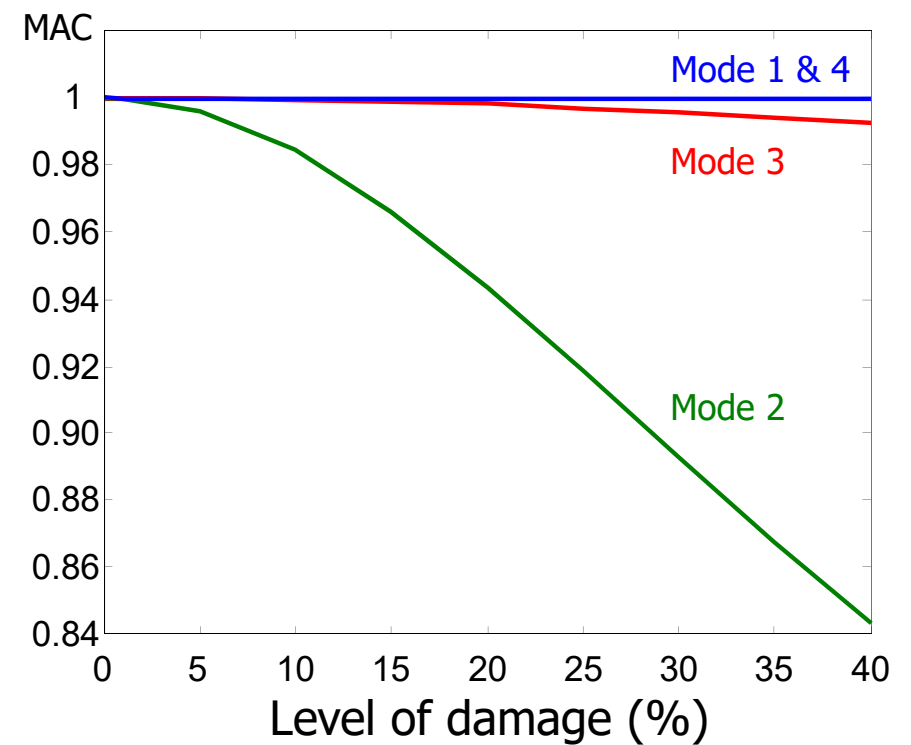
Experimental mode n° 4 (158.59 Hz)



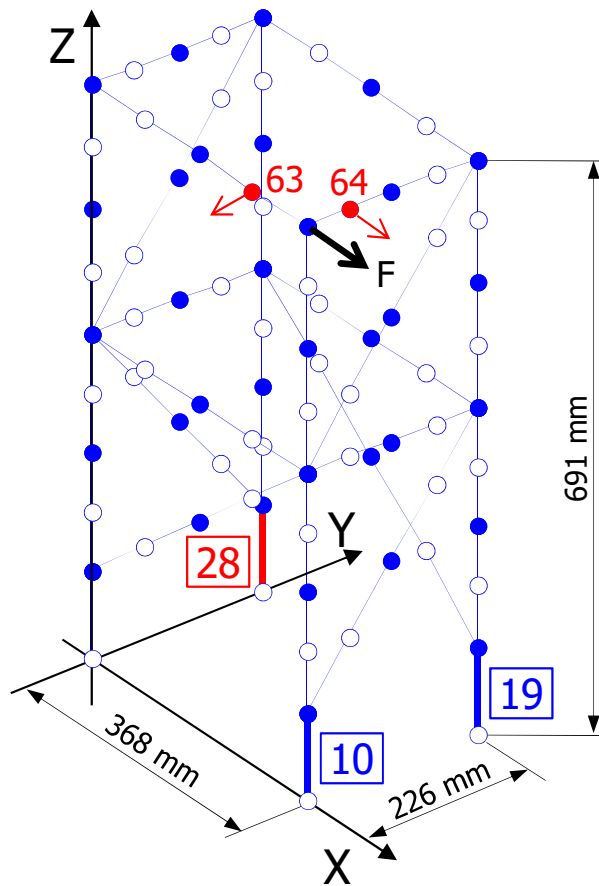
Relative error on natural frequencies



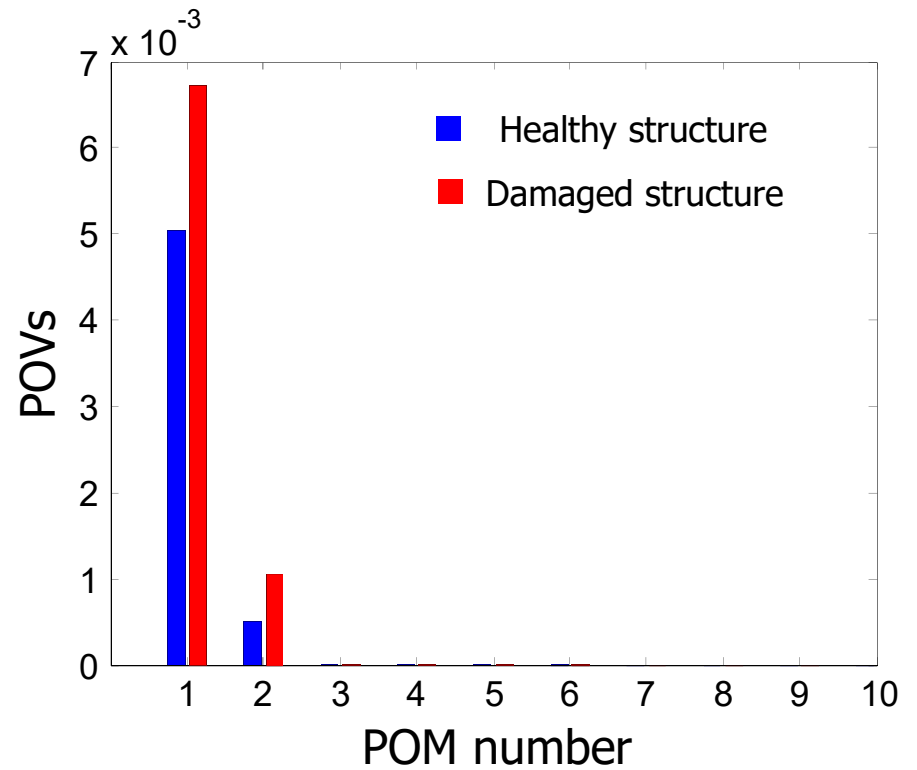
Modal Assurance Criterion



Harmonic force \mathbf{F} of 1 N at 130 Hz

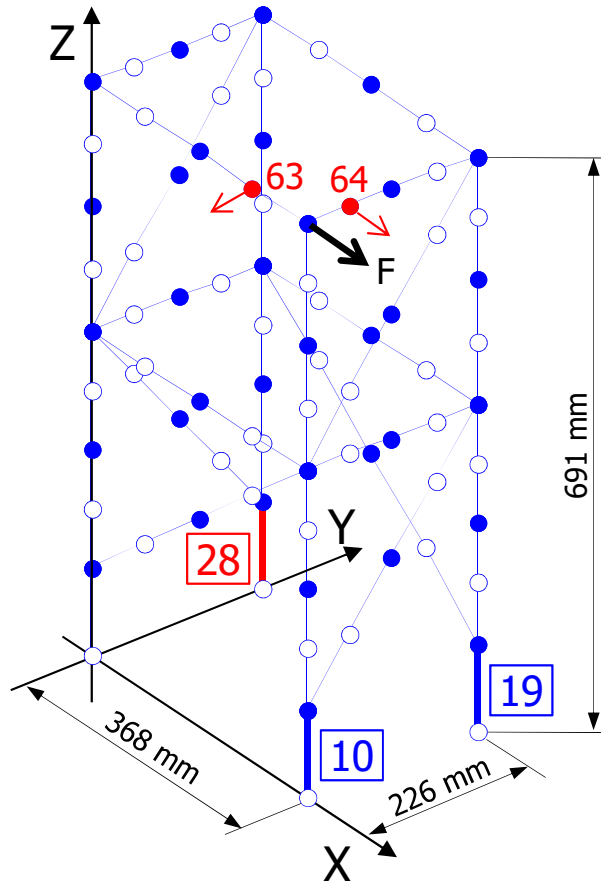


Proper orthogonal values

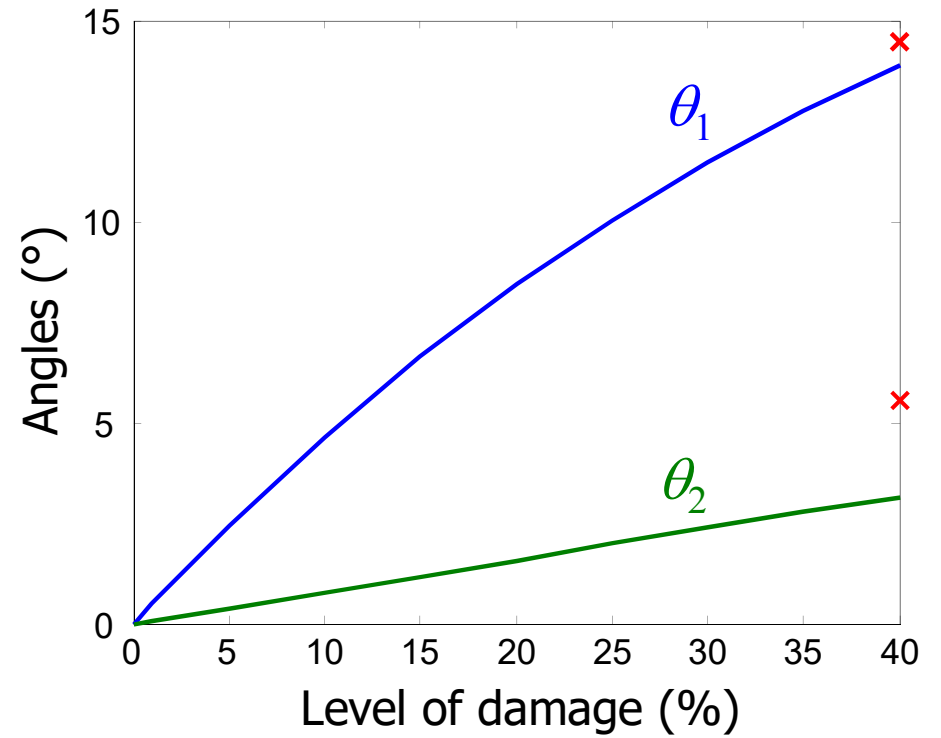


→ Presence of two POMs

Harmonic force \mathbf{F} of 1 N at 130 Hz



Detection of damage



The strain energy function may be used to localize damage.

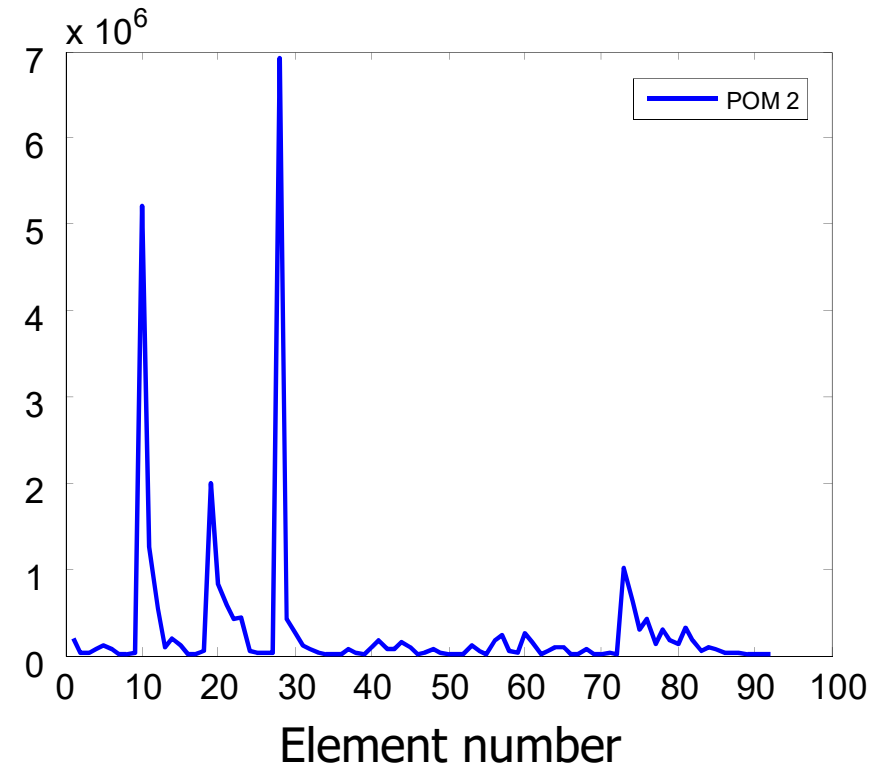
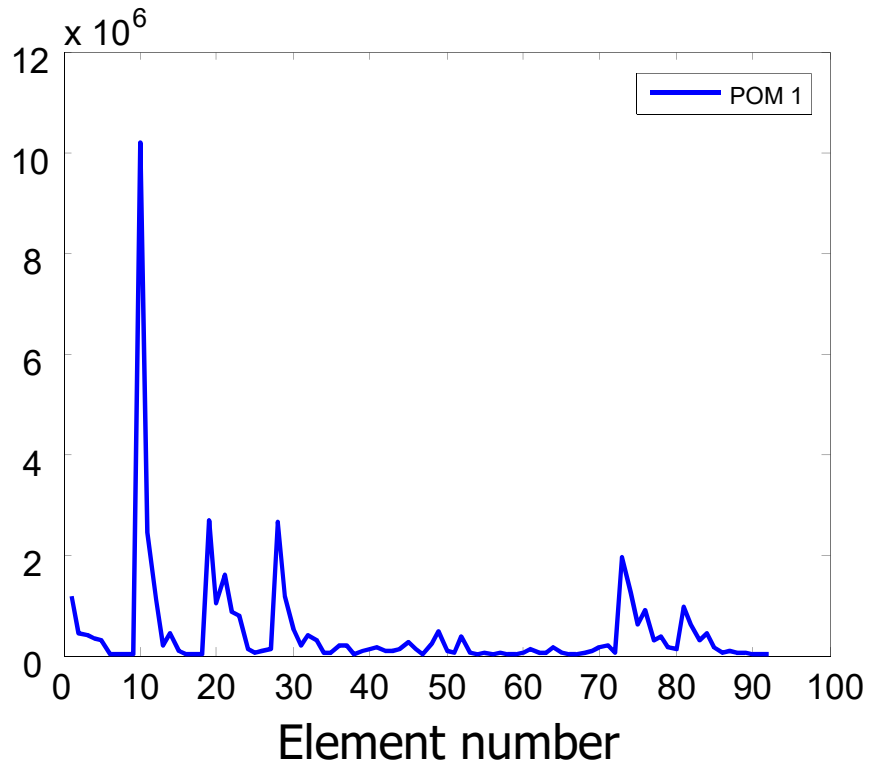
For the j^{th} element, it writes

$$\Delta E_{(k)}^j = \left(\mathbf{u}_{d,(k)}^j - \mathbf{u}_{h,(k)}^j \right)^T \mathbf{K}^j \left(\mathbf{u}_{d,(k)}^j - \mathbf{u}_{h,(k)}^j \right) \quad (k = 1, 2)$$

↓ stiffness matrix
↓
↓

↓ k^{th} POM (damaged structure)
↓ k^{th} POM (healthy structure)

Strain energy functions



- Use of PCA for damage detection problem in the case of harmonically excited structures
- Advantages:
- Direct processing of time-responses (EMA is not required).
- The damage indicator based on the concept of subspace angle is a global indicator (selection of modes is not required).
- The POMs are scaled by the excitation force → they can be interpreted as 'deformation modes' enabling damage localization.

Thank you for your attention.