

Chapter 8

Generally, the risk process is the stochastic process (S_t) representing the cumulative claim amounts, for the company, of a portfolio of (same kind of) contracts up to time t .

Risk process

- In this chapter, we will only need the r.v. S corresponding to the time interval $[0; 1]$. In the next chapter, we will use the generalization (S_t) .
- Individual model
 - Collective model
 - Comparison of the two models

Individual model

Definition and hypotheses

- Definition and hypotheses
- Probability distribution of the risk process
 - o Cumulative distribution function
 - o Moment generating function
 - o Moments
- Particular case : degenerated claim amounts
- Example

We consider here the portfolio as the sum of n independent risks (= contracts) Y_1, \dots, Y_n

For each risk (the j -th), the claim amount is a r.v.
and we define

$$\begin{aligned} p_j &= \Pr[0 \text{ claim}] \\ q_j &= 1 - p_j = \Pr[1 \text{ claim}] \end{aligned}$$

$$I_j \sim \begin{pmatrix} 0 & 1 \\ p_j & q_j \end{pmatrix}$$

Y_j = claim amount, conditionally to $[I_j = 1]$

Then,

$$S = I_1 Y_1 + \dots + I_n Y_n$$

with the hypothesis of independence of

$$I_1, \dots, I_n, Y_1, \dots, Y_n$$

Example of shape of the c.d.f. of $I_j Y_j$

Probability distribution of the risk process



Cumulative distribution function

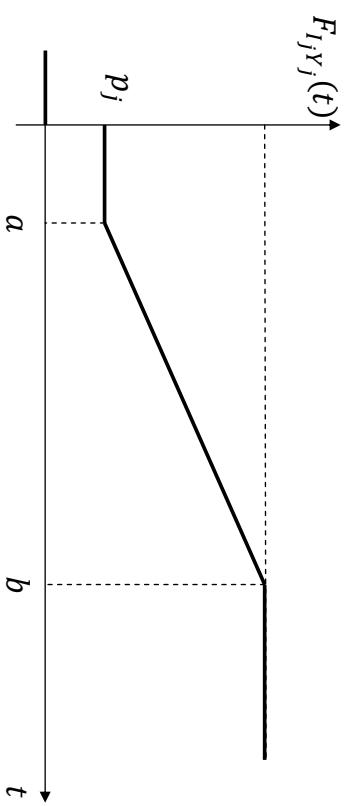
$$F_S(t) = (F_{I_1 Y_1} * \dots * F_{I_n Y_n})(t)$$

For $t \geq 0$,

$$F_{I_j Y_j}(t) = \Pr[I_j Y_j \leq t]$$

- the height of the jump at 0 is the probability that no claim occur
- M is the maximum intervention of the company

Example : if $Y_j \sim \mathcal{U}(a; b)$, then



Moment generating function

$$\begin{aligned}
 m_S(t) &= \prod_{j=1}^n m_{I_j Y_j}(t) \\
 &= \prod_{j=1}^n E(e^{t I_j Y_j}) \\
 &= \prod_{j=1}^n E(E(e^{t I_j Y_j} | I_j))
 \end{aligned}$$

But, for an ω such that

- $I_j(\omega) = 0$, then $E(e^{t I_j Y_j} | I_j) = 1$
- $I_j(\omega) = 1$, then $E(e^{t I_j Y_j} | I_j) = m_{Y_j}(t)$

$$m_S(t) = \prod_{j=1}^n (p_j + q_j m_{Y_j}(t))$$

Moments

$$E(S) = \sum_{j=1}^n E(I_j Y_j) = \sum_{j=1}^n q_j E(Y_j)$$

$$\text{var}(S)$$

$$\begin{aligned}
 &= \sum_{j=1}^n \text{var}(I_j Y_j) \\
 &= \sum_{j=1}^n \left\{ E(\text{var}(I_j Y_j | I_j)) + \text{var}(E(I_j Y_j | I_j)) \right\} \\
 &= \sum_{j=1}^n \left\{ E(I_j^2 \cdot \text{var}(Y_j | I_j)) + \text{var}(I_j \cdot E(Y_j | I_j)) \right\} \\
 &= \sum_{j=1}^n \left\{ E(I_j^2) \text{var}(Y_j) + \text{var}(I_j) E^2(Y_j) \right\} \\
 &= \sum_{j=1}^n \{q_j \text{var}(Y_j) + p_j q_j E^2(Y_j)\}
 \end{aligned}$$

$$\text{var}(S) = \sum_{j=1}^n q_j \{\text{var}(Y_j) + p_j E^2(Y_j)\}$$

Particular case : degenerated claim amounts

Example

If $Y_j \equiv y_j$ for any j ,

- c.d.f. : $F_{Y_j}(t) = \begin{cases} 0 & \text{if } t < y_j \\ 1 & \text{if } t \geq y_j \end{cases}$

Note : even in this particular case, convolutions are not easy to calculate : if $n = 2$ with $y_1 < y_2$,

$$S \sim \begin{pmatrix} 0 & y_1 & y_2 & y_1 + y_2 \\ p_1 p_2 & q_1 p_2 & p_1 q_2 & q_1 q_2 \end{pmatrix}$$

(Do it for $n = 5$)

- m.g.f. : $m_S(t) = \prod_{j=1}^n (p_j + q_j e^{ty_j})$

• moments

It is not easy to obtain c.d.f. or m.g.f. (possible values of S : $\{0, 100, 200, \dots, 4000\}$)

$$E(S) = \sum_{j=1}^n q_j y_j \quad \text{var}(S) = \sum_{j=1}^n p_j q_j y_j^2$$

$$E(S) = 395 \quad \text{var}(S) = 114475$$

N°	cat.	cl amount	q_j	p_j	$q_j y_j$	$p_j q_j y_j^2$
1	1	100	0,05	0,95	5	475
2	1	200	0,05	0,95	10	1900
3	1	200	0,05	0,95	10	1900
4	1	200	0,05	0,95	10	1900
5	1	300	0,05	0,95	15	4275
6	1	300	0,05	0,95	15	4275
7	2	300	0,10	0,90	30	8100
8	2	400	0,10	0,90	40	14400
9	2	400	0,10	0,90	40	14400
10	2	400	0,10	0,90	40	14400
11	3	200	0,15	0,85	30	5100
12	3	300	0,15	0,85	45	11475
13	3	300	0,15	0,85	45	11475
14	3	400	0,15	0,85	60	20400
			1,30		395	114475

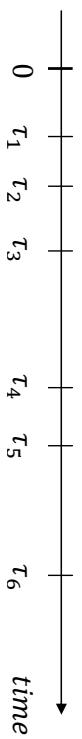
Collective model

Definition and hypotheses

- Definition and hypotheses
- Probability distribution of the risk process
 - o Cumulative distribution function
 - o Moment generating function
 - o Moments
 - Panjer's recursion formula
 - Other distributions ?

The claims are no more generated individually :
they are generated by the portfolio during the
time interval

Occurrences of claim is a counting process



N (N_t in the general case) = number of claims
during 1 year

X_j = claim amount for the claim occurring at τ_j

Then,

$$S = X_1 + \dots + X_N$$

where

- X_1, X_2, \dots are i.i.d. r.v.
- N is independent of the X_k 's

Such a process is a compound counting process

- N : claim frequency
- X : severity of the claim

Cumulative distribution function

Various conditions can affect these factors in different ways :

- seat belt : affects more X than N
- daytime headlights : affects more N than X

So, in practice,

- study the two components separately
- put them together in the model

Moment generating function

$$\begin{aligned}m_S(t) &= m_N(\ln m_X(t)) \\&= e^{\lambda(e^{\ln m_X(t)} - 1)} \\&= e^{\lambda(m_X(t) - 1)}\end{aligned}$$

Additional hypothesis : the counting process is a Poisson process with parameter λ

Moments

$$E(S) = E(N) \cdot E(X) = \lambda E(X)$$

The risk process is then a compound Poisson process

$$\begin{aligned}\text{var}(S) &= E(N) \cdot \text{var}(X) + \text{var}(N) \cdot E^2(X) \\&= \lambda E(X^2)\end{aligned}$$

Probability distribution of the risk process

Panjer's recursion formula

Proof for $s = 0$

The probability distribution of S is again not easy to calculate, because of convolutions

Solution for the case where the possible values of the X_k 's are positive integers : Panjer's formula

$$\Pr[S = 0] = \exp\{-\lambda(1 - \Pr[X = 0])\}$$

and, for $s \in \mathbb{N}_0$,

$$\begin{aligned} \Pr[S = s] &= \sum_{k=0}^{\infty} \Pr([S = 0] \mid [N = k]) \Pr[N = k] \\ &= \sum_{k=0}^{\infty} \Pr([X_1 + \dots + X_k = 0] \mid [N = k]) \\ &\quad \cdot \Pr[N = k] \\ &= \sum_{k=0}^{\infty} \Pr[X_1 + \dots + X_k = 0] \Pr[N = k] \\ &= \sum_{k=0}^{\infty} (\Pr[X = 0])^k e^{-\lambda} \frac{\lambda^k}{k!} \\ &= \exp\{-\lambda(1 - \Pr[X = 0])\} \end{aligned}$$

Proof for $s \geq 1$

$$\Pr[S = s] = \sum_{j=1}^s j \cdot \frac{\Pr([X_1 = j] \cap [X_2 + \dots + X_k = s - j])}{\Pr[X_1 + \dots + X_k = s]}$$

$$\Pr[S = s]$$

$$= \sum_{k=0}^{\infty} \Pr([S = s] | [N = k]) \Pr[N = k]$$

$$= \sum_{k=0}^{\infty} \Pr([S = s] | [N = k]) \Pr[N = k]$$

\bullet

$$= \sum_{k=1}^{\infty} \Pr([X_1 + \dots + X_k = s] | [N = k])$$

$$\cdot \Pr[N = k]$$

$$= \sum_{k=1}^{\infty} \Pr[X_1 + \dots + X_k = s] \Pr[N = k]$$

\bullet

But, for $i \in \{1, \dots, k\}$

$$E(X_i | [X_1 + \dots + X_k = s])$$

$$= s/k$$

$$= \sum_{j=1}^s j \cdot \Pr([X_1 + \dots + X_k = s] | [X_1 + \dots + X_{k-1} = s - j])$$

and

$$\Pr[X_1 + \dots + X_k = s]$$

$$= \frac{k}{s} \sum_{j=1}^s j \cdot \Pr[X = j] \cdot \Pr[X_1 + \dots + X_{k-1} = s - j]$$

Then,

$$\Pr[S = s]$$

$$= \sum_{k=1}^{\infty} \frac{k}{s} \sum_{j=1}^s j \cdot \Pr[X = j]$$

$$\cdot \Pr[X_1 + \dots + X_{k-1} = s - j] \cdot \Pr[N = k]$$

$$= \frac{1}{s} \sum_{j=1}^s j \cdot \Pr[X = j]$$

$$\cdot \sum_{k=1}^{\infty} \Pr[X_1 + \dots + X_{k-1} = s - j] e^{-\lambda} \frac{\lambda^k}{(k-1)!}$$

Other probability distributions ?

$$= \frac{\lambda}{s} \sum_{j=1}^s j \cdot \Pr[X = j]$$

In the original counting process

$$\begin{aligned} & \cdot \sum_{k=1}^{\infty} \Pr[X_1 + \cdots + X_{k-1} = s-j] \\ & \cdot \Pr[N = k-1] \end{aligned}$$

$$= \frac{\lambda}{s} \sum_{j=1}^s j \cdot \Pr[X = j]$$

$$\sum_{j=1}^{\infty} \Pr[X_1 + \cdots + X_k = s-j] \cdot \Pr[N = k]$$

$$= \frac{\lambda}{s} \sum_{j=1}^s j \cdot \Pr[X = j]$$

The Poisson distribution is characterized by the fact that

$$E(N) = \text{var}(N) \quad (= \lambda)$$

Sometimes, because of the heterogeneity of risks, we have $\text{var}(N) > E(N)$

It is then possible to use mixed Poisson r.v.

- Λ is a positive r.v.
- Conditionally to $[\Lambda = \lambda]$, $N \sim \mathcal{P}(\lambda)$

- Probability distribution : for $k \in \mathbb{N}$,

$$\begin{aligned} \Pr[N = k] &= E(\Pr([N = k] | \Lambda)) \\ &= \int_0^{+\infty} \Pr([N = k] | [\Lambda = \lambda]) dF_\Lambda(\lambda) \\ &= \int_0^{+\infty} e^{-\lambda} \frac{\lambda^k}{k!} dF_\Lambda(\lambda) \end{aligned}$$

- Moment generating function

$$\begin{aligned}
 m_N(t) &= E(e^{tN}) \\
 &= E(E(e^{tN} | \Lambda)) \\
 &= E(e^{\Lambda(e^t - 1)}) \\
 &= m_\Lambda(e^t - 1)
 \end{aligned}$$

- Moments

$$E(N) = E(E(N|\Lambda))$$

$$= E(\Lambda)$$

$$\text{var}(N) = E(\text{var}(N|\Lambda)) + \text{var}(E(N|\Lambda))$$

$$= E(\Lambda) + \text{var}(\Lambda)$$

Note 1 : $\text{var}(N) > E(\Lambda) = E(N)$

and, for $s \in \mathbb{N}_0$,

$$\begin{aligned}
 \Pr[S = 0] &= \Pr[N = 0] && \text{if } \Pr[X = 0] = 0 \\
 &= \begin{cases} \Pr[N = 0] & \text{if } \Pr[X = 0] > 0 \\ m_N(\ln(\Pr[X = 0])) & \text{if } \Pr[X = 0] = 0 \end{cases}
 \end{aligned}$$

Note 2

- If Λ degenerated ($\Lambda \equiv \lambda$), then $N \sim \mathcal{P}(\lambda)$
- If $\Lambda \sim \text{gamma}$, then $N \sim \text{negative binomial}$
- If $\Lambda \sim \text{exponential}$, then $N \sim \text{geometric}$

Thanks to Panjer's formula

The Poisson distribution is such that

$$\Pr[N = k] = e^{-\lambda} \frac{\lambda^k}{k!} = \frac{\lambda}{k} \Pr[N = k - 1]$$

In fact, Panjer's formula may be generalized for any distribution such that

$$\Pr[N = k] = \left(a + \frac{b}{k} \right) \cdot \Pr[N = k - 1]$$

$$\begin{aligned}
 \Pr[S = s] &= \frac{1}{1 - a \cdot \Pr[X = 0]} \\
 &\cdot \sum_{j=1}^s \left(a + \frac{bj}{s} \right) \cdot \Pr[X = j] \cdot \Pr[S = s - j]
 \end{aligned}$$

- If $a = 0$ and $b = \lambda (> 0)$, then $N \sim \mathcal{P}(\lambda)$

- If $a = 1 - p$ and $b = (1 - p)(r - 1)$ with $0 < p < 1$ and $r \in \mathbb{N}_0$, then $N \sim \mathcal{NB}(r; p)$

- If $a = \frac{-p}{1-p}$ and $b = \frac{p(n+1)}{1-p}$ with $0 < p < 1$ and $n \in \mathbb{N}_0$, then $N \sim \mathcal{B}(n; p)$

Comparison of the two models

- Quality of modeling
- Comparison of the two probability laws
 - Principle
 - Expected values
 - Variances
- Example

Quality of modeling

Comparison of the two probability laws

- Individual model is concerned by situations where only 0 or 1 claim occur during the time interval

- o No problem for life insurance

- o For non-life insurance, the model is wrong, except if the claim probability is such that $\Pr[\geq 2 \text{ claims for one risk}]$ is negligible

- Collective model is adaptable to much more situations

- The collective model is easier to handle, thanks to Panjer's formula

Principle

We identify the two first moments of

- X for the collective model
- the weighted average of the Y_j 's for the individual model

$$E(X^k) = E\left(\sum_{j=1}^n \frac{q_j}{\sum q_i} Y_j^k\right) \quad (k = 1, 2)$$

Expected values

$$\begin{aligned} E(S^{coll}) &= \lambda E(X) \\ &= \lambda E\left(\sum_j \frac{q_j}{\sum q_i} Y_j\right) \\ &= \frac{\lambda}{\sum q_i} \sum_j q_j E(Y_j) \\ &= \frac{\lambda}{\sum q_i} E(S^{ind}) \\ &= \sum_j q_j E(Y_j^2) \\ &= \sum_j q_j \{var(Y_j) + E^2(Y_j)\} \\ &> \sum_j q_j \{var(Y_j) + p_j E^2(Y_j)\} \\ &= var(S^{ind}) \end{aligned}$$

The two models are linked by the relation

$$\lambda = \sum_{j=1}^n q_j$$

The collective model is more “careful” because of its greater dispersion

Variances

Example

By Panjer's formula,

With the same data (portfolio with 14 risks)

N°	cat.	cl amount	q_i	p_j	$q_i y_j$	$p_j q_i y_j^2$
1	1	100	0,05	0,95	5	475
2	1	200	0,05	0,95	10	1900
3	1	200	0,05	0,95	10	1900
4	1	200	0,05	0,95	10	1900
5	1	300	0,05	0,95	15	4275
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7	2	300	0,10	0,90	30	8100
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9	2	400	0,10	0,90	40	14400
10	2	400	0,10	0,90	40	14400
11	3	200	0,15	0,85	30	5100
12	3	300	0,15	0,85	45	11475
13	3	300	0,15	0,85	45	11475
14	3	400	0,15	0,85	60	20400
			1,30		395	114475

We have $\lambda = \sum q_i = 1,3$

$$X \sim \begin{pmatrix} 100 & 200 & 300 & 400 \\ 0,0385 & 0,2308 & 0,3846 & 0,3462 \end{pmatrix}$$

e.g.

$$\Pr[X = 200] = \frac{3 \cdot 0,05 + 0,15}{1,3} = 0,2308$$

Distribution du coût cumulé des sinistres

