

# Implementation of the blade element theory to investigate the aerodynamic performance of a ducted fan UAV

A. Guissart, D. Arendt,  
V. Terrapon & T. Andrianne

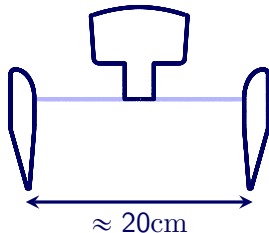
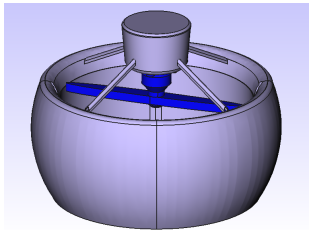
University of Liege

March 19, 2015

1<sup>st</sup> Workshop of  
Belgian OpenFOAM users

# Motivation

**FLEYE: micro UAV intended for safe aerial photography**



- Study aerodynamics
- Increase generated thrust
- Optimize geometry

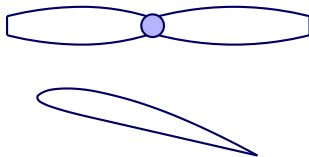
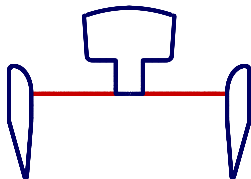
**Use of CFD to test quickly  
different geometries**

# How to model the propeller ?

Should be easy and fast



**Fan is modeled using  $\Delta p$**



$\Delta p$  should be linked to  
**blades characteristics**

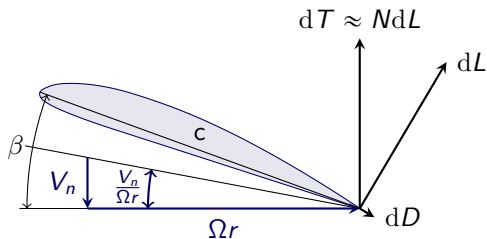
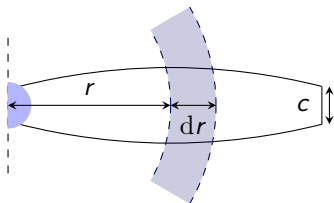
⇒ geometry:  $c$ ,  $\beta$ ,  $N$

⇒ aerodynamics:  $a$ ,  $\alpha_{L_0}$

⇒ **Use Blade Element Theory**

# What is BET?

$$dA = 2\pi r dr$$



$$c_l = a \left( \beta - \frac{V_n}{\Omega r} - \alpha_{L_0} \right)$$

$$dT \approx \frac{1}{2} c_l \rho N (\Omega r)^2 dS$$

$$\Delta p(r) = \frac{dT}{dA} = \frac{\rho N a c}{4\pi} ([\beta - \alpha_{L_0}] \Omega^2 r - V_n \Omega)$$

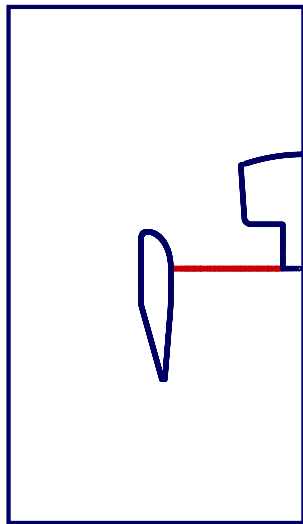
# BET in OF framework

$$\Delta p(r) = \frac{\rho N a c}{4\pi} ([\beta - \alpha_{L_0}] \Omega^2 r - V_n \Omega)$$

## **New boundary condition based on fan**

- ⇒ Blade characteristics are input given as  $\sum a_i r^i$
- ⇒ Normal velocity  $V_n$  is computed by the solver
- ⇒  $\Delta p = 0$  if negative or in recirculation

# Modelization of the UAV



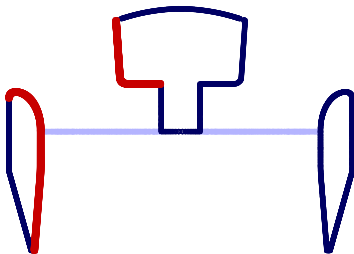
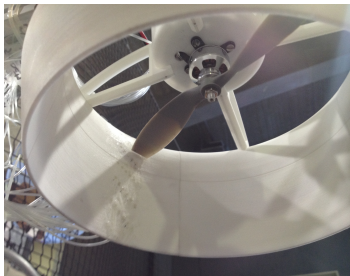
## CFD model

- Use of axisymmetry
- Steady solver simpleFoam
- Turbulence model  $k - \omega$  SST

## Model for propeller

- $c$ ,  $a$  and  $\alpha_{L_0}$  constant along  $r$
- $\beta(r)$  determined from pitch
- Different RPM are tested

# Experimental setup

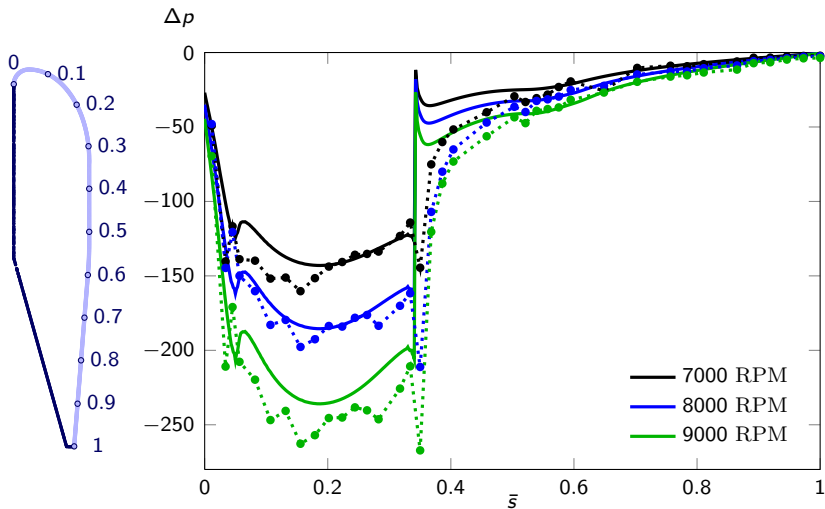


## Validation of CFD

- Total forces
- Pressure along duct
- Pressure along hub

# Comparison CFD-experiments

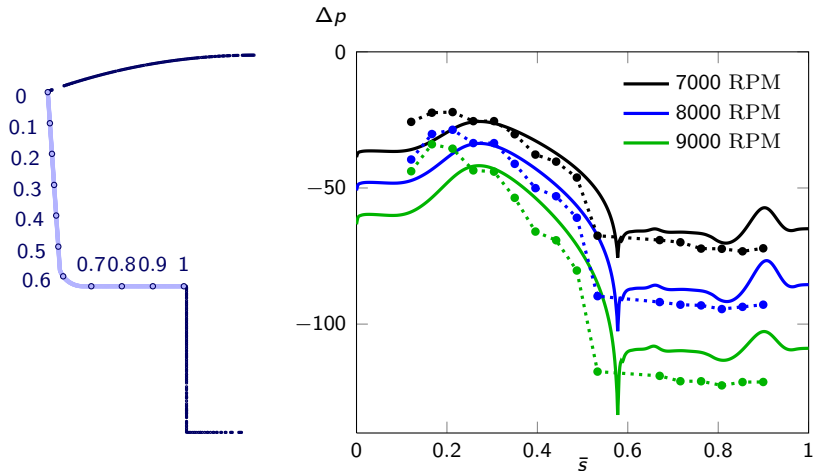
Relative pressure along the duct





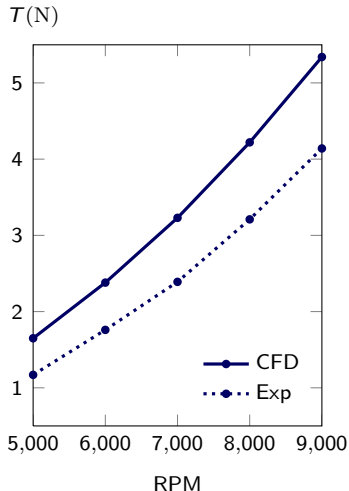
# Comparison CFD-experiments

Relative pressure along the hub



# Comparison CFD-experiments

## Total thrust



## Conclusions of validation

### Pressure along the duct and hub

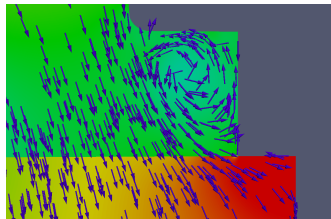
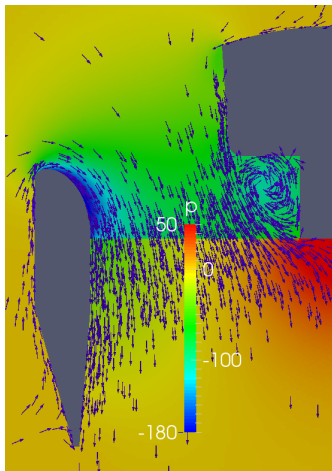
- Well approximated < 15%
- Variation with RPM
- Discrepancies at tip clearance
- Differences near the motor

### Total forces

- Variation with RPM
- Higher error < 30%
- Should come from propeller

# Comparison CFD-experiments

## Model validity



$$\Delta p(r) = \frac{\rho N a c}{4\pi} \left( [\beta - \alpha_{L_0}] \Omega^2 r - V_n \Omega \right)$$

### Zone near root of the propeller

- Low  $V_n$  due to incidence
- High  $\Delta p$  due to recirculation

⇒ **BET fails in this zone**

# Conclusions

## **BET leads to discrepancies**

- In recirculation zone
- With absolute thrust

## **However BET is able to**

- Provide a good estimation of pressure
- Determine evolution of relative thrust with RPM

## **This implementation of BET enables**

- **Fast simulations with physical parameters**
- **Optimization of the UAV geometry**