

ON A MODIFIED BILINEAR LAW TO MODEL BIT/ROCK INTERACTION IN PERCUSSIVE DRILLING

A. Depouhon, V. Denoël, E. Detournay

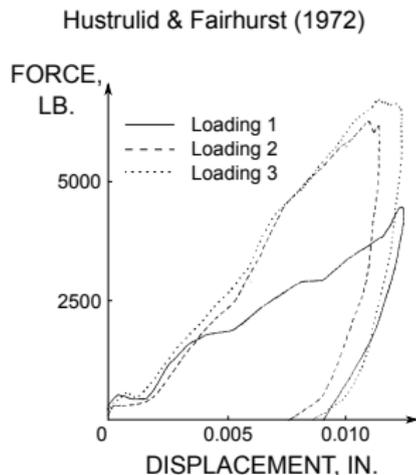
Université de Liège (Belgium)
University of Minnesota (USA)

Nonlinear Dynamics in Engineering
Aberdeen, August 21, 2013

BIT/ROCK INTERACTION: SINGLE IMPACT

Experimental facts

- Multiple failure mechanisms
 - Indentation & crushing
 - Chipping
- 2 main phases
 - Loading (\sim compression)
 - Unloading (\sim expansion)
- Rate-independent

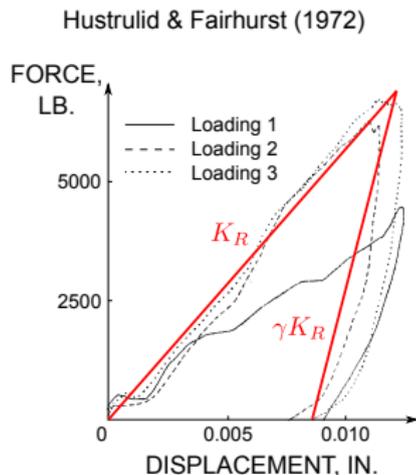


→ FORCE/PENETRATION \sim BILINEAR LAW: (K_R, γ)

BIT/ROCK INTERACTION: SINGLE IMPACT

Experimental facts

- Multiple failure mechanisms
 - Indentation & crushing
 - Chipping
- 2 main phases
 - Loading (\sim compression)
 - Unloading (\sim expansion)
- Rate-independent



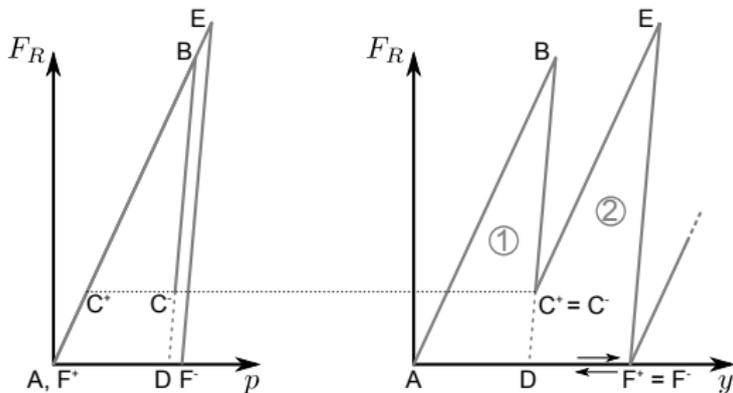
→ FORCE/PENETRATION \sim BILINEAR LAW: (K_R, γ)

BIT/ROCK INTERACTION: REPEATED IMPACTS

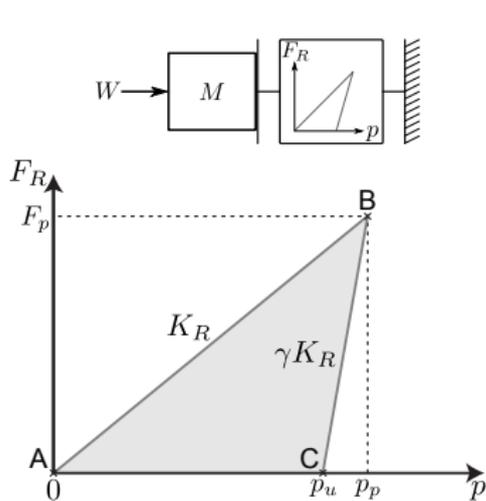
- Hyp: bilinear law holds

- Need: penetration definition

$$p^{(n)}(t) = y(t) - y_\ell^{(n)} + \frac{F_{R,\ell}^{(n)}}{K_R} \rightarrow F_R^{(n)}(t) = \begin{cases} K_R p^{(n)}(t) & \text{forward cont.} \\ \gamma K_R (p^{(n)}(t) - p_u^{(n)}) & \text{backward cont.} \\ 0 & \text{free flight} \end{cases}$$



ANALYSIS OF THE DRILLING CYCLE



$$p_p = \frac{W}{K_R} \left(1 + \sqrt{1 + \frac{K_R}{W} \frac{M \dot{p}_\ell^2}{W}} \right)$$

$$p_u = \frac{\gamma - 1}{\gamma} p_p$$

$$\dot{p}_u = -\frac{1}{\sqrt{\gamma}} \dot{p}_\ell$$

$$T = \sqrt{\frac{M}{K_R}} \left(1 + \frac{1}{\sqrt{\gamma}} \right) \left(\frac{\pi}{2} + \arccos \frac{\dot{p}_\ell}{\sqrt{\dot{p}_\ell^2 + \frac{W^2}{K_R M}}} \right)$$

Learnings

- ~~BC, FF~~ at the limit $\gamma \rightarrow \infty$
- Need to discern static from dynamic indentation

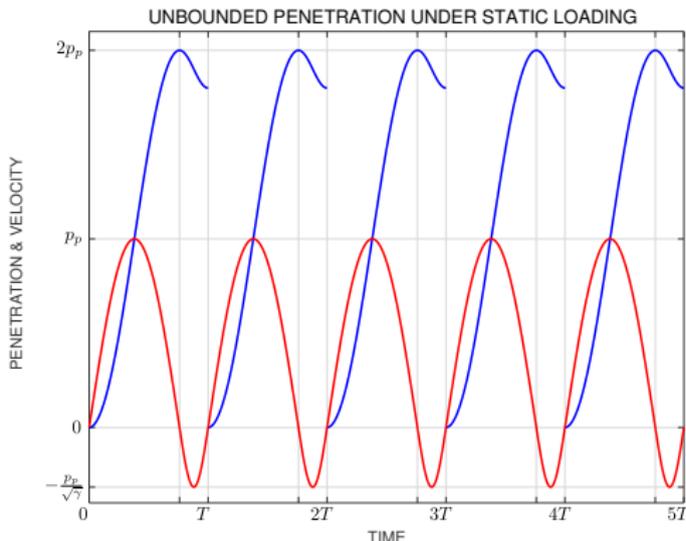
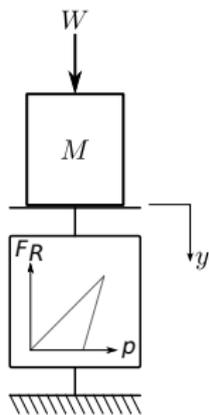
$$\begin{aligned} \Delta K &= M \frac{\dot{p}_2^2 - \dot{p}_1^2}{2} \\ &= W(p_2 - p_1) - W_{F_R}^{1 \rightarrow 2} \end{aligned}$$

$$p_\ell = \dot{p}_\ell = 0 \rightarrow (p_u, \dot{p}_u) = (2W/K_R, 0)$$

BIT/ROCK INTERACTION: RATE-INDEPENDENCE

Domain of validity

- Upper bound: $\dot{p} < c_0$, verified in practice
- Lower bound: static vs. dynamic, requires adjustment of BRI (no \Rightarrow)



BIT/ROCK INTERACTION: RATE-INDEPENDENCE

Domain of validity

- Upper bound: $\dot{p} < c_0$, verified in practice
- Lower bound: static vs. dynamic, requires adjustment of BRI (no \Rightarrow)

→ Introduce energy barrier & instantaneous dissipation

Definition

At the beginning of a drilling cycle, part of the bit kinetic energy is instantaneously dissipated by fast processes, e.g. wave radiation

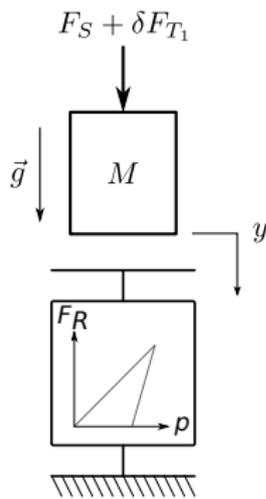
$$\dot{y}_\ell^+ = \begin{cases} 0 & \text{if } \frac{1}{2}M (\dot{y}_\ell^-)^2 \leq E_\ell^k \\ \sqrt{(\dot{y}_\ell^-)^2 - 2E_\ell^k/M} & \text{otherwise} \end{cases}$$

In accordance with Lundberg and Okrouhlik (2006): $\mathcal{O}(5)\%$ of percussive energy is dissipated by radiation

BIT DYNAMICS: IMPACT OSCILLATOR

Timescales

- T_1 : Percussive activation period $\rightarrow \mathcal{O}(50)\text{ms}$
- T_2 : Percussive impact duration $\rightarrow \mathcal{O}(1)\text{ms}$
- T_3 : Drilling cycle duration $\rightarrow T_1 > T_3 > T_2$
 $T_3 \sim \sqrt{\frac{M}{K_R}}$



Model specificities

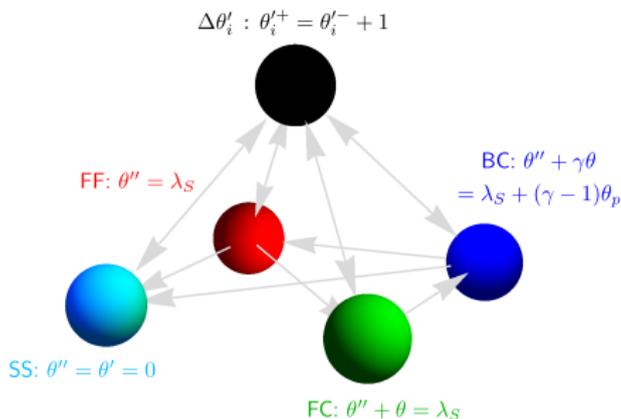
- Periodic impulsive force activation

$$\delta F_{T_1}(t) = I \sum_{n \in \mathbb{Z}^+} \delta(t - nT_1 - t_s)$$

- Modified bilinear interaction law

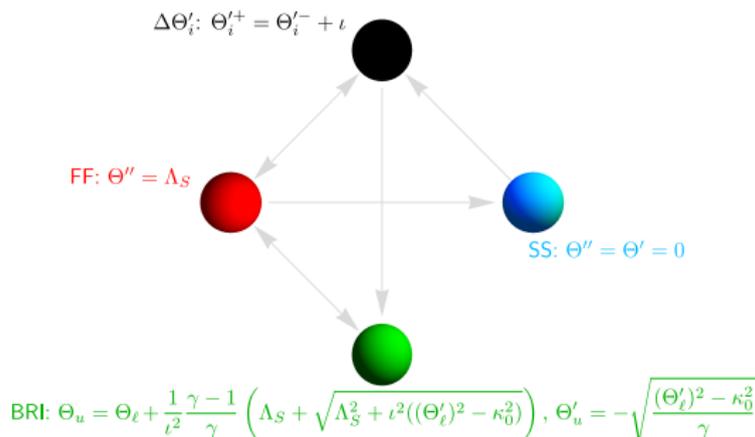
TIMESCALE SEPARATION – $T_1, T_3 \gg T_2$

- Reference scales: $t_* = \sqrt{M/K_R}$, $l_* = I/\sqrt{MK_R}$
- Variables: $\tau = t/t_*$, $\theta = p/l_*$
- Parameters: $\gamma = \gamma K_R/K_R$, $\lambda_S = (Mg + F_S)t_*/I$
- $\psi = T_1/t_*$, $\kappa_0 = \sqrt{2E_\ell^k M/I}$
- Hybrid model: 5 modes, 10 transitions



TIMESCALE SEPARATION – $T_1 \gg T_2, T_3$

- Reference scales: $T_* = T_1$, $L_* = I/\sqrt{MK_R}$
- Variables: $T = t/T_*$, $\Theta = p/L_*$
- Parameters: $\gamma = \gamma K_R/K_R$, $\Lambda_S = (Mg + F_S)T_*^2/ML_*$
 $\iota = T_*\sqrt{K_R/M}$, $\kappa_0 = \sqrt{2E_\ell^k/M}T_*/L_*$
- Hybrid model: 4 modes, 5 transitions



TIME INTEGRATION: EVENT-DRIVEN SCHEME

Piecewise linear hybrid system

1. Integrate smooth vector field until next non-smooth event
2. Accurately locate non-smooth event
3. Identify next drilling phase and set appropriate initial conditions

Example – $T_1, T_3 \gg T_2$ – IC: $(FC, \theta_0, \theta'_0)$

1. Exploit closed-form solution of governing ODEs

$$\text{FC} : \theta'' + \theta = \lambda_S \quad \rightarrow \quad \theta(\tau) = (\theta_0 - \lambda_S) \cos \tau + \theta'_0 \sin \tau + \lambda_S$$

2. Locate closest non-smooth event among all possible events

$$\tau_{EVT} = \min(\tau_p, \tau_i) \text{ with } \tan \tau_p = \frac{\theta'_0}{\theta_0 - \lambda_S} \text{ and } \tau_i = n\psi + \tau_s$$

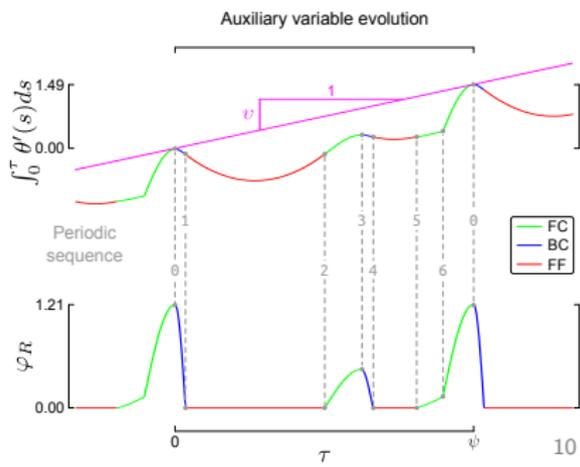
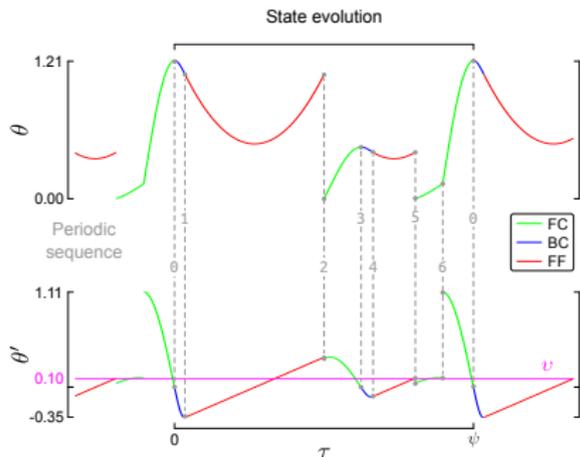
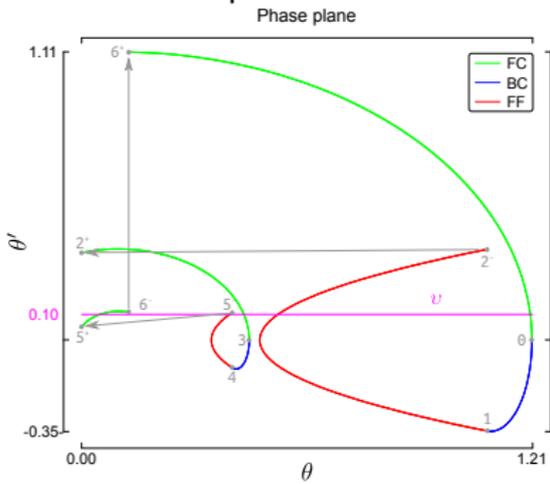
3. Set adequate initial conditions

$$\tau_{EVT} = \tau_i : \text{DP} = \text{FC}, \quad \theta^+ = \theta^-, \quad \theta'^+ = \theta'^- + 1$$

$$\tau_{EVT} = \tau_p : \text{DP} = \text{BC}, \quad \theta^+ = \theta^-, \quad \theta'^+ = \theta'^-$$

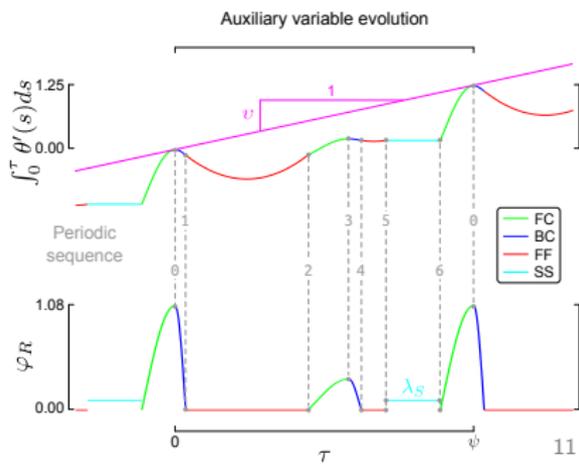
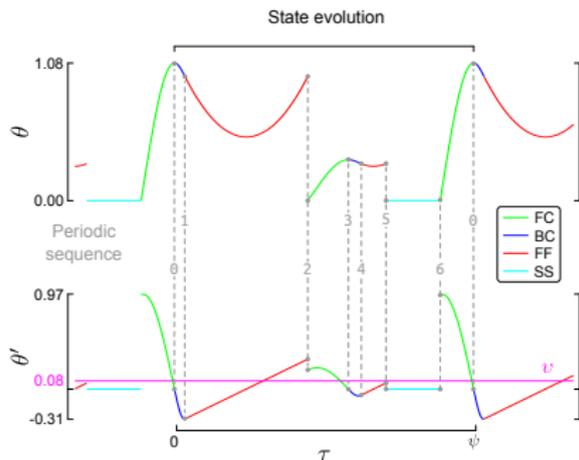
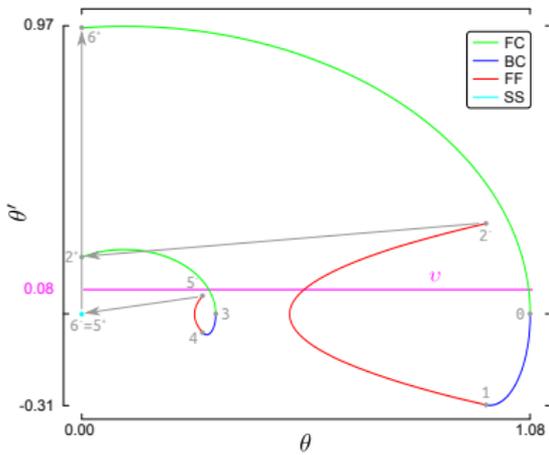
PERIODIC SOLUTIONS – $T_1, T_3 \gg T_2$

- $(\gamma, \lambda_S, \psi, \kappa_0)$
= (10, 0.1, 15, 0.30)
- Shooting method: θ_p, τ_s
- Descriptors:
 - $m/n = 2/1$
 - $((FC \rightarrow BC \rightarrow FF)_2 \rightarrow FC \rightarrow \Delta\theta'_i) \circlearrowleft$
 - Phase portrait



PERIODIC SOLUTIONS – $T_1, T_3 \gg T_2$

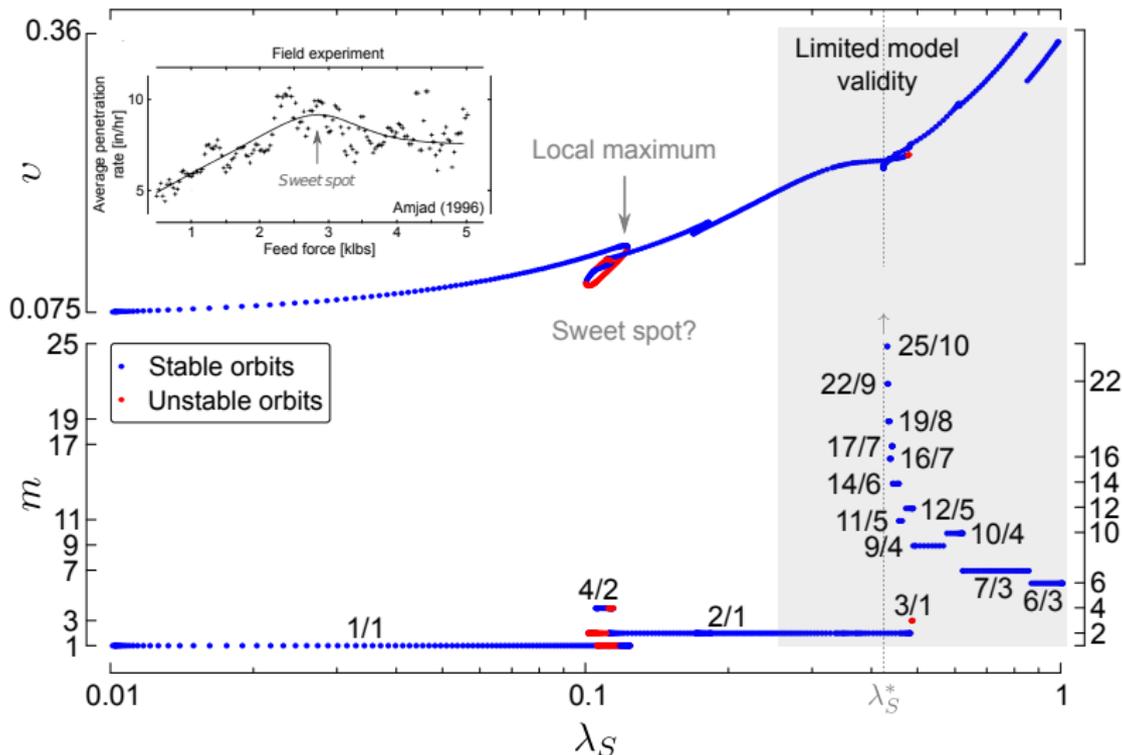
- $(\gamma, \lambda_S, \psi, \kappa_0)$
= (10, 0.1, 15, 0.75)
- Shooting method: θ_p, τ_s
- Descriptors:
 - $m/n = 2/1$
 - $((FC \rightarrow BC \rightarrow FF)_2 \rightarrow SS \rightarrow \Delta\theta'_i) \circlearrowleft$
 - Phase portrait



BIFURCATION DIAGRAM – $T_1, T_3 \gg T_2$

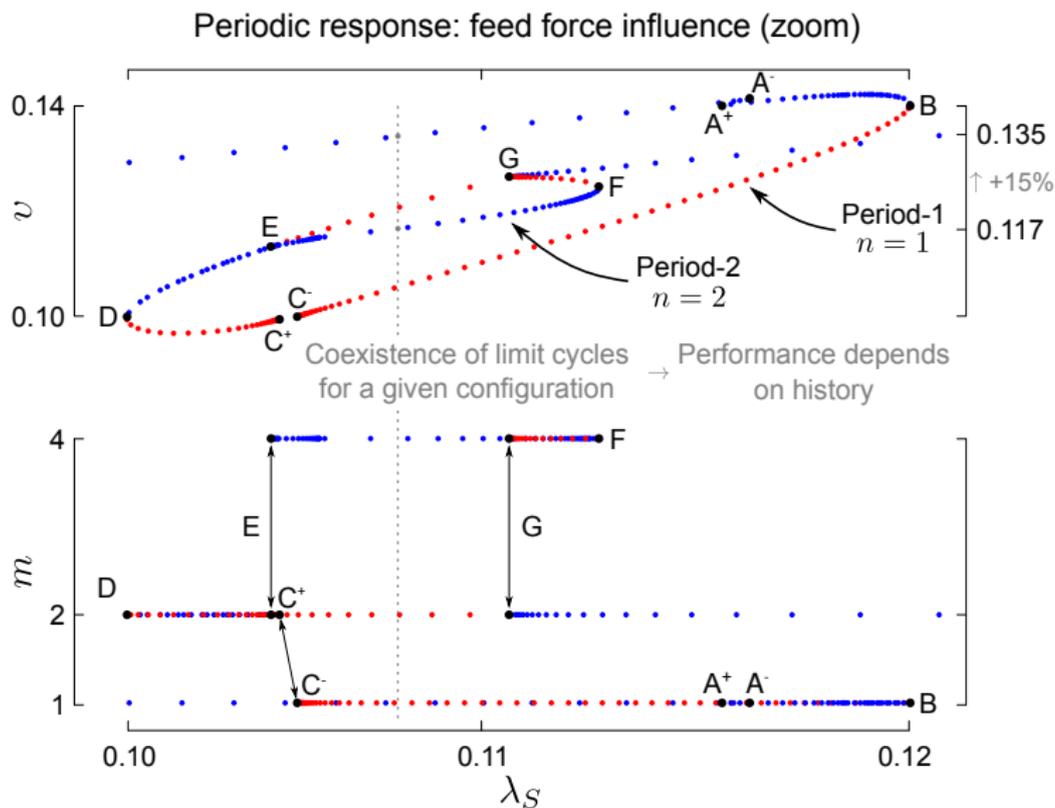
$$(\gamma, \psi, \kappa_0) = (10, 10, 0.3)$$

Periodic response: feed force influence



BIFURCATION DIAGRAM – $T_1, T_3 \gg T_2$

$(\gamma, \psi, \kappa_0) = (10, 10, 0.3) - \lambda_S \in [0.10, 0.12]$



SUMMARY

Modified bilinear bit/rock interaction model

- Follows from experimental evidence
- Energy barrier is essential to discriminate static & dynamic contact

Impact oscillator + modified bilinear BRI model

- two possible models, depending on BRI timescale
 - coexistence of periodic solutions
 - clues of the experimentally-observed sweet spot
- this suggests the sweet spot to result from the process dynamics, not from a change of bit/rock interaction mechanisms

For further details:

Depouhon, Denoël, Detournay – A drifting impact oscillator with periodic impulsive loading: Application to percussive drilling. *Physica D* 258 (2013) 1–10.

CONTENTS

Bit/rock interaction

- Single impact

- Repeated impact

- Analysis of the drilling cycle

- Rate-independence

Bit dynamics

- Impact oscillator

- Timescale separation – $T_1, T_3 \gg T_2$

- Timescale separation – $T_1 \gg T_2, T_3$

- Time integration

Limit-cycling behavior – $T_1, T_3 \gg T_2$

- Periodic solutions & descriptors

- Bifurcation diagram

Summary