

General lotsizing problem in a closed-loop supply chain with uncertain returns

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Introduction

- Uncertainty in the return process is a common feature of closed loop supply chains.
- The uncertain quantity of returned items affects the production process.

Aim

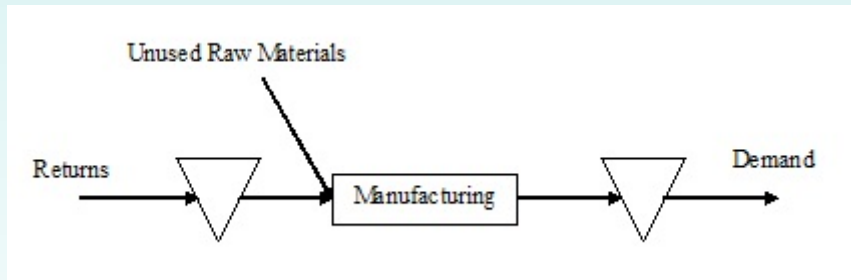
Develop a mathematical model and an efficient algorithm to solve a general lotsizing and scheduling problem with uncertain returns.

Definition: Markov decision process

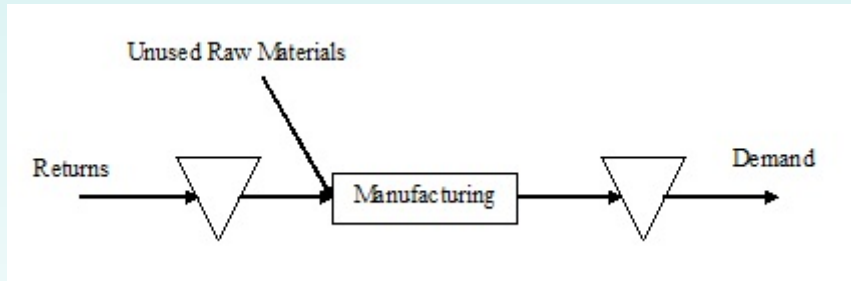
A Markov decision process is a 4-uple $(S, A, P(.,.), V(.,.))$ where:

- S is a finite set of states.
- A is a finite set of actions.
- $P_a(s, s')$ is the probability that action a in state s will lead to state s' .
- $V(s, s')$ is the immediate reward received after transition from state s to state s' .

General features

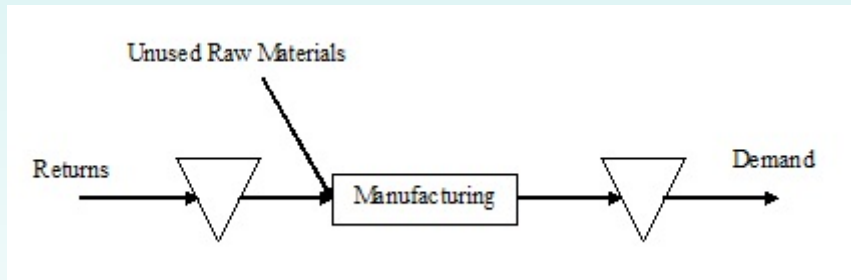


- There is a single production line without work-in-process inventories.
- This line produces several products in lots. The size of each lot may vary and each product has a given production rate.
- The production planning is realized for several periods.
- The production capacity is limited but may vary between periods.



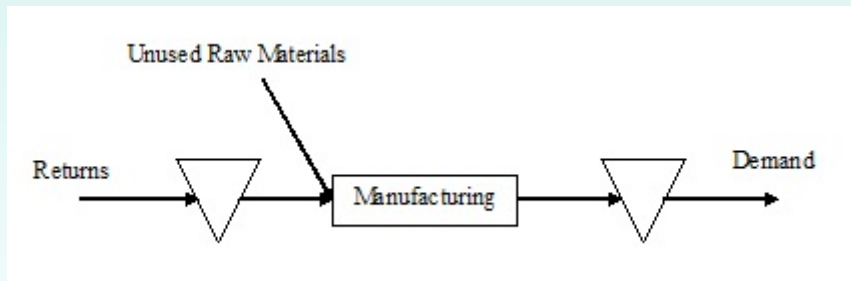
- The demand for each product is considered as deterministic over the planning horizon.
- Backorders are not allowed.
- Building up an inventory is possible for the returned products and for the finished products.

Setup features



- There are setup costs and times incurred whenever the production is switched from one product to another. The setup time consumes the capacity of the production line.
- Setup costs and times are sequence dependent, i.e they are determined based on the product produced before the changeover and the product produced after the changeover.

Inputs features



- Production uses either returned items or new items.
- The quantity of returned items that will be available in each period is not known with certainty.
- The amount of available new items is considered unlimited.

Costs features

- Both returned items and end-products incur inventory costs.
- There is a cost per new item used. On the other hand, using returned items is free.
- Sequence dependant setup costs are considered.

Problem

Find a production schedule that minimizes the expected cost over the planning horizon, respects the production capacity, and satisfies demand at each period.

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Deterministic Model

- One way to deal with the scheduling aspect is to divide each period into sub-periods.
- Only one type of item can be produced during a sub-period.
- This is the most common approach used in the literature (Mohammadi et al. (2010), Clark and Clark (2000), Fleischmann and Meyer (1997), Araujo et al. (2007)).

$$\text{Min } \sum_{n=1}^N \sum_{o=1}^P \sum_{p=1}^P CS_{op} \cdot y_{opn} \\ + \sum_{t=1}^T \sum_{p=1}^P CJ_p \cdot w_{pt} + CB_p \cdot x_{pt}^n + Cl_p \cdot z_{pt}$$

$$\text{s.t } x_{pt}^r + x_{pt}^n \leq \sum_{o=1}^P \sum_{n=F_t}^{L_t} y_{opn} * C_t \quad \forall p, t$$

$$z_{pt} = z_{p,t-1} + R_{pt} - x_{pt}^r \quad \forall p, t$$

$$w_{pt} = w_{p,t-1} + x_{pt}^r + x_{pt}^n - D_{pt} \quad \forall p, t$$

$$\sum_{p=1}^P L_p \cdot (x_{pt}^r + x_{pt}^n) + \sum_{n=F_t}^{L_t} \sum_{o=1}^P \sum_{p=1}^P S_{op} \cdot y_{opn} \leq C_t \quad \forall t$$

$$\sum_{p=1}^P y_{O_0 p 1} = 1$$

$$\sum_{p=1}^P y_{op1} = 0 \quad \forall o \neq O_0$$

$$\sum_{o=1}^N y_{opn} = \sum_{q=1}^N y_{pq, n+1} \quad \forall p, n \neq N$$

$$y_{opn} \in \{0; 1\} \quad \forall o, p, n$$

$$x_{pt}^r, x_{pt}^n, z_{pt}, w_{pt}, b_{pt} \geq 0 \quad \forall p, t$$

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Stochastic Model

During a period, the following sequence of events occurs:

- 1 Decisions are made about production and inventories.
- 2 Returns become available.
- 3 Production starts and demand is satisfied.

$$\text{Min } CJ.w_1 + CS.y_1 + E_{R_1} [f_1(S_1, R_1)]$$

$$\begin{aligned} \text{s.t } & x_1 \leq C_1.y_1 \\ & w_1 = w_0 + x_1 - D_1 \\ & x_1, w_1 \geq 0 \\ & y_1 \in \{0, 1\} \end{aligned}$$

where $f_t(S_t, R_t)$ is equal to:

$$\begin{aligned} \text{Min} \quad & CI.z_t + CB.x_t^n + CJ.w_{t+1} \\ & + CS.y_{t+1} + E_{R_{t+1}} [f_{t+1}(X_{t+1}, R_{t+1})] \end{aligned}$$

$$\begin{aligned} \text{s.t} \quad & x_t^n + x_t^r = x_t \\ & z_t = z_{t-1} + R_t - x_t^r \\ & x_{t+1} \leq C_{t+1} \cdot y_{t+1} \\ & w_{t+1} = w_t + x_{t+1} - D_{t+1} \\ & x_t^n, x_t^r, x_{t+1}, w_{t+1} \geq 0 \\ & y_{t+1} \in \{0, 1\} \end{aligned}$$

Markov decision process representation

- A state is a triple (t, z_{t-1}, w_t) .
- y_t and x_t define the set of actions.
- The transition function is defined by the constraints.
- The reward perceived after a transition is given by the objective function.

The transition

$$(t-1, Z_{t-2}, W_{t-1}) \xrightarrow{(y_t, x_t, R_t)} (t, Z_{t-1}, W_t)$$

where:

$$\begin{aligned} Z_{t-1} &= \max(0, Z_{t-2} + R_t - x_{t-1}) \\ W_t &= W_{t-1} + x_t - D_t \end{aligned}$$

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Approximate Dynamic Programming

This technique is described in Powell (2011) and has been used in various production problems (Qiu and Loulou (1995), Erdelyi and Topaloglu (2011)) .

Idea

Iteratively solve an approximation of the deterministic problem. After each iteration, use the preceding results to affine the approximation.

At each iteration of the algorithm, the following sequence of operations are:

- 1 Select a scenario (R_1, \dots, R_T) .
- 2 Solve the sub-problem $f_t(X_t, R_t)$ for each period where the expectation is replaced by an approximation.
- 3 Update the approximation using the obtained results.

The current characteristics of the algorithm are:

- The algorithm stops after a certain number of iterations.
- The scenario selection is totally random.
- The transition cost function is represented as a table.
- Update of the transition cost table uses a k-nearest neighbour procedure.

Preliminary Results

T	5		10		15	
μ	0.5	0.75	0.5	0.75	0.5	0.75
ACE	3%	0%	3%	0%	2%	1%
HCE	7%	0%	5%	0%	7%	1%
Time (s)	65	66	117	124	181	185

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Future work

- Use other types of procedures to improve the algorithm.
- Expand the algorithm to the multi-product problem.

Thank you for your attention!

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