

Evenstad, 15/08/12



Using hurdle models to create maps of prey density in southeastern of Norway



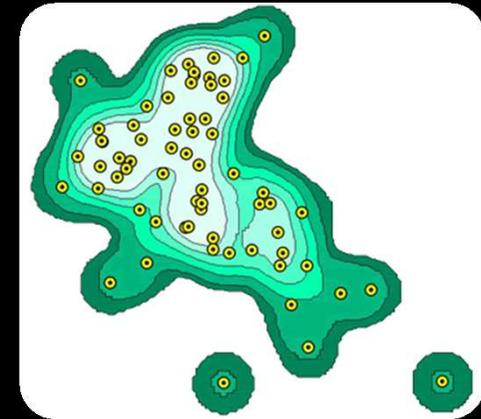
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Pascal Poncin, John Linnell

- **Return of large carnivores**
- **Managing their recovery in the heavily human-modified landscapes of Europe**
- **Prey distribution and density in areas where carnivores are present = understanding of carnivore movements and habitat use**



PREY DENSITIES MAPS

- **Large carnivore home ranges: 100km² to 1500 km²**
- **Herbivore home ranges: 1km² to 50km²**



- **Models of prey habitat = much smaller scales than the areas over which it will be applied**
- **With large carnivores: use of predictive models needed to extend the model to a larger scale in order to include all the individual home-ranges**

- **Prey species :**



Capreolus capreolus



Alces alces



Cervus elaphus

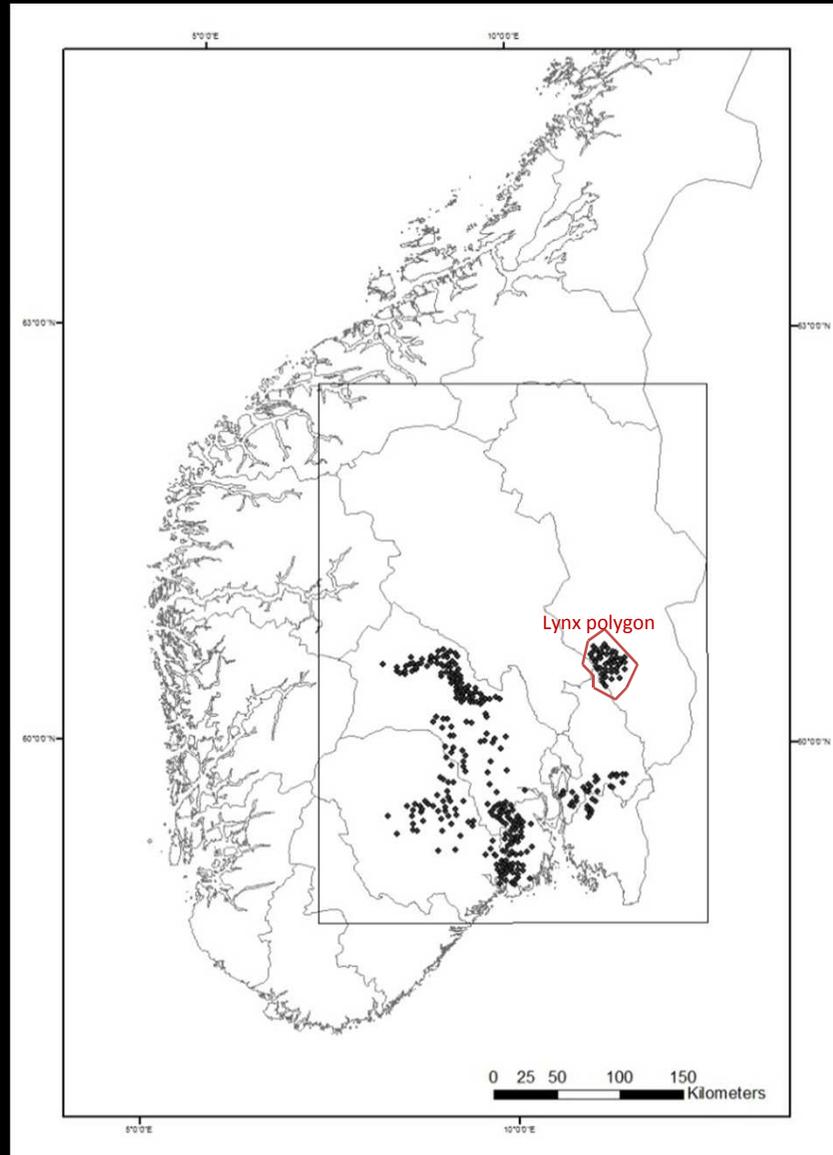


Lepus timidus

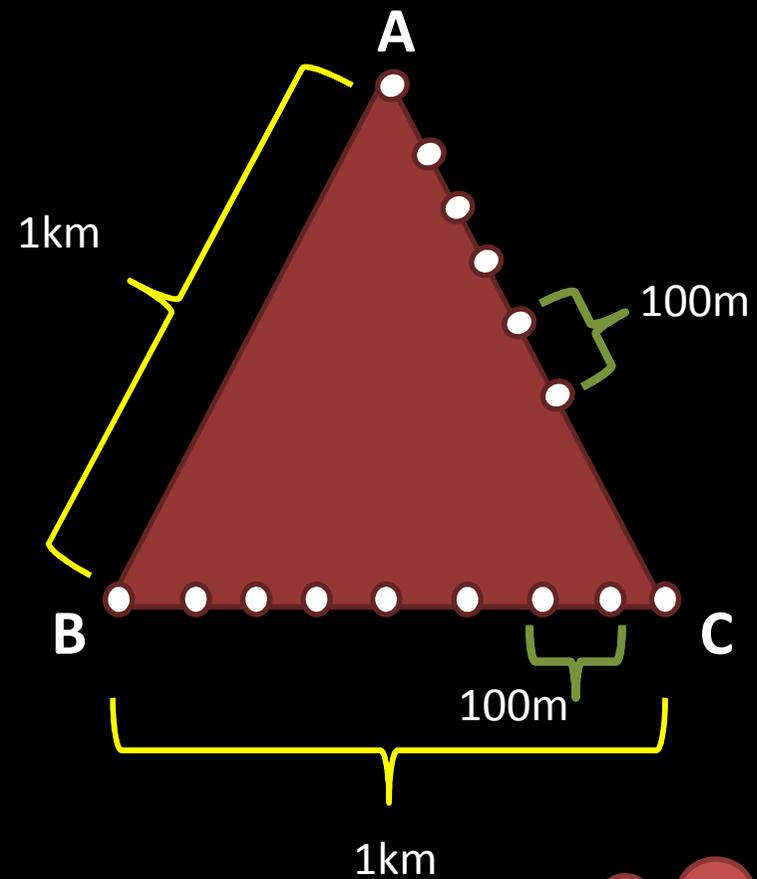
- **NO MAPS AVAILABLE IN NORWAY YET**

- **Pellet groups, Hurdle models**





430 transects covered between 2005, 2007, 2008 and 2011



- **Pellet group**

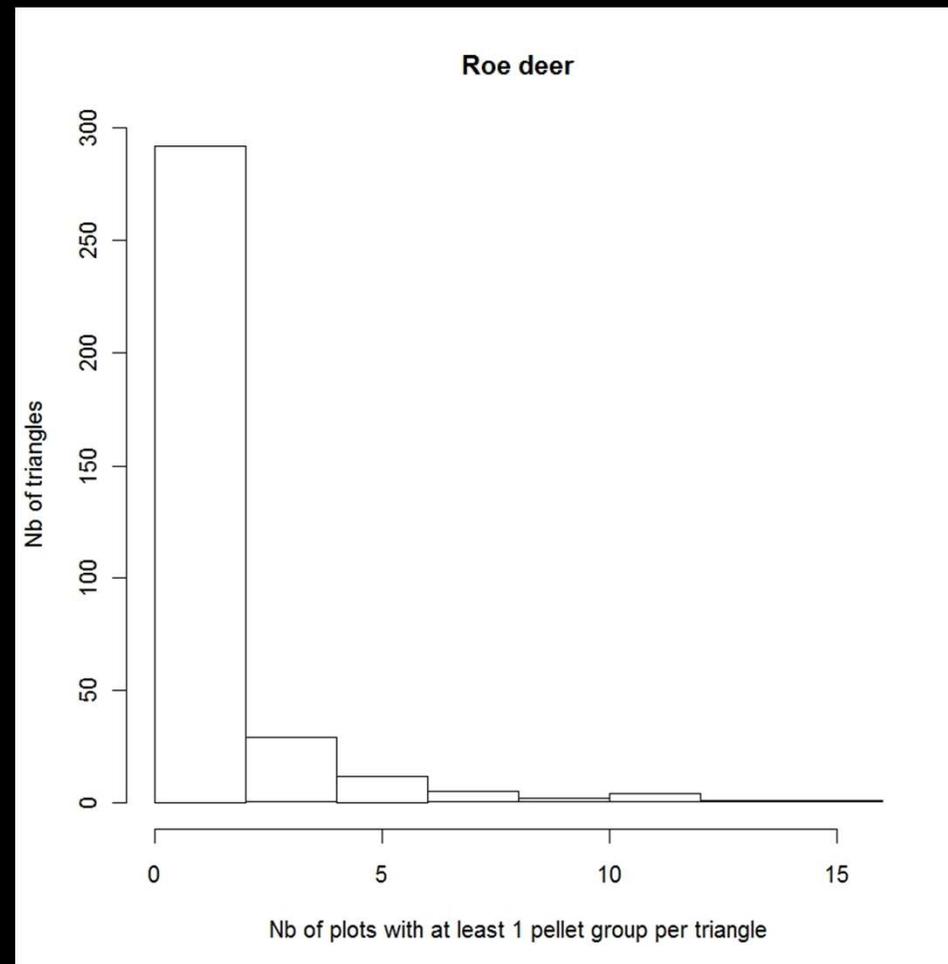


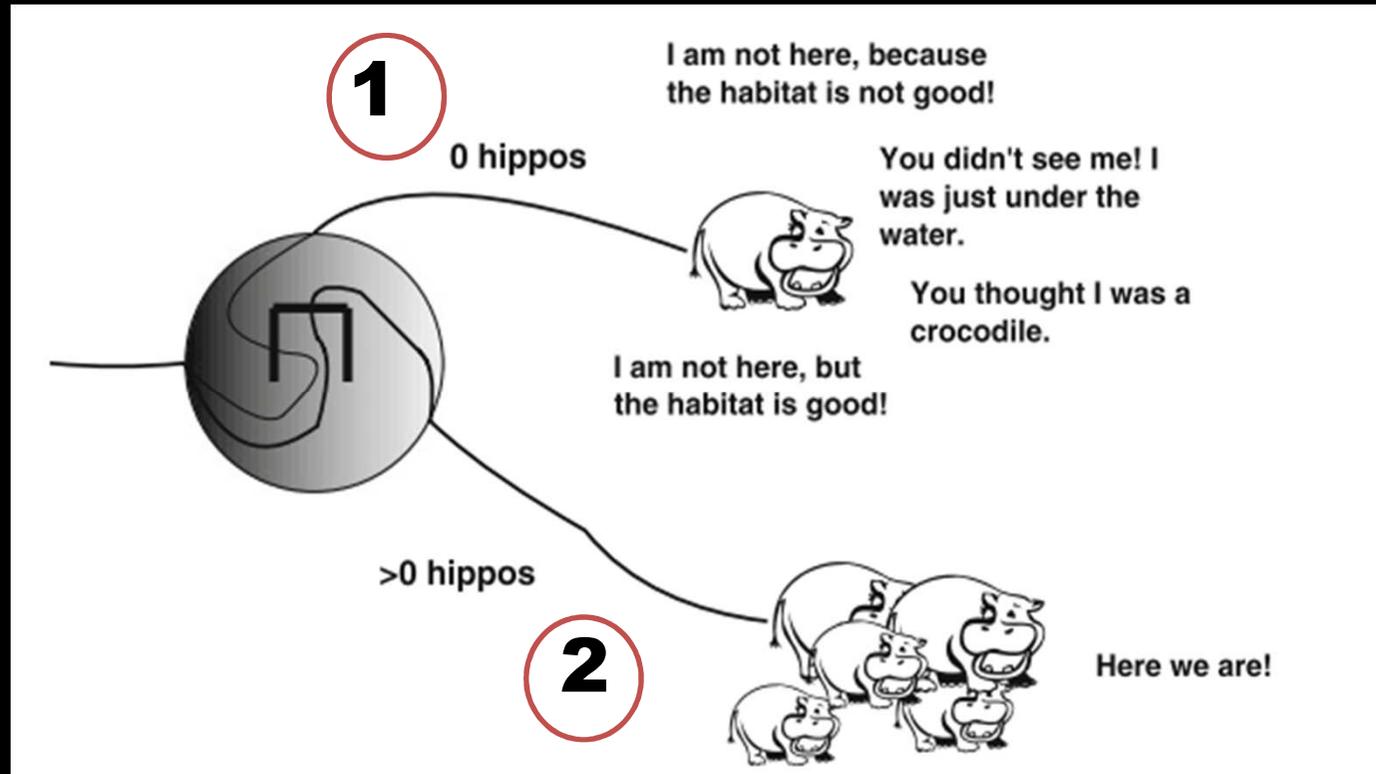
- **Data collected in spring (April-May) and autumn (September) to avoid a too high vegetation in summer and snow cover in winter**
- **346 triangles were kept for the analysis**
- **For red deer, only 245 triangles**

Environmental variables within a radius of 1250m or 2500m from the center of the plot

Data	Signification
Habitat	
Forest	The km ² of forest within each pixel
Bogs	The km ² of bogs within each pixel
Temperature	The annual mean temperature (degree) within each pixel
Snow	The mean snow depth (mm) during winter within each pixel
Elevation	Mean elevation within each pixel
Slope	Mean of the slope (degrees) within each pixel
Hillshade	Index of the combination of the slope and aspect of the terrain in relationship to the azimuth and aspect of the sun within each pixel
Climatic Gradient	Regional variation (gradient) from coast to inland and from oceanic/humid to continental areas within each pixel
Human activity	
Field	The km ² of agricultural fields within each pixel
Public Roads	The km of public roads within each pixel
Private Roads	The km of private roads within each pixel
Human Density	The density of humans within each pixel

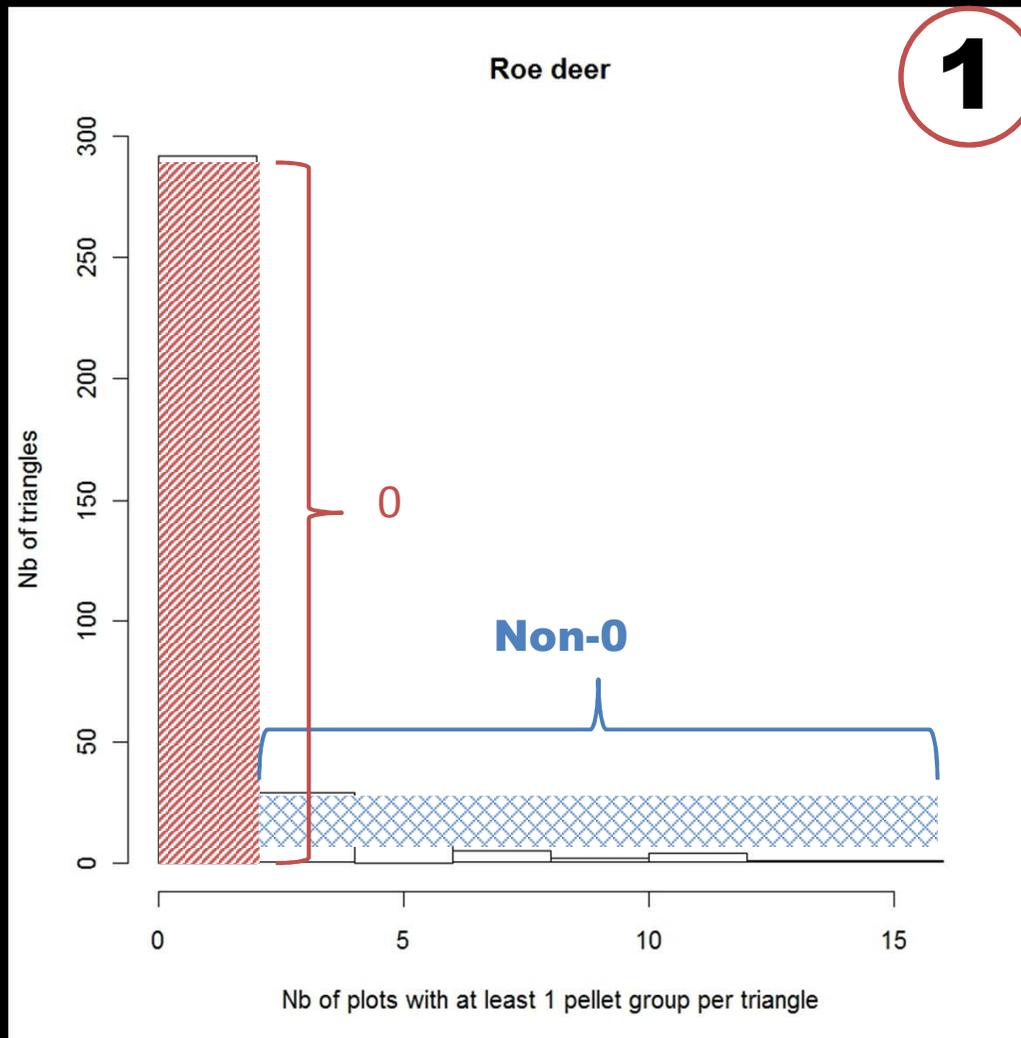
Hurdle models: used when the response variable contains more zeros than expected based on a Poisson or on a negative binomial distribution





Two ecological processes :

- 1) Absence
- 2) When presence, influence on the number of animals



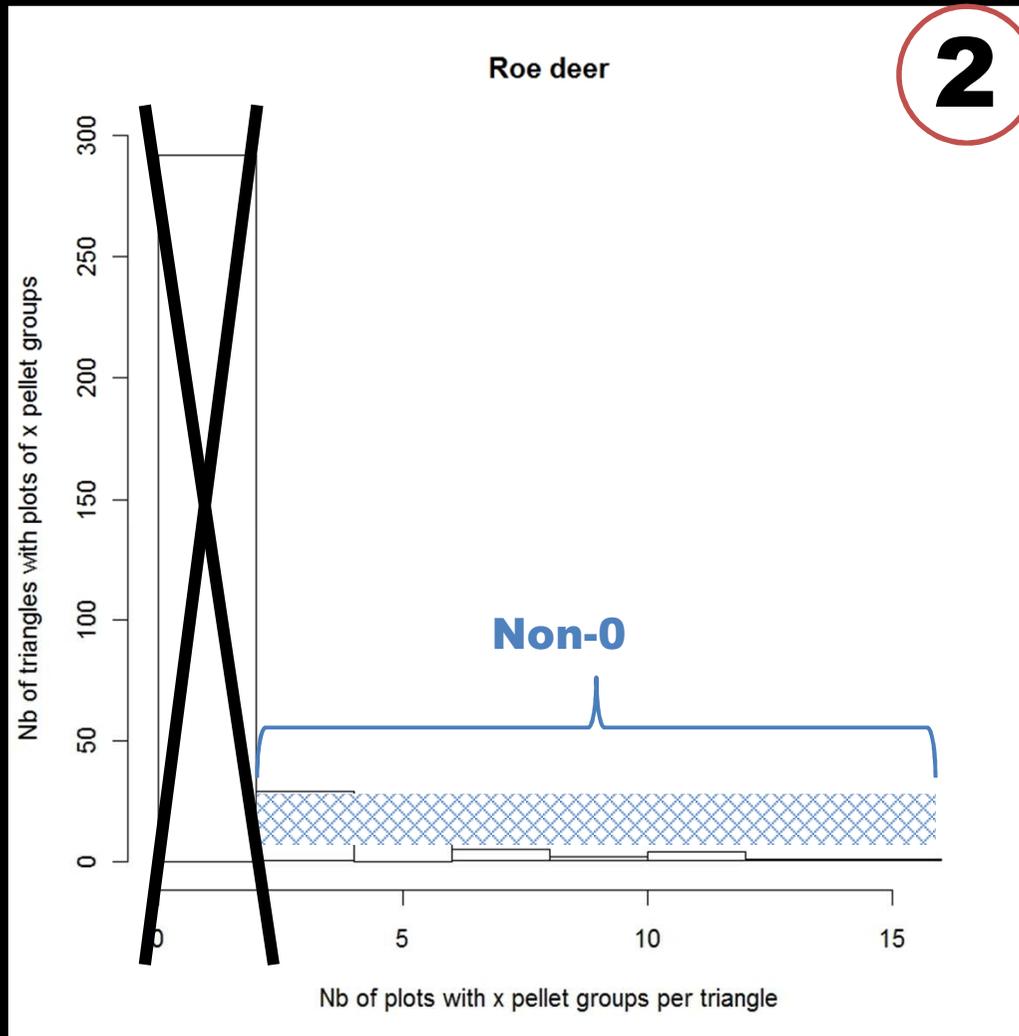
Two parts model



1. Data = 0 vs. non-0

→ **binomial model : proba that a 0 is observed**

Presence/absence



Two parts model



2. non-0 modeled with a truncated Poisson or truncated negative binomial model

→ cannot produce 0

Abundance

Model evaluation:

1) A cross-validation based on a leave-one-out procedure carried out n times was realized with the same dataset used to create the distribution maps

2) A. Snow-tracks



B. Hunting data at the municipality level



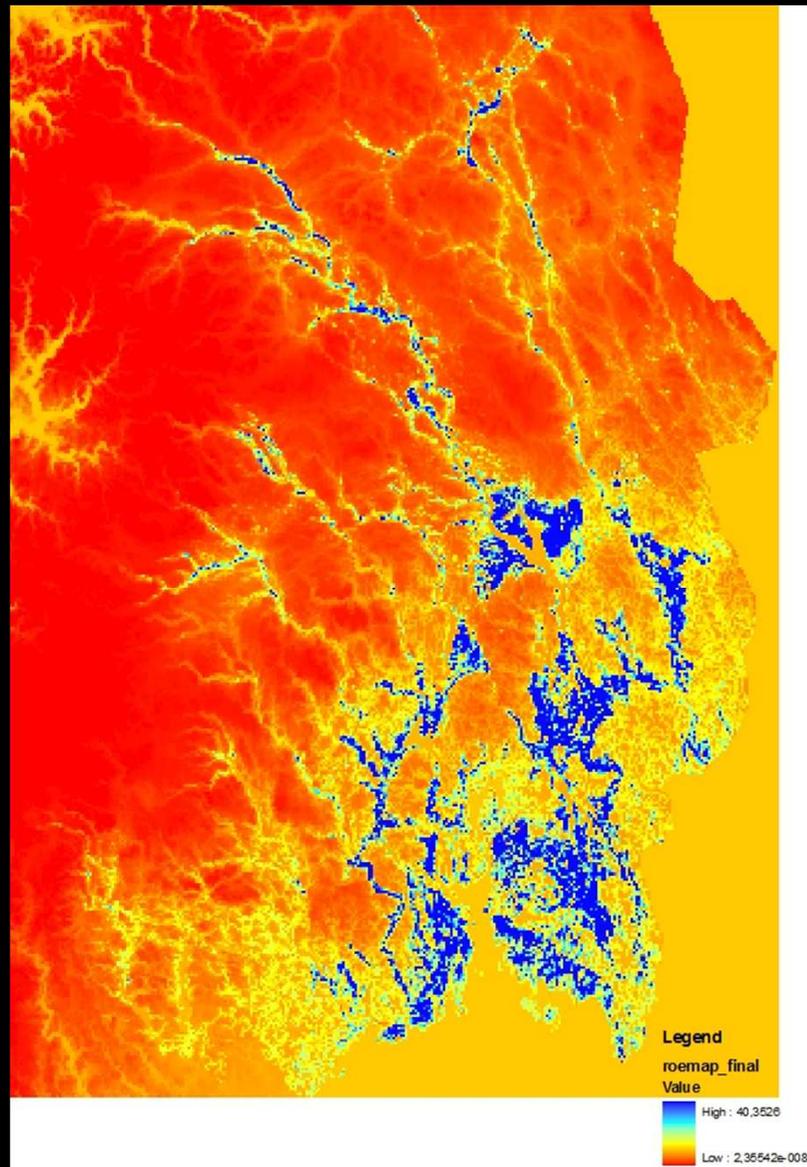
Results

	1 Binomial part			2 Negative binomial part		
	Estimate	SE	p-value	Estimate	SE	p-value
Roe deer						
Fields	5.123	1.093	<0.001	2.411	0.529	<0.001
Private Roads	–	–	–	0.985	0.316	0.001
Snow	-0.004	0.0007	<0.001	-0.005	0.001	<0.001
Private Roads ²	–	–	–	-0.262	0.129	0.04
Red Deer						
Forest	2.938	1.160	0.01	3.821	1.122	<0.001
Public Roads	–	–	–	0.505	0.161	0.001
Bogs	10.388	3.019	<0.001	–	–	–
Slope	0.109	0.042	0.01	–	–	–
Moose						
Bogs	–	–	–	-2.629	1.15	0.023
Fields	–	–	–	-1.05	0.45	0.021
Human Density	–	–	–	-0.003	0.001	0.024
Snow	-3.548	1.284	0.006	-0.001	0.0005	0.0292
CG	-5.554	1.894	0.003	352.69	73.24	<0.001
Hillshade	1.484	2.096	<0.001	–	–	–
Private Roads	-7.674	2.125	<0.001	–	–	–
Mountain Hare						
Bogs	–	–	–	-2.538	1.266	0.044
Public Roads	–	–	–	-0.3527	0.141	0.012
Snow	0.003	0.0004	<0.001	0.002	0.0006	<0.001
CG	570	159	<0.001	551	103	<0.001

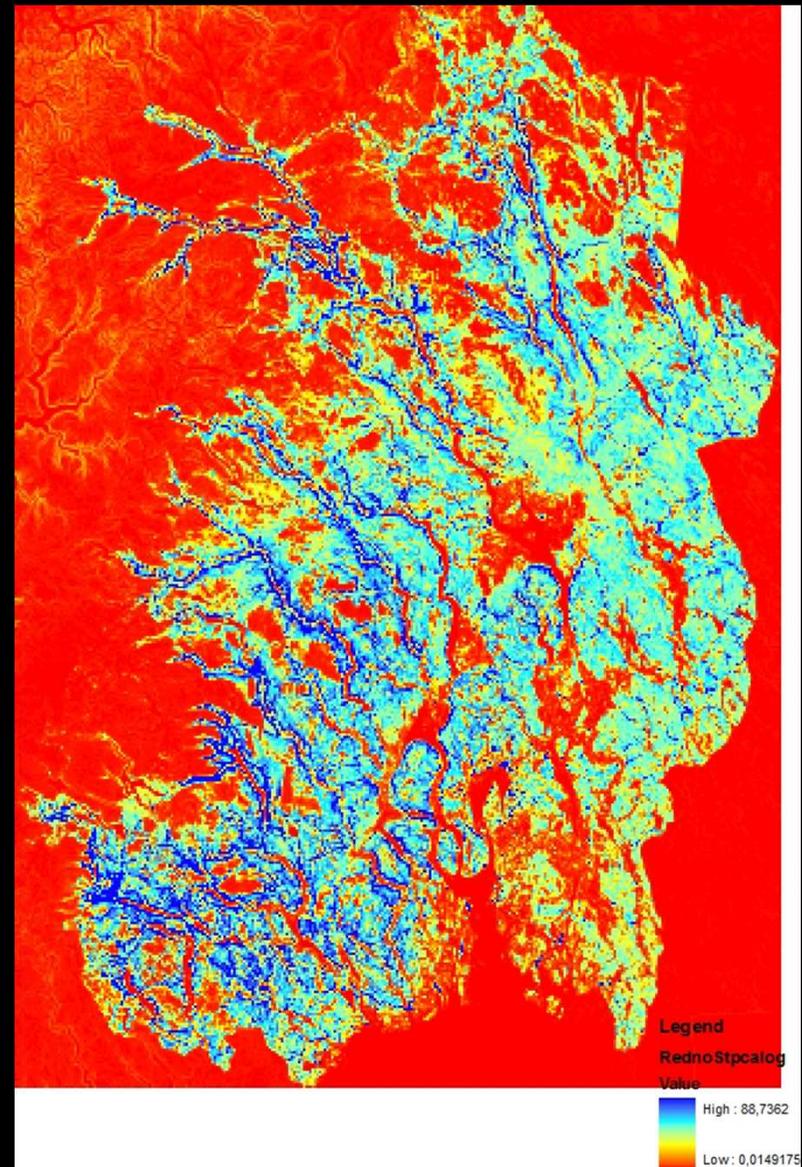
Cross-validation	Roe deer	Red deer	Moose	Hare
RMSE	2.30	36.04	10.84	2.90
Rcor	0.41	0.26	0.21	0.37

Spearman's rank correlation	Roe deer	Red deer	Moose	Hare
Snowtrack data	0.30	0.13	0.28	0.53
Hunting data	0.87	0.23	0.54	—

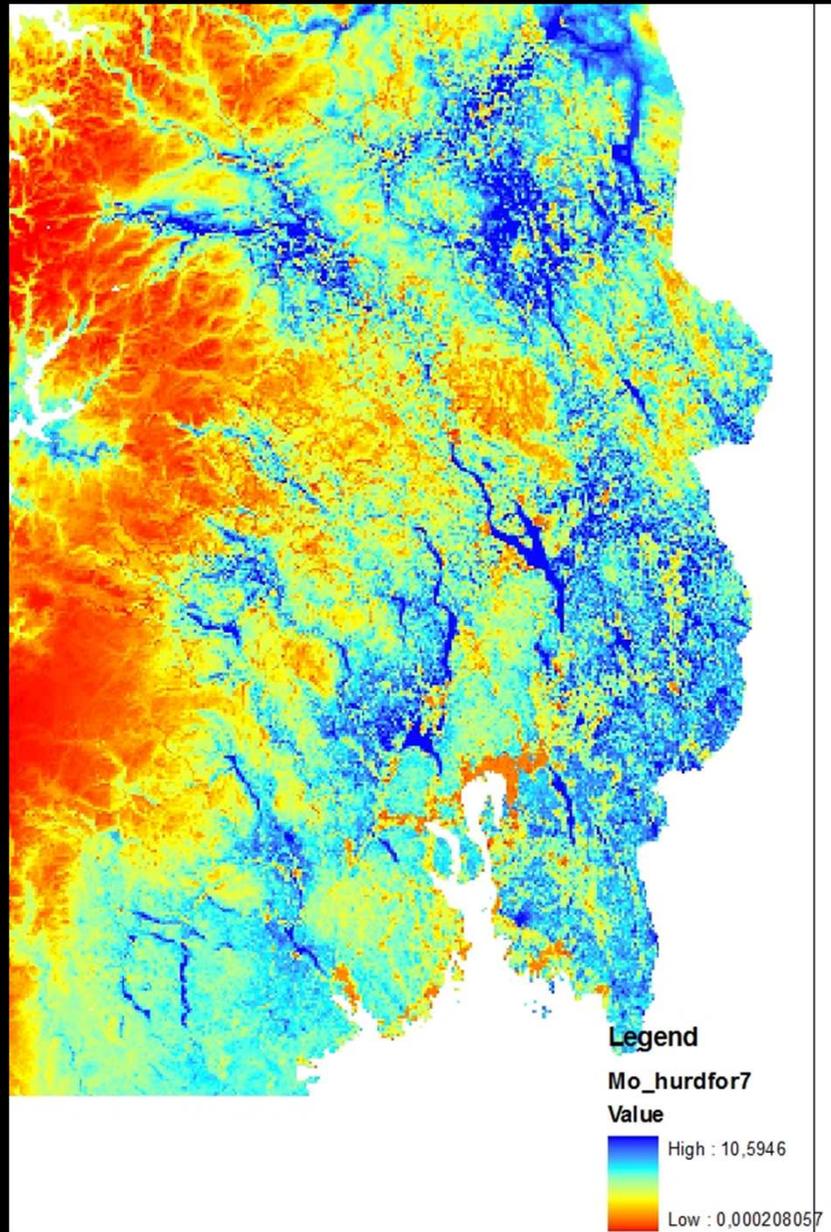
Roe deer



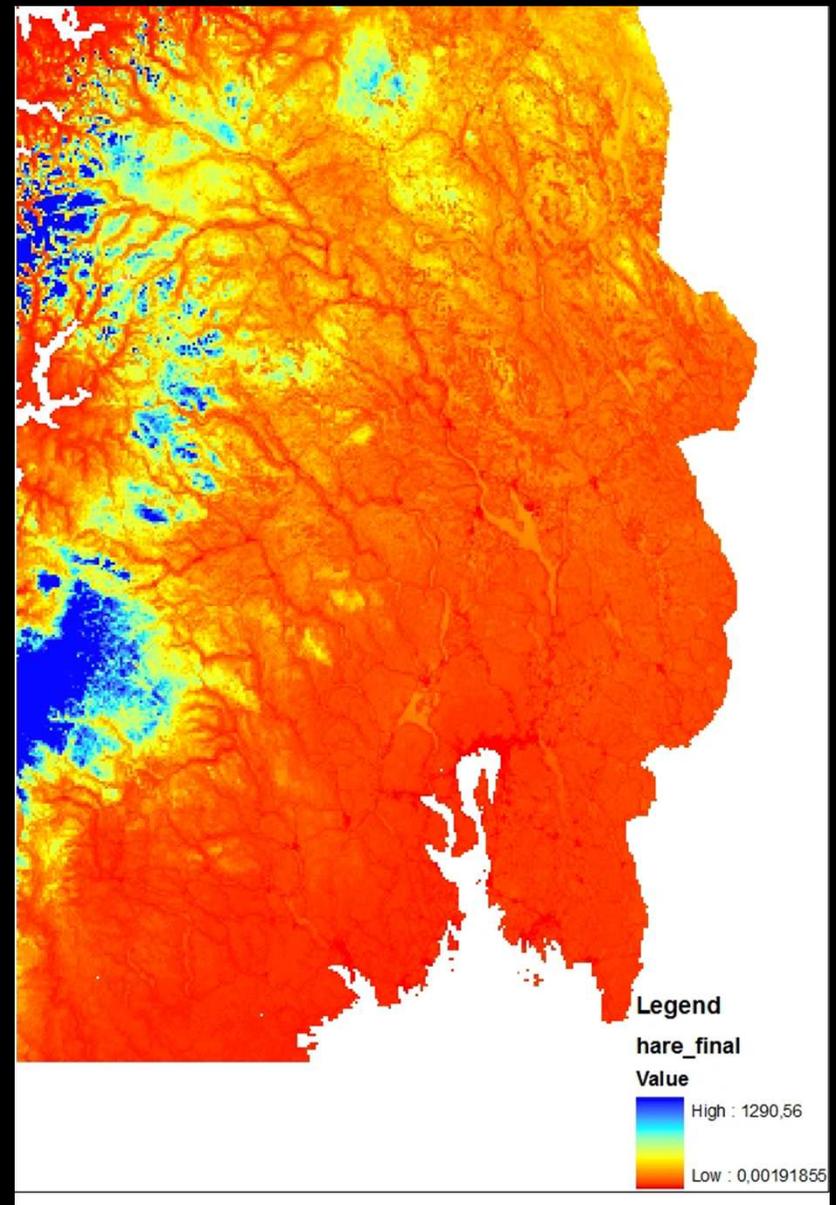
Red deer



Moose



Hare



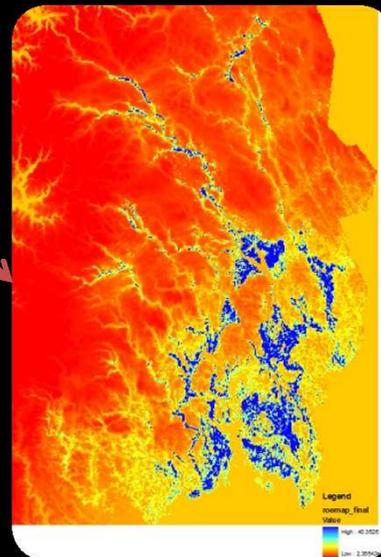
- **Hurdle models environmental variables conform with what we know of the species**
- **Create maps with pellet count groups and hurdle models**
- **Two validation approaches show that the predictive maps are a good representation of the real density and distribution of each species**

BUT

Very generalist species !

Extension of scale → errors

Herbivores management in Norway:



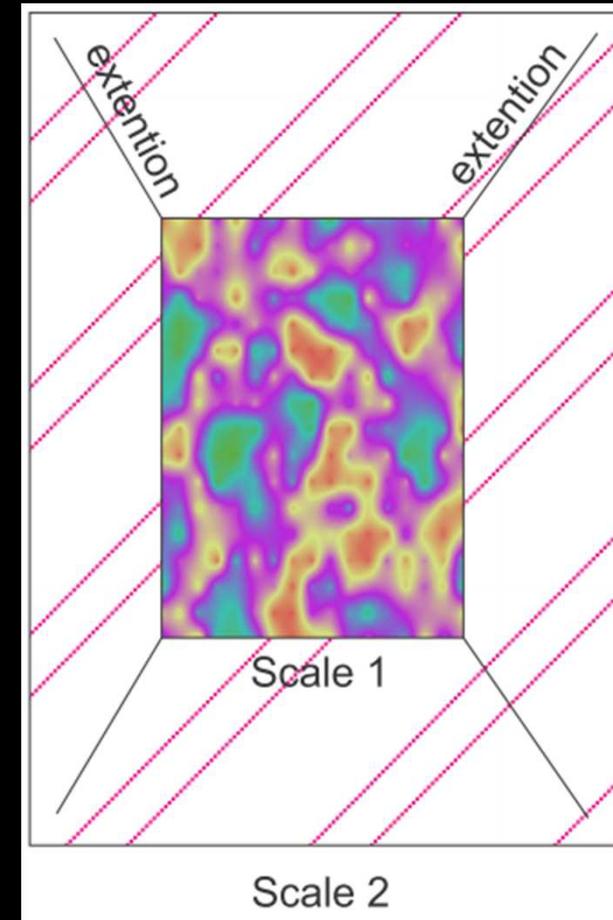


Thanks for your attention

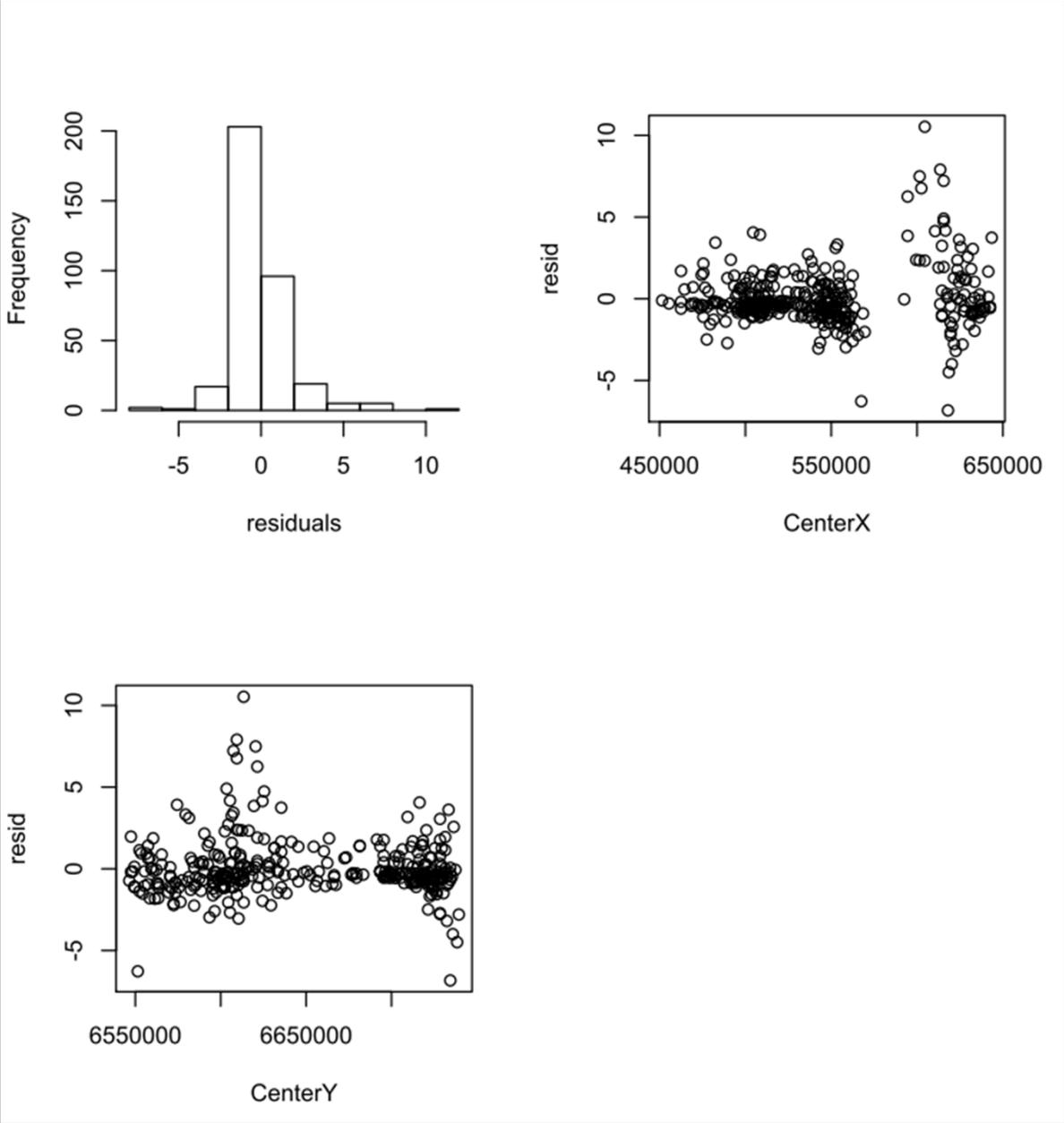
Source of 0

- 1. Structural errors = a bird is not present because the habitat is not suitable.**
- 2. Design error = where poor experimental design or sampling practises are thought to be the reason. As an example, imagine counting the number of puffins on the cliffs in the winter. It is highly likely that all samples will be 0 as it is the wrong season and they are all at sea. Another design error is sampling for too short a time period or sampling too small an area.**
- 3. Observer error = some bird species look similar, or are difficult to detect. The less experienced the observer, the more likely he/she will end up with zero counts for bird species that are difficult to identify. Alter-natively, the observer may be highly experienced, but it is extremely difficult to detect a tiny dark bird in a dark field on a dark day.**
- 4. The 'bird' error. This means that the habitat is suitable, but the site is not used.**

- **Predictive models – Indirect gradients (slope, elevation, aspect...)**
- **Drawback: model applied within a limited geographical extent without significant errors**
- **But: in ecology, it is sometimes necessary to extend a model to a larger scale than the scale of the sampling**



Roe deer



RMSE is the square root of the variance

In [statistics](#), the **mean squared error (MSE)** of an [estimator](#) is one of many ways to quantify the difference between values implied by an estimator and the true values of the quantity being estimated.