SYMMETRIC APPROXIMATIONS OF PSEUDO-BOOLEAN FUNCTIONS WITH APPLICATIONS TO INFLUENCE INDEXES

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Abstract. We introduce an index for measuring the influence of the kth smallest variable on a pseudo-Boolean function. This index is defined from a weighted least squares approximation of the function by linear combinations of order statistic functions. We give explicit expressions for both the index and the approximation and discuss some properties of the index. Finally, we show that this index subsumes the concept of system signature in engineering reliability and that of cardinality index in decision making.

1. Introduction

Boolean and pseudo-Boolean functions play a central role in various areas of applied mathematics such as cooperative game theory, engineering reliability, and decision making (where fuzzy measures and fuzzy integrals are often used). In these areas indexes have been introduced to measure the importance of a variable or its influence on the function under consideration (see, e.g., [3, 7]). For instance, the concept of importance of a player in a cooperative game has been studied in various papers on values and power indexes starting from the pioneering works by Shapley [13] and Banzhaf [1]. These power indexes were rediscovered later in system reliability theory as Barlow-Proschan and Birnbaum measures of importance (see, e.g., [10]).

In general there are many possible influence/importance indexes and they are rather simple and natural. For instance, a cooperative game on a finite set \([n] = \{1, \ldots, n\}\) of players is a set function \(v: 2^{[n]} \to \mathbb{R}\) with \(v(\emptyset) = 0\), which associates with any coalition of players \(S \subseteq [n]\) its worth \(v(S)\). The Banzhaf value of player \(i \in [n]\) in the game \(v\) is then defined as

\[
\varphi_B(v, i) = \frac{1}{2^{n-1}} \sum_{S \subseteq [n] \setminus \{i\}} (v(S \cup \{i\}) - v(S)) = \frac{1}{2^{n-1}} \sum_{S \ni i} v(S) - \frac{1}{2^{n-1}} \sum_{S \not\ni i} v(S).
\]

Thus, \(\varphi_B(v, i)\) is the average of the marginal contributions of player \(i\) to all coalitions \(S \subseteq [n] \setminus \{i\}\), or the difference between the average worth over all coalitions \(S \ni i\) and the average worth over all coalitions \(S \not\ni i\). Considering weighted averages instead of symmetric averages gives rise to various probabilistic values (see [14]), including the Shapley value and weighted Banzhaf values (see [8]).

The choice of a suitable influence/importance index depends on the practical problem under consideration and is usually made by considering the properties

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that the index should satisfy. This is why many indexes have been characterized axiomatically. Besides these characterizations, it is well known in statistics that one can measure the influence of a variable using linear regression. This approach was applied successfully to pseudo-Boolean functions by Hammer and Holzman [5], who showed that the Banzhaf value appears as the coefficients of the linear terms of the standard least squares approximation of a game (or its corresponding pseudo-Boolean function) by a function of degree at most 1. Weighted versions of this least squares approach were also considered to characterize the Shapley value [4] and weighted Banzhaf values [8].

Slightly different influence indexes emerged in certain applications where it is not the influence of a variable on a function that is to be measured but rather the influence of adding a variable to a given subset of variables. For instance, considering a system made up of \( n \) interconnected components with independent and identically distributed (i.i.d.) lifetimes, Samaniego [11, 12] defined the signature of the system as the \( n \)-tuple \((s_1, \ldots, s_n)\) where \( s_k \) is the probability that the \( k \)th failure causes the system to fail. Due to the i.i.d. assumption, the signature only depends on the (Boolean) structure function of the system. Thus, the number \( s_k \) can be interpreted as a measure of the influence on the structure function of adding a \( k \)th element to the set of failed components. Another example of such a measure of influence was introduced by Yager [15] in the context of fuzzy measures. Considering a fuzzy measure on an \( n \)-set \( X \), he introduced the cardinality index as the \( n \)-tuple \((C_0, \ldots, C_{n-1})\), where \( C_k \) is the average gain in certitude one gets when going from a \( k \)-subset to a \((k+1)\)-subset.

In this paper we show that the concepts of system signature and cardinality index are special instances of a more general notion of influence index: the influence index of the \( k \)th smallest variable on a pseudo-Boolean function. We define this index by considering the least squares approximation of a given function by a linear combination of order statistic functions. Such linear combinations are particularly suitable for encoding the influence that we want to measure and are exactly the symmetric (i.e., invariant under a permutation of the variables) pseudo-Boolean functions (see Proposition 1). Here we consider the general framework of arbitrarily weighted least squares approximations. In Section 2 we give explicit expressions for the approximation and discuss some of its properties. In Sections 3 and 4 we introduce our influence index and show how it subsumes the concepts of system signature and cardinality index. We also show how this index can be used in cooperative game theory to define a new influence index.

We employ the following notation throughout the paper. We denote by \( \mathbb{B} \) the two-element set \( \{0, 1\} \). For any \( \mathbf{x} \in \mathbb{B}^n \), we set \( |\mathbf{x}| = \sum_{i=1}^{n} x_i \). For any \( S \subseteq [n] = \{1, \ldots, n\} \), we denote by \( \mathbf{1}_S \) the \( n \)-tuple whose \( i \)th coordinate is 1, if \( i \in S \), and 0, otherwise (with the particular cases \( \mathbf{0} = \mathbf{1}_{\emptyset} \) and \( \mathbf{1} = \mathbf{1}_{[n]} \)).

Through the usual identification of the elements of \( \mathbb{B}^n \) with the subsets of \([n]\), a pseudo-Boolean function \( f: \mathbb{B}^n \rightarrow \mathbb{R} \) can be equivalently described by a set function \( v_f: 2^{[n]} \rightarrow \mathbb{R} \). We simply write \( v_f(S) = f(\mathbf{1}_S) \). To avoid cumbersome notation, we henceforth use the same symbol to denote both a given pseudo-Boolean function and its underlying set function, thus writing \( f: \mathbb{B}^n \rightarrow \mathbb{R} \) or \( f: 2^{[n]} \rightarrow \mathbb{R} \) interchangeably.

Recall that if the \( \mathbb{B} \)-valued variables \( x_1, \ldots, x_n \) are rearranged in ascending order of magnitude \( x_{(1)} \leq \cdots \leq x_{(n)} \), then \( x_{(k)} \) is called the \( k \)th order statistic and the function \( \text{os}_k: \mathbb{B}^n \rightarrow \mathbb{B} \), defined as \( \text{os}_k(\mathbf{x}) = x_{(k)} \), is the \( k \)th order statistic function.
We then have $os_k(x) = 1$, if $\sum_{i=1}^{n} x_i \geq n - k + 1$, and 0, otherwise. As a matter of convenience, we also formally define $os_0 \equiv 0$ and $os_{n+1} \equiv 1$. An $L$-statistic function is a linear combination of the functions $os_1, \ldots, os_n$ while a shifted $L$-statistic function is a linear combination of the functions $os_1, \ldots, os_{n+1}$.

2. **Symmetric approximations**

In this section we present and solve the problem of approximation of pseudo-Boolean functions by shifted $L$-statistic functions and discuss a few properties of the approximations.

Recall that any $n$-ary pseudo-Boolean function $f$ can always be represented by a multilinear polynomial of degree at most $n$ (see [6]). More precisely, $f$ can always be written in the form

$$f(x) = \sum_{S \subseteq [n]} f(S) \prod_{i \in S} x_i \prod_{i \in [n] \setminus S} (1 - x_i).$$

By expanding the second product, we see that this polynomial can be further simplified into

$$f(x) = \sum_{S \subseteq [n]} a_f(S) \prod_{i \in S} x_i,$$

where the set function $a_f : 2^{[n]} \rightarrow \mathbb{R}$, called the M"{o}bius transform of $f$, is defined by

$$a_f(S) = \sum_{T \subseteq S} (-1)^{|S| - |T|} f(T).$$

Denote by $F(\mathbb{B}^n)$ the vector space of $n$-ary pseudo-Boolean functions and by $F_S(\mathbb{B}^n)$ the subspace of symmetric $n$-ary pseudo-Boolean functions. It is clear that a function $f \in F(\mathbb{B}^n)$ is symmetric if and only if it is cardinality-based, i.e., it satisfies the property $f(S) = f(T)$ for every $S, T \subseteq [n]$ such that $|S| = |T|$. Equivalently, there exists a unique function $\overline{f} : \{0, 1, \ldots, n\} \rightarrow \mathbb{R}$ such that $f(S) = \overline{f}(|S|)$.

The following proposition shows that the shifted $L$-statistic functions are precisely those pseudo-Boolean functions that are symmetric.

**Proposition 1.** A pseudo-Boolean function is symmetric if and only if it is a shifted $L$-statistic function.

**Proof.** The class of $n$-ary shifted $L$-statistic functions is clearly a subspace of $F_S(\mathbb{B}^n)$. Since each of these spaces has dimension $n + 1$, they must coincide. $\square$

Given a weight function $w : \mathbb{B}^n \rightarrow ]0, \infty[$ and a function $f \in F(\mathbb{B}^n)$, we define the best symmetric approximation of $f$ with respect to $w$ as the unique function $f_L \in F_S(\mathbb{B}^n)$ that minimizes the weighted squared distance

$$\|f - g\|^2 = \sum_{x \in \mathbb{B}^n} w(x)(f(x) - g(x))^2$$

among all symmetric functions $g \in F_S(\mathbb{B}^n)$. Since $\| \cdot \|$ is the norm associated with the inner product

$$\langle f, g \rangle = \sum_{x \in \mathbb{B}^n} w(x)f(x)g(x),$$

the solution $f_L$ of this approximation problem exists and is uniquely determined by the orthogonal projection of $f$ onto $F_S(\mathbb{B}^n)$. We then write $f_L = A(f)$.

We will henceforth assume (without loss of generality) that the weights are multiplicatively normalized so that $\sum_{x \in \mathbb{B}^n} w(x) = 1$. Although this assumption is not
necessary for most of the results, it will enable us to interpret \( w \) as a probability distribution and make use of certain concepts in probability theory.

**Definition 2.** For every \( f \in F(\mathbb{B}^n) \), define \( \overline{f} : \{0, 1, \ldots, n\} \to \mathbb{R} \) as

\[
\overline{f}(s) = E(f(x) \mid |x| = s) = \frac{\sum_{|x|=s} w(x) f(x)}{\sum_{|x|=s} w(x)}, \quad 1
\]

We also formally define \( \overline{f}(-1) = 0 \).

The next theorem gives an explicit expression for \( A(f) \).

**Theorem 3.** The best symmetric approximation of \( f \in F(\mathbb{B}^n) \) is given by

\[
A(f) = \sum_{j=1}^{n+1} c_j \text{o}_j,
\]

where \( c_j = \overline{f}(n-j+1) - \overline{f}(n-j) \) for every \( j \in [n+1] \).

**Proof.** Since \( F_q(\mathbb{B}^n) \) is spanned by the \( n+1 \) functions \( \text{o}_1, \ldots, \text{o}_n, \text{o}_{n+1} \), the projection \( A(f) \) is characterized by the conditions

\[
(f - A(f), \text{o}_i) = 0 \quad (i \in [n+1]),
\]

that is,

\[
\sum_{|x|=n-i+1} w(x)(f(x) - A(f)(x)) = 0 \quad (i \in [n+1]).
\]

We observe that the system (6) remains equivalent if we replace the inequality \( |x| \geq n-i+1 \) with the equality. Using (4), we then obtain

\[
\left( \sum_{j=1}^{n+1} c_j \right) \left( \sum_{|x|=n-i+1} w(x) \right) = \sum_{|x|=n-i+1} w(x)f(x) \quad (i \in [n+1])
\]

We finally obtain the result by using (3) and subtracting equation \( i+1 \) from equation \( i \). \( \square \)

We now provide alternative expressions for \( A(f) \) as a shifted L-statistic function and symmetric multilinear polynomials. Observing first that \( \overline{f}(0) = f(0) \) and then using (4) and (5) for \( i = n+1 \), we obtain

\[
A(f) = f(0) + \sum_{j=1}^{n} c_j \text{o}_j = (f, 1) + \sum_{j=1}^{n} c_j (\text{o}_j - (\text{o}_j, 1)),
\]

where \( c_j = \overline{f}(n-j+1) - \overline{f}(n-j) \) for every \( j \in [n] \). Then, using (3), (4), and (7), we obtain

\[
A(f)(S) = \sum_{j=n-|S|+1} c_j = E(f(x) \mid |x| = |S|) = \overline{f}(|S|) \quad (S \subseteq [n])
\]

so that by (2) we obtain immediately

\[
A(f)(x) = \sum_{S \subseteq [n]} \overline{f}(|S|) \prod_{i \in S} x_i \prod_{i \in [n] \setminus S} (1 - x_i) = \sum_{S \subseteq [n]} \Delta^{|S|}_{k=0} \overline{f}(k)s \prod_{i \in S} x_i,
\]

\(^{1}\text{Although } \overline{f} \text{ depends explicitly on } w, \text{ we use this notation for it is consistent with that introduced for cardinality-based set functions. Note also that, in the special case when the weight function } w \text{ is symmetric, } \overline{f}(s) \text{ clearly reduces to } \binom{n}{s}^{-1} \sum_{|x|=s} f(x).\)
Proof. The first equality follows from the symmetry of Sym

Proposition 8. Let $S_n$ denote the symmetric group on $[n]$. A permutation $\pi \in S_n$ acts on a pseudo-Boolean function $f \in F(\mathbb{B}^n)$ by $\pi(f)(x_1, \ldots, x_n) = f(x_{\pi(1)}, \ldots, x_{\pi(n)})$. A permutation $\pi \in S_n$ is said to be a symmetry of $f \in F(\mathbb{B}^n)$ if $\pi(f) = f$.

**Proposition 4.** If $\pi \in S_n$ is a symmetry of the weight function $w$, then for every $f \in F(\mathbb{B}^n)$ we have $A(\pi(f)) = A(f)$ and $\|A(f) - A(\pi(f))\| = \|f - A(f)\|$.  

*Proof.* If $\pi$ is a symmetry of $w$, then clearly it is an isometry of $F(\mathbb{B}^n)$, that is, $\langle \pi(f), \pi(g) \rangle = \langle f, g \rangle$. Now, if $g \in F_\delta(\mathbb{B}^n)$, then by (5), we have $\langle \pi(f), g \rangle = \langle \pi(f), \pi(g) \rangle = \langle f, g \rangle = \langle A(f), g \rangle$, which shows that $A(\pi(f)) = A(f)$. We prove the second equality similarly since $\|\pi(f) - A(f)\|^2 = \|f - A(f)\|^2$. \qed

With any pseudo-Boolean function $f \in F(\mathbb{B}^n)$, we can associate the symmetric function $\text{Sym}(f) = \frac{1}{n!} \sum_{\pi \in S_n} \pi(f)$. We then have the following result.

**Corollary 5.** If the weight function $w$ is symmetric, then for every $f \in F(\mathbb{B}^n)$ we have $\text{Sym}(f) = A(\text{Sym}(f)) = A(f)$.  

*Proof.* The first equality follows from the symmetry of $\text{Sym}(f)$. The second one follows from Proposition 4 and the linearity of the projector $A$. \qed

We end this section by analyzing the effect of dualization of $f$ on the symmetric approximation $A(f)$. The dual of a function $f \in F(\mathbb{B}^n)$ is the function $f^d \in F(\mathbb{B}^n)$ defined by $f^d(x) = f(0) + f(1) - f(1_{\{n\}} - x)$.

**Proposition 6.** If the weight function $w$ satisfies $w(1_{\{n\}} - x) = w(x)$ for all $x \in \mathbb{B}^n$, then for every $f \in F(\mathbb{B}^n)$ we have $A(f^d) = A(f)^d$.  

*Proof.* By (5) and (9), we have $A(f)(1) - f(1) = A(f)(0) - f(0) = \langle A(f), 1 \rangle - \langle f, 1 \rangle = 0$. From these equalities, we obtain $\langle f^d - A(f)^d, g^d \rangle = \langle (f - A(f))^d, g^d \rangle = \langle f - A(f), g \rangle = 0$ for every function $g \in F_\delta(\mathbb{B}^n)$. The result then follows. \qed

3. INFLUENCE OF THE kTH SMALLEST VARIABLE

Following Hammer and Holzman’s approach [5], to measure the influence of the $k$th smallest variable $x_{\{k\}}$ on a pseudo-Boolean function $f \in F(\mathbb{B}^n)$, it is natural to define an index $I: F(\mathbb{B}^n) \times [n] \rightarrow \mathbb{R}$ as $I(f, k) = \delta_k$, where $\delta_k$ is defined in Theorem 3.2

**Definition 7.** Let $I: F(\mathbb{B}^n) \times [n] \rightarrow \mathbb{R}$ be defined as $I(f, k) = \overline{f}(n-k+1) - \overline{f}(n-k)$.  

Thus we have defined an influence index from an elementary approximation (projection) problem. Conversely, the following result shows that $A(f)$ is the unique function of $F_\delta(\mathbb{B}^n)$ that preserves the average value and the influence index of $f$.

**Proposition 8.** A function $g \in F_\delta(\mathbb{B}^n)$ is the best symmetric approximation of $f \in F(\mathbb{B}^n)$ if and only if $\langle f, 1 \rangle = \langle g, 1 \rangle$ and $I(f, k) = I(g, k)$ for all $k \in [n]$.  

\[2\] We observe that, by definition, this index remains invariant under normalization of $w$.  

Proof. The necessity is trivial (use Eq. (5) for \( i = n + 1 \)). To prove the sufficiency, observe that any \( g \in F_S(\mathbb{B}^n) \) satisfying the assumptions of the proposition is of the form

\[
g = g(0) + \sum_{j=1}^n I(g,j) \sigma_j = g(0) + \sum_{j=1}^n I(f,j) \sigma_j.
\]

We then have \( g(0) + \sum_{j=1}^n I(f,j) \langle \sigma_j, 1 \rangle = \langle g, 1 \rangle = \langle f, 1 \rangle \). Using (8), we finally obtain \( g = A(f) \).

The next proposition reassembles several properties of the index \( I(f,k) \). These properties follow easily from the definition of the index and the properties of the approximations.

**Proposition 9.** Let \( k \in [n] \) and let \( w: \mathbb{B}^n \to [0, \infty[ \) be a weight function. Then

(i) The map \( f \mapsto I(f,k) \) is linear.
(ii) If \( \pi \) is a symmetry of \( w \), then \( I(\pi(f), k) = I(f, k) \) for every \( f \in F(\mathbb{B}^n) \).
(iii) If \( w \) is symmetric, then \( I(f,k) = I(\text{Sym}(f), k) \) for every \( f \in F(\mathbb{B}^n) \).
(iv) If \( w \) satisfies \( w(\{1_{[n]} - x\}) = w(x) \) for all \( x \in \mathbb{B}^n \), then \( I(f^n, k) = I(f, n-k+1) \) for every \( f \in F(\mathbb{B}^n) \).
(v) We have \( \sum_{j=1}^n I(f,j) = f(1) - f(0) \).

It is a well-known fact of linear algebra that a linear map on a finite dimensional inner product space can be expressed as an inner product with a fixed vector. The next proposition gives the explicit form of such a vector for \( I(\cdot, k) \). To this extent, for every \( k \in [n] \) we introduce the function \( g_k: \mathbb{B}^n \to \mathbb{R} \) as \( g_k(x) = \Delta_k(d_k \Delta_k \sigma_{n-k-1}) \), where \( d_k = -1/\sum_{|x|=n-k+1} w(x) \).

**Proposition 10.** For every \( f \in F(\mathbb{B}^n) \) and every \( k \in [n] \), we have \( I(f,k) = \langle f, g_k \rangle \).

Proof. We have \( d_{k+1} f, \Delta_k \sigma_k = d_{k+1} \sum_{|x|=n-k} w(x)f(x) = -f(n-k) \), which leads immediately to the result.

Proposition 10 shows that the index \( I(f,k) \) is the covariance of the random variables \( f \) and \( g_k \). Indeed, we have \( I(f,k) = E(f g_k) = \text{cov}(f,g_k) + E(f) E(g_k) \), where \( E(g_k) = \langle 1, g_k \rangle = I(1, k) = 0 \). From the usual interpretation of the concept of covariance, we see that an element \( \mathbf{x} \in \mathbb{B}^n \) makes a positive contribution to \( I(f,k) \) whenever the values of \( f(x) - E(f) \) and \( g_k(x) - E(g_k) = g_k(x) \) have the same sign. Note that \( g_k(x) \) is positive whenever \( x(k) \) is greater than the value \( (d_{k+1} x_{(k+1)} + d_k x_{(k-1)})/(d_{k+1} + d_k) \), which lies in the range of \( x(k) \) when the other order statistics are fixed at \( x \).

4. Two special cases: Cardinality index and system signature

We now show that the **cardinality index** and **system signature** are particular instances of our influence index.

4.1. The cardinality index of a fuzzy measure. A fuzzy measure on the finite set \( X = [n] \) is a nondecreasing set function \( \mu: 2^X \to [0,1] \) satisfying the boundary conditions \( \mu(\emptyset) = 0 \) and \( \mu(X) = 1 \). For any subset \( S \subseteq X \), the number \( \mu(S) \) can be interpreted as the certitude that we have that a variable will take on its value in the set \( S \subseteq X \). In this context, Yager [15] introduced the **cardinality index** associated with a fuzzy measure \( \mu \) as the \( n \)-tuple \( (C_0, \ldots, C_{n-1}) \) where \( C_k \) is the average gain
in certitude that we obtain by adding an arbitrary element to an arbitrary \( k \)-subset, that is,
\[
C_k = \frac{1}{(n-k){n \choose k}} \sum_{|S|=k} \sum_{x \in S} \left( \mu(S \cup \{x\}) - \mu(S) \right).
\]
We observe that this expression, which resembles the Banzhaf value (1), could be used in cooperative game theory to measure the marginal contribution of an additional player to a \( k \)-coalition. It is also clear that this index can be written as
\[
C_k = \frac{1}{(n-k){n \choose k}} \sum_{|S|=k+1} \mu(S) - \frac{1}{|S|=k} \sum_{|S|=k} \mu(S),
\]
which shows that we have \( C_k = I(\mu, n-k) = I(\mu^d, k+1) \) in the special case when the weight function \( w \) defining the index \( I \) is symmetric.

4.2. System signatures in engineering reliability. Consider a system consisting of \( n \) interconnected components. When the components have continuous and i.i.d. lifetimes \( X_1, \ldots, X_n \), the signature of the system is defined as the \( n \)-tuple \( (s_1, \ldots, s_n) \in [0, 1]^n \) with \( s_k = \Pr(T = X_{(k)}) \), where \( T \) denotes the system lifetime. That is, \( s_k \) is the probability that the \( k \)th failure causes the system to fail (for a recent reference, see [12]). It was proved [2] that
\[
s_k = \frac{1}{(n-k){n \choose n-k+1}} \sum_{|\mathbf{x}|=n-k+1} \phi(\mathbf{x}) - \frac{1}{|S|=n-k} \sum_{|S|=n-k} \phi(\mathbf{x}),
\]
where \( \phi: \mathbb{B}^n \to \mathbb{B} \) is the structure function of the system. Thus, in view of Definitions 2 and 7, we have \( s_k = I(\phi, k) \) in the special case where the weight function \( w \) is symmetric. Interestingly, the identity \( s_k = I(\phi, k) \) still holds in the non-i.i.d. case if we define the weight function \( w \) as the (non-normalized) relative quality function
\[
w(S) = \Pr\left( \max_{i \in [n] \setminus S} X_i < \min_{j \in S} X_j \right)
\]
for which we have \( \sum_{|\mathbf{x}|=s} w(\mathbf{x}) = 1 \) for all \( s \in [n] \) (see [9]). Therefore \( s_k \) can be obtained from a weighted least squares approximation problem of the structure function and can always be interpreted as the influence on the system of the component that has the \( k \)th smallest lifetime.

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