

Cuts from two rows of the simplex tableau

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Joint work with K. Andersen, R. Weismantel, L. Wolsey

The mixed-integer programming problem

$$\begin{array}{ll}\max & cx + dw \\ \text{s. t.} & Ax + Gw \leq b \\ & x \in \mathbb{Z}^{n_1}, w \in \mathbb{R}^{n_2}\end{array}$$

Cutting plane generation

Cutting plane generation in mixed-integer programming

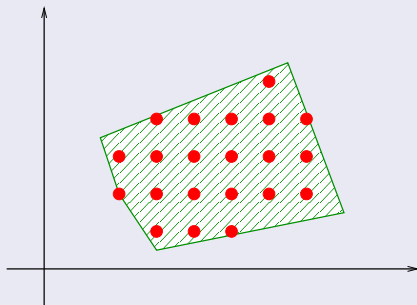
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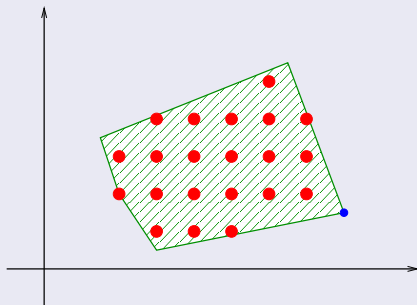
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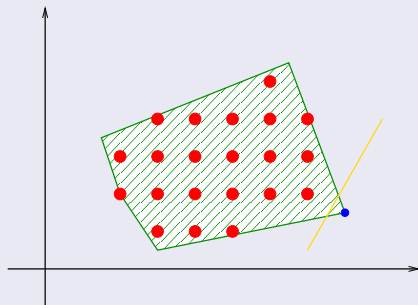
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Central question : generation of cutting planes

- ① Methods depending on the structure of the problem
→ network problems, TSP, ...
- ② General methods
 - Gomory mixed-integer cut (or MIR)

$$X = \{(x, y) \in \mathbb{Z} \times \mathbb{R}_+ \mid x + y \geq b\}$$

The only missing inequality is

$$x + \frac{1}{1 - f(b)} y \geq \lceil b \rceil$$

- Split cut
Generalization of the Gomory cuts

All based on the information of **one constraint** or several constraints **aggregated in one inequality**.

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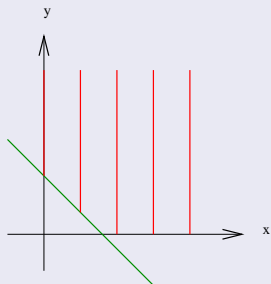
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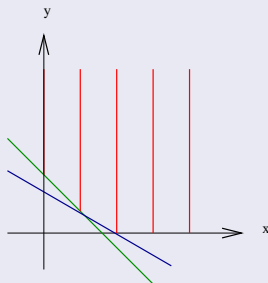
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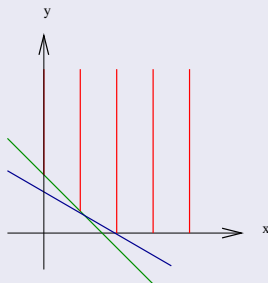
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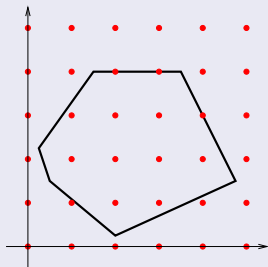
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The geometry

Theoretical results

- Every cut that can be obtained from *one row* or from the *aggregation in one row* is a split cut.
 - Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only *does not guarantee* to converge to the convex hull in *finite time*.

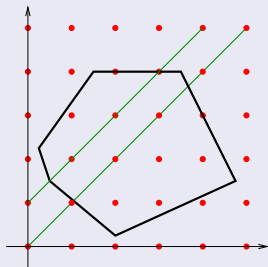
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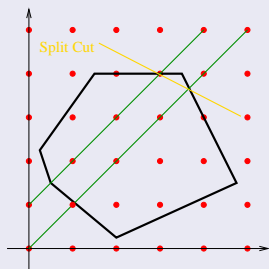
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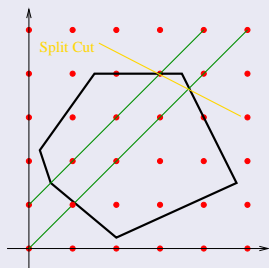
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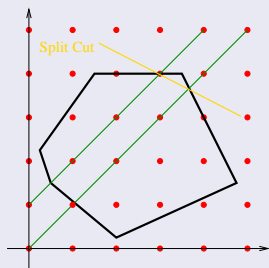
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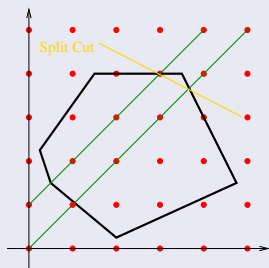
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The simplex tableau

$$x_1 - \bar{a}_{11}s_1 - \cdots - \bar{a}_{1n}s_n = \bar{b}_1$$

$$\vdots$$

$$x_m - \bar{a}_{m1}s_1 - \cdots - \bar{a}_{mn}s_n = \bar{b}_m$$

- Select two rows
- Relax the integrality requirements of the non-basic variables
- Relax the nonnegativity requirements of the basic variables

The model

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} s_j$$

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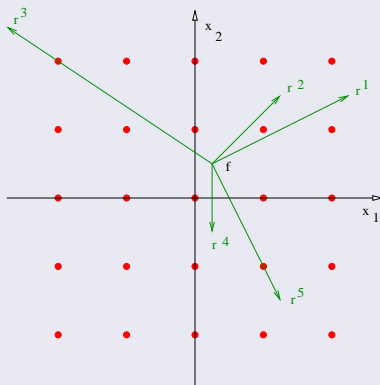
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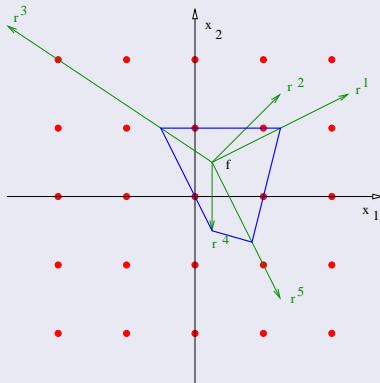
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$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1/4 \\ 1/2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} s_1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_2 + \begin{pmatrix} -3 \\ 2 \end{pmatrix} s_3 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} s_4 + \begin{pmatrix} 1 \\ -2 \end{pmatrix} s_5$$



Graphic representation of a facet

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$



Basic properties of the polyhedron

$$\text{conv}(P_I) = \text{conv}\{(\mathbf{x}, \mathbf{s}) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} s_j\}$$

- 1 The dimension of the polyhedron is n (when nonempty)
- 2 The vectors (r^j, e_j) are **extreme rays** of the polyhedron
→ If the rays are rational, one solution can always be extended
- 3 Every facet can be written in the form

$$\sum_{j=1}^n \alpha_j s_j \geq 1,$$

with $\alpha_j \geq 0$.

- 4 **Extreme point** = **One integer point** and **two non-zero rays**

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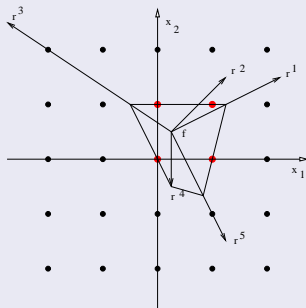
Main results

- 1 Every facet is **tangent** to **exactly** 3 or 4 important integer points
- 2 Every facet is **completely** determined by **exactly** 3 or 4 rays
- 3 Classification of the facets in 3 categories :
dissection cuts, lifted 2 variable-cuts, split cuts

The facets from the first 2 categories are **never split cuts**
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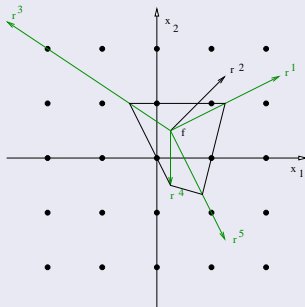
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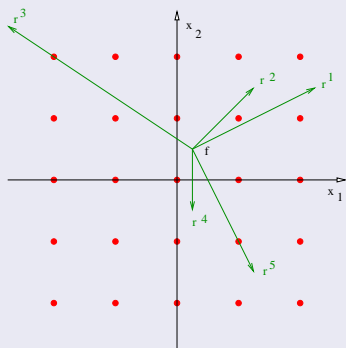
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The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

α_1, α_3

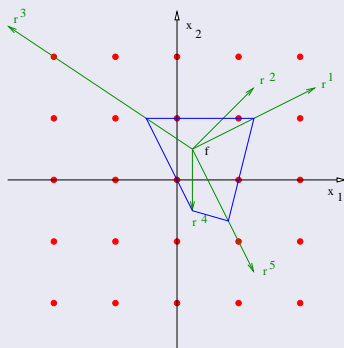


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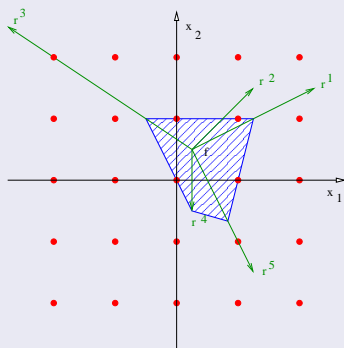


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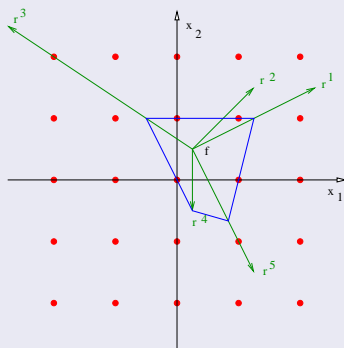


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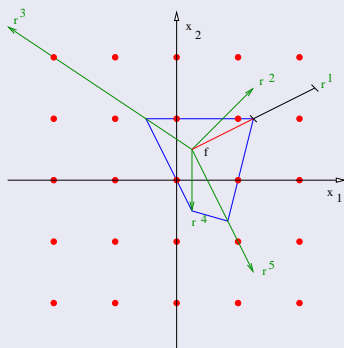


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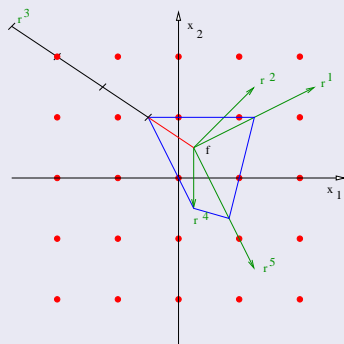


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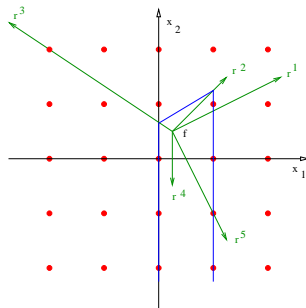
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Facets with a 0 coefficient are actually split cuts.

$$\frac{8}{3}s_1 + \frac{4}{3}s_2 + 12s_3 + 0s_4 + \frac{4}{3}s_5 \geq 1$$

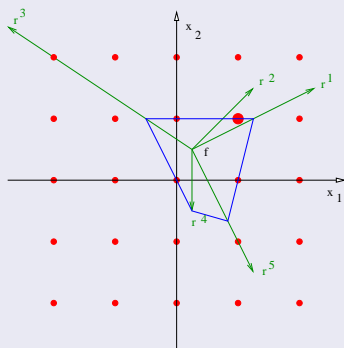


There cannot be a facet with two 0-coefficients unless two rays are parallel.

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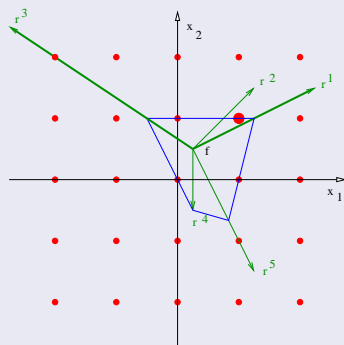
- What about tight integer points?
- It can be represented as a minimal combination of two s_j in several cones
 $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
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- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



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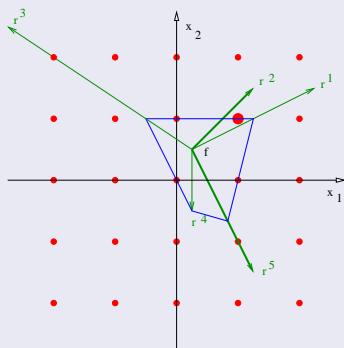
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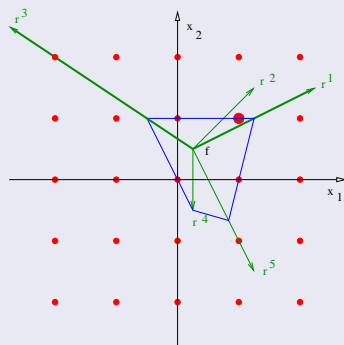
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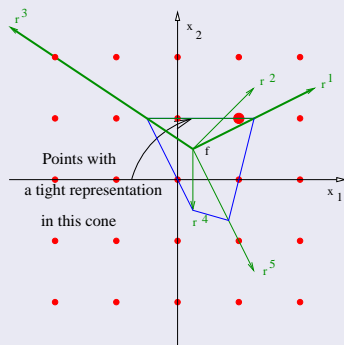
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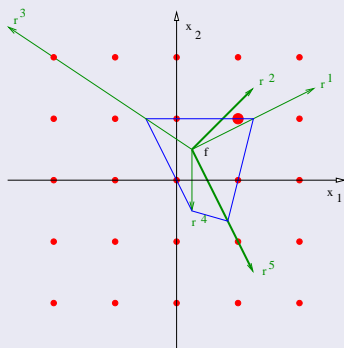
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The projection picture

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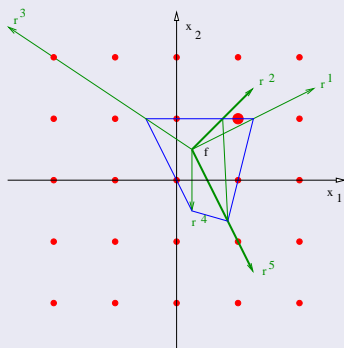
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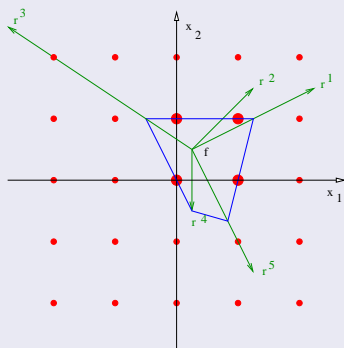
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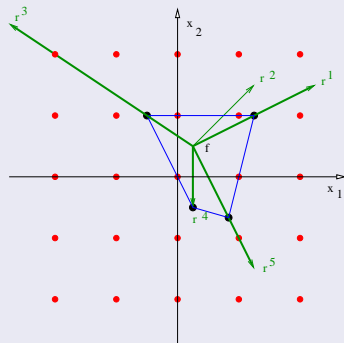
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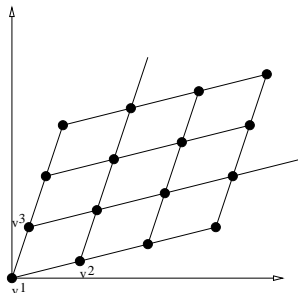
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Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.

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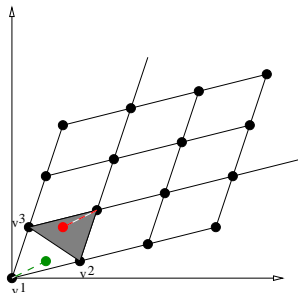
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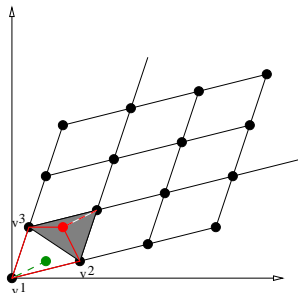
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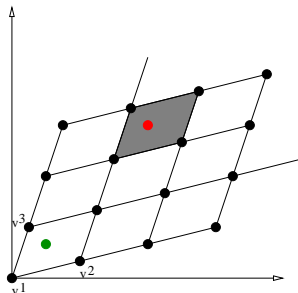
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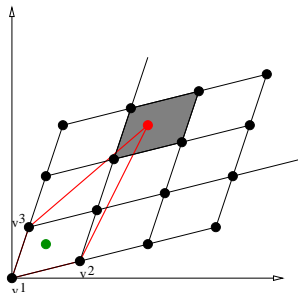
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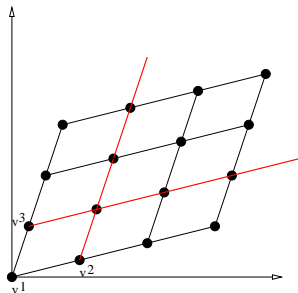
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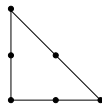
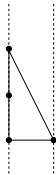
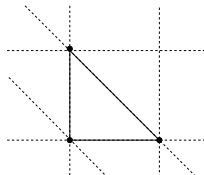
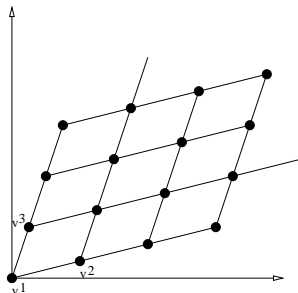
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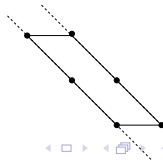
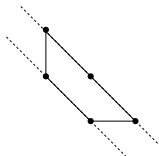
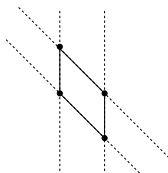
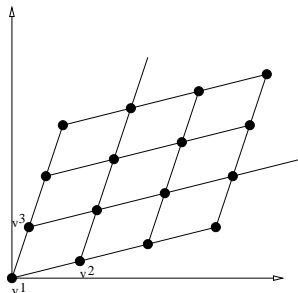
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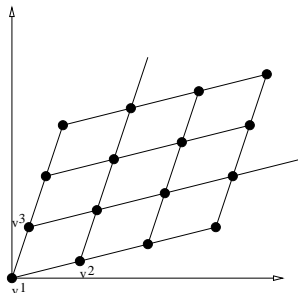
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No split cuts

Why three or four rays?

- There exists a **minimal** system that determines the facet
- Every tight integer point provides an equality

$$\alpha_i \gamma_i + \alpha_j \gamma_j = 1$$

in one **tight** representation, where (γ_i, γ_j) is the representation of the point in the cone (r^i, r^j) .

- All other tight representations are **automatically** satisfied
- To have the minimally uniquely determined system
 - 3 tight integer points \Rightarrow 3 variables i.e. 3 rays
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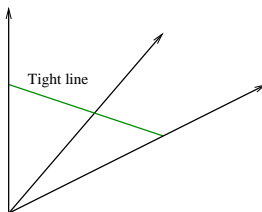
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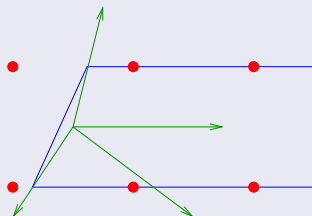
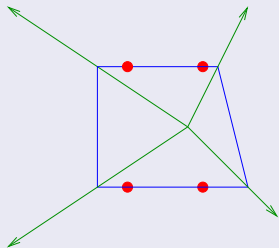
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Split cuts

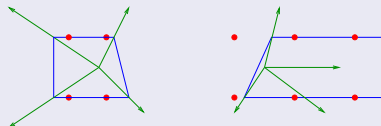


Dissection cuts and Lifted 2-var cuts

These are never split cuts!

An important pathological case

Split cuts



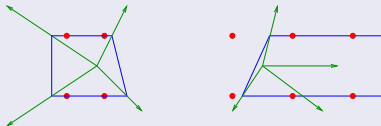
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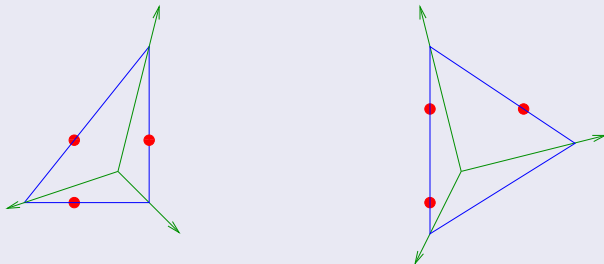
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Classification of the facets

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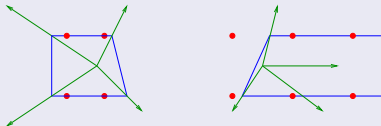


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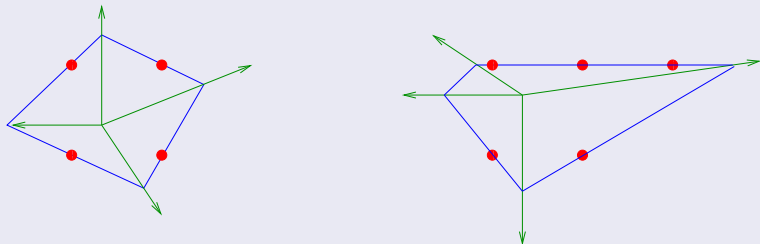
Figures

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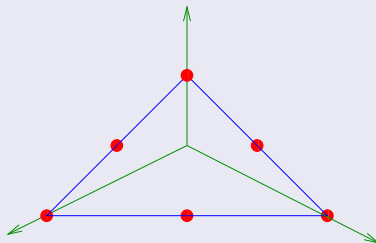
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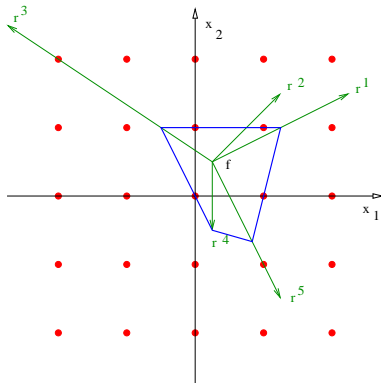
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Simultaneous lifting by reading the coefficients on the figure

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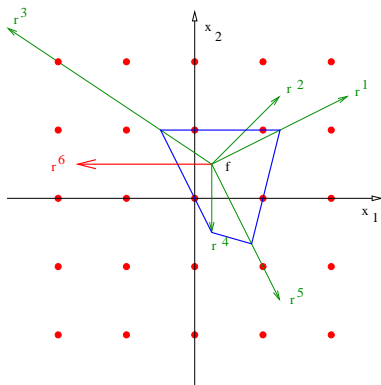
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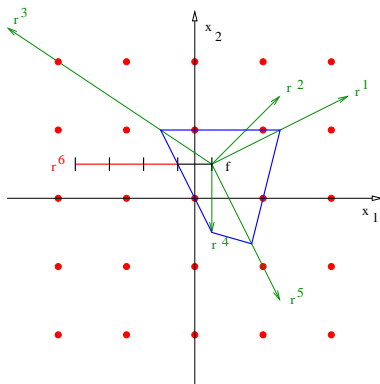
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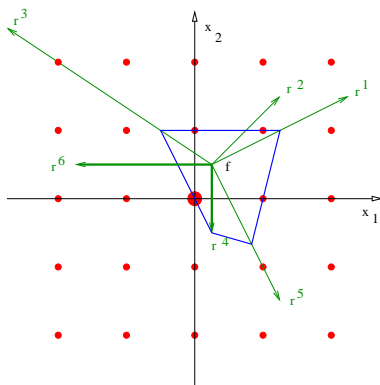
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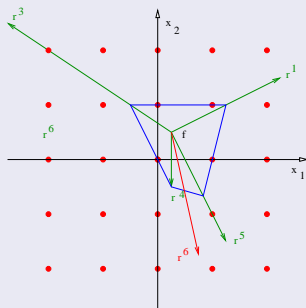
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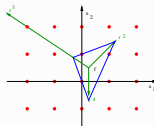
It is a facet !

Lifted 2 variable cuts

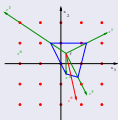


The lifted valid inequality is **not a facet** !

Dissection cuts are universally liftable

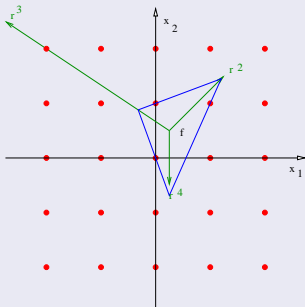


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Towards practice ?

① General principle to generate cuts

- Choose 3 or 4 **integer points**
Which points ?
- Choose 3 or 4 **rays**
- Compute the **cut**

② Important related questions

- Strengthen an inequality by considering the **integrality** of a ray ?
- **Bounds** on x and on y
- Generalization to **several constraints**
Includes a generalization of the split to a d -dimensional body with no integer point in its interior

Finite convergence for a cutting plane algorithm

- ① Which black box is necessary to converge in finite time ?
- ② Problem with m constraints \rightarrow black box with m constraints ?

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