

Cuts from two rows of the simplex tableau

Quentin Louveaux

Université catholique de Louvain - CORE - INMA

October, 31 2006

Joint work with K. Andersen, R. Weismantel, L. Wolsey

The mixed-integer programming problem

$$\begin{aligned} & \max cx + dw \\ \text{s. t. } & Ax + Gw \leq b \\ & x \in \mathbb{Z}^{n_1}, w \in \mathbb{R}^{n_2} \end{aligned}$$

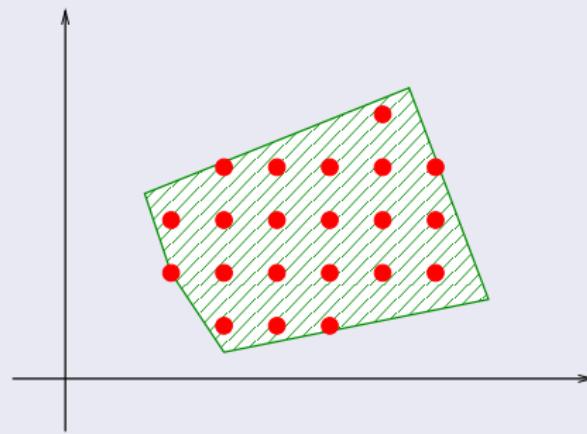
Cutting plane generation

Cutting plane generation in mixed-integer programming

The mixed-integer programming problem

$$\begin{aligned} & \max cx + dw \\ \text{s. t. } & Ax + Gw \leq b \\ & x \in \mathbb{Z}^{n_1}, w \in \mathbb{R}^{n_2} \end{aligned}$$

Cutting plane generation

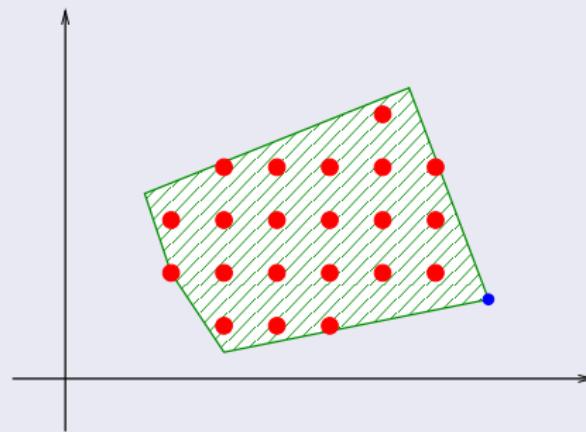


Cutting plane generation in mixed-integer programming

The mixed-integer programming problem

$$\begin{aligned} & \max cx + dw \\ \text{s. t. } & Ax + Gw \leq b \\ & x \in \mathbb{Z}^{n_1}, w \in \mathbb{R}^{n_2} \end{aligned}$$

Cutting plane generation

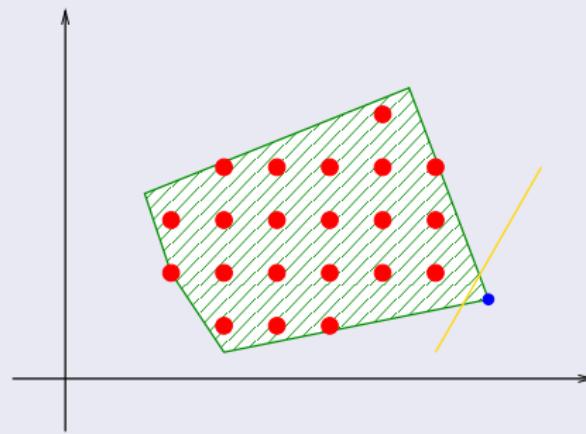


Cutting plane generation in mixed-integer programming

The mixed-integer programming problem

$$\begin{aligned} & \max cx + dw \\ \text{s. t. } & Ax + Gw \leq b \\ & x \in \mathbb{Z}^{n_1}, w \in \mathbb{R}^{n_2} \end{aligned}$$

Cutting plane generation



Cutting plane generation in integer programming

Central question : generation of cutting planes

- ① Methods depending on the structure of the problem
 - network problems, TSP, ...
- ② General methods
 - Gomory mixed-integer cut (or MIR)

$$X = \{(x, y) \in \mathbb{Z} \times \mathbb{R}_+ \mid x + y \geq b\}$$

The only missing inequality is

$$x + \frac{1}{1 - F(b)} y \geq \lceil b \rceil$$

• Split cut

Generalization of the Gomory cuts

All based on the information of one constraint or several constraints aggregated in one inequality.

Cutting plane generation in integer programming

Central question : generation of cutting planes

- ① Methods depending on the structure of the problem
 - network problems, TSP, ...
- ② General methods
 - Gomory mixed-integer cut (or MIR)

$$X = \{(x, y) \in \mathbb{Z} \times \mathbb{R}_+ \mid x + y \geq b\}$$

The only missing inequality is

$$x + \frac{1}{1 - F(b)} y \geq \lceil b \rceil$$

- Split cut
Generalization of the Gomory cuts

All based on the information of one constraint or several constraints aggregated in one inequality.

Cutting plane generation in integer programming

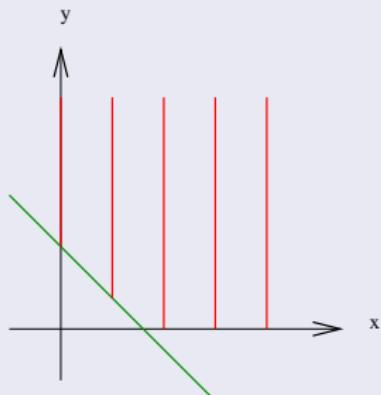
Central question : generation of cutting planes

- ① Methods depending on the structure of the problem
 - network problems, TSP, ...
- ② General methods
 - Gomory mixed-integer cut (or MIR)

$$X = \{(x, y) \in \mathbb{Z} \times \mathbb{R}_+ \mid x + y \geq b\}$$

The only missing inequality is

$$x + \frac{1}{1 - \mathcal{F}(b)}y \geq \lceil b \rceil$$



- Split cut

Generalization of the Gomory cuts

All based on the information of **one constraint** or several constraints **aggregated in one inequality**.

Cutting plane generation in integer programming

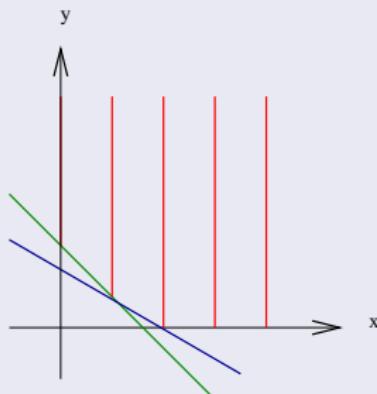
Central question : generation of cutting planes

- ① Methods depending on the structure of the problem
 - network problems, TSP, ...
- ② General methods
 - Gomory mixed-integer cut (or MIR)

$$X = \{(x, y) \in \mathbb{Z} \times \mathbb{R}_+ \mid x + y \geq b\}$$

The only missing inequality is

$$x + \frac{1}{1 - \mathcal{F}(b)}y \geq \lceil b \rceil$$



- Split cut
- Generalization of the Gomory cuts

All based on the information of one constraint or several constraints aggregated in one inequality.

Cutting plane generation in integer programming

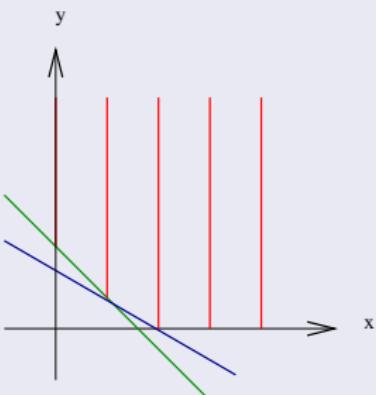
Central question : generation of cutting planes

- ① Methods depending on the structure of the problem
 - network problems, TSP, ...
- ② General methods
 - Gomory mixed-integer cut (or MIR)

$$X = \{(x, y) \in \mathbb{Z} \times \mathbb{R}_+ \mid x + y \geq b\}$$

The only missing inequality is

$$x + \frac{1}{1 - \mathcal{F}(b)}y \geq \lceil b \rceil$$



- Split cut
- Generalization of the Gomory cuts

All based on the information of **one constraint** or several constraints **aggregated in one inequality**.

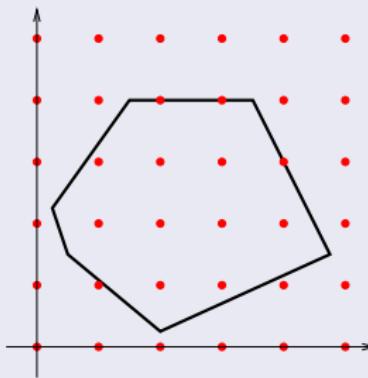
The geometry

Theoretical results

- Every cut that can be obtained from one row or from the aggregation in one row is a split cut.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only does not guarantee to converge to the convex hull in finite time.

Split cuts

The geometry

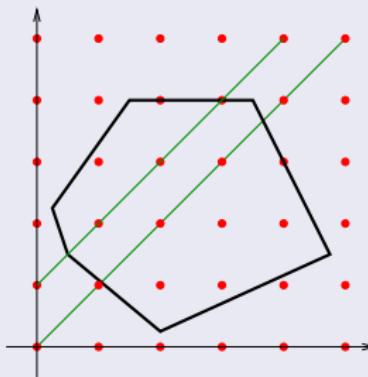


Theoretical results

- Every cut that can be obtained from **one row** or from the **aggregation in one row** is a split cut.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only **does not guarantee** to converge to the convex hull in **finite time**.

Split cuts

The geometry

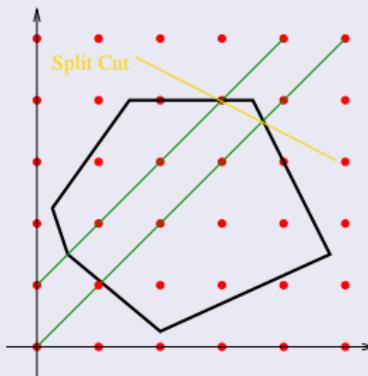


Theoretical results

- Every cut that can be obtained from **one row** or from the **aggregation in one row** is a split cut.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only **does not guarantee** to converge to the convex hull in **finite time**.

Split cuts

The geometry

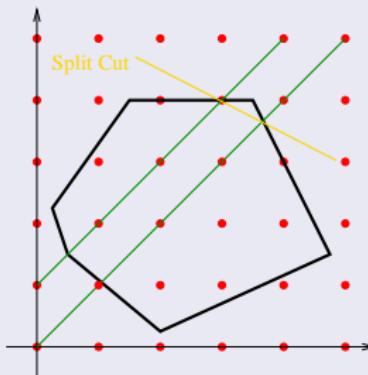


Theoretical results

- Every cut that can be obtained from **one row** or from the **aggregation in one row** is a split cut.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only **does not guarantee** to converge to the convex hull in **finite time**.

Split cuts

The geometry

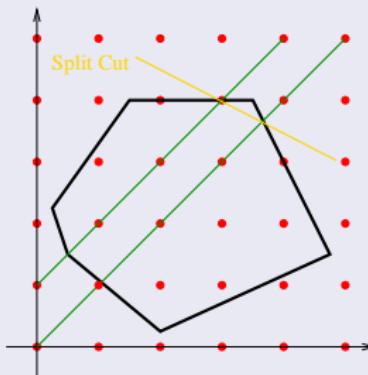


Theoretical results

- Every cut that can be obtained from **one row** or from the **aggregation in one row** is a **split cut**.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only **does not guarantee** to converge to the convex hull in **finite time**.

Split cuts

The geometry

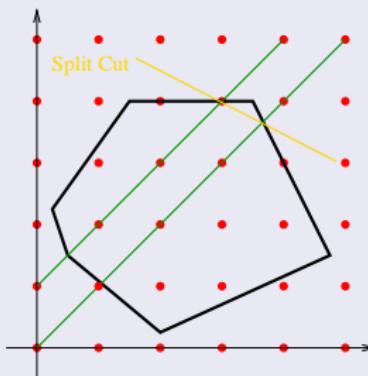


Theoretical results

- Every cut that can be obtained from **one row** or from the **aggregation in one row** is a **split cut**.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only **does not guarantee** to converge to the convex hull in **finite time**.

Split cuts

The geometry



Theoretical results

- Every cut that can be obtained from **one row** or from the **aggregation in one row** is a **split cut**.
→ Very general class
- Includes MIR which is commonly used in commercial softwares.
- Using split cuts only **does not guarantee** to converge to the convex hull in **finite time**.

Fundamental problem with two constraints

The simplex tableau

$$x_1 - \bar{a}_{11}s_1 - \cdots - \bar{a}_{1n}s_n = \bar{b}_1$$

⋮

$$x_m - \bar{a}_{m1}s_1 - \cdots - \bar{a}_{mn}s_n = \bar{b}_m$$

- Select two rows
- Relax the integrality requirements of the non-basic variables
- Relax the nonnegativity requirements of the basic variables

The model

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} s_j$$

$$x_1, x_2 \in \mathbb{Z}, s_j \in \mathbb{R}_+$$

Fundamental problem with two constraints

The simplex tableau

$$x_1 - \bar{a}_{11}s_1 - \cdots - \bar{a}_{1n}s_n = \bar{b}_1$$

⋮

$$x_m - \bar{a}_{m1}s_1 - \cdots - \bar{a}_{mn}s_n = \bar{b}_m$$

- Select two rows
- Relax the integrality requirements of the non-basic variables
- Relax the nonnegativity requirements of the basic variables

The model

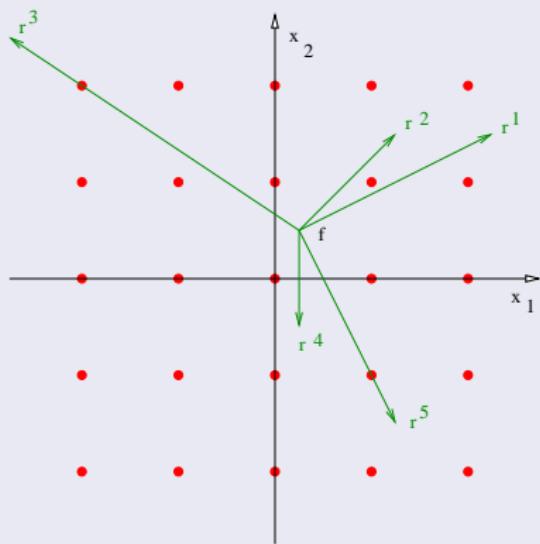
$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} s_j$$

$$x_1, x_2 \in \mathbb{Z}, s_j \in \mathbb{R}_+$$

Fundamental problem with two constraints

The geometry

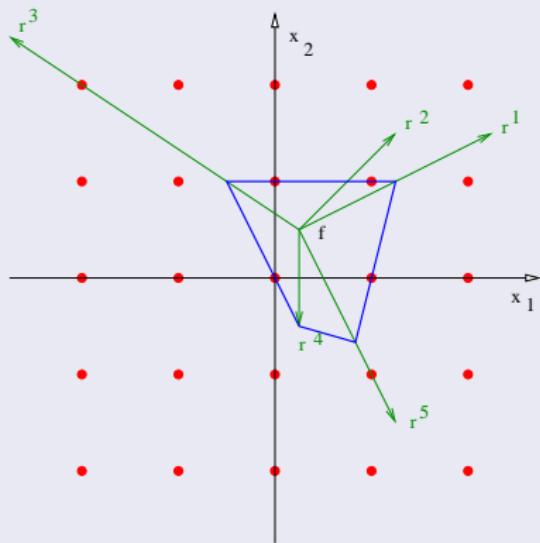
$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1/4 \\ 1/2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} s_1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_2 + \begin{pmatrix} -3 \\ 2 \end{pmatrix} s_3 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} s_4 + \begin{pmatrix} 1 \\ -2 \end{pmatrix} s_5$$



Fundamental problem with two constraints

Graphic representation of a facet

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$



Basic properties of the polyhedron

$$\text{conv}(P_I) = \text{conv}\{(\mathbf{x}, s) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} s_j\}$$

- ① The dimension of the polyhedron is n (when nonempty)
- ② The vectors (r^j, e_j) are **extreme rays** of the polyhedron
 - If the rays are rational, one solution can always be extended
- ③ Every facet can be written in the form

$$\sum_{j=1}^n \alpha_j s_j \geq 1,$$

with $\alpha_j \geq 0$.

- ④ Extreme point = One integer point and two non-zero rays

Basic properties of the polyhedron

$$\text{conv}(P_I) = \text{conv}\{(\mathbf{x}, \mathbf{s}) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid \begin{pmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{pmatrix} = \begin{pmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} \mathbf{r}_1^j \\ \mathbf{r}_2^j \end{pmatrix} \mathbf{s}_j \}$$

- ① The dimension of the polyhedron is n (when nonempty)



- ② The vectors $(\mathbf{r}^j, \mathbf{e}_j)$ are **extreme rays** of the polyhedron

→ If the rays are rational, one solution can always be extended

- ③ Every facet can be written in the form

$$\sum_{j=1}^n \alpha_j s_j \geq 1,$$

with $\alpha_j \geq 0$.

- ④ Extreme point = One integer point and two non-zero rays

Basic properties of the polyhedron

$$\text{conv}(P_I) = \text{conv}\{(\mathbf{x}, \mathbf{s}) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid \begin{pmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{pmatrix} = \begin{pmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} \mathbf{s}_j\}$$

- ① The dimension of the polyhedron is n (when nonempty)
- ② The vectors (r^j, e_j) are **extreme rays** of the polyhedron
 - *If the rays are rational, one solution can always be extended*
- ③ Every facet can be written in the form

$$\sum_{j=1}^n \alpha_j s_j \geq 1,$$

with $\alpha_j \geq 0$.

- ④ Extreme point = One integer point and two non-zero rays

Basic properties of the polyhedron

$$\text{conv}(P_I) = \text{conv}\{(\mathbf{x}, \mathbf{s}) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} \mathbf{s}_j\}$$

- ① The dimension of the polyhedron is n (when nonempty)
- ② The vectors (r^j, e_j) are **extreme rays** of the polyhedron
 - If the rays are rational, one solution can always be extended
- ③ Every facet can be written in the form

$$\sum_{j=1}^n \alpha_j s_j \geq 1,$$

with $\alpha_j \geq 0$.

- ④ Extreme point = One integer point and two non-zero rays

Basic properties of the polyhedron

$$\text{conv}(P_I) = \text{conv}\{(\mathbf{x}, \mathbf{s}) \in \mathbb{Z}^2 \times \mathbb{R}_+^n \mid \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} f_1 \\ f_2 \end{pmatrix} + \sum_{j=1}^n \begin{pmatrix} r_1^j \\ r_2^j \end{pmatrix} \mathbf{s}_j\}$$

- ① The dimension of the polyhedron is n (when nonempty)
- ② The vectors (r^j, e_j) are **extreme rays** of the polyhedron
 - If the rays are rational, one solution can always be extended
- ③ Every facet can be written in the form

$$\sum_{j=1}^n \alpha_j s_j \geq 1,$$

with $\alpha_j \geq 0$.

- ④ **Extreme point** = One integer point and two non-zero rays

Main results

- ① Every facet is **tangent** to **exactly** 3 or 4 important integer points
- ② Every facet is **completely** determined by **exactly** 3 or 4 rays
- ③ Classification of the facets in 3 categories :
disection cuts, lifted 2 variable-cuts, split cuts

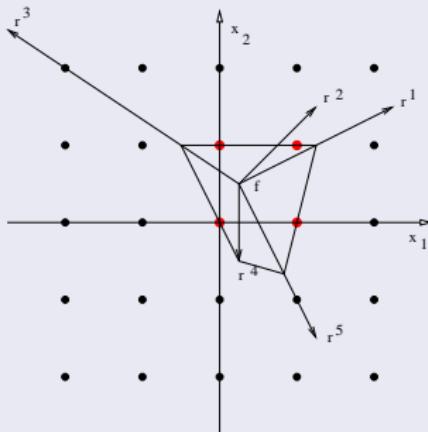
The facets from the first 2 categories are **never split cuts**

- ④ Combinatorial algorithm to compute the extreme points in polynomial time

Fundamental problem with two constraints

Main results

- ① Every facet is **tangent** to **exactly** 3 or 4 important integer points



- ② Every facet is **completely** determined by **exactly** 3 or 4 rays

- ③ Classification of the facets in 3 categories :
disection cuts, lifted 2 variable-cuts, split cuts

The facets from the first 2 categories are **never split cuts**

- ④ Combinatorial algorithms to compute the extreme points in polynomial time

Main results

- ① Every facet is **tangent** to **exactly** 3 or 4 important integer points
- ② Every facet is **completely** determined by **exactly** 3 or 4 rays
- ③ Classification of the facets in 3 categories :
disection cuts, lifted 2 variable-cuts, split cuts

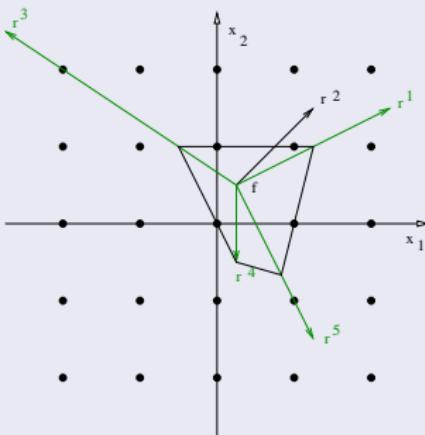
The facets from the first 2 categories are **never split cuts**

- ④ Combinatorial algorithm to compute the extreme points in polynomial time

Fundamental problem with two constraints

Main results

- ① Every facet is **tangent** to **exactly** 3 or 4 important integer points
- ② Every facet is **completely** determined by **exactly** 3 or 4 rays



- ③ Classification of the facets in 3 categories :
dissection cuts, lifted 2 variable-cuts, split cuts

The facets from the first 2 categories are **never split cuts**

- ④ Combinatorial algorithm to compute the extreme points in polynomial time

Main results

- ① Every facet is **tangent** to **exactly** 3 or 4 important integer points
- ② Every facet is **completely** determined by **exactly** 3 or 4 rays
- ③ Classification of the facets in 3 categories :
disection cuts, lifted 2 variable-cuts, split cuts

The facets from the first 2 categories are **never split cuts**

- ④ Combinatorial algorithm to compute the extreme points in polynomial time

Main results

- ① Every facet is **tangent** to **exactly** 3 or 4 important integer points
- ② Every facet is **completely** determined by **exactly** 3 or 4 rays
- ③ Classification of the facets in 3 categories :
disection cuts, lifted 2 variable-cuts, split cuts

The facets from the first 2 categories are **never split cuts**

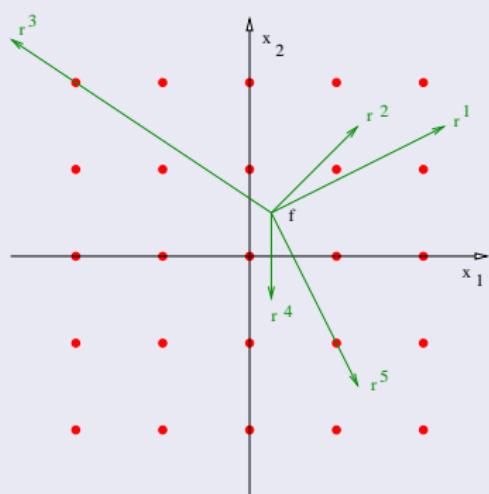
- ④ Combinatorial algorithm to compute the extreme points in polynomial time

The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

a_1/a_3

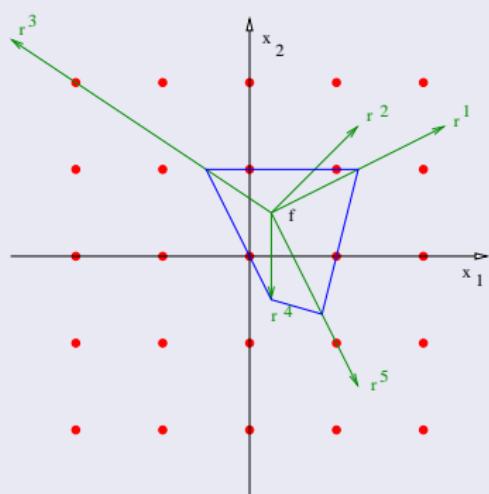


The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

a_1/a_3

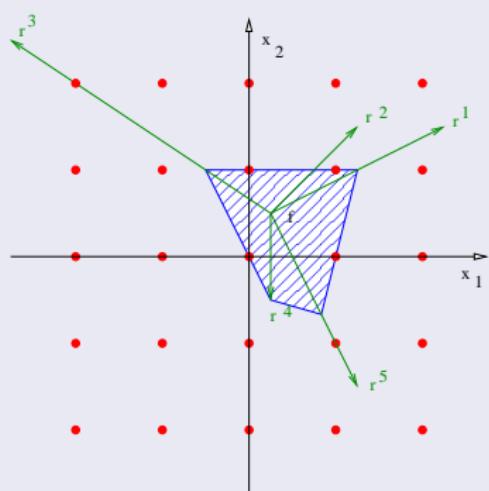


The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

r_1, r_2, \dots

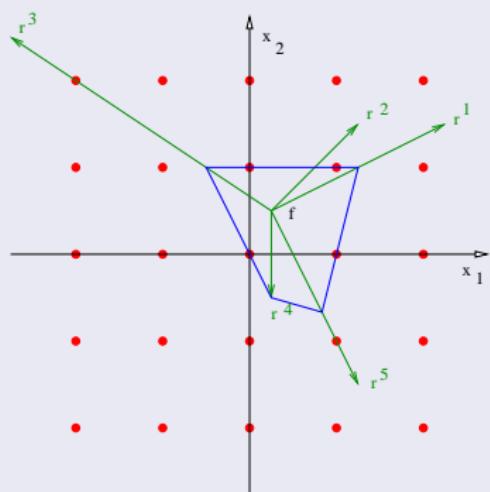


The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

$\alpha_1 \ \alpha_3$

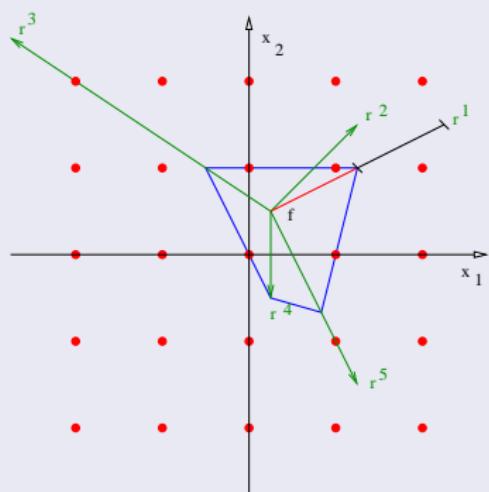


The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

α_1 α_3

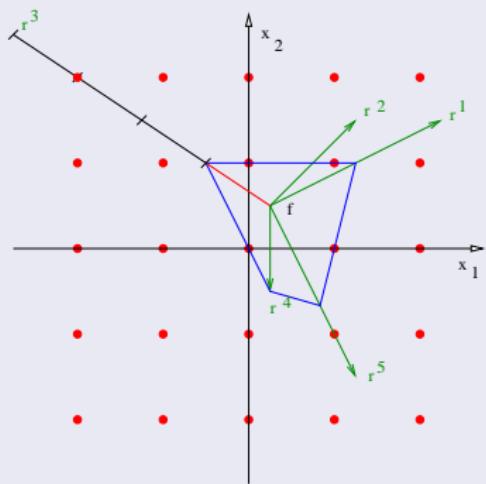


The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- We project the $n + 2$ -dim space onto the x -space
- The facet is represented by a polygon L_α
- There is no integer point in the interior of L_α
- The coefficients are a ratio of distances on the figure

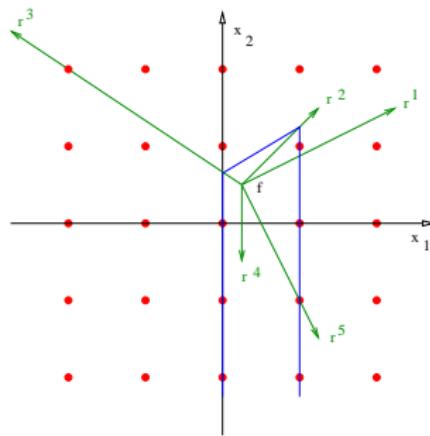
α_1 α_3



Facets with a 0 coefficient

Facets with a 0 coefficient are actually split cuts.

$$\frac{8}{3}s_1 + \frac{4}{3}s_2 + 12s_3 + 0s_4 + \frac{4}{3}s_5 \geq 1$$

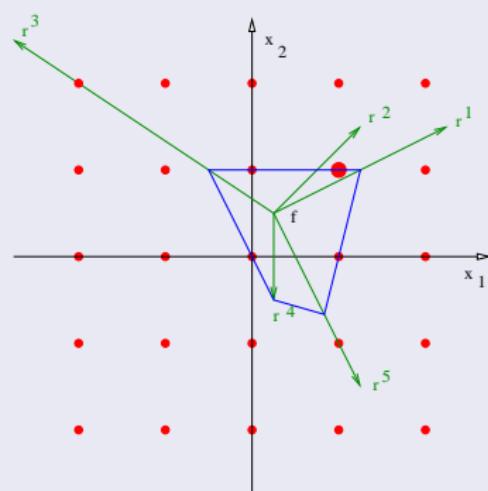


There cannot be a facet with two 0-coefficients unless two rays are parallel.

The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

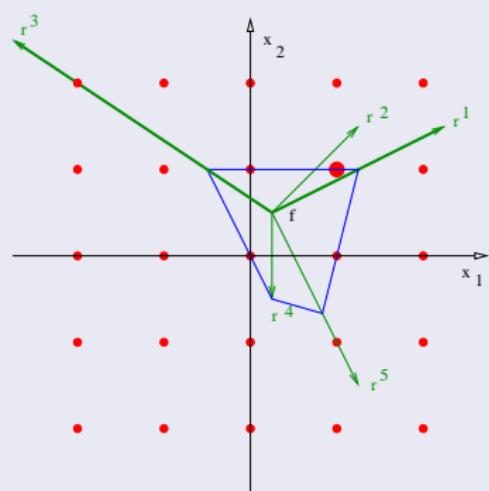
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones $\text{cone}\{r^1, r^3\}$, $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

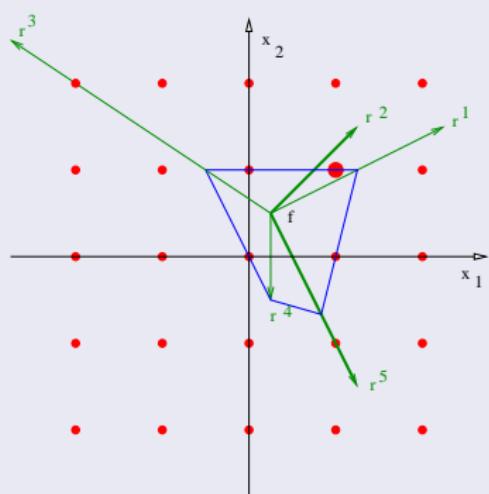
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

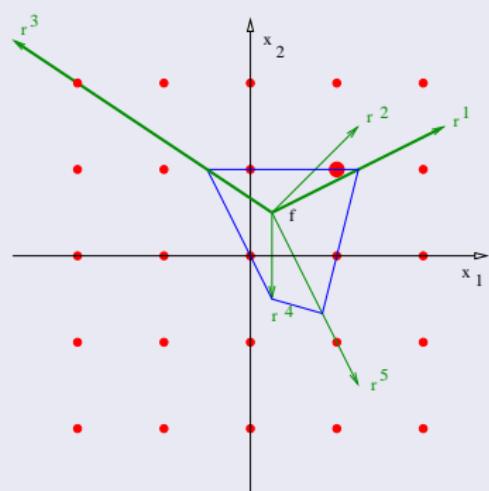
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones
 $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

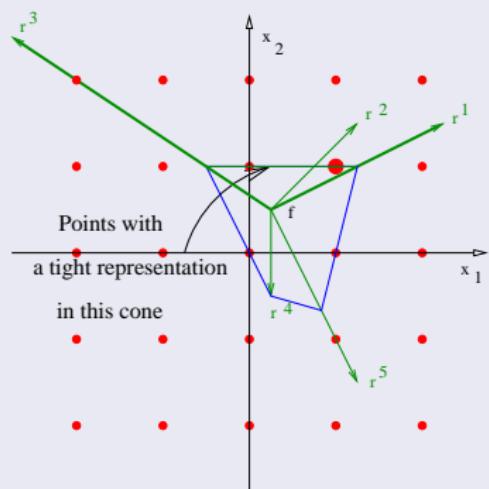
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones $\text{cone}\{r^1, r^3\} \text{ cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

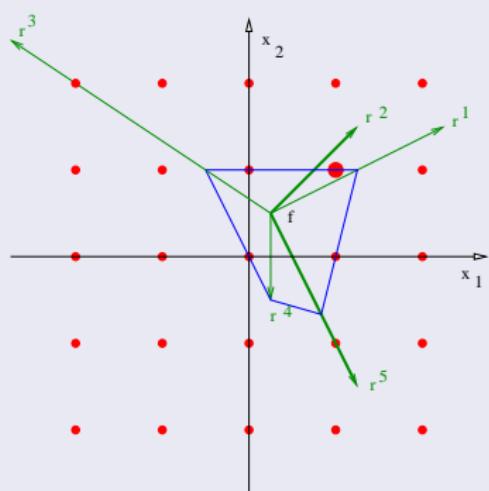
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones
 $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

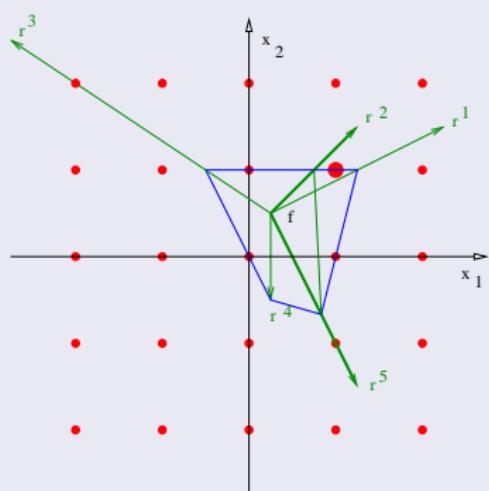
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

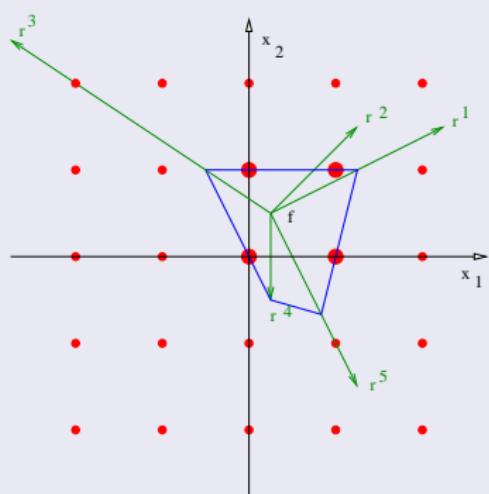
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

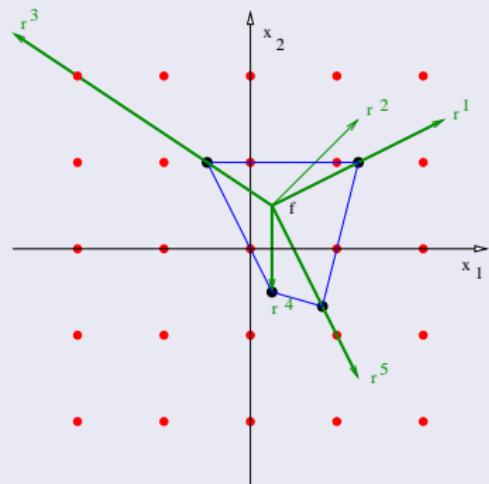
- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



The projection picture

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$

- What about tight integer points ?
- It can be represented as a minimal combination of two s_j in several cones
 $\text{cone}\{r^1, r^3\}$ $\text{cone}\{r^2, r^5\}$
- In $\text{cone}\{r^1, r^3\}$ it has a representation that is tight wrt. the facet
- In $\text{cone}\{r^2, r^5\}$ it has not
- In total there are four tight integer points (in some representation)
- By maximality the vertices of L_α are on the rays



Why three or four integer points ?

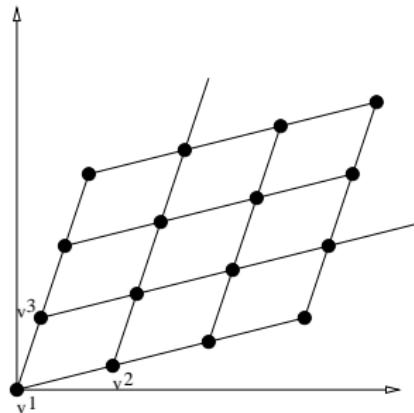
Theorem

Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.

Why three or four integer points ?

Theorem

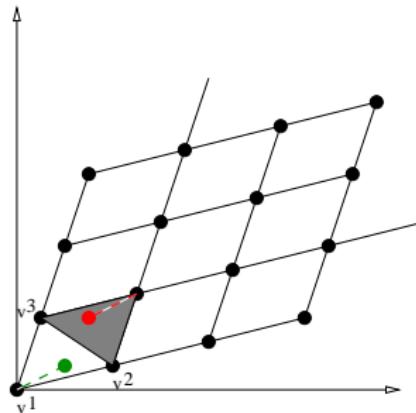
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points?

Theorem

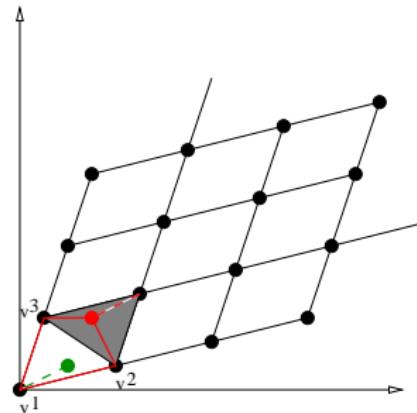
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points ?

Theorem

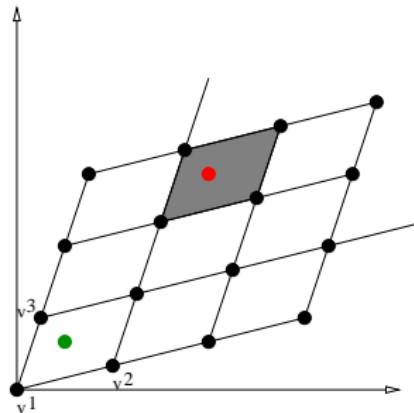
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points ?

Theorem

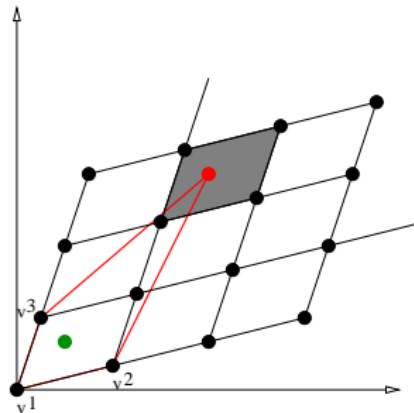
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points ?

Theorem

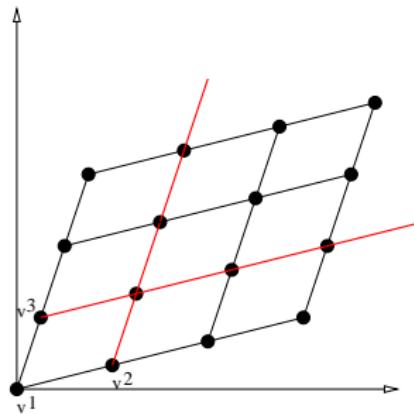
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points?

Theorem

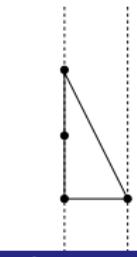
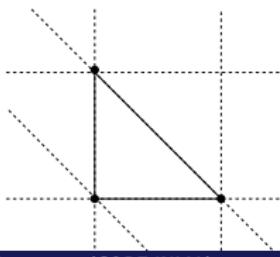
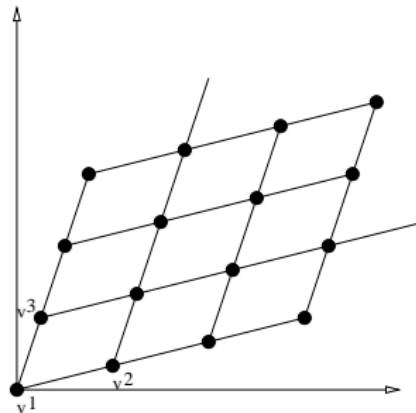
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points ?

Theorem

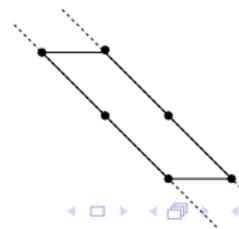
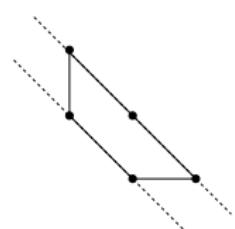
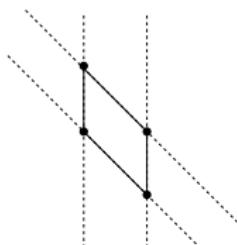
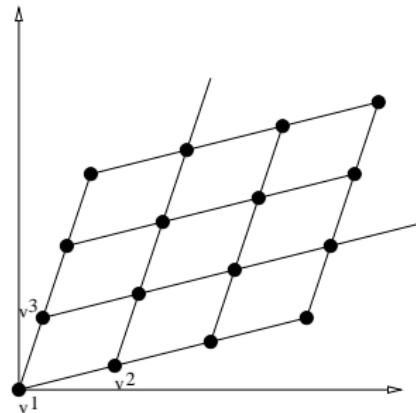
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points ?

Theorem

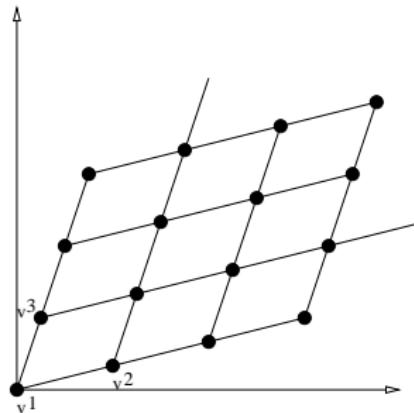
Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



Why three or four integer points ?

Theorem

Let P be a convex polygon (2D). If the vertices of P are integer and if P has no integer point in its interior, then P has at most four vertices.



No split cuts

Why three or four rays?

- There exists a **minimal** system that determines the facet
- Every tight integer point provides an equality

$$\alpha_i \gamma_i + \alpha_j \gamma_j = 1$$

in one **tight** representation, where (γ_i, γ_j) is the representation of the point in the cone (r^i, r^j) .

- All other tight representations are **automatically** satisfied
- To have the minimally uniquely determined system
 - 3 tight integer points \Rightarrow 3 variables i.e. 3 rays
 - 4 tight integer points \Rightarrow 4 variables i.e. 4 rays

Why three or four rays?

- There exists a **minimal** system that determines the facet
- Every tight integer point provides an equality

$$\alpha_i \gamma_i + \alpha_j \gamma_j = 1$$

in one **tight** representation, where (γ_i, γ_j) is the representation of the point in the cone (r^i, r^j) .

Figure

- All other tight representations are **automatically** satisfied
- To have the minimally uniquely determined system
 - 3 tight integer points \Rightarrow 3 variables i.e. 3 rays
 - 4 tight integer points \Rightarrow 4 variables i.e. 4 rays

Why three or four rays?

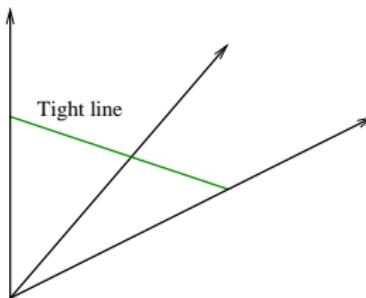
- There exists a **minimal** system that determines the facet
- Every tight integer point provides an equality

$$\alpha_i \gamma_i + \alpha_j \gamma_j = 1$$

in one **tight** representation, where (γ_i, γ_j) is the representation of the point in the cone (r^i, r^j) .

Figure

- All other tight representations are **automatically** satisfied



- To have the minimally uniquely determined system
 - 3 tight integer points \Rightarrow 3 variables i.e. 3 rays
 - 4 tight integer points \Rightarrow 4 variables i.e. 4 rays

Why three or four rays?

- There exists a **minimal** system that determines the facet
- Every tight integer point provides an equality

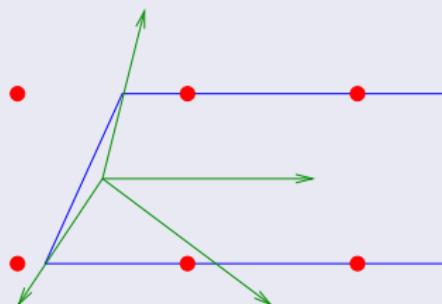
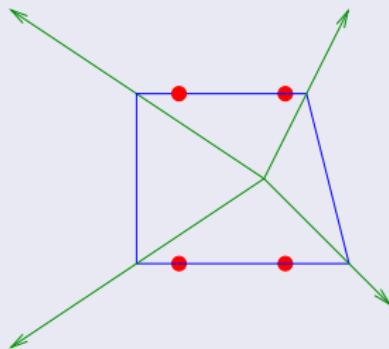
$$\alpha_i \gamma_i + \alpha_j \gamma_j = 1$$

in one **tight** representation, where (γ_i, γ_j) is the representation of the point in the cone (r^i, r^j) .

Figure

- All other tight representations are **automatically** satisfied
- To have the minimally uniquely determined system
 - 3 tight integer points \Rightarrow 3 variables i.e. 3 rays
 - 4 tight integer points \Rightarrow 4 variables i.e. 4 rays

Split cuts

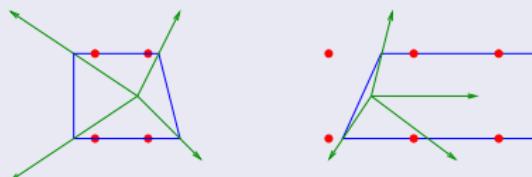


Dissection cuts and Lifted 2-var cuts

These are never split cuts!

An important pathological case

Split cuts



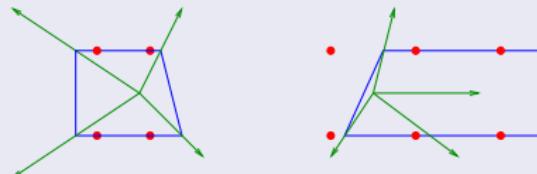
Dissection cuts and Lifted 2-var cuts

These are never split cuts!

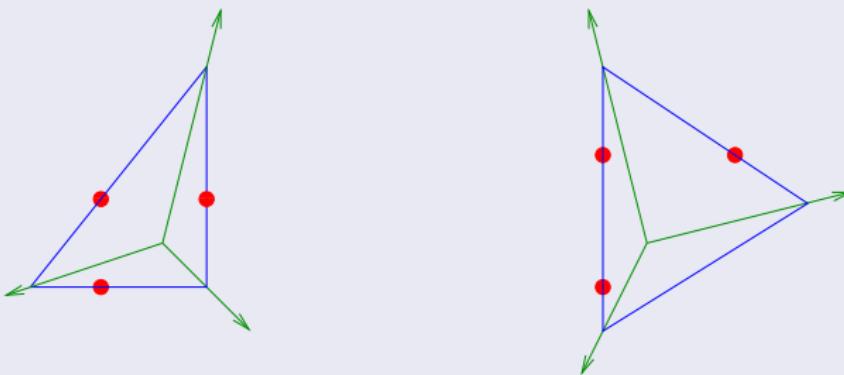
An important pathological case

Classification of the facets

Split cuts



Disection cuts and Lifted 2-var cuts

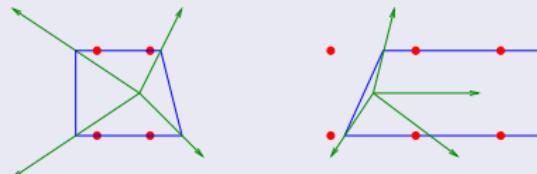


These are never split cuts !

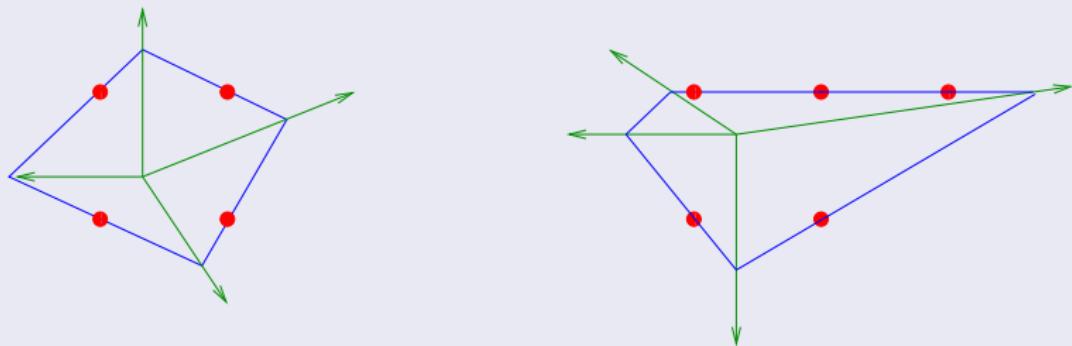
Figures

Classification of the facets

Split cuts



Disection cuts and Lifted 2-var cuts



These are never split cuts !

Figures

An important pathological case

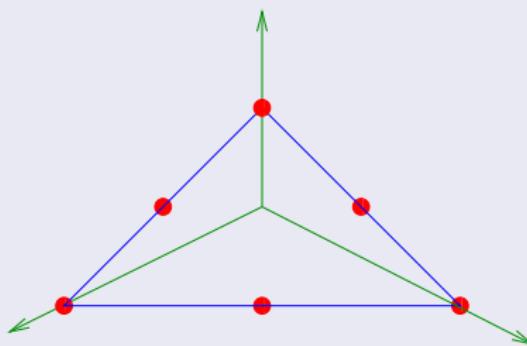
Classification of the facets

Split cuts

Disection cuts and Lifted 2-var cuts

These are never split cuts !

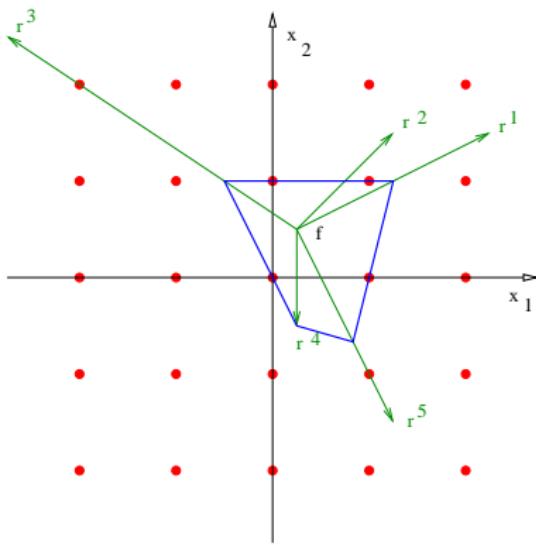
An important pathological case



Simultaneous lifting by reading the coefficients on the figure

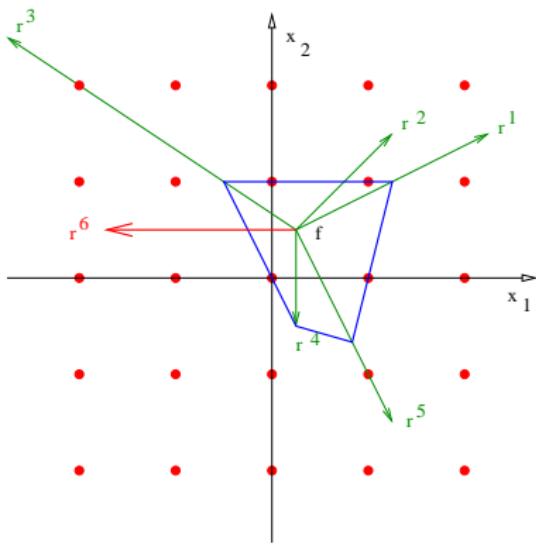
$$\begin{pmatrix} 1/4 \\ 1/2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} s_1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_2 + \begin{pmatrix} -3 \\ 2 \end{pmatrix} s_3 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} s_4 + \begin{pmatrix} 1 \\ -2 \end{pmatrix} s_5$$

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$



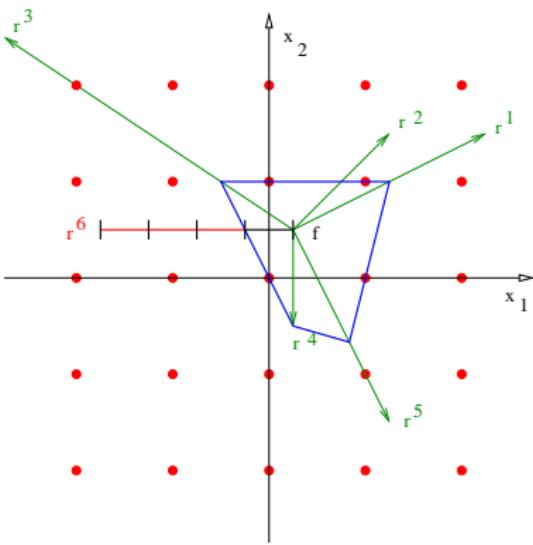
Simultaneous lifting by reading the coefficients on the figure

$$\begin{pmatrix} 1/4 \\ 1/2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} s_1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_2 + \begin{pmatrix} -3 \\ 2 \end{pmatrix} s_3 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} s_4 + \begin{pmatrix} 1 \\ -2 \end{pmatrix} s_5 + \begin{pmatrix} -2 \\ 0 \end{pmatrix} s_6$$
$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 \geq 1$$



Simultaneous lifting by reading the coefficients on the figure

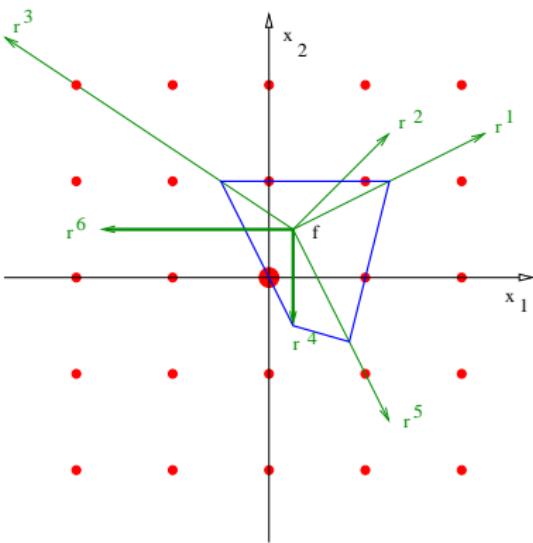
$$\begin{pmatrix} 1/4 \\ 1/2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} s_1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_2 + \begin{pmatrix} -3 \\ 2 \end{pmatrix} s_3 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} s_4 + \begin{pmatrix} 1 \\ -2 \end{pmatrix} s_5 + \begin{pmatrix} -2 \\ 0 \end{pmatrix} s_6$$
$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 + 4s_6 \geq 1$$



Simultaneous lifting by reading the coefficients on the figure

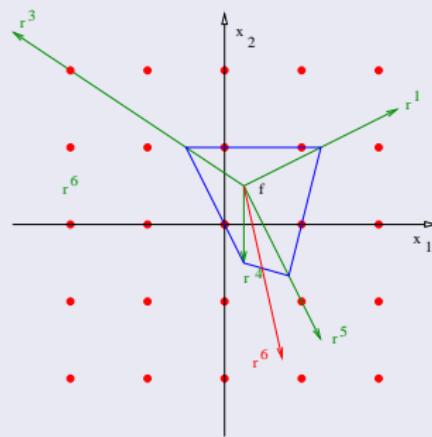
$$\begin{pmatrix} 1/4 \\ 1/2 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \end{pmatrix} s_1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix} s_2 + \begin{pmatrix} -3 \\ 2 \end{pmatrix} s_3 + \begin{pmatrix} 0 \\ -1 \end{pmatrix} s_4 + \begin{pmatrix} 1 \\ -2 \end{pmatrix} s_5 + \begin{pmatrix} -2 \\ 0 \end{pmatrix} s_6$$

$$2s_1 + 2s_2 + 4s_3 + s_4 + \frac{12}{7}s_5 + 4s_6 \geq 1$$



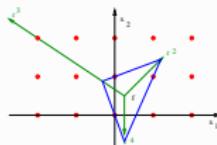
It is a facet!

Lifted 2 variable cuts



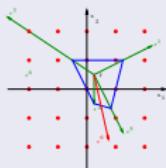
The lifted valid inequality is **not a facet**!

Dissection cuts are universally liftable



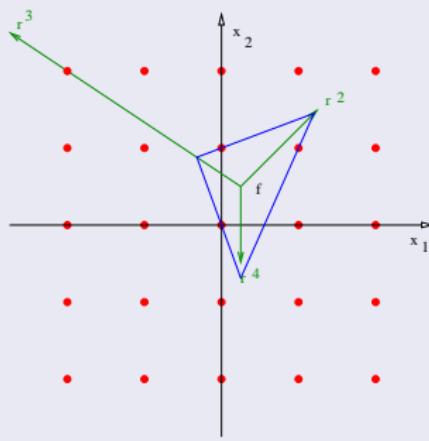
Issues related to lifting

Lifted 2 variable cuts



The lifted valid inequality is **not a facet**!

Disection cuts are universally liftable



Remaining questions

Towards practice ?

① General principle to generate cuts

- Choose 3 or 4 **integer points**
Which points ?
- Choose 3 or 4 **rays**
- Compute the **cut**

② Important related questions

- Strengthen an inequality by considering the **integrality** of a ray ?
- Bounds on x and on y
- Generalization to **several constraints**
Includes a generalization of the split to a d -dimensional body with no integer point in its interior

Finite convergence for a cutting plane algorithm

- ① Which black box is necessary to converge in finite time ?
- ② Problem with m constraints \rightarrow black box with m constraints ?

Towards practice?

① General principle to generate cuts

- Choose 3 or 4 **integer points**
Which points?
- Choose 3 or 4 **rays**
- Compute the **cut**

② Important related questions

- Strengthen an inequality by considering the **integrality** of a **ray**?
- **Bounds** on x and on y
- Generalization to **several constraints**

Includes a generalization of the split to a d -dimensional body with no integer point in its interior

Finite convergence for a cutting plane algorithm

- ① Which black box is necessary to converge in finite time?
- ② Problem with m constraints \rightarrow black box with m constraints?

Towards practice?

① General principle to generate cuts

- Choose 3 or 4 **integer points**
Which points?
- Choose 3 or 4 **rays**
- Compute the **cut**

② Important related questions

- Strengthen an inequality by considering the **integrality** of a **ray**?
- **Bounds** on x and on y
- Generalization to **several constraints**

Includes a generalization of the split to a d -dimensional body with no integer point in its interior

Finite convergence for a cutting plane algorithm

- ① Which black box is necessary to converge in finite time?
- ② Problem with m constraints \rightarrow black box with m constraints?

Towards practice?

① General principle to generate cuts

- Choose 3 or 4 **integer points**
Which points?
- Choose 3 or 4 **rays**
- Compute the **cut**

② Important related questions

- Strengthen an inequality by considering the **integrality** of a **ray**?
- **Bounds** on x and on y
- Generalization to **several constraints**

Includes a generalization of the split to a d -dimensional body with no integer point in its interior

Finite convergence for a cutting plane algorithm

- ① Which black box is necessary to converge in finite time?
- ② Problem with m constraints \rightarrow black box with m constraints?