

# Application of the X-FEM to the fracture of piezoelectric materials

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# Outline

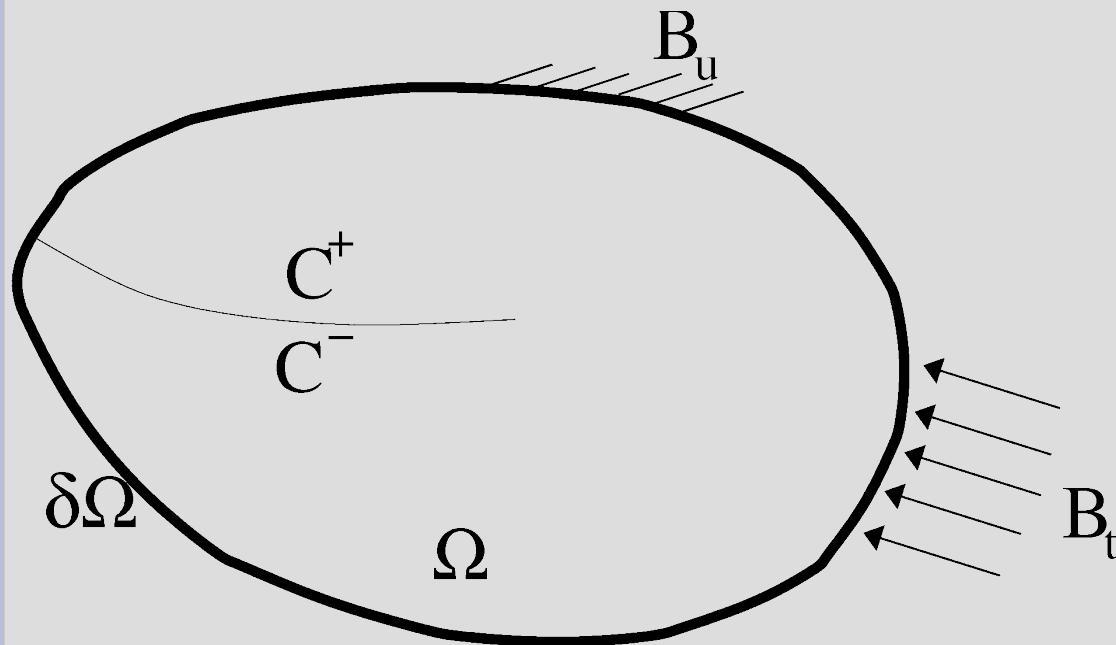
- Introduction
- Updated X-FEM formulation
  - New crack tip enrichment functions
  - Updated SIF computation scheme
  - Use of specific preconditionner
- Convergence study
- Conclusions

# Introduction

- Goal
  - Propose a updated enrichment scheme for a cracked anisotropic piezoelectric media
  - Convergence study of the method
    - Energy error
    - SIFS and energy release rate
  - Development of a SIF evaluation scheme based on interaction integrals specific to piezoelectric materials
  - Numerical crack propagation using empirical laws

# Introduction

- Physical model : linear piezoelectric media, electrically impermeable crack



$$\begin{aligned} \sigma_{ij} \cdot n_i &= 0 \\ D_i \cdot n_i &= 0 \end{aligned} \quad \text{on } C^+ \cup C^-$$

$$\sigma_{ij} = c_{ijkl} \varepsilon_{kl} - e_{kij} E_k$$

$$D_i = e_{ikl} \varepsilon_{kl} + \kappa_{ik} E_k$$

$$\sigma_{ij,j} = 0$$

$$D_{j,j} = 0$$

$$\varepsilon_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i})$$

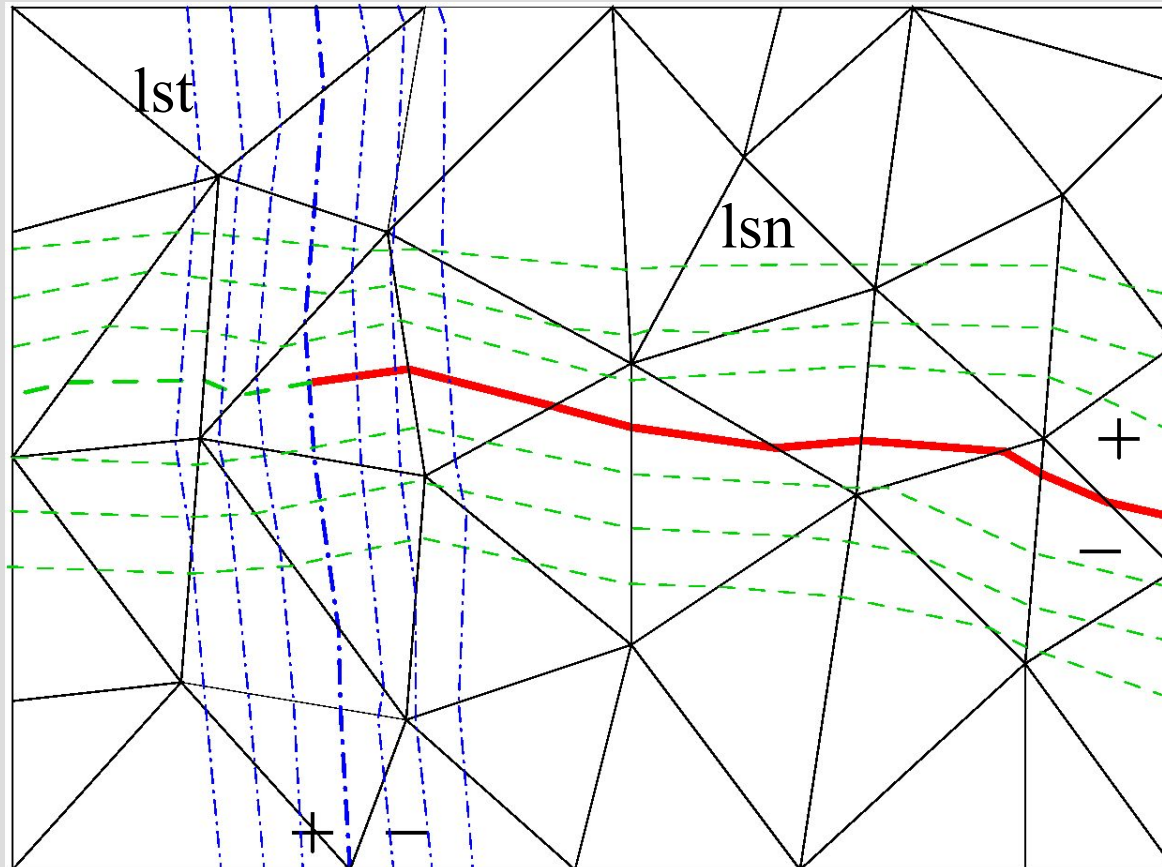
$$E_j = -\varphi_{,i}$$

# Introduction

- Numerical Model
  - Xfem field approximation
  - No remeshing
  - Interaction integrals used to compute the SIFs

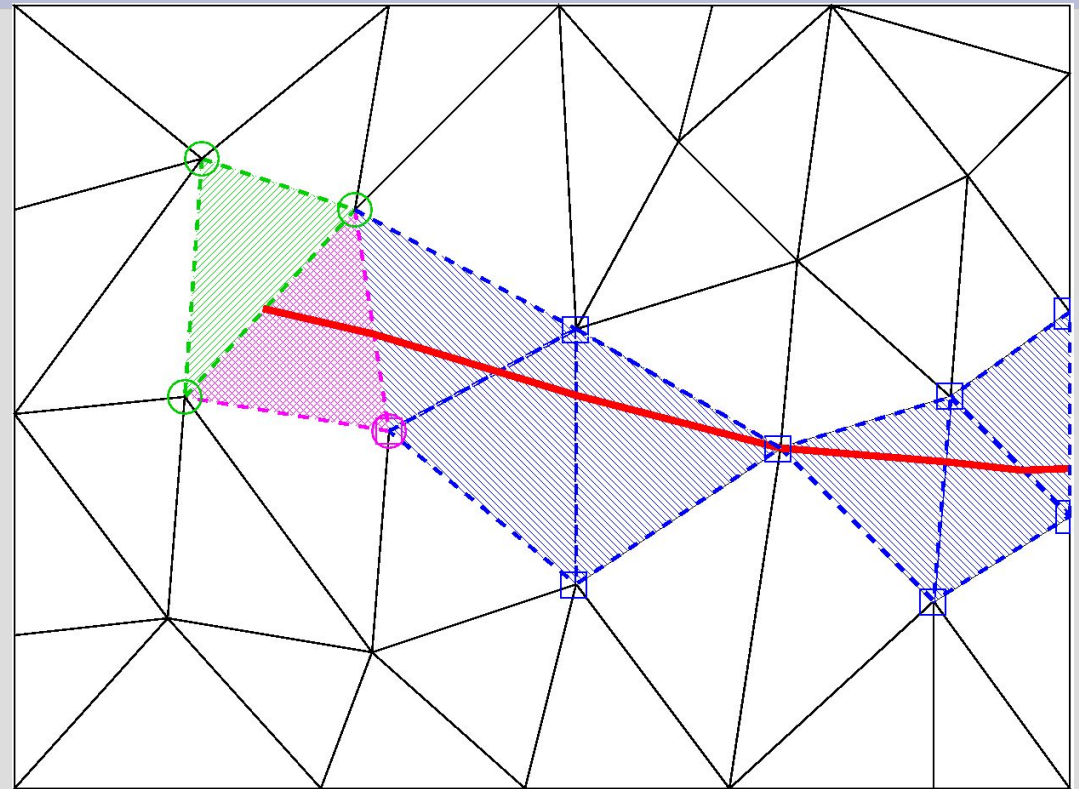
# X-FEM

- Crack represented by level-sets
  - Local coordinates at the crack tip



# X-FEM

- Local partition of unity enrichment
  - Singular functions around crack tip
  - Heaviside along crack surface
  - Remaining dofs unenriched



$$\mathbf{u}^h = \sum_{i \in R} \mathbf{N}_i a_i + \sum_{i \in R} \sum_{j=1 \dots n} \mathbf{N}_i g_j b_{ij} + \sum_{i \in H} \mathbf{N}_i h c_i$$

$$\varphi^h = \sum_{i \in R} N_i \alpha_i + \sum_{i \in R} \sum_{j=1 \dots n} N_i g_j \beta_{ij} + \sum_{i \in H} N_i h \gamma_i$$

# Enrichment functions

- Enrichment functions
  - Jump across the crack for displacements and potential :

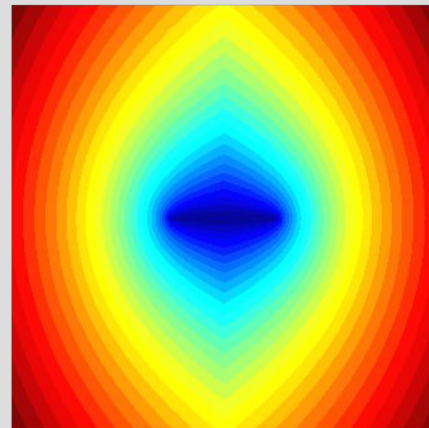
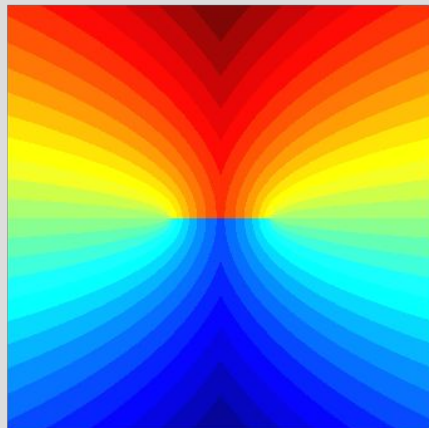
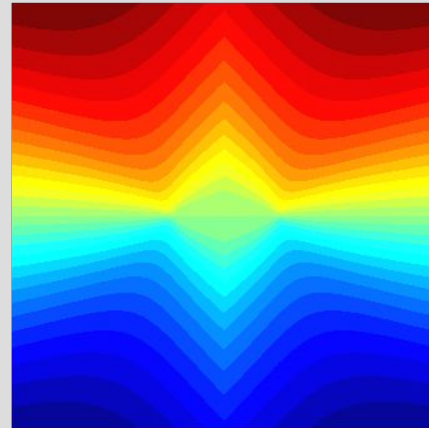
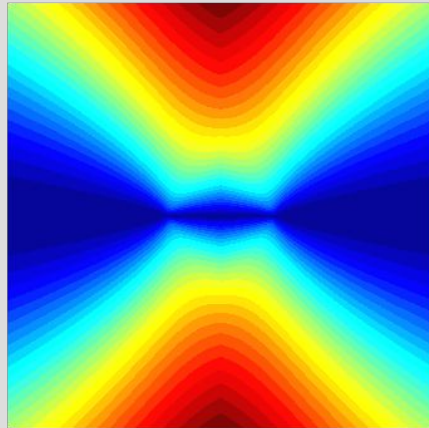
$$h(\varphi) = \begin{cases} +1 & \text{if } \varphi \geq 0 \\ -1 & \text{if } \varphi < 0 \end{cases}$$

- Crack tip for in a pure mechanical setting

$$g_i(r, \theta) = \left\{ \sqrt{r} \sin \frac{\theta}{2}, \sqrt{r} \cos \frac{\theta}{2}, \sqrt{r} \sin \frac{\theta}{2} \sin \theta, \sqrt{r} \cos \frac{\theta}{2} \sin \theta \right\}$$

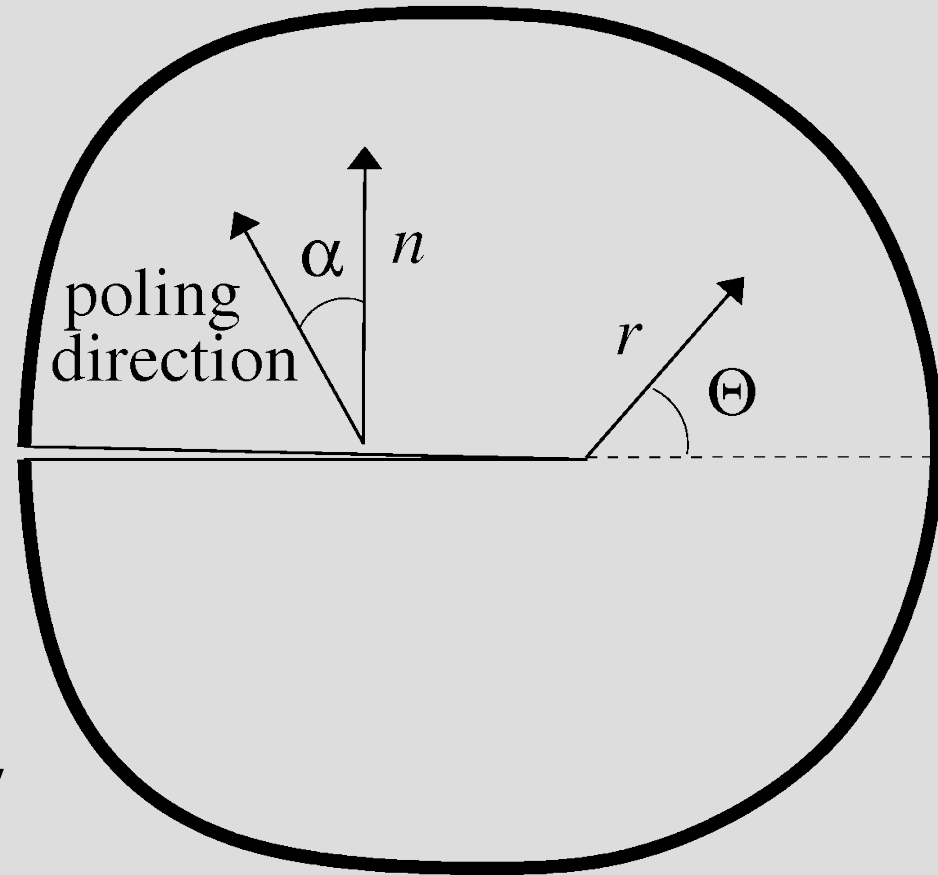


# Enrichment functions



# Enrichment functions

- Crack tip functions for a piezoelectrical setting
  - Must span the eigenfunction's space at the crack tip for displacements and potential
  - Depends on the material characteristics and the orientation
  - Depends on the permeability of the crack



$$g_i(r, \theta) = \{ \sqrt{r} f_1(\theta), \sqrt{r} f_2(\theta), \sqrt{r} f_3(\theta), \sqrt{r} f_4(\theta), \sqrt{r} f_5(\theta), \sqrt{r} f_6(\theta) \}$$

# Enrichement functions

$$f_i(\theta) = \phi(\omega(\theta, \alpha), a_{i,re}, a_{i,im})$$

$$= \begin{cases} \rho(\omega, a_{i,re}, a_{i,im}) \cos \frac{\psi(\omega, a_{i,re}, a_{i,im})}{2} & \text{if } a_{i,im} > 0 \\ \rho(\omega, a_{i,re}, a_{i,im}) \sin \frac{\psi(\omega, a_{i,re}, a_{i,im})}{2} & \text{if } a_{i,im} \leq 0 \end{cases}$$

$$\omega = \theta - \alpha$$

$$\rho(\omega, a_{i,re}, a_{i,im}) =$$

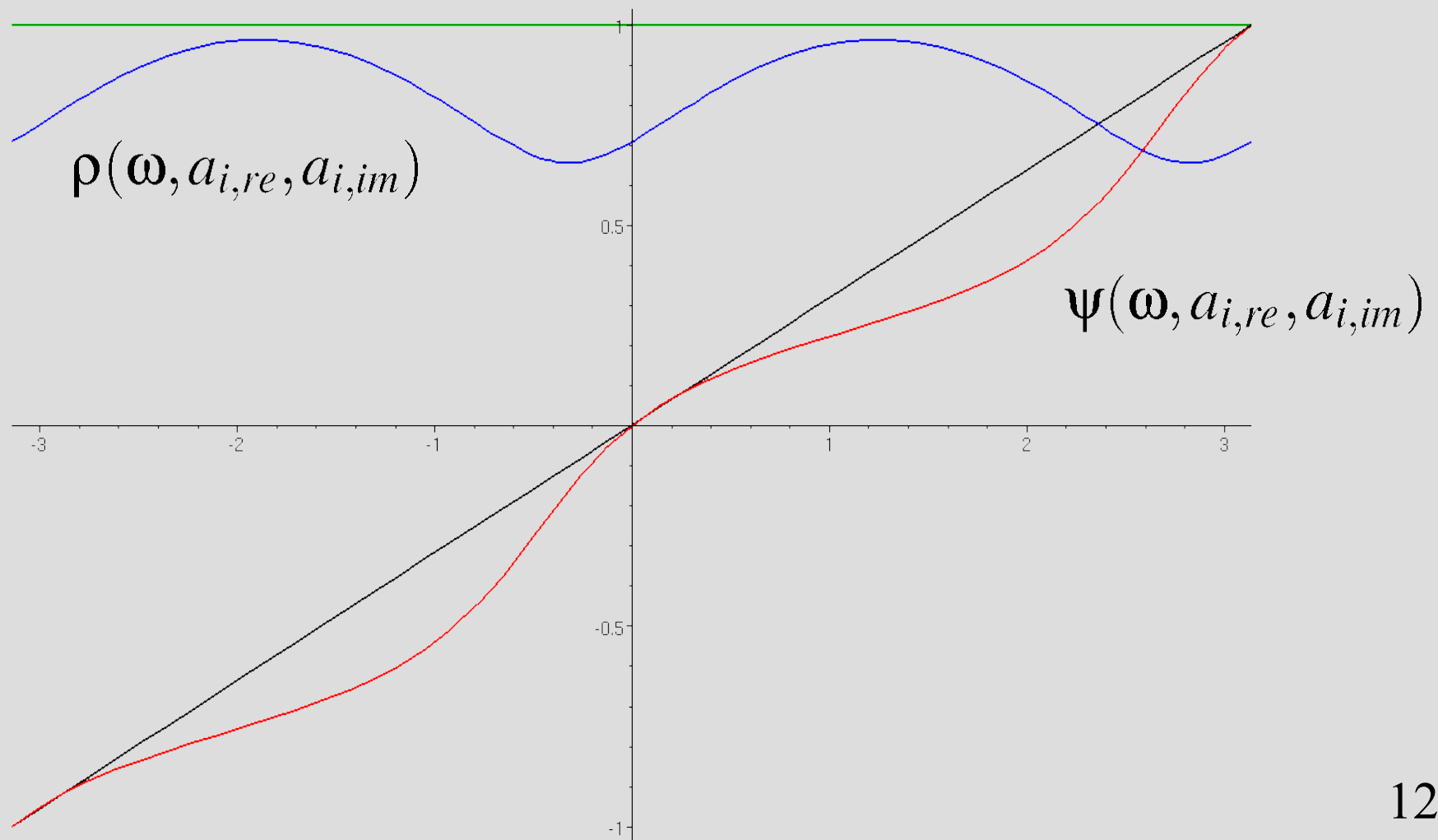
$$\frac{1}{\sqrt{2}} \sqrt[4]{a_{i,re}^2 + a_{i,im}^2 + a_{i,re} \sin 2\omega - (a_{i,re}^2 + a_{i,im}^2 - 1) \cos 2\omega}$$

$$\psi(\omega, a_{i,re}, a_{i,im}) = \frac{\pi}{2} + \pi \operatorname{int} \left( \frac{\omega}{\pi} \right)$$

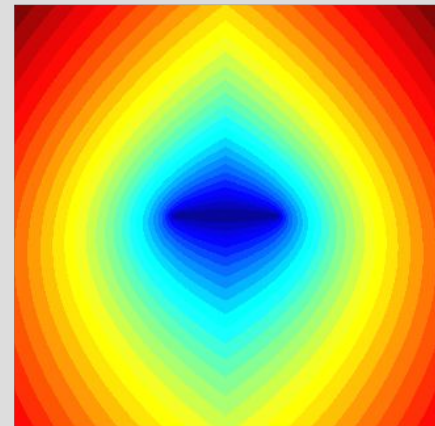
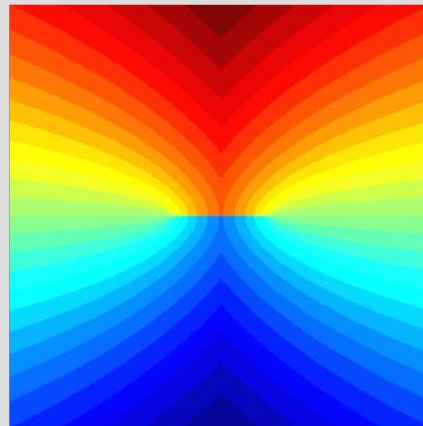
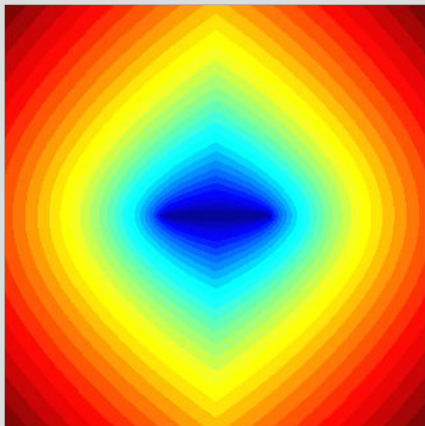
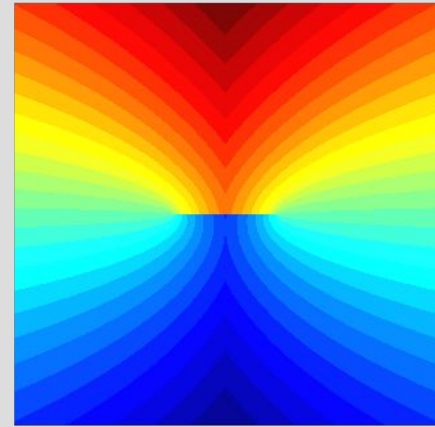
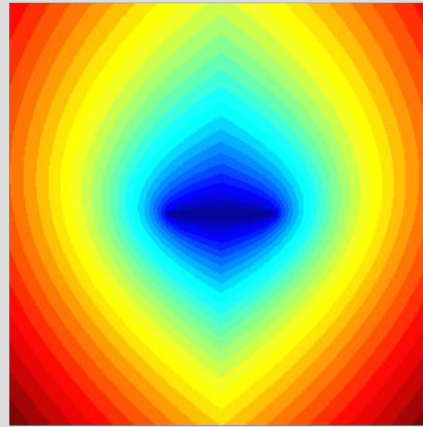
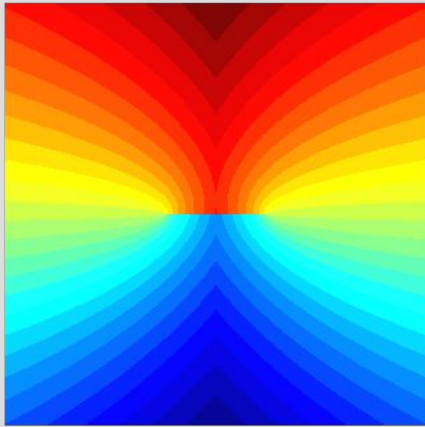
$$- \arctan \left( \frac{\cos \left( \omega - \pi \operatorname{int} \left( \frac{\omega}{\pi} \right) \right) + a_{i,re} \sin \left( \omega - \pi \operatorname{int} \left( \frac{\omega}{\pi} \right) \right)}{|a_{i,im}| \sin \left( \omega - \pi \operatorname{int} \left( \frac{\omega}{\pi} \right) \right)} \right)$$

# Enrichment functions

- Modified functions

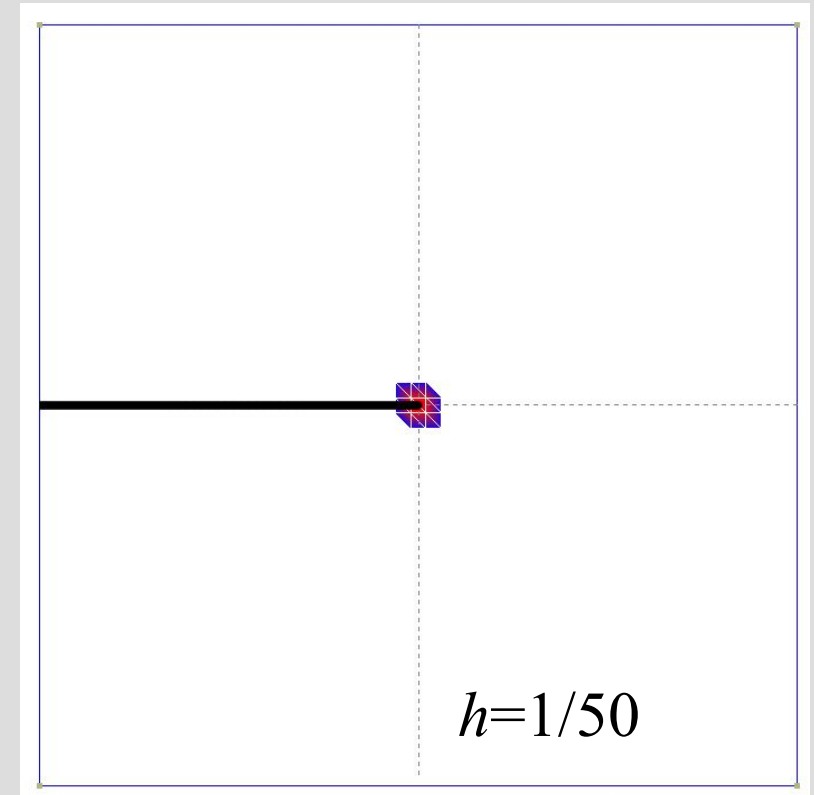
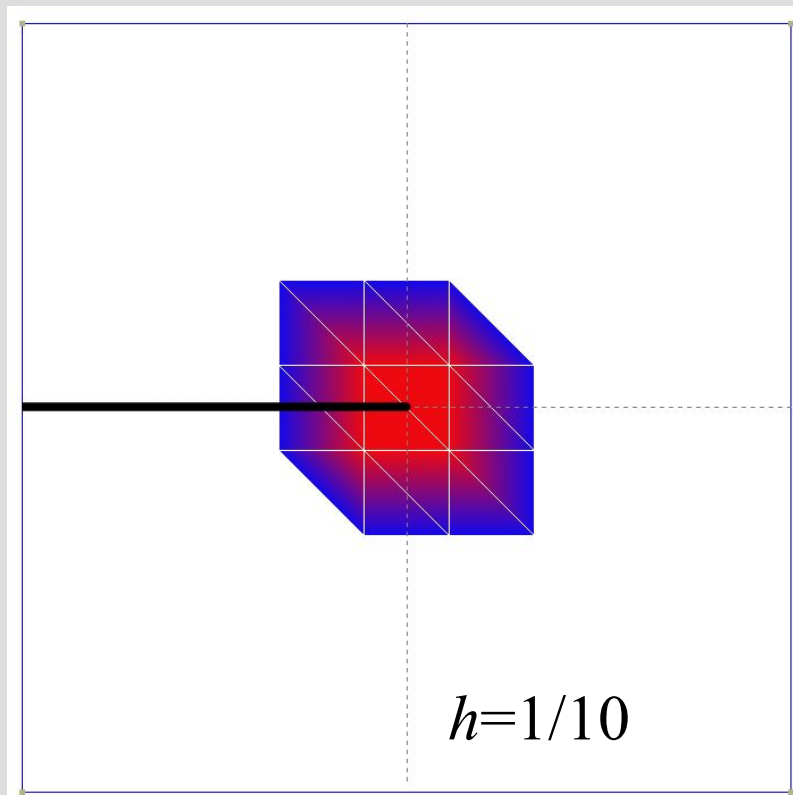


# Enrichment functions



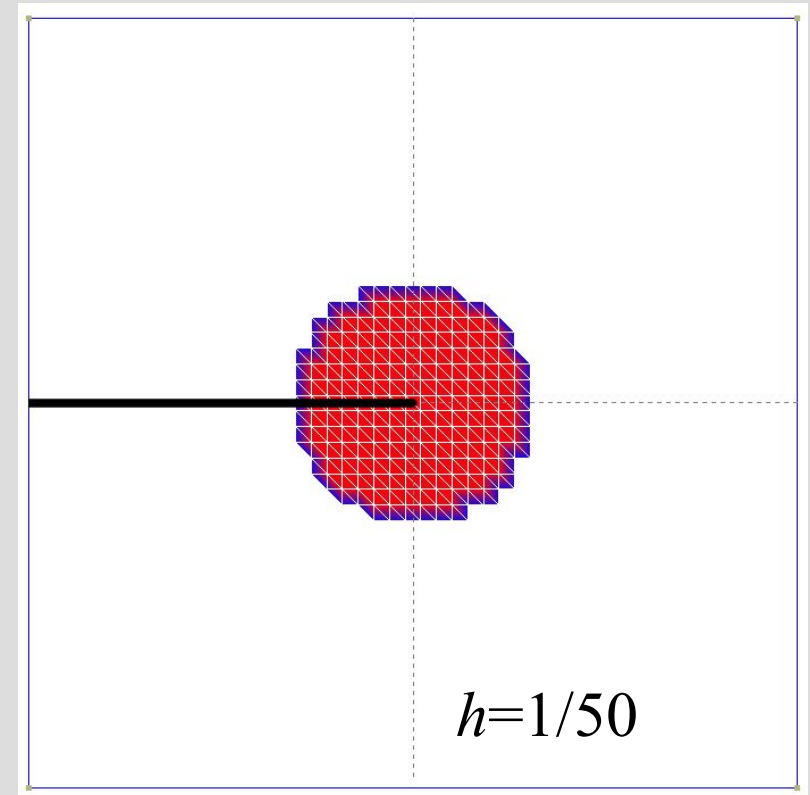
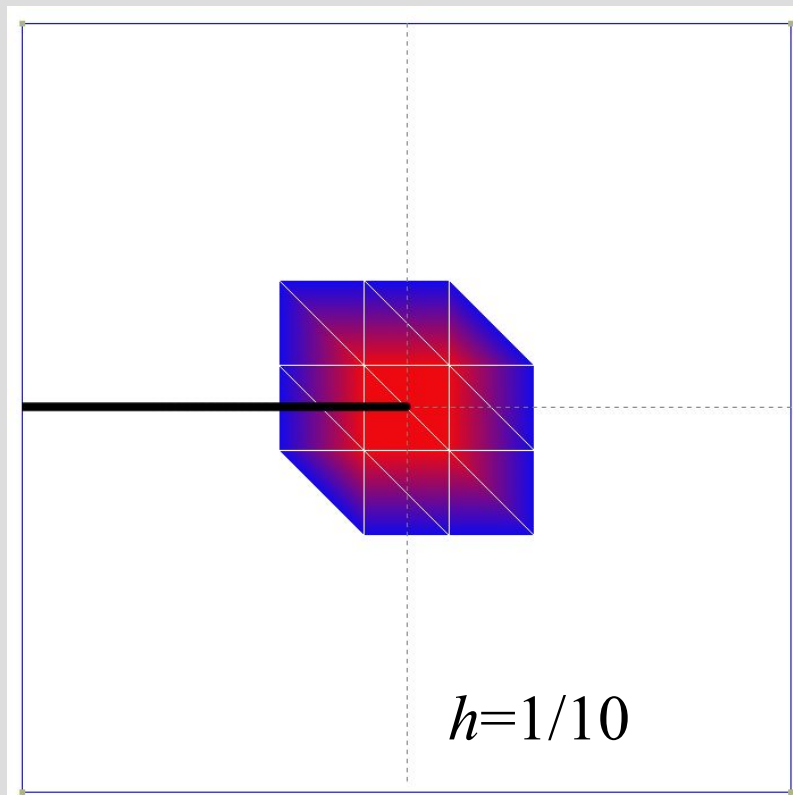
# Updated enrichment scheme

“topological” Enrichment



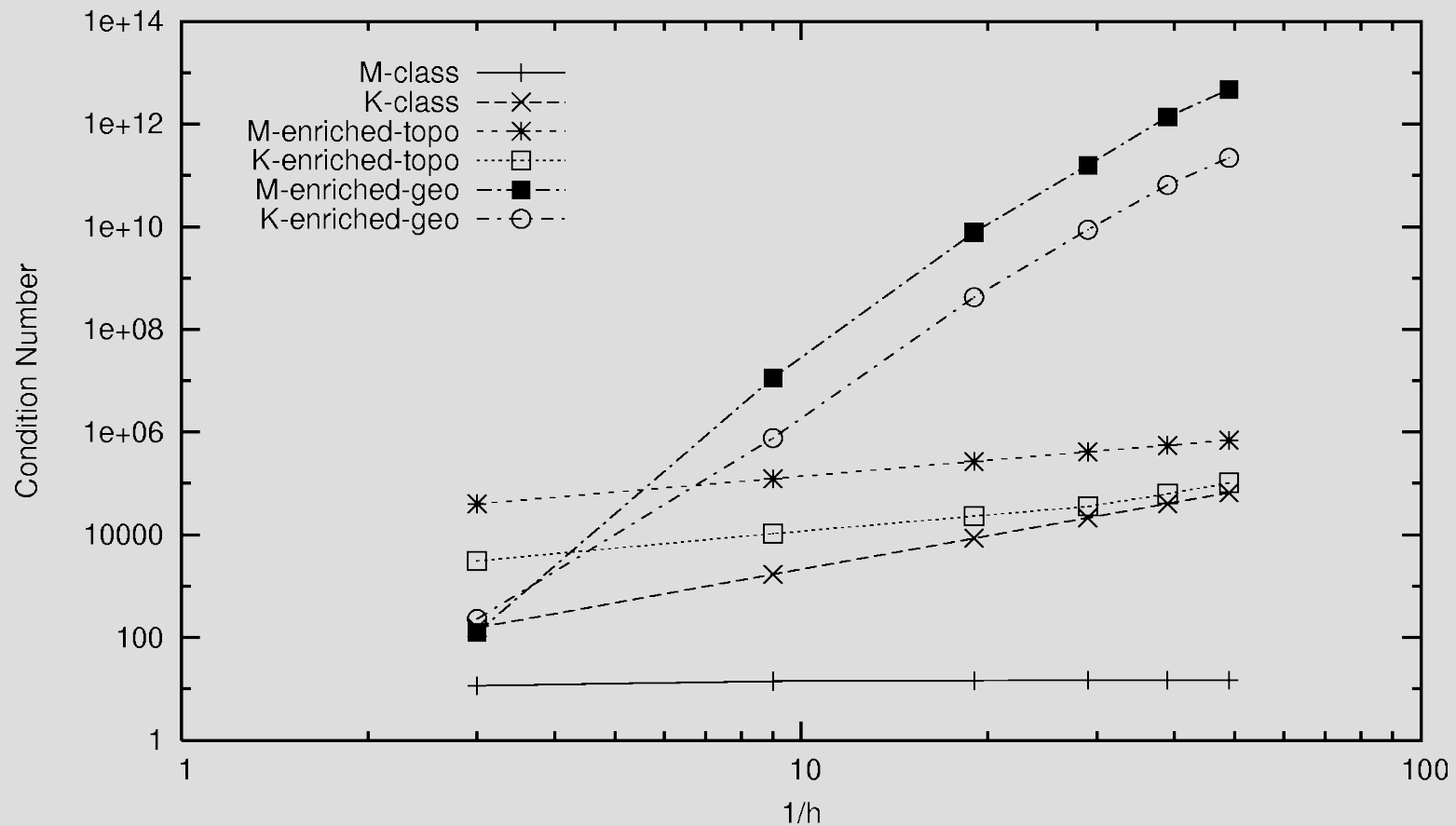
# Updated enrichment scheme

## “Geometrical” Enrichment



# Condition number

- The enrichment may lead to almost-singular matrices → difficult to use iterative solvers





# Preconditionner

- Orthogonalize each subset of enriched dofs

$$\begin{bmatrix} \vdots & \vdots & & \\ a & b & \dots & \\ b & c & \dots & \\ & & \ddots & \end{bmatrix} \mathbf{u} = \mathbf{f} \rightarrow \begin{bmatrix} \vdots & \vdots & & \\ a & 0 & \dots & \\ 0 & c & \dots & \\ & & \ddots & \end{bmatrix} \tilde{\mathbf{u}} = \tilde{\mathbf{f}}$$

# Preconditionner

- Cholesky decomposition & scaling for node  $k$  :

$$\mathbf{A} = \begin{bmatrix} a & b \\ b & c \end{bmatrix} \quad \mathbf{A} = \mathbf{G}\mathbf{G}^T$$

$$\mathbf{D}_{ij} = \sqrt{\mathbf{A}_{ij}\delta_{ij}} \quad (\text{no summation})$$

$$\mathbf{R} = \mathbf{G}^{-1}\mathbf{D}$$

“Assembly” of every submatrix  $\mathbf{R}$  gives  $\mathbf{R}^*$

$$\mathbf{R}^*\mathbf{K}\mathbf{R}^{*T}\tilde{\mathbf{u}} = \mathbf{R}^*\mathbf{f} \quad \text{with } \mathbf{u} = \mathbf{R}^{*T}\tilde{\mathbf{u}}$$

# Preconditionner

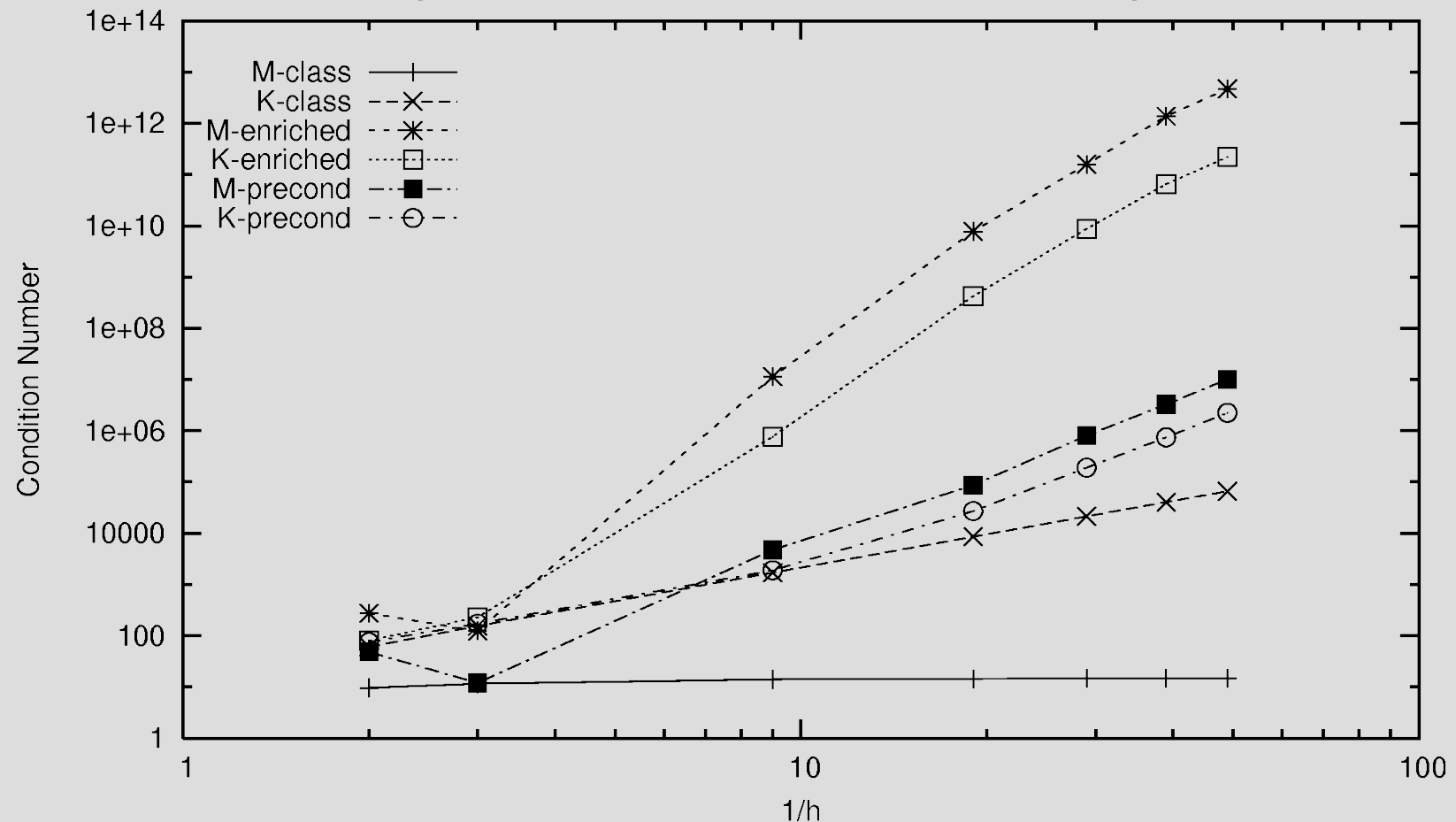
- Trick for handling non positive definite systems (but blockwise positive definite)
  - If the matrix  $A$  belongs to the electrostatic part:
    - $a$ ,  $b$  and  $c$  are negative
    - we need to take the opposite matrix (which is positive definite) in order to generate the preconditionner

$$\begin{array}{ccc|c}
 \cdot & \cdot & \cdot & \cdot \\
 \cdot & K & \cdot & d^T \\
 \cdot & \cdot & \cdot & \cdot \\
 \hline
 \cdot & d & \cdot & -\varepsilon
 \end{array}
 \quad
 \mathbf{A} = \begin{bmatrix} -a & -b \\ -b & -c \end{bmatrix}$$

$$\mathbf{A} = \mathbf{G}\mathbf{G}^T$$

# Preconditionner

Condition number of  $\mathbf{R}^* \mathbf{K} \mathbf{R}^{*T}$  or  $\mathbf{R}^* \mathbf{M} \mathbf{R}^{*T}$   
(Geometrical enrichment)



# Convergence study

- Exact solution – use of complex potentials
  - cf. H. Sosa, Plane problems in piezoelectric media with defects, Int. J. Sol. Struct. (1991)

$$\varepsilon_{xx} = 2\Re \left( \sum_{k=1}^3 (a_{11}\tau_k^2 + a_{12} - b_{12}\kappa_k) \phi_k(z_k) \right) \quad \kappa_k = -\frac{(b_{21} + b_{13})\tau_k + b_{22}}{\delta_{11}\tau_k^2 + \delta_{22}}$$

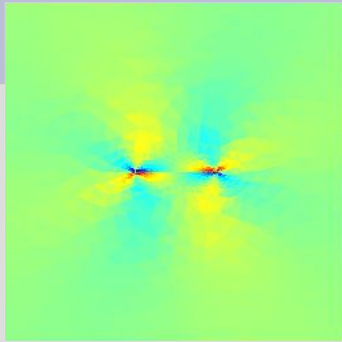
$$\varepsilon_{xy} = 2\Re \left( \sum_{k=1}^3 (a_{12}\tau_k^2 + a_{22} - b_{22}\kappa_k) \phi_k(z_k) \right) \quad z_k = x + \tau_k y$$

$$\varepsilon_{xy} = \Re \left( \sum_{k=1}^3 (-a_{33}\tau_k + b_{13}\tau_k\kappa_k) \phi_k(z_k) \right) \quad \phi_k(z_k) = \frac{A_k z_k}{\sqrt{z_k^2 - a^2}} + B_k$$

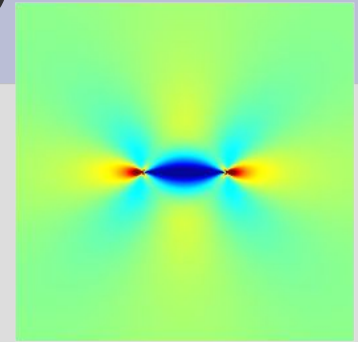
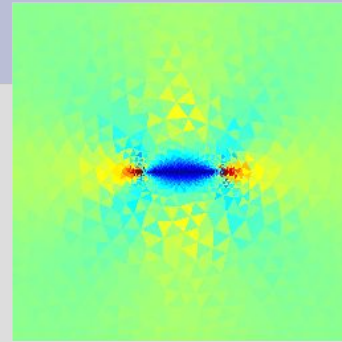
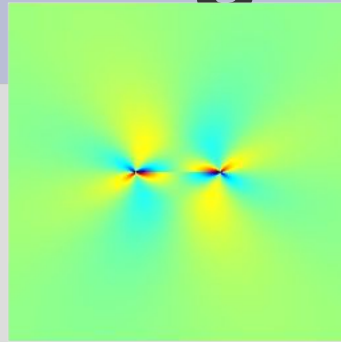
$$E_x = 2\Re \left( \sum_{k=1}^3 (b_{13} + \delta_{11}\kappa_k) \tau_k \phi_k(z_k) \right) \quad \tau_k \text{ are roots of the characteristic equation.}$$

$$E_y = -2\Re \left( \sum_{k=1}^3 (b_{21}\tau_k^2 + b_{22} + \delta_{22}\kappa_k) \phi_k(z_k) \right)$$

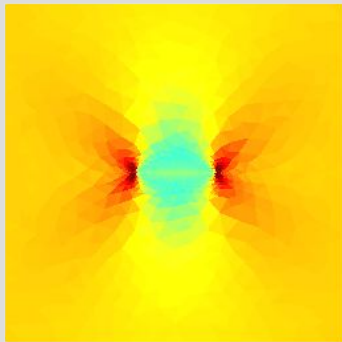
# Convergence study



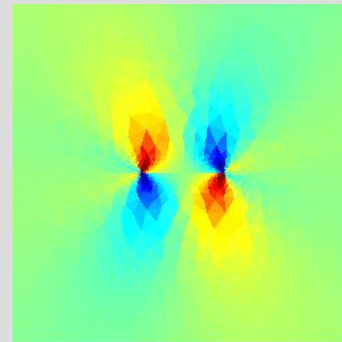
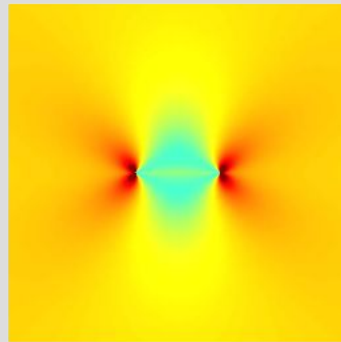
EDx



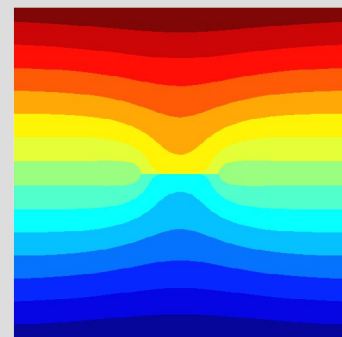
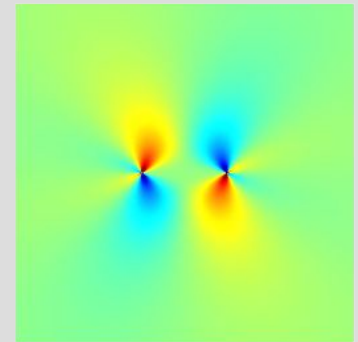
EDy



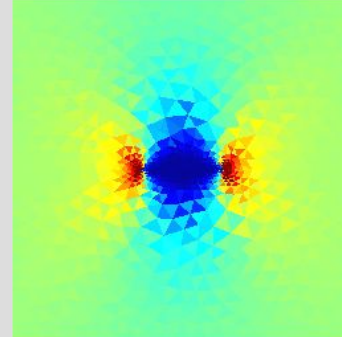
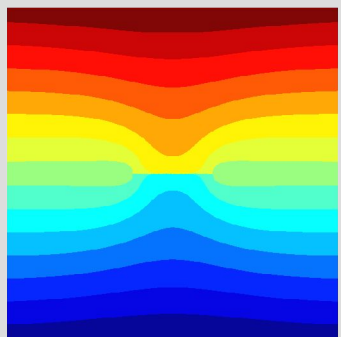
Sxx



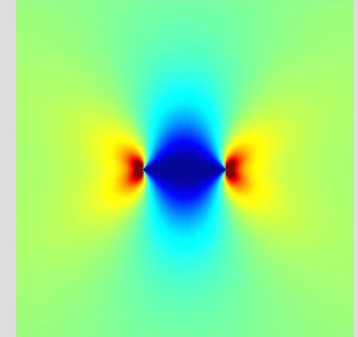
Sxy



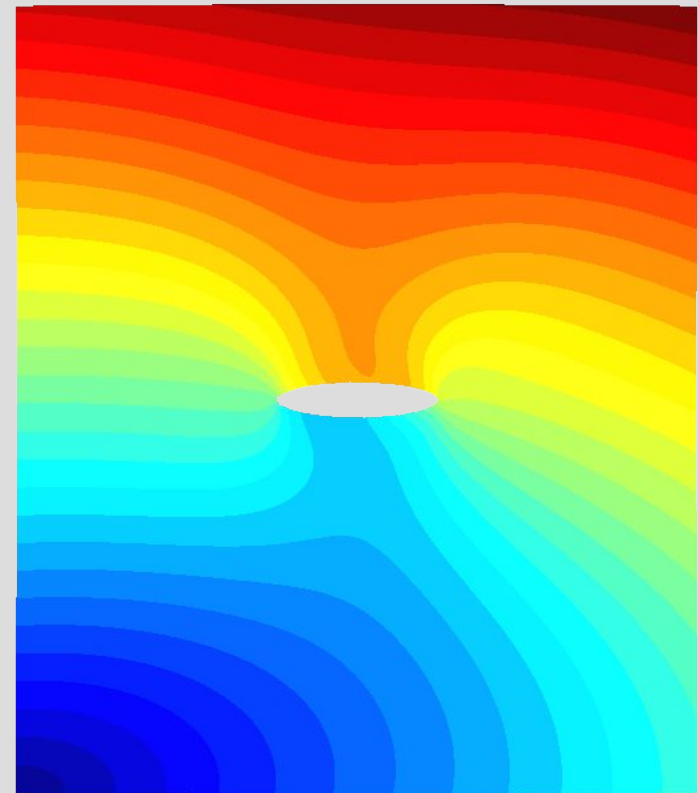
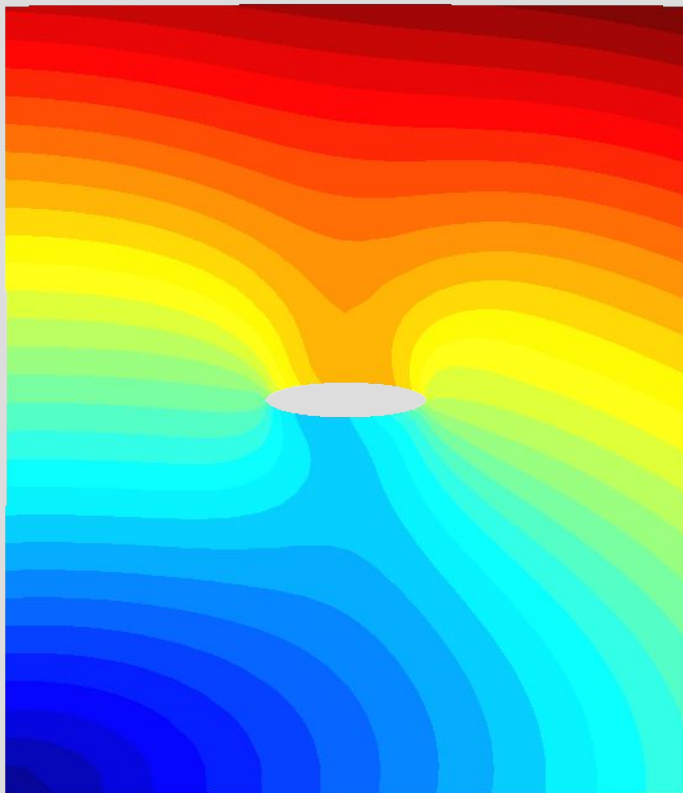
Potential



Syy



# Convergence study



Displacement

# Convergence study

- Energy norm with respect to the internal energy

$$U = \int_V \left( \frac{1}{2} \epsilon_{ij} c_{ijkl} \epsilon_{kl} + \frac{1}{2} E_i \epsilon_{ij} E_j \right) dV$$

$$E_U =$$

$$\int_V \sqrt{\frac{1}{2} \left( \epsilon_{ij} - \epsilon_{ij}^{ex} \right) c_{ijkl} \left( \epsilon_{kl} - \epsilon_{kl}^{ex} \right) + \frac{1}{2} \left( E_i - E_i^{ex} \right) \epsilon_{ij} \left( E_j - E_j^{ex} \right)} dV$$

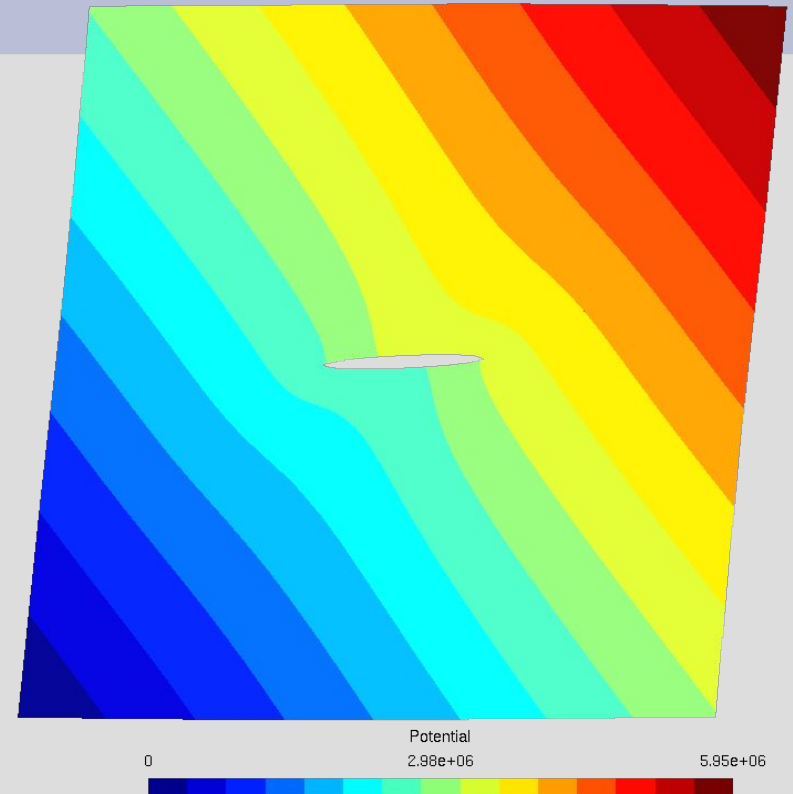
=

$$\int_V \sqrt{\frac{1}{2} \left( u_i - u_i^{ex} \right)_{,j} c_{ijkl} \left( u_k - u_k^{ex} \right)_{,l} + \frac{1}{2} \left( \varphi - \varphi^{ex} \right)_{,i} \epsilon_{ij} \left( \varphi - \varphi^{ex} \right)_{,j}} dV$$



# Convergence study

- Energy norm
  - comparison with standard crack tip enrichment
  - Infinite body with embedded crack
  - inclined material axes ( $30^\circ$ )
  - PZT4 orthotropic material



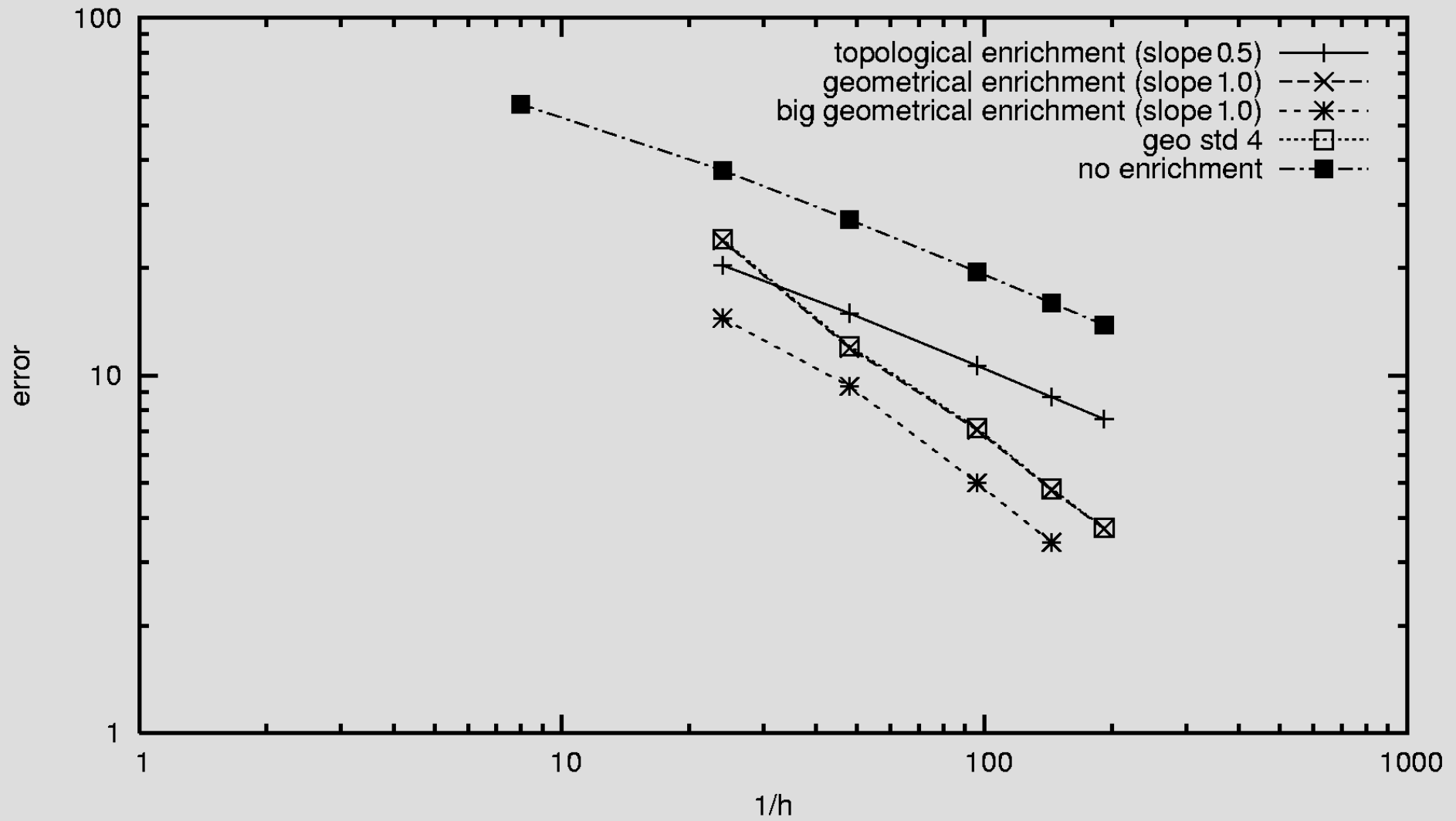
$$c = 10^{10} \begin{bmatrix} 14.02 & 7.892 & 7.565 & 0 & 0 & 0 \\ 7.892 & 14.02 & 7.565 & 0 & 0 & 0 \\ 7.565 & 7.565 & 11.58 & 0 & 0 & 0 \\ 0 & 0 & 0 & 2.527 & 0 & 0 \\ 0 & 0 & 0 & 0 & 2.527 & 0 \\ 0 & 0 & 0 & 0 & 0 & 3.064 \end{bmatrix}$$

$$e = 10^0 \begin{bmatrix} 0 & 0 & 0 & 0 & 13.0 & 0 \\ 0 & 0 & 0 & 13.0 & 0 & 0 \\ -5.268 & -5.268 & 15.44 & 0 & 0 & 0 \end{bmatrix}$$

$$\varepsilon = 10^{-9} \begin{bmatrix} 6.68 & 0 & 0 \\ 0 & 6.68 & 0 \\ 0 & 0 & 5.523 \end{bmatrix}$$

# Energy error

- Exact vs finite element fields



# Energy error

- The “classical” enrichment gives almost the same results as the specific enrichment, with less computational overhead.
- It is not clear whether different material laws (e.g. “more” anisotropic) lead to different results

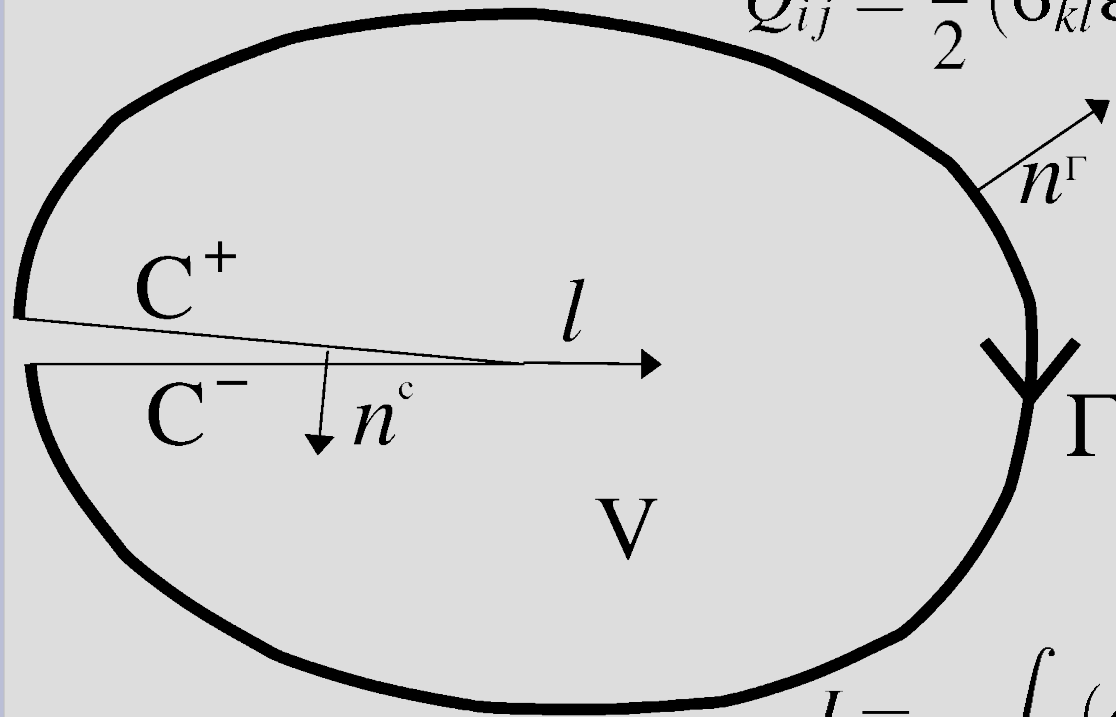
$$g_i(r, \theta) = \left\{ \sqrt{r} \sin \frac{\theta}{2}, \sqrt{r} \cos \frac{\theta}{2}, \sqrt{r} \sin \frac{\theta}{2} \sin \theta, \sqrt{r} \cos \frac{\theta}{2} \sin \theta \right\}$$

# SIFs computation

- Contour integrals on  $\Gamma \rightarrow$  Domain integrals over  $V$

$$Q_{ij} = \frac{1}{2} (\sigma_{kl} \varepsilon_{kl} - D_k E_k) \delta_{ij} - \sigma_{kj} u_{k,i} - D_j \varphi_{,i}$$

$$q_i = \Lambda l_i$$



$$J = - \int_{\Gamma} q_i n_j Q_{ij} d\Gamma$$

$$J = - \int_V (q_i Q_{ij})_{,j} dV + \int_{C^+ \cup C^-} q_i Q_{ij} n_j dS$$

# Interaction integrals

- Same procedure used to compute interaction integrals (no crack loading) :

$$\begin{aligned}
 I &= \int_V q_{i,j} \left( \sigma_{kj} u_{k,i}^{aux} + \sigma_{kj}^{aux} u_{k,i} + D_j \varphi_{,i}^{aux} + D_j^{aux} \varphi_{,i} \right) dV \\
 &+ \int_V q_i \left( \sigma_{kj} u_{k,ij}^{aux} + \sigma_{kj,j}^{aux} u_{k,i} + D_j \varphi_{,ij}^{aux} + D_{j,j}^{aux} \varphi_{,i} \right) dV \\
 &- \int_V q_{i,j} \left( \sigma_{kl} \varepsilon_{kl}^{aux} - D_k E_k^{aux} \right) \delta_{ij} dV \\
 &- \int_V q_i \left( \sigma_{kl} \varepsilon_{kl,i}^{aux} - D_k E_{k,i}^{aux} \right) dV
 \end{aligned}$$

$$I = \int_{\Gamma} G^{aux} \Lambda d\Gamma \quad G^{aux} = Y_{MN} K_M K_N^{aux} \quad Y_{MN} K_M K_N^{aux} = \frac{I}{\int_{\Gamma} \Lambda d\Gamma}$$

# Interaction integrals

- Relation between  $G$  and the  $K$  factors
  - Simpler case of the isotropic elasticity well known

$$Y_{MN} K_M K_N^{aux} = \{K_I K_{II} K_{III}\} \begin{bmatrix} \frac{2(1-\nu^2)}{E} & 0 & 0 \\ 0 & \frac{2(1-\nu^2)}{E} & 0 \\ 0 & 0 & \frac{2(1+\nu)}{E} \end{bmatrix} \begin{Bmatrix} K_I^{aux} \\ K_{II}^{aux} \\ K_{III}^{aux} \end{Bmatrix}$$

- The Irwin matrix depends on the material orientation and is not explicitly known for piezos.

$$G^{aux1,aux2} = Y_{MN} K_M^{aux1} K_N^{aux2}$$

$$I^{aux1,aux2} = \int_{\Gamma} G^{aux1,aux2} \Lambda d\Gamma \quad Y_{MN} K_M^{aux1} K_N^{aux2} = \frac{I^{aux1,aux2}}{\int_{\Gamma} \Lambda d\Gamma}$$

# Interaction integrals

- By using the eigenfunction set, every term in the Irwin matrix can be determined

– for instance :

$$\left\{ K_I^{aux1} = 1 \quad K_{II}^{aux1} = 0 \quad K_{III}^{aux1} = 0 \quad K_{IV}^{aux1} = 0 \right\}$$

$$\left\{ K_I^{aux2} = 0 \quad K_{II}^{aux2} = 1 \quad K_{III}^{aux2} = 0 \quad K_{IV}^{aux2} = 0 \right\}$$

$$\frac{I^{aux1,aux2}}{\int_{\Gamma} \Lambda d\Gamma} = Y_{MN} K_M^{aux1} K_N^{aux2}$$

$$= Y_{12} = Y_{21}$$

- No need of finite element support because the Irwin matrix is intrinsic (for a given material orientation)

$$I^{aux1,aux2} = \int_{\Gamma} q_i n_j \left( \sigma_{kj}^{aux1} u_{k,i}^{aux2} + \sigma_{kj}^{aux2} u_{k,i}^{aux1} + D_j^{aux1} \phi_{,i}^{aux2} + D_j^{aux2} \phi_{,i}^{aux1} \right) d\Gamma$$

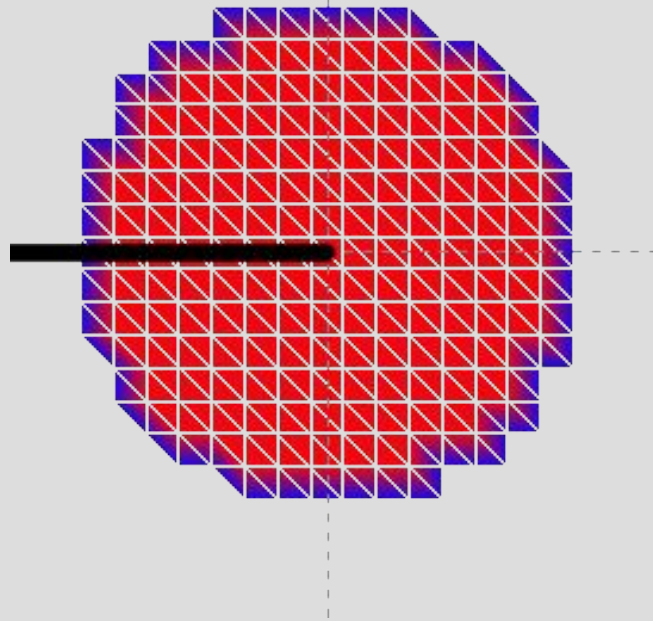
$$- \int_{\Gamma} q_i n_j \frac{1}{2} \left( \sigma_{kl}^{aux1} \epsilon_{kl}^{aux2} + \sigma_{kl}^{aux2} \epsilon_{kl}^{aux1} - D_k^{aux1} E_k^{aux2} - D_k^{aux2} E_k^{aux1} \right) \delta_{ij} d\Gamma$$

# Choice of $\Lambda$

The field  $\Lambda$  describes the geometry of the integration domain  $S$ .

$$\Lambda = \sum_i N_i \Lambda_i$$

$$\Lambda_i = \begin{cases} 1 & \text{if } \text{support}(N_i) \subset S \\ 0 & \text{otherwise} \end{cases}$$



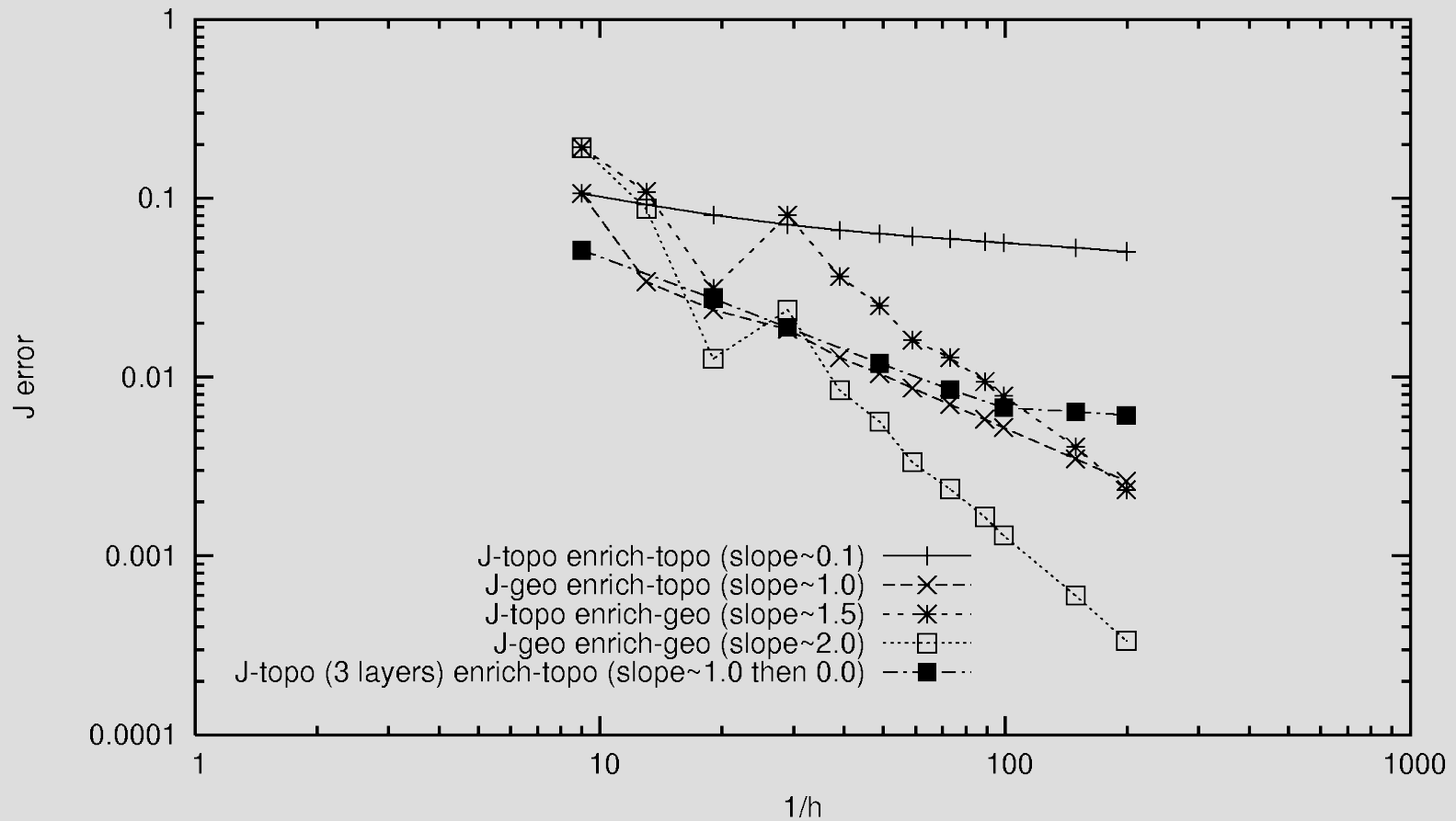
Two choices of integration domain with regard to  $h$ :

- Topological
- Geometrical



# J error

- Exact J vs computed J-integral



# Conclusion & future work

- Application of the X-Fem for piezos
- The convergence study shows that the four classical enrichment functions are enough
- Use of equivalence volume integrals to compute the electromechanical J-integral
- Interaction integrals will be used to extract K factors
- Auxiliary fields can also be used to compute the local Irwin matrix

# Conclusion & future work

- Systematic investigations of J and the K factors's accuracy
- Propagation laws
- Investigation for a electrically permeable crack
- 3D extensions (esp. for the eigenfunctions needed for K extraction)